

```

yschoe@brain:~/teaching/src/prover
Run `fwupdmgr get-upgrades` for more information.

You have new mail.
Last login: Thu Sep 22 11:07:58 2022 from 128.194.120.224
yschoe@brain:~$ cd teaching/src/prover/
yschoe@brain:~/teaching/src/prover$ ls
dupe2.lsp dupe.lsp prover.lsp
yschoe@brain:~/teaching/src/prover$ gcl
GCL (GNU Common Lisp) 2.6.12 CLtL1 Fri Apr 22 15:51:11 UTC 2016
Source License: LGPL(gcl,gmp), GPL(unexec,bfd,xgcl)
Binary License: GPL due to GPL'ed components: (XGCL UNEXEC)
Modifications of this banner must retain notice of a compatible license
Dedicated to the memory of W. Schelter

Use (help) to get some basic information on how to use GCL.
Temporary directory for compiler files:
/tmp/

>(load "prover.lsp")
;; Loading "prover.lsp"
;; Loading "dupe2.lsp"

"[1] T
"
"[2] NIL
"
"[3] NIL
" ; Finished loading "dupe2.lsp"
;; Finished loading "prover.lsp"
T

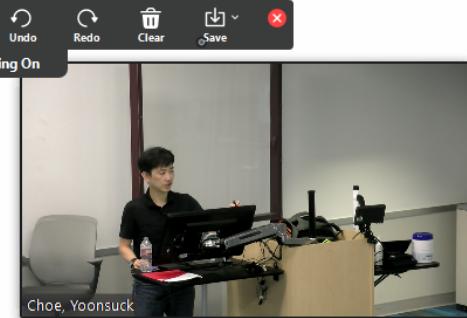
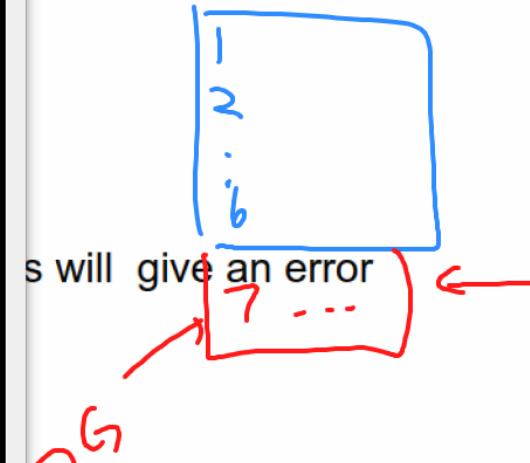
>*customs*

((1 ((V X) (S X (F X))) ((E X))) (2 ((V Y) (C (F Y))) ((E Y)))
 (3 ((E (A))) NIL) (4 ((D (A))) NIL) (5 ((D Z)) ((S (A) Z)))
 (6 NIL ((D W) (V W))) (7 NIL ((D R) (C R)))))

>(two-pointer *customs* 7)

```

set of support



So you want to tell the approval where to look for these.

yschoe@brain: ~/teaching/src/prover

```
>*customs*
((1 ((V X) (S X (F X))) ((E X))) (2 ((V Y) (C (F Y))) ((E Y)))
(3 ((E (A))) NIL) (4 ((D (A))) NIL) (5 ((D Z)) ((S (A) Z)))
(6 NIL ((D W) (V W))) (7 NIL ((D R) (C R))))
```

function

```
>(two-pointer *customs* 7)
1: (1 ((V X) (S X (F X))) ((E X)))
2: (2 ((V Y) (C (F Y))) ((E Y)))
3: (3 ((E (A))) NIL)
4: (4 ((D (A))) NIL)
5: (5 ((D Z)) ((S (A) Z)))
6: (6 NIL ((D W) (V W)))
7: (7 NIL ((D R) (C R)))
8: (8 ((V Y) ((D (F Y)) (E Y)))
9: (9 NIL ((C (A))))
10: (10 NIL ((C Z) (S (A) Z)))
11: (11 ((V A))) ((D (F (A)))))
12: (12 ((V Y)) ((E Y) (S (A) (F Y))))
13: (13 NIL ((E Y) (D (F Y)) (D Y)))
14: (14 ((V A))) ((C (F (A))) (E (A))))
15: (15 ((V (A))) ((S (A) (F (A)))))
16: (16 NIL ((D (F (A))) (D (A))))
17: (17 ((V (A))) ((E (A))))
18: (18 NIL ((S (A) (F Y)) (E Y) (D Y)))
19: (19 NIL ((D (F (A))) (E (A))))
20: (20 NIL ((D (F Z)) (E Z) (S (A) Z)))
21: (21 ((V (A))) ((C (F (A)))))
22: (22 NIL ((E (A)) (C (F (A))) (D (A))))
23: (23 NIL ((S (A) (F (A))) (D (A))))
24: (24 NIL ((D (F (A)))))
25: (25 NIL ((D (F (A))) (S (A) (A))))
26: (26 ((V (A))) NIL)
27: (27 NIL ((E (A)) (D (A))))
28: (28 ((V (A))) ((D (A)) (E (A))))
29: (29 NIL ((E (A)) (S (A) (F (A)))))
30: (30 NIL ((E Z) (S (A) (F Z)) (S (A) Z)))
31: (31 ((V (A))) ((E (F (A))) (D (F (F (A)))) (E (A))))
```

constant.

Who can see what you share here? Recording On

Choe, Yoonsuck

(Q) How many steps will this take?

1
2
3
...
7

s will give an error

① 5
② 10
③ > 30

you have not deal with. so this is on the positive side and this is the negative side, if, when you have your why so you have that, that and that as the resulting clothes.

yschoe@brain: ~/teaching/src/prover

```

5,22: (34 NIL ((C (F (A))) (E (A)) (S (A) (A))))
4,23: (35 NIL ((S (A) (F (A)))))
5,23: (36 NIL ((S (A) (F (A))) (S (A) (A))))
6,26: (37 NIL ((D (A))))
4,27: (38 NIL ((E (A))))
5,27: (39 NIL ((E (A)) (S (A) (A))))
3,28: (40 ((V (A))) ((D (A))))
5,28: (41 ((V (A))) ((E (A)) (S (A) (A))))
1,30: (42 ((V (A))) ((S (A) (F (F (A)))) (E (F (A))) (E (A))))
3,31: (43 ((V (A))) ((D (F (F (A)))) (E (F (A)))))
6,31: (44 NIL ((E (A)) (D (F (F (A)))) (E (F (A))) (D (A))))
4,32: (45 NIL ((C (F (A)))))
5,32: (46 NIL ((C (F (A))) (S (A) (A))))
4,37: (47 NIL NIL)
T

>(unit-preference *customs*)
_,-,: (1 ((V X) (S X (F X))) ((E X)))
_,-,: (2 ((V Y) (C (F Y))) ((E Y)))
_,-,: (3 ((E (A))) NIL)
_,-,: (4 ((D (A))) NIL)
_,-,: (5 ((D Z)) ((S (A) Z)))
_,-,: (6 NIL ((D W) (V W)))
_,-,: (7 NIL ((D R) (C R)))
4,6: (8 NIL ((V (A))))
3,1: (9 ((S (A) (F (A))) (V (A))) NIL)
4,7: (10 NIL ((C (A))))
3,2: (11 ((C (F (A))) (V (A))) NIL)
8,9: (12 ((S (A) (F (A)))) NIL)
12,5: (13 ((D (F (A)))) NIL)
8,11: (14 ((C (F (A)))) NIL)
13,6: (15 NIL ((V (F (A)))))
8,1: (16 ((S (A) (F (A)))) ((E (A))))
13,7: (17 NIL ((C (F (A)))))
14,17: (18 NIL NIL)
T

>[ ]

```

Who can see what you share here? Recording On

Choe, Yoonsuck

two-pointer (40)

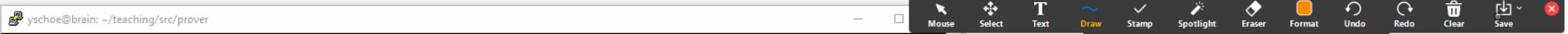
s will give an error

unit-preference- (11)

And this took 11 steps.

