# Machine Learning, Spring 2019

### Homework 3

### Due on **April 7**, **11:59 PM**

- 1. Submit your solutions to Gradescope (www.gradescope.com). Homework of this week contains two part, **theoretical part** and **programming part**. So there are two assignments in gradescope, the assignment titled with programming part will require you to submit your code.
- 2. Make sure each solution page is assigned to the corresponding problems when you submit your homework.
- 3. Any programming language is allowed for your code, but make sure it is clear and readable with necesary comments.

#### 1 Subdifferential

For the following functions, verify whether the function is subdifferentiable everywhere, if it is, calculate a subgradient at a given x, if not, give your proof.

- (a)  $f(x) = \max_{i=1,...,m} |a_i^T x + b_i|$ . (5 points)
- (b)  $f(x) = x_{[1]} + \cdots + x_{[k]}$ , where  $x_{[i]}$  is the *i*th largest element of  $x \in \mathbb{R}^n$ . (5 points)
- (c)  $f: \mathbb{R} \to \mathbb{R}$  with dom  $f = \mathbb{R}_+$ :(5 points)

$$f(x) = \begin{cases} 1 & x = 0, \\ 0 & x > 0. \end{cases}$$

## 2 Backtracking line search

Consider the following optimization problem:

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \ f(x), \tag{1}$$

where  $f: \mathbb{R}^n \to \mathbb{R}$  is a convex and differentiable function, and its gradient is Lipschitz continuous, i.e., there exists L > 0 such that

$$\|\nabla f(x) - \nabla f(y)\|_2 \le L\|x - y\|_2, \quad \forall x, y \in \mathbb{R}^n.$$

The gradient descent method for solving problem (1) updates as

$$x_{k+1} = x_k - \alpha_k \nabla f(x_k). \tag{2}$$

Here we apply backtracking line search to determine the stepsize  $\alpha_k$  in (2). The gradient descent method using backtracking line search updates according to:

- Initialization: Fix parameter  $\gamma \in (0,1)$ .
- At the kth iteration:
  - Starts with  $\alpha_k = 1$ .
  - If

$$f(x_k - \alpha_k \nabla f(x_k)) > f(x_k) - \frac{\alpha_k}{2} \|\nabla f(x_k)\|_2^2$$

update  $\alpha_k = \gamma \alpha_k$  and repeat this sub-step. Otherwise, k = k + 1.

(a) Show that  $\|\nabla f(x_k)\|_2 \to 0$  when  $k \to \infty$ . (10 points)

Hint: The proof can be taken in three steps and we give the hint of the first two steps

- Step 1: find a lower bound of step size such that  $\underline{\alpha} \leq \alpha_k$  for each k.
- Step 2: find a upper bound of  $f(x_k) f(x_{k+1})$  in terms of  $\|\nabla f(x_k)\|_2$ .
- Step 3: (No hint).
- (b) Instead of using the negative gradient as the descent direction, we consider a more general direction  $d_k$ , where  $||d_k|| = ||\nabla f(x_k)||$  and the angle between  $d_k$  and  $-\nabla f(x_k)$  satisfies  $0^{\circ} \leq \angle(d_k, -\nabla f(x_k)) \leq \theta < 90^{\circ}$  for some  $\theta$ . The new update follows

$$x_{k+1} = x_k + \alpha_k d_k. (3)$$

Here we also consider using backtracking line search to determine the stepsize  $\alpha_k$ . At the kth iteration, (??) with backtracking line search check whether the following condition holds:

$$f(x_k + \alpha_k d_k) > f(x_k) + \frac{\alpha_k}{2} \langle \nabla f(x_k), d_k \rangle.$$
 (4)

The remaining part of the algorithm is the same as it for gradient descent. Show that  $\|\nabla f(x_k)\| \to 0$  when  $k \to \infty$ . (10 points)

## 3 Stationary Points

#### 3.1 Finding Stationary Points

Find the stationary points for the following functions f(x):

(Hint: notice whether the domain of the function includes the stationary points you find.)

