

# Clayton Salinger Ketner

Mechanical Engineering & Computer Science

www.claytonketner.com  
claytonketner@me.com

## INTRODUCTION

Eager Mechanical Engineer and software developer with strong practical experience, close attention to detail, and an interest in robotics, design, and fabrication. Highly organized, friendly, and able to quickly learn and adapt to changing environments and technologies.

## WORK

### Counsyl – Automation Service Engineer

June 2014  
– Present  
(2 years)

- Principal mechanical design engineer
- R&D new automation hardware and software
  - Designed mechanical parts in SolidWorks
  - Programming with Django and Python - writing new apps, features, and bugfixes
- Perform error recovery and troubleshooting on high-uptime production robotics
- Research and document production issues to identify root cause

### San Bruno Pet Hospital – System Administrator

Summer 2013  
(4 months)

- Independently maintained and installed computer systems.
- Communicated with employees and external tech support to report and resolve technical issues.
- **Received praise for improving reliability of hardware and software.**

### OSIsoft – Virtual Campus Intern

Summer 2011  
(3 months)

- Independently researched & integrated OSIsoft PI System with SAS analytics software.
- Concluded findings in a White Paper posted to OSIsoft's vCampus website.
- **Received praise from an outside company for quality of the White Paper.**

## EDUCATION

Graduated from University of Southern California (USC)

2009 – 2014

**B.S.:** Mechanical Engineering – *Advanced computer aided design (CAD + FEA), linear control systems, dynamic systems, vibrations, heat transfer, advanced strength of materials*

**Minor:** Computer Science – *Robotics algorithms, artificial intelligence*

## PROJECTS

Fall 2013  
(4 months)

### Design of a Mechanical Governor – AME 408 Final Project at USC

Managed team to design a rotating governor part, given deformation and natural frequency requirements using SolidWorks.

Fall 2013  
(4 months)

### Intro to Robotics – CSCI 445 at USC

Learned localization (particle & Kalman filters), mapping (SLAM & FastSLAM), decision processes (MDP & POMDP), and sensor calibration and use.

Fall 2012  
(4 months)

### Remote Inspection Vehicle – Senior Project at USC

Remote control robot for the 2013 ASME design competition. Designed and built the controller. Programmed and wired the controller and robot.

Summer 2012  
(2 months)

### Robotic Arm – personal, for-fun project

Designed, manufactured, wired, and programmed independently.

## SKILLS

My Favorite  
Tools

**Mechanical** – SolidWorks

**Programming** – Python, Django, VIM, tmux

**Software Prototyping** – Arduino, Teensy, Raspberry Pi

**Hardware Prototyping** – my Makergear M2 3D printer, machine shop

Mechanical  
Engineering

**CAD** – SolidWorks, Pro-E, Solid Edge, PDM

**Design** – design for assembly and manufacture (DFA, DFM), mechanical simulation (FEA),

**Disciplines** – control systems, MATLAB & Simulink, LabVIEW, Mathematica, technical report writing

Programming

**Languages** – Python (+Django), Java, C++, LaTeX, web dev

**Methodologies, etc.** – TDD, version control (git), moving fast and not breaking things

**Hands-on**      Machining and wrenching (machine shop tools), construction and assembly, 3D printing

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**Other**      Mechatronics, PLC (realtime) programming

## AFFILIATIONS & AWARDS

**2011 – 2014**      **Sigma Phi Delta** – *Professional Engineering Fraternity*  
                                 – (Fall 2013) House Manager & Executive Board Member

**Spring 2014**      **USC Aerial Robotics Team** – *Mechanical team*

**Fall 2013**      **Dean's List** – *USC*

**Spring 2010**      **Dean's List** – *UMass*

**March 2012**      **Certified SolidWorks Associate** – *Score: 100%*