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You are screen sharing Stop Share



```
yschoe@brain: ~/teaching/src/prover
1,30: (42 ((V (A))) ((S (A) (F (F (A)))) (E (F (A))) (E (A))))
3,31: (43 ((V (A))) ((D (F (F (A)))) (E (F (A))))))
6,31: (44 NIL ((E (A)) (D (F (F (A)))) (E (F (A))) (D (A))))
4,32: (45 NIL ((C (F (A))))))
5,32: (46 NIL ((C (F (A))) (S (A) (A))))
4,37: (47 NIL NIL)
```

T

```
>(unit-preference *customs*)
_,' _: (1 ((V X) (S X (F X))) ((E X)))
_,' _: (2 ((V Y) (C (F Y))) ((E Y)))
_,' _: (3 ((E (A))) NIL)
_,' _: (4 ((D (A))) NIL)
_,' _: (5 ((D Z)) ((S (A) Z)))
_,' _: (6 NIL ((D W) (V W)))
_,' _: (7 NIL ((D R) (C R)))
4, 6: (8 NIL ((V (A))))
3, 1: (9 ((S (A) (F (A))) (V (A))) NIL)
4, 7: (10 NIL ((C (A))))
3, 2: (11 ((C (F (A))) (V (A))) NIL)
8, 9: (12 ((S (A) (F (A))) NIL)
12, 5: (13 ((D (F (A))) NIL)
8,11: (14 ((C (F (A))) NIL)
13, 6: (15 NIL ((V (F (A))))))
8, 1: (16 ((S (A) (F (A))) ((E (A)))))
13, 7: (17 NIL ((C (F (A))))))
14,17: (18 NIL NIL)
```

T

```
>*howling*
```

```
((1 ((HOWL Z)) ((HOUND Z)))
(2 NIL ((HAVE X Y) (CAT Y) (HAVE X Z) (MOUSE Z)))
(3 NIL ((LS W) (HAVE W V) (HOWL V))) (4 ((HAVE (JOHN) (A)) NIL)
(5 ((CAT (A)) (HOUND (A))) NIL) (6 ((MOUSE (B)) NIL))
(7 ((LS (JOHN)) NIL) (8 ((HAVE (JOHN) (B)) NIL)))
```

```
>[green square]
```

6
6

s will give an error

So when you run the two pointer method, you have to
specify number six.

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You are screen sharing Stop Share

yschoe@brain: ~/teaching/src/prover

```

26,36: (79 NIL ((HAVE X (B)) (HAVE X (A))))
8,37: (80 NIL ((HOUND (B))))
33,37: (81 NIL ((MOUSE (B)) (HAVE (JOHN) (A))))
21,39: (82 NIL ((HAVE (JOHN) (A)) (HAVE (JOHN) (B))))
34,39: (83 NIL ((HAVE (JOHN) (A))))
26,44: (84 NIL ((MOUSE (A))))
8,45: (85 ((HOUND (A))) NIL)
12,47: (86 ((HOWL (A))) NIL)
28,47: (87 NIL ((LS W) (HAVE W (A))))
31,47: (88 NIL ((LS (JOHN))))
26,48: (89 NIL ((HAVE (JOHN) (B))))
26,49: (90 NIL ((MOUSE (B))))
47,54: (91 NIL NIL)
T

>(unit-preference *howling*)
-, -: (1 ((HOWL Z)) ((HOUND Z)))
-, -: (2 NIL ((HAVE X Y) (CAT Y) (HAVE X G46405) (MOUSE G46405)))
-, -: (3 NIL ((LS W) (HAVE W V) (HOWL V)))
-, -: (4 ((HAVE (JOHN) (A))) NIL)
-, -: (5 ((CAT (A)) (HOUND (A))) NIL)
-, -: (6 ((MOUSE (B))) NIL)
-, -: (7 ((LS (JOHN))) NIL)
-, -: (8 ((HAVE (JOHN) (B))) NIL)
4, 3: (9 NIL ((HOWL (A)) (LS (JOHN))))
4, 2: (10 NIL ((MOUSE G46405) (HAVE (JOHN) G46405) (CAT (A))))
4, 2: (11 NIL ((MOUSE (A)) (CAT Y) (HAVE (JOHN) Y)))
4,10: (12 NIL ((CAT (A)) (MOUSE (A))))
7, 9: (13 NIL ((HOWL (A))))
13, 1: (14 NIL ((HOUND (A))))
6,10: (15 NIL ((CAT (A)) (HAVE (JOHN) (B))))
14, 5: (16 ((CAT (A))) NIL)
7, 3: (17 NIL ((HOWL V) (HAVE (JOHN) V)))
8,15: (18 NIL ((CAT (A))))
16,18: (19 NIL NIL)
T

>[ ]

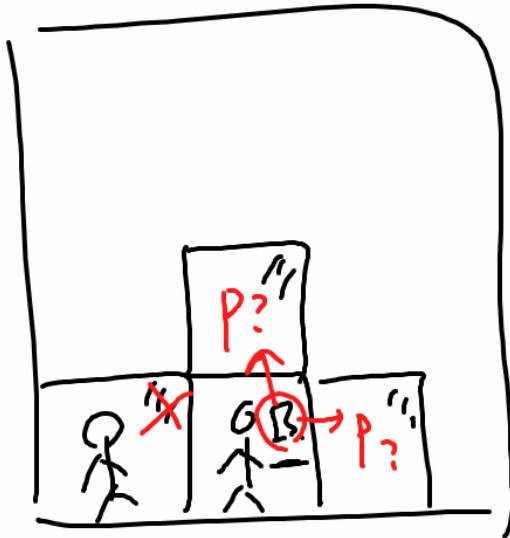
```

(mouse 646405)
 ↓
 mouse (g46405)

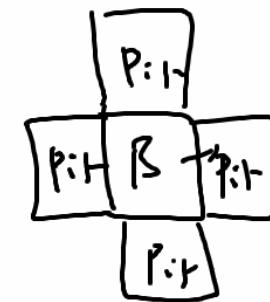
c1: P(x)
 c2: P(x) g46405



Example Domain: Wumpus World

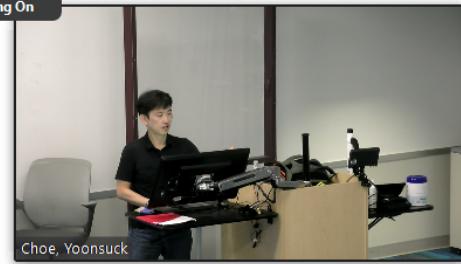


Stench		Breeze	PIT
Wumpus	Breeze	PIT	Breeze
Stench		Breeze	
START	Breeze	PIT	Breeze

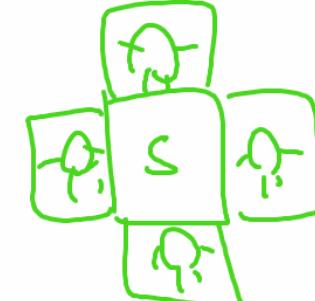
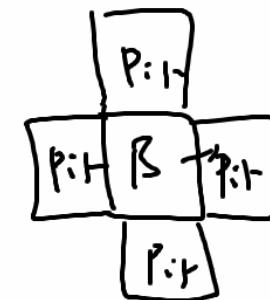
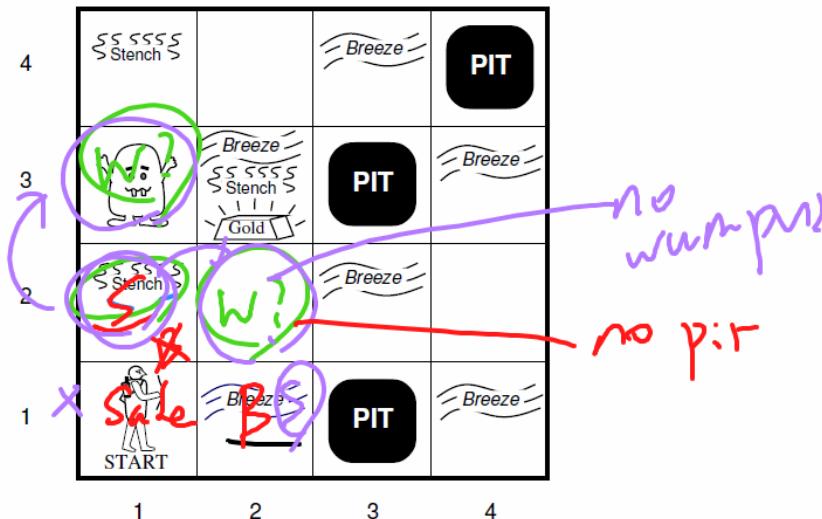
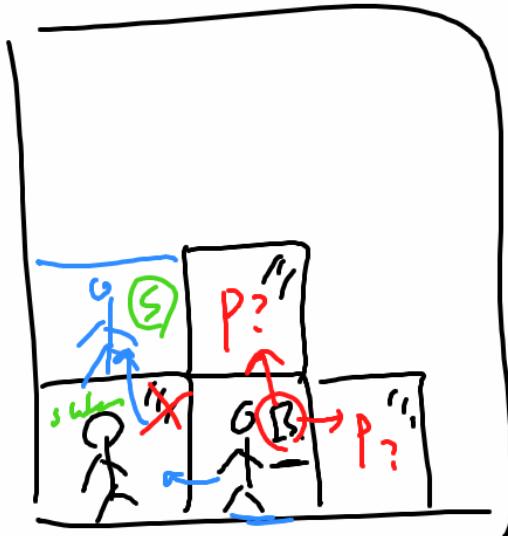


