

K

This handout is a corpus of background knowledge used by example ADJ problems. The knowledge listed here is taken as ground truth in assumptions in the example ADJ problem(s). It also serves as an example K. **This document does not apply to any assignments in any class. Do not use it to solve any homework.**

SER222: Priority Queues

Definition 1. Binary Tree: A binary tree is a recursive data structure composed of elements called nodes that contain a value, and then references to at most two child nodes.

Definition 2. Complete Binary Tree: a complete binary tree is one where every level is full except the last, and the last level is filled from the left to the right.

Definition 3. Maximum Heap: “A binary tree is heap-ordered if each node is larger than or equal to the keys in that node’s two children (if any).” (Sedgewick). The term *key* refers to the label of a conceptual node in a heap, and the term *value* refers to some piece of data that is attached to that node. Any pair of keys may be compared to check their relative order.

Definition 4. Heap-ordered Array: We say that an array is heap-ordered if the root element of the heap (if it exists) is stored in at index 1, and where the following formulas may be used to find a parent’s (call it p) left (call it c_{left}) and right children (call it c_{right}): $p = \lfloor \frac{k}{2} \rfloor$, $c_{left} = 2k$, $c_{right} = 2k + 1$.

Definition 5. Priority Queue: a priority queue is an abstract data structure that supports adding (“insert”) and removing elements (“delMax”). Data is represented as a complete binary tree, and is stored as a heap-ordered array. Assume that keys are unique. Per the Sedgewick implementation, both operations take $O(\log n)$ time, and both result in a complete and heap-ordered tree. These times will be taken to be optimal. See Algorithm 1.

Algorithm 1 Pseudocode for standard priority queue implementation.

```
Integer N           //number of entries in PQ
Key[] keys          //contains N elements
Value[] values      //contains N elements
```

```
boolean less(int i, int j):
    return (keys[i] is less than keys[j])
```

```
void swim(int k):
    while (k > 1 AND less(k/2, k)):
        parent = k/2
        exchange keys(k, parent)
        exchange values(k, parent)
        k = parent;
```

```
void sink(int k):
    while (2*k <= N):
        integer j = 2*k
        if (j < N AND less(j, j+1)) j++
        if NOT less(k, j) break
        exchange keys(k, j)
        exchange values(k, j)
        k = j
```

```
void insert(Key k, Value v):
    N = N + 1
    keys[N] = k
    values[N] = v
    swim(N)
```

```
public Key, Value delMax():
    Key maxK = keys[1]
    Key maxV = values[1]
    N = N - 1
    exchange keys(1, N)
    exchange values(1, N)
    sink(1)
    return maxK, maxV
```
