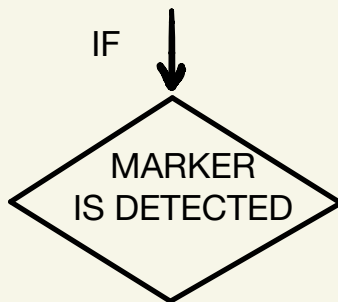
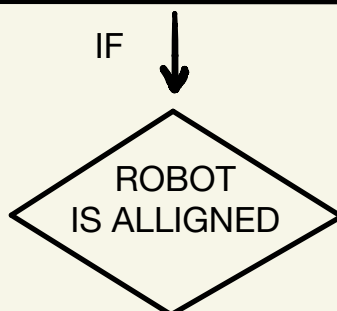




The robot is stopped.
The camera is rotating looking
for marker detection.



The robot (and the camera) are
aligning in the marker direction.



The robot is going forward
through the target.



The robot stops and go backwards
to allow next iterations.