- Want to get to the gold and grab it.
- Want to avoid pits and the “wumpus”.
- Clues: breeze near pits and stench near the wumpus.
- Other sensors: wall (bump), gold (glitter), kill (scream)
- Actions: move, grab, or shoot

then what do you do in the next step, you come back.

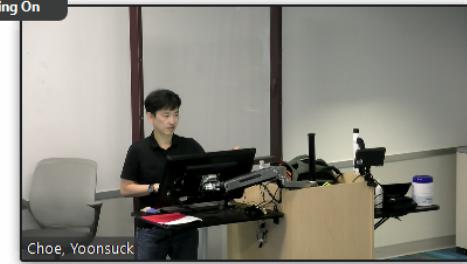


Example Domain: Wumpus World

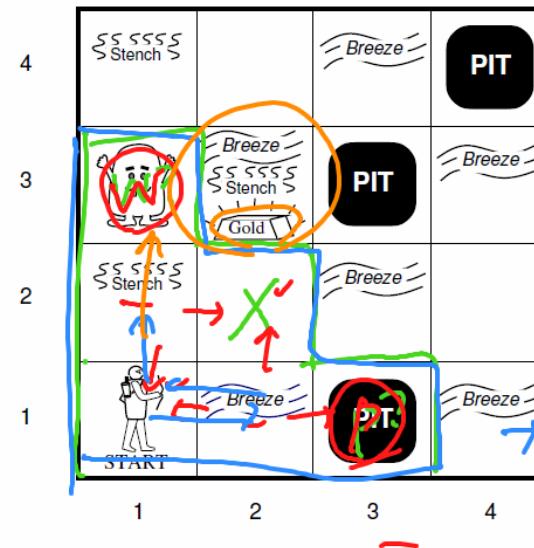
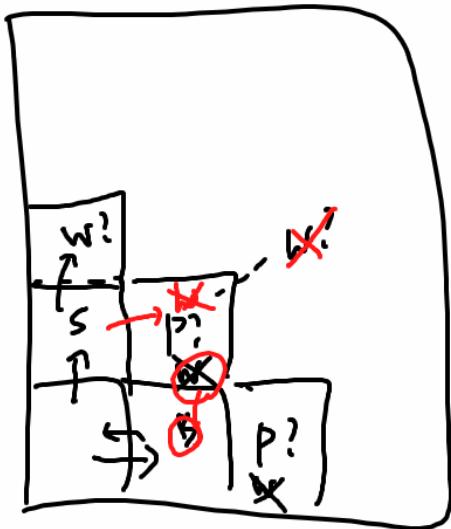


- Want to get to the gold and grab it.
- Want to avoid pits and the “wumpus”.
- Clues: breeze near pits and stench near the wumpus.
- Other sensors: wall (bump), gold (glitter), kill (scream)
- Actions: move, g

You can use all of the information that you get so far, to eliminate all of these possibilities. Right.

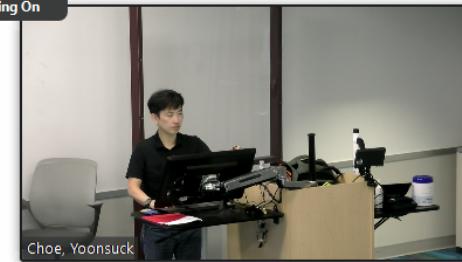


Example Domain: Wumpus World

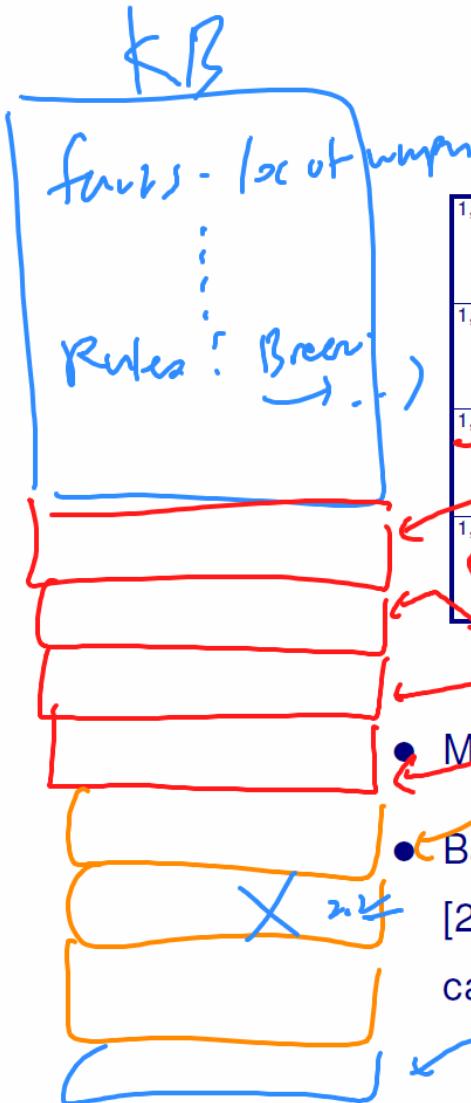


- Want to get to the gold and grab it.
- Want to avoid pits and the "wumpus".
- Clues: breeze near pits and stench near the wumpus.
- Other sensors: wall (bump), gold (glitter), kill (scream)
- Actions: move, grab or shoot

There is no danger there, so it is safe to move.



Evolution of Knowledge in WW



A = Agent
 B = Breeze
 G = Glitter, Gold
 OK = Safe square
 P = Pit
 S = Stench
 V = Visited
 W = Wumpus

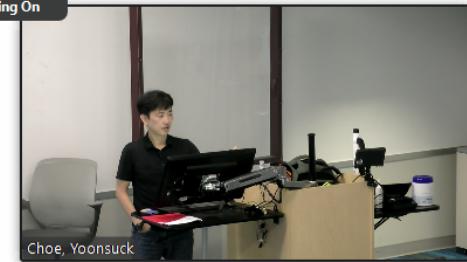
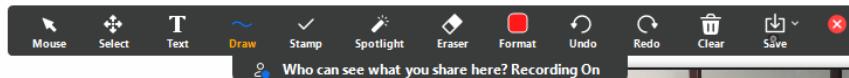
1,4	2,4	3,4	4,4
1,3	2,3	3,3	4,3
1,2	2,2	3,2	4,2
1,1	2,1	3,1	4,1
A			
OK			
V			
P?			
B			

(b)

Move from [1,1] to [2,1].

- Based on the sensory data (breeze: marked **B**), we can mark [2,2] and [3,1] as potential pits (marked **P?**), but not [1,1] since we came from there and we already know there's no pit there.

So keep updating knowledge base base on this kind of exploration.