(a) 
$$f(x) = (x-1)/(x^2+5x+3)$$
. (3 points)

(b) 
$$f(x) = \ln(x^3 - 6x^2 - 15x + 1)$$
. (3 points)

(c) 
$$f(x) = 7 + (2x^2 - 10x)\sqrt{x}$$
.(3 points)

#### 3.2 Testing Stationary Points

You are given the function f(x) and you have to find its stationary points. For each stationary point determine if it is a local maximum or local minimum (or neither) using the second derivative information.

(a) 
$$f(x) = \ln(x) + 1/x$$
.(3 points)

(b) 
$$f(x) = 2x^3 - 3x^2 - 12x + 5.$$
(3 points)

### 4 Convergence rates of Gradient Descent

We analysis the convergence rate from three possible cases, and suppose that:

$$w_* \in \arg\min_w F(w)$$

where F is convex.

(a) The Smooth Case:

Suppose F is L smooth and we can obtain:

$$F(w') \le F(w) + \nabla F(w) \cdot (w' - w) + \frac{L}{2} ||w - w'||^2$$

We consider the update rule:

$$w_{t+1} = w_t - \eta \nabla F(w_t)$$

Please try to show that the gradient descent converges at rate of 1/t in this case. (Hint:  $\eta = 1/L$  and it equals to proof that  $F(w_t) - F(w_*) < \frac{L}{t} ||w_0 - w_*||^2$ , where  $w_*$  is a new point.)(10 points)

(b) The Smooth and Strongly Convex Case:

A function F is  $\mu$  strongly convex if

$$F(w') \ge F(w) + \nabla F(w) \cdot (w' - w) + \frac{\mu}{2} ||w - w'||^2$$

Similarly, we suppose that:

$$w_{t+1} = w_t - \eta \nabla F(w_t)$$

And we know the supporting lemma that:

$$\|\nabla F(w)\|^2 \le 2L(F(w) - F(w_*))$$

Please try to show that the GD algorithm has a constant learning rate. (Hint: In  $\frac{L}{\mu}log(\|w_0 - w_*\|/\epsilon)$  iterations our distance to the optimal point is  $\mathcal{O}(\epsilon)$ , and try to proof that:  $\|w_t - w_*\| \le (1 - \frac{\mu}{L})^t \|w_0 - w_*\|$ .(10 points)

(c) Non-smooth optimization and (sub-)gradient descent:

We denote that the update rule is:

$$w_{t+1} = w_t - \eta \nabla F(w_t)$$

where  $\nabla F(w_t)$  is the sub-gradient at  $w_t$  and it satisfies:

$$F(w') \ge F(w) + \nabla F(w) \cdot (w' - w)$$

Suppose that for all w we have that  $\|\nabla F(w)\| \leq B$  and  $\|w_0 - w_*\| \leq R$ . Set  $\eta = \frac{R}{B}\sqrt{\frac{2}{T}}$ , then please show that (10 points)

$$F(\frac{1}{T}\sum_{t} w_{t}) - F(w_{*}) \le \frac{RB}{\sqrt{T}}$$

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### 5 Programming Problem

(a) Given the following basic least squares formulation,

$$\min \quad f(x) = ||Ax - b||_2^2 \tag{5}$$

where,  $A \in \mathbb{R}^{80\times3}, x \in \mathbb{R}^3, b \in \mathbb{R}^{80}$ . Please implement the gradient descent method using the given data set (**A.txt** and **b.txt**) and plot the iteration process.(5 points)

- (b) Let's look deeper into above problem and use the optimal value of x you get (approximate value is fine). Generate matrix A, b by yourself to make the Hessian matrix have different condition number, verify the relation between convergence rate and condition number and plot your results. (5 points)
- (c) Given the following function, please compare the performance of different stepsize/learning rate iteration methods (at least two) and plot your results.(10 points)

$$f(x,y) = (1-x)^2 + 100(y-x^2)^2$$