layton Salinger Ketner

Mechanical Engineering & Computer \overline{S} cience

www.claytonketner.com ⊠ claytonketner@me.com ☎ (650) 533 9695

Home: 1407 Tarrytown st.

San Mateo, CA 94402

School: 817 W. 30th st.

Los Angeles, CA 90007

INTRODUCTION

Fifth year (of five) undergraduate Mechanical Engineering and Computer Science student with strong practical experience, close attention to detail, and an interest in robotics, design, and fabrication. Friendly and effective team leader able to quickly adapt to changing environments and technology

leader	able to quickly adapt to changing environments and technologies.				
	EDUCATION				
	Major: Mechanical Engineering – Minor: Computer Science				
Fall 2011 – Spring 2014	University of Southern California GPA: [fall '13]: 3.71 – Graduate B.S. in May, 2014				
	Advanced computer aided design $(CAD + FEA)$, linear control systems, dynamic systems, vibrations, heat transfer, advanced strength of materials, engineering algorithms, robotics algorithms, artificial intelligence				
Fall 2009 – Spring 2011	University of Massachusetts, Amnerst GPA: Imajori: 358 = Transfer to USC				
	Statics, dynamics, strength of materials, thermodynamics				
	EXPERIENCE				
Fall 2013 (4 Months)	Design of a Mechanical Governor – AME 408 Final Project – Managed team to design a rotating governor part, given deformation and natural frequency requirements using SolidWorks. Tags: LEADERSHIP TEAMWORK SOLIDWORKS CAD FEA – <u>more info</u>				
Fall 2013 (4 Months)	Intro to Robotics — CSCI 445 — Learned localization (particle & Kalman filters), mapping (SLAM & FastSLAM), decision processes (MDP & POMDP), and sensor calibration and use. Tags: ROBOTICS ARDUINO RASPBERRY PI ALGORITHMS SENSORS — <u>more info</u>				
Fall 2012 (4 Months)	Senior Project — Remote Inspection Vehicle — Remote control robot for the 2013 ASME design competition. Designed and built the controller. Coded and wired the controller and robot. Tags: CAD DESIGN LEADERSHIP CODE WIRELESS ROBOTICS — <u>more info</u>				

(2 Months)

Summer 2012

OSIsoft – Virtual Campus Intern (40 hr/wk)

Summer 2011 (3 Months)

- Independently researched and integrated OSIsoft PI System with SAS analytics.
- Gave two live progress presentations to the Virtual Campus team.

Tags: CAD | CNC | DESIGN | FABRICATION | CODE | MATLAB | ROBOTICS - more info

- Concluded findings in a White Paper posted to OSIsoft's vCampus website.
- Received praise from an outside company for quality of the White Paper.

Robotic Arm – Designed, manufactured, wired, and coded independently and from scratch.

	SKILLS			
Engineering	SOLIDWORKS & SIM ●●●	SOLID EDGE €	PRO-E ●	TECHNICAL REPORTS ●●●
	LABVIEW ●	MATLAB & SIMULINK •••	MATHEMATICA ●	CONTROL SYSTEMS ●●
Hands-On	HAND TOOLS ••••	MECHATRONICS ●●◀	ROBOTICS ●● (ELECTRONICS PROTO ●●●
	3D PRINTING €	CNC MILL/ROUTER €	MACHINE SHOP ●●	
Programming	●●● TINUL & AVAL	PYTHON ● €	C++ ●	LATEX ● (
	UI & UX ●	WEB DEVELOPMENT (
Miscellaneous	WORD & EXCEL ●●●●	COMMUNICATION ••••	LEADERSHIP ●●	

AFFILIATIONS & AWARDS

2011 - Present Sigma Phi Delta - Professional Engineering Fraternity - Active member - (Fall 2013) House Manager & Executive Board Member 2014 - Present USC Aerial Robotics Team - Mechanical team

 $\begin{array}{lll} \mbox{Fall 2013} & \mbox{\bf Dean's List} & \mbox{(USC)} \\ \mbox{Spring 2010} & \mbox{\bf Dean's List} & \mbox{(UMass)} \end{array}$

March 2012 Certified SolidWorks Associate - Score: 100%