Evolution of Knowledge in WW

1,4	2,4	3,4	4,4
1,3 W!	2,3	3,3	4,3
1,2 A S OK	2,2 OK	3,2 definite P?	4,2
1,1 V OK	2,1 B V OK	3,1 P! =	4,1

(a)

A = Agent
B = Breeze
G = Glitter, Gold
OK = Safe square
P = Pit
S = Stench
V = Visited
W = Wumpus

1,4	2,4 P?	3,4	4,4
1,3 W!	2,3 A S G B	3,3 P?	4,3
1,2 S V OK	2,2 V OK	3,2	4,2
1,1 V OK	2,1 B V OK	3,1 P!	4,1

(b)

- Move back to [1,1] and then to [1,2]. At this point, the agent can infer that the wumpus is in [1,3]
 - In [1,2], stench **S** is perceived, and all neighboring grid except [1,3] are known to be **OK** (been to [1,1], and no breeze **B**, so [2,2] is **OK**).
- Then move to [2,2] and then to [2,3] where the gold can be found (glitter).

ATM 22 FALL CSCE 420 501: ARTIFICIAL INTELLIGENCE ATM Files

ATM 22 FALL CSCE 420 5... ATM 22 FALL CSCE 633 6... Video Conferencing...

Who can see what you share here? Recording On

CS.Fall.2022

				theorem proving				11:59pm		
6	9/27/2022	9/29/2022	First-order logic and theorem proving	Ch 8, 9	Ch 8, 9			slide03-logic		
7	10/4/2022	10/6/2022	First-order logic and theorem proving; Prolog ; Planning;	Ch 8, 9	Ch 8, 9			slide03-logic, slide04-planning		
8	no class	10/13/2022	Midterm Exam (Thu, in class)	Ch 10	Ch 11	hw3 announced	hw2 due: 40/11 Tuesday 11:59pm:		10/10: midsemester grades due	
9	10/18/2022	10/20/2022	Uncertainty and probabilistic reasoning	Ch 13, 14	Ch 12, 13					
10	10/25/2022	10/27/2022	Uncertainty and probabilistic reasoning	Ch 13, 14	Ch 12, 13					
11	11/1/2022	11/3/2022	Machine learning intro	Ch 18.1-18.2	Ch 19.1-19.2	hw4 announced	hw3 due			
12	11/8/2022	11/10/2022	Machine learning : decision tree	Ch 18.3	Ch 19.3					
13	11/15/2022	11/17/2022	Machine learning:	Ch 19.7-20.1						

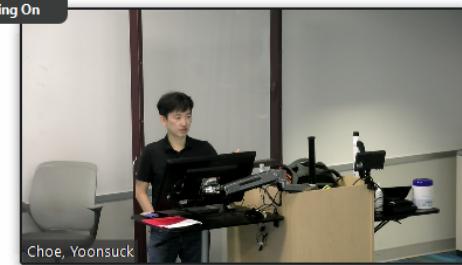
Choe, Yoonsuck

You are screen sharing Stop Share

I'll be happy to ar Mute Stop Video Security Participants Chat Polls New Share Pause Share Annotate Remote Control Apps More

Type here to search

11:13 AM 10/6/2022



'instead of W?

Evolution of Knowledge in WW

1,4	2,4	3,4	4,4
1,3 W!	2,3	3,3	4,3
1,2 A S OK	2,2 OK	3,2	4,2
1,1 V OK	2,1 B	3,1 P!	4,1

(a)

A = Agent
B = Breeze
G = Glitter, Gold
OK = Safe square
P = Pit
S = Stench
V = Visited
W = Wumpus

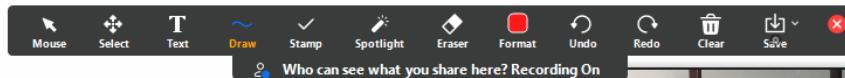
pt.

definite

1,4	2,4 P?	3,4	4,4
1,3 W!	2,3 A S G B	3,3 P?	4,3
1,2 S V OK	2,2 V OK	3,2	4,2
1,1 V OK	2,1 B V OK	3,1 P!	4,1

(b)

- Move back to [1,1] and then to [1,2]. At this point, the agent can infer that the wumpus is in [1,3]
 - In [1,2], stench **S** is perceived, and all neighboring grid except [1,3] are known to be **OK** (been to [1,1], and no breeze **B**, so [2,2] is **OK**).
- Then move to [2,2] and then to [2,3] where the gold can be found (glitter).



Evolution of Knowledge in WW

1,4	2,4	3,4	4,4
1,3 W!	2,3	3,3	4,3
1,2 A S OK	2,2	3,2	4,2
1,1 V OK	2,1 B	3,1 P!	4,1

(a)

A = Agent
B = Breeze
G = Glitter, Gold
OK = Safe square
P = Pit
S = Stench
V = Visited
W = Wumpus

1,4	2,4 P?	3,4	4,4
1,3 W!	2,3 A S G	3,3 P?	4,3
1,2 S V OK	2,2 V OK	3,2 OK	4,2
1,1 V OK	2,1 B V OK	3,1 P! V OK	4,1

(b)

Glitter

- Move back to [1,1] and then to [1,2]. At this point, the agent can infer that the wumpus is in [1,3]
 - In [1,2], stench **S** is perceived, and all neighboring grid except [1,3] are known to be **OK** (been to [1,1], and no breeze **B**, so [2,2] is **OK**).
- Then move to [2,2] and then to [2,3] where the gold can be found (glitter).

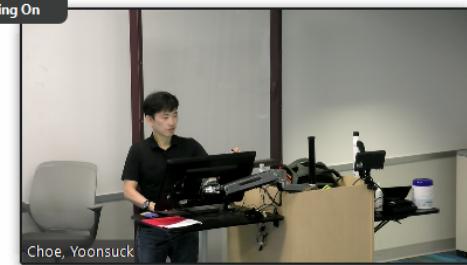
And then you can grab the gold, and you'd be done was some of these tests might actually asked you to bring it back to the initial position.

