

# **CODE DIARY**

## Mini-Verilog 8-bit CPU

## **Overview:**

0. Introduction	3
1. Definition of the Architecture	3
2. Design of the ISA	3
3. Implementation of the Datapath	4
4. Implementation of the FSM	4
5. Hexadecimal Programs Creation	4
6. Development of an Assembler in Python	4
7. Generation of the List File	5
8. Automatization with Makefile	5
9. Simulation and Verification	5
10. References	5

## 0. Introduction:

This project consists of the design and implementation of a mini processor using Verilog[1] for its description. The main objective was to understand the internal functionality of a simple architecture, from the definition of the ISA[2] (Instruction Set Architecture) to the execution of very simple programs on simulation.

On the next points it is described the main elements that were developed during the project:

### 1. Definition of the Architecture:

The defined architecture consists of:

Datapath of 8 bits.

- ❖ 8 general registers (R0-R7).
- ❖ Data memory of 8 bits.
- ❖ Instructions memory apart from data memory.
- ❖ Instructions of 16 bits.

Even though the processor works with 8-bit data, the instructions are composed by 16 bits for:

- ❖ The Opcode (4 bits)
- ❖ Destination Register (3 bits)
- ❖ Two source registers (3 bits)

This decision comes from:

- ❖ We have 10 different instructions, to define each one of them as a different instruction we will need at least 4 bits ( $2^4 = 16$  possible combinations,  $2^3 = 8$ , which wouldn't be enough to define 10 instructions).
- ❖ At least 3 bits to define 7 different registers ( $2^3 = 8$ ). To be able to specify each one of the registers that we need (for a non immediate operation) we need to specify a different register, 9 bits in total.

### 2. Design of the ISA[2]:

The definition of the format follows the next structure:

```
[15:12] opcode
[11:9]  rd
[8:6]  rs1
[5:3]  rs2
[2:0]  not used - useful in case the processor becomes "bigger"
```

Implemented instructions:

- ❖ NOP
- ❖ ADD
- ❖ SUB
- ❖ AND
- ❖ OR

- ❖ LDI (load immediate)
- ❖ LD (load from memory)
- ❖ ST (store to memory)
- ❖ JMP (incondicional jump)
- ❖ HALT

### **3. Implementation of the Datapath[3]:**

Using Verilog[1], the following modules have been defined:

- ❖ ALU (alu.v)  
Implements arithmetico-logic operations of 8 bits.
- ❖ Register bank (regfile.v)  
8 registers of 8 bits with two read ports and one write port.
- ❖ Data memoria (dmem.v)  
Simple RAM for LD and ST operations.
- ❖ Instruction memory (imem.v)  
Loads the program from a .hex file.
- ❖ CPU (cpu.v)  
Implements the control unit by a multi-cycle FSM[4].

### **4. Implementation of the FSM[4] (Control Unit):**

The CPU is based on a finite state machine with the next phases:

- ❖ FETCH
- ❖ DECODE
- ❖ EXECUTE
- ❖ MEMORY (if we need it)
- ❖ WRITEBACK (if we need it)

This structure lets the user correctly execute simple instructions, such as ADD or even instructions with additional words, such as LDI, LD, etc.

### **5. Hexadecimal[5] Programs Creation:**

In the beginning, hexadecimal were created by hand, manually codifying the instructions following the defined format previously.

Such as:

```
5200
0003
5400
0005
1650
F000
```

Which loads values to the registers, adds them and finally ends the execution of the program.

### **6. Development of an Assembler[6] in Python:**

To make easier running programs on this mini-processor, its been developed an assembler[6] which:

- ❖ Converts assembly code (which is easier to use to code a program) to hexadecimal.
- ❖ Manages labels.
- ❖ Generates automatically the binary codification.
- ❖ Creates a .asm.lst file with the information of the depuration.

## 7. Generation of the List File:

To make the depuration of a code easier, the assembler[6] generates the “lst” file, which was previously mentioned, but in this point of the documentation will be defined a little bit better. This file includes:

- ❖ Address of each instruction
- ❖ Codification in hexadecimal
- ❖ Original line in Assembly

This makes possible to verify that the assembly translation to machine code is correct.

## 8. Automatization with Makefile:

In the repository a Makefile can be found. This integrates the automatization of the execution of the whole machine by:

Executing the assembler[6] (`make asm`)

Compiling and simulating with Icarus Verilog[1] (`make sim`)

Execute the whole flow of the machine (`make run`)

## 9. Simulation and Verification:

The CPU gets tested by:

- ❖ Testbenching it with Verilog[1].
- ❖ Simulating it with iverilog[7].
- ❖ Generating a “.vcd” to visualize signaling.

## 10. References:

- [1] <https://www.verilog.com>
- [2] <https://www.geeksforgeeks.org/computer-organization-architecture/microarchitecture-and-instruction-set-architecture/>
- [3] <https://www.youtube.com/watch?v=5ox9Yt3z5d0>
- [4] <https://www.freecodecamp.org/news/finite-state-machines/>
- [5] <https://www.freecodecamp.org/news/finite-state-machines/>
- [6] <https://www.lenovo.com/in/en/glossary/assembler/?orgRef=https%253A%252F%252Fwww.google.com%252F>
- [7] <https://github.com/steveicarus/iverilog>