KN

~~Wumpus~~



Who can see what you share here? Recording On

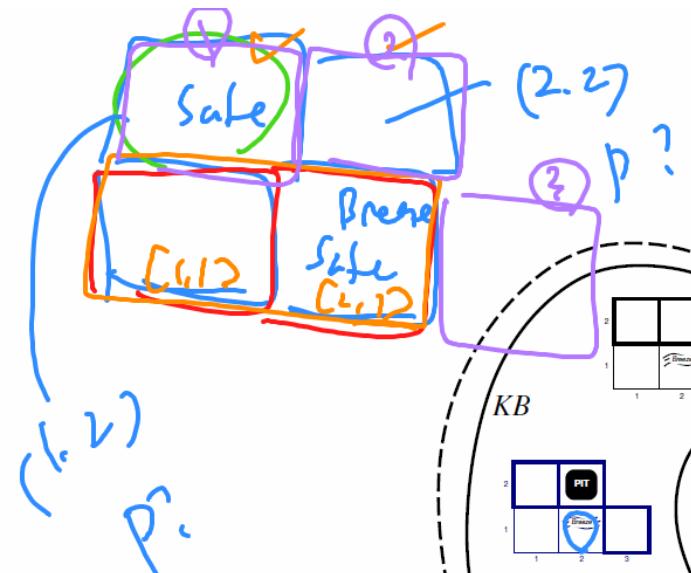


Inference in Wumpus World

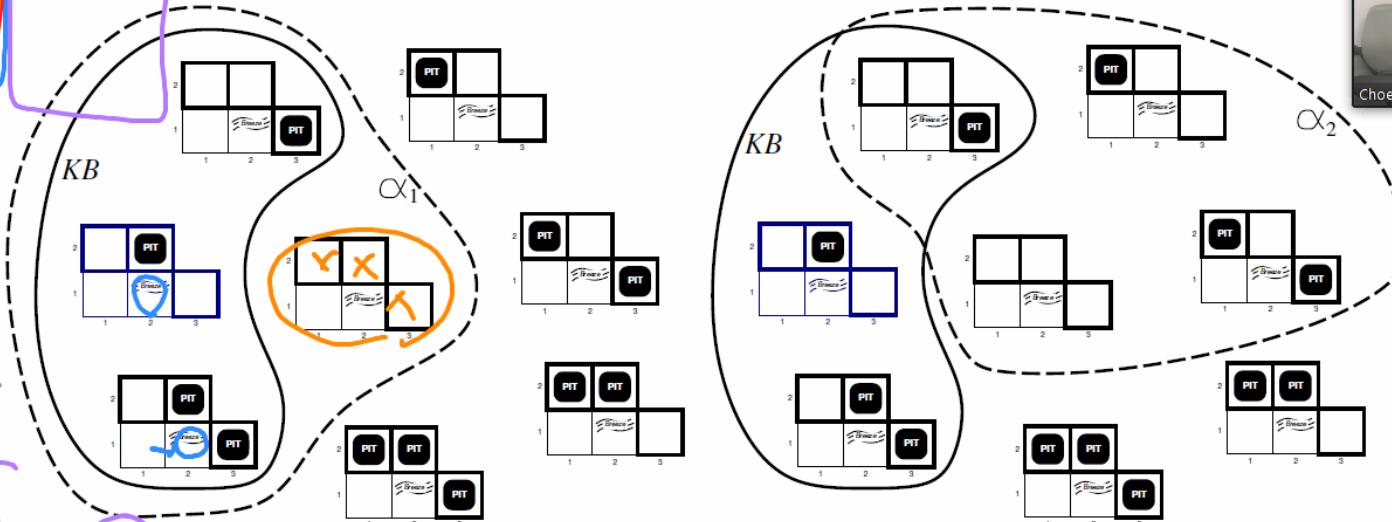
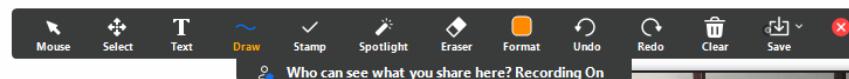
	SSSS Stench >		Breeze	PIT
4				
3		Breeze	SSSS Stench >	PIT
			Gold	Breeze
2	SSSS Stench >		Breeze	
1	START	Breeze	PIT	Breeze
	1	2	3	4

- Knowledge Base: basic rules of the Wumpus World.
- Additional knowledge is added to the KB: facts you gather as you explore ($[x,y]$ has stench, breeze, etc.)
- We can ask if a certain statement is a logical consequence of the KB: “There is a pit in [1,2]”

So, one to this this is the location.



Inference in Wumpus World



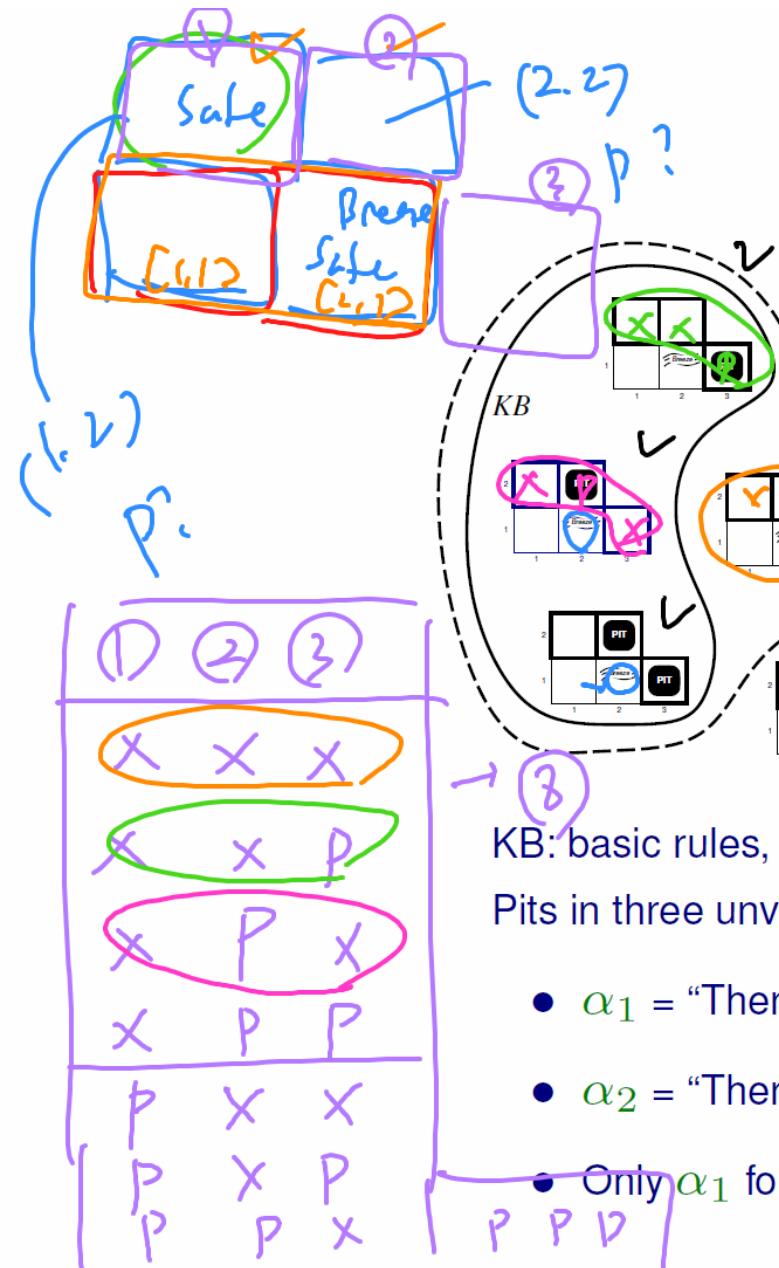
KB: basic rules, plus [1,1] and [2,1] explored

Pits in three unvisited grid [1,2], [2,2], [3,1]: $2^3 = 8$ possible cases

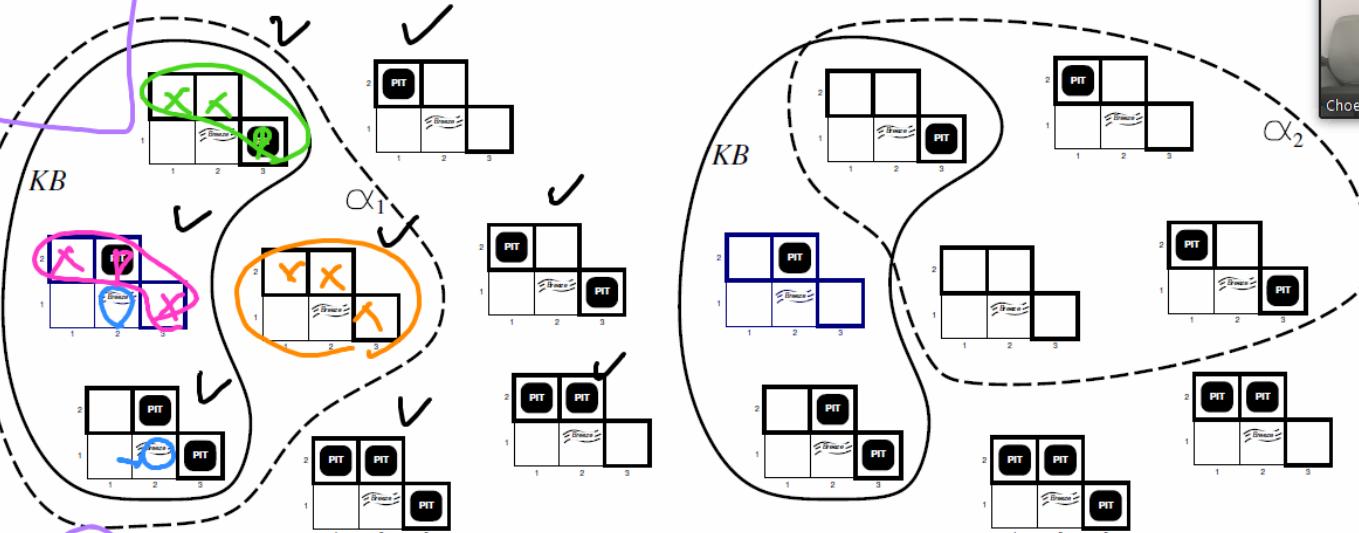
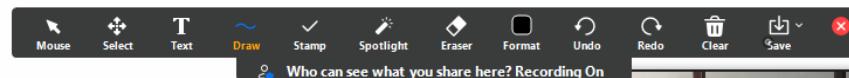
- α_1 = "There is no pit in [1,2]"
- α_2 = "There is no pit in [2,2]"

• Only α_1 follows from the KB (KB is the subset of α_1), but not α_2 .

And that's exactly what we have here so this would be this case know pit no kids no pets.



Inference in Wumpus World



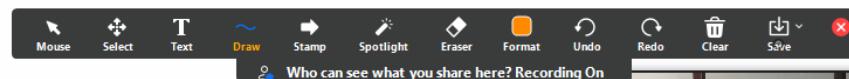
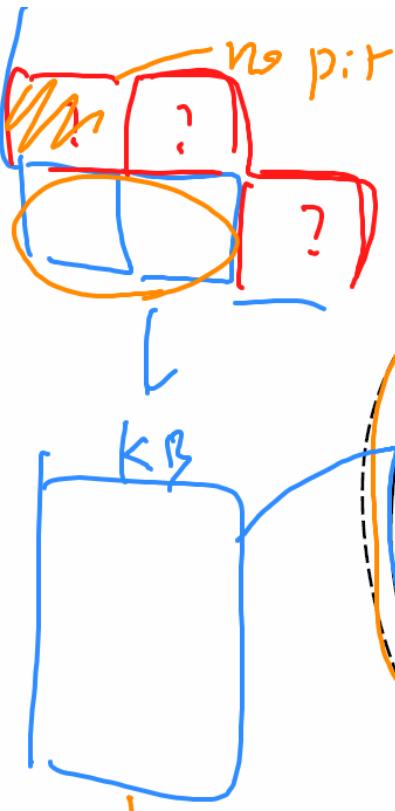
KB: basic rules, plus [1,1] and [2,1] explored

Pits in three unvisited grid [1,2], [2,2], [3,1]: $2^3 = 8$ possible cases

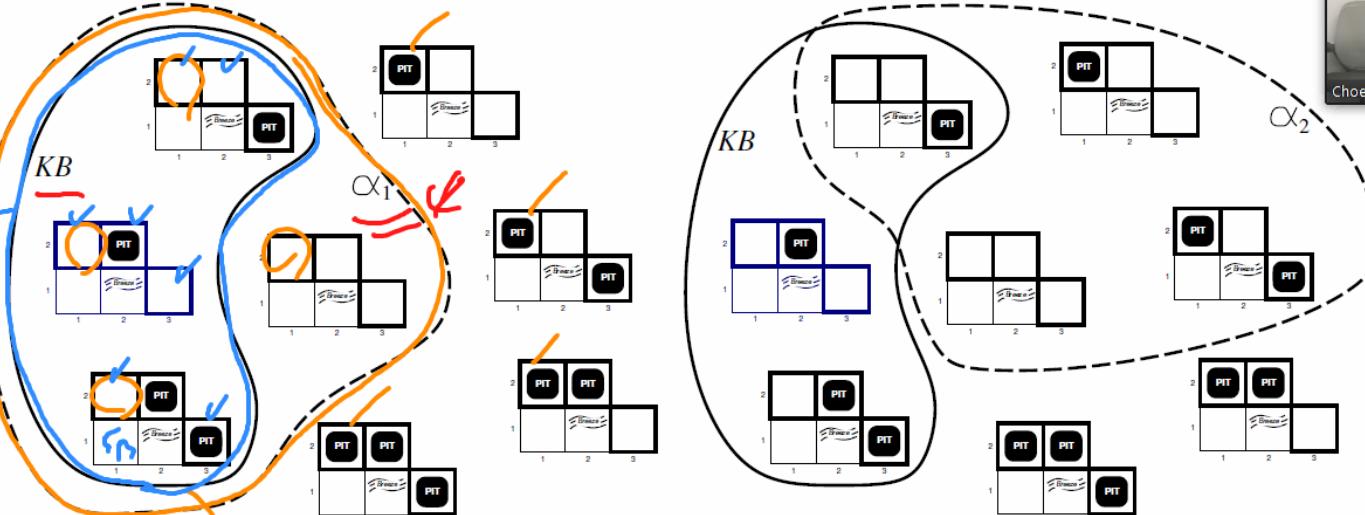
- α_1 = "There is no pit in [1,2]"
- α_2 = "There is no pit in [2,2]"

• Only α_1 follows from the KB (KB is the subset of α_1), but not α_2 .

So, what do you think should it.



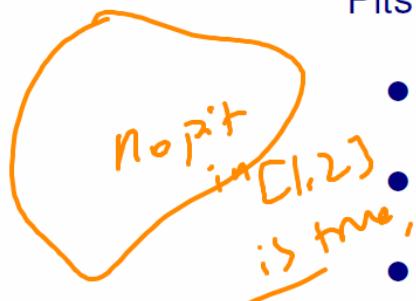
Inference in Wumpus World



KB: basic rules, plus [1,1] and [2,1] explored

Pits in three unvisited grid [1,2], [2,2], [3,1]: $2^3 = 8$ possible cases

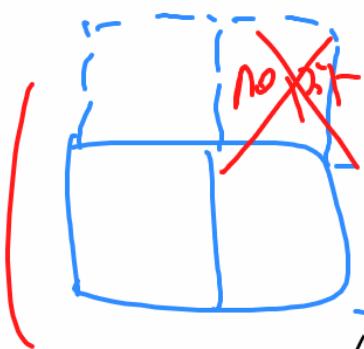
- α_1 = "There is no pit in [1,2]"
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- Only α_1 follows from the KB (KB is the subset of α_1), but not α_2 .



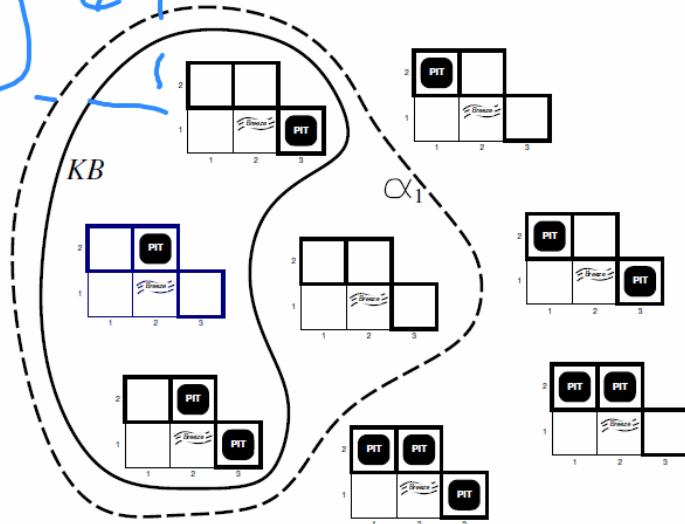
So now using the same.

You are screen sharing

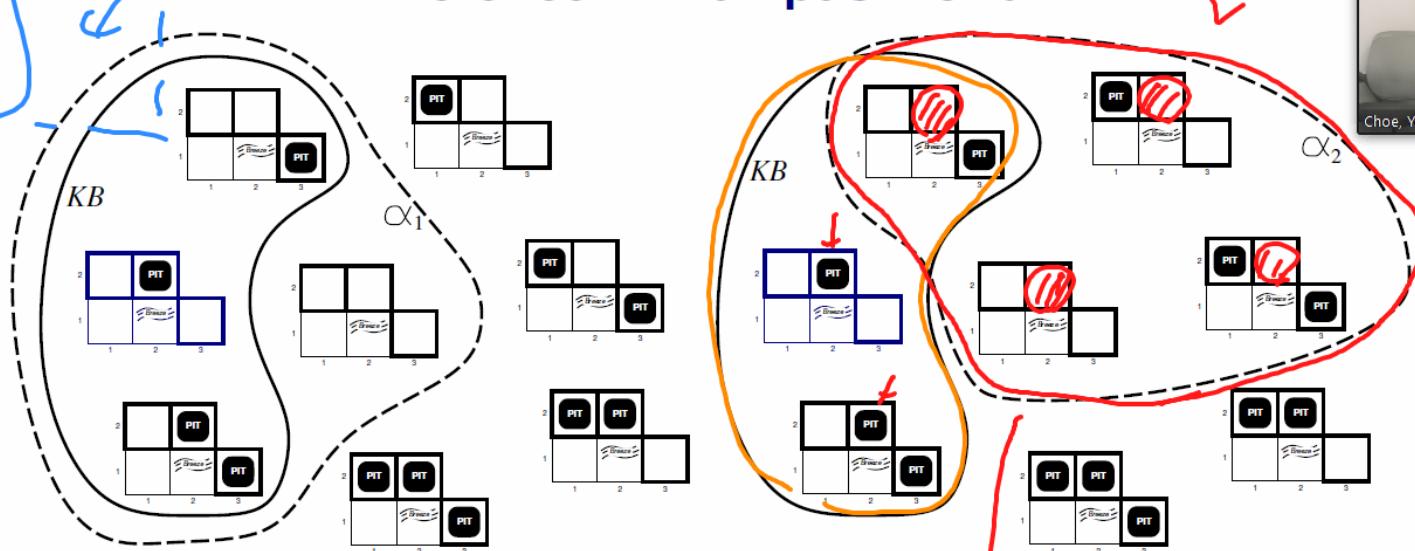
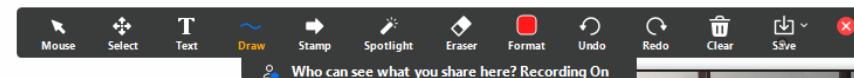
Stop Share



(2,2)



Inference in Wumpus World

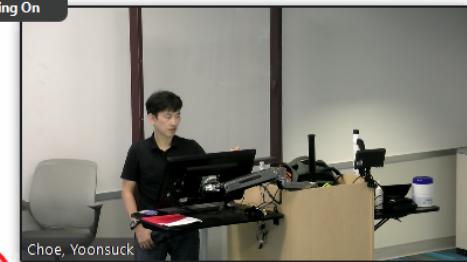
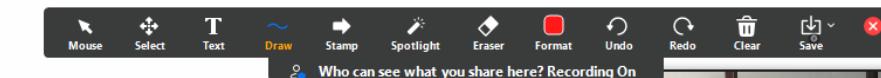
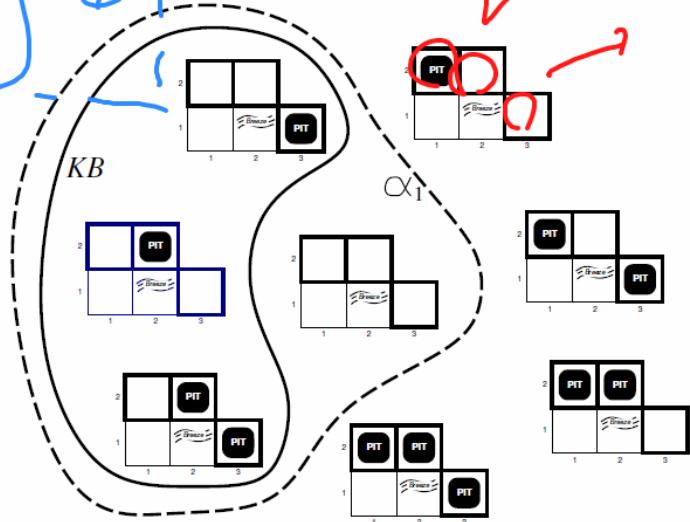
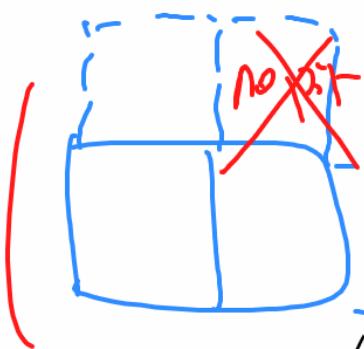


KB: basic rules, plus [1,1] and [2,1] explored

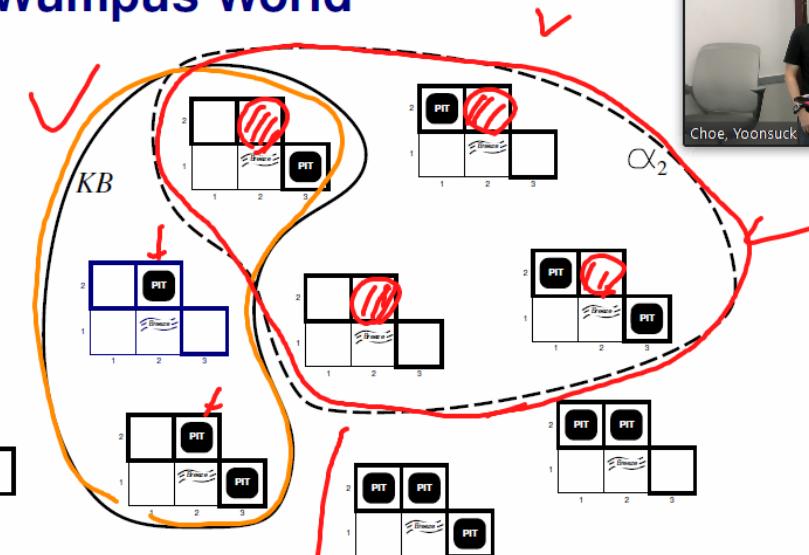
Pits in three unvisited grid [1,2], [2,2], [3,1]: $2^3 = 8$ possible cases

- α_1 = "There is no pit in [1,2]"
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- Only α_1 follows from the KB (KB is the subset of α_1), but not α_2 .

of the knowledge base.



Inference in Wumpus World



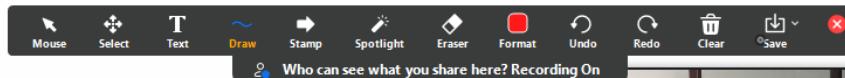
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Pits in three unvisited grid [1,2], [2,2], [3,1]: $2^3 = 8$ possible cases

- α_1 = "There is no pit in [1,2]"
- α_2 = "There is no pit in [2,2]"
- Only α_1 follows from the KB (KB is the subset of α_1), but not α_2 .

And then just based on your query, get the subset, and then check if the subset includes the knowledge.

You are screen sharing Stop Share



Breeze felt at (x,y) Propositional-logic-based Agent

- Query KB: Is there a Wumpus in $[x,y]$? Is there a pit in $[x,y]$?
- Add knowledge to KB (perceptual input): Breeze felt in $[x,y]$, Stench detected in $[x,y]$, etc.
- Decide which action to take (move where, etc.): Move to $[x,y]$, grab gold, etc.

Note: here, there's only one goal, to grab the gold. Can we specify an arbitrary goal and derive a plan?

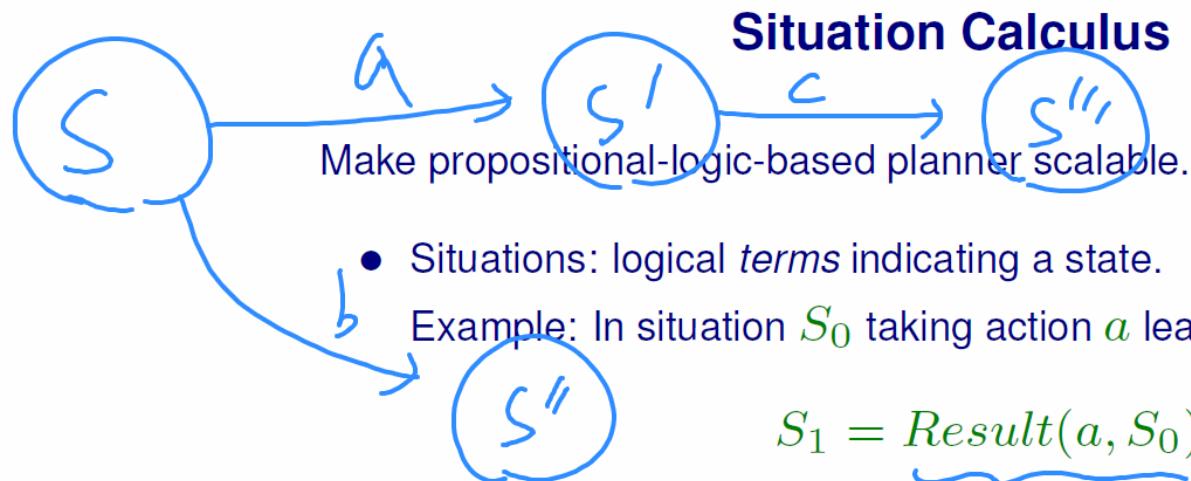
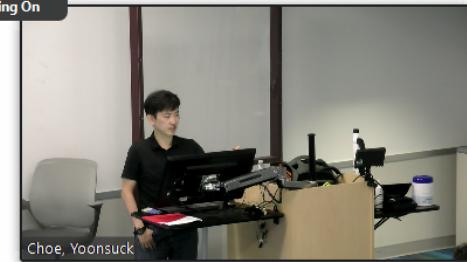
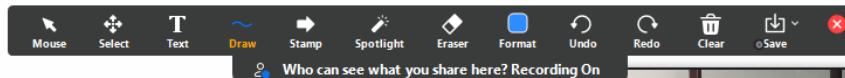
① One P redick
Breeze (x,y)

② p₁ Breeze_{1,2}
p₂ Breeze_{2,2}

Problem: Propositions need to be explicit about location, e.g.,

$Breeze_{x,y}, Stench_{x,y}, \neg Wumpus_{x,y}$.

You have to have a position like that.



- Situations: logical *terms* indicating a state.

Example: In situation S_0 taking action a leads to situation S_1 :

$$S_1 = \underline{\underline{Result(a, S_0)}}.$$

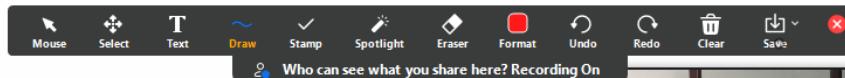
- Fluents: *functions* and *predicates* that vary from one situation to the next.

Example: $\neg Holding(Gold_1, S_0)$, $Age(Wumpus)$

Other stuff: Atemporal/eternal predicates $Gold(Gold_1)$, empty actions $Result([], s) = s$, sequence of actions

$$Result([a|seq], s) = Result(seq, Result(a, s)).$$

So you can represent that as some.



Prolog 3/5

- you can insert

- `write('string')`
- `write(X)`
- etc. anywhere in the rule to printout a message or the content of a variable.
- It can be chained:

`write('string: '), write(X), write('string2: '),
write(Y)`

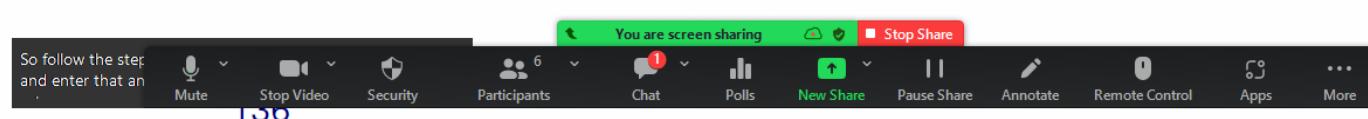
- enter [user]. to begin manual entry:

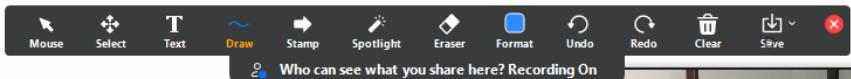
② Facts

- loves(john,jane).
- loves(jane,john).

③ Rules

- couple(X,Y) :- loves(X,Y) , loves(Y,X).
- CTRL-D to end





Situation Calculus

Make propositional-logic-based planner scalable.

- { • Situations: logical *terms* indicating a state.
Example: In situation S_0 taking action a leads to situation S_1 :

$$S_1 = \text{Result}(a, S_0). \quad \cancel{S_1} = \text{Result}(a, S_0)$$

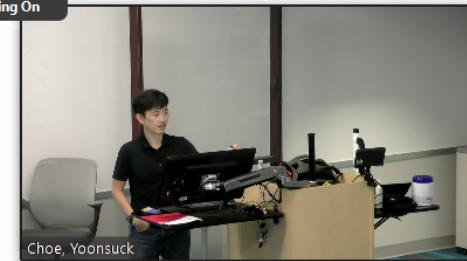
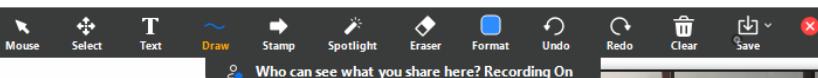
- Fluents: *functions* and *predicates* that vary from one situation to the next.

Example: $\neg \text{Holding}(\text{Gold}_1, S_0), \text{Age}(\text{Wumpus})$

Other stuff: Atemporal/eternal predicates $\text{Gold}(\text{Gold}_1)$, empty actions $\text{Result}([], s) = s$, sequence of actions

$\text{Result}([a|seq], s) = \text{Result}(seq, \text{Result}(a, s)).$

But something different, like, as for something.



Make propositional logic-based planner scalable.

- Situations: logical *terms* indicating a state.

Example: In situation S_0 taking action a leads to situation S_1 :

$$S_1 = \text{Result}(a, S_0).$$

value *T/F*

- Fluents: *functions* and *predicates* that vary from one situation to the next.

Example: $\neg \text{Holding}(\text{Gold}_1, S_0), \text{Age}(\text{Wumpus})$ *no situation*

Other stuff: Atemporal/eternal predicates $\text{Gold}(\text{Gold}_1)$, empty actions $\text{Result}([], s) = s$, sequence of actions seq ;

$\text{Result}([a|seq], s) = \text{Result}(\text{seq}, \text{Result}(a, s)).$

Right. So actually what is the result of as, so actually.



Make propositional-logic-based planner scalable.

- Situations: logical *terms* indicating a state.

Example: In situation S_0 taking action a leads to situation S_1 :

$$S_1 = \text{Result}(a, S_0).$$

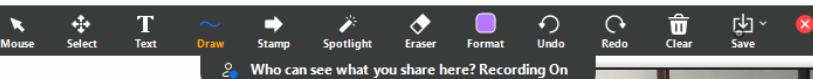
- Fluents: *functions* and *predicates* that vary from one situation to the next.

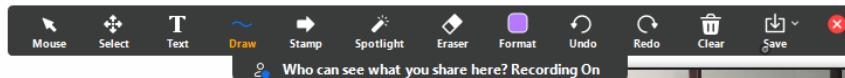
Example: $\neg \text{Holding}(\text{Gold}_1, S_0), \text{Age}(\text{Wumpus})$

Other stuff: Atemporal/eternal predicates $\text{Gold}(\text{Gold}_1)$, empty actions $\text{Result}([], s) = s$, sequence of actions

$$\text{Result}([a|seq], s) = \text{Result}(seq, \text{Result}(a, s)).$$

And then followed by this sequence. And finally, you get the resulting situation. As a result.





Describing Actions in Situation Calculus

Two axioms:

- Possibility axiom: when it is possible to execute an action

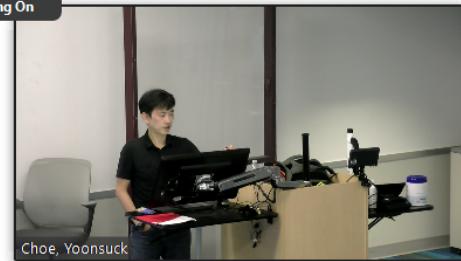
$$\text{Preconditions} \rightarrow \text{Poss}(a, s)$$

- Effect axiom: What happens when a possible action is taken

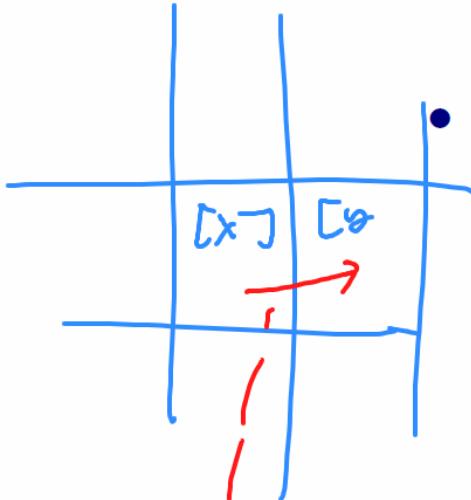
$$\text{Poss}(a, s) \rightarrow \text{Changes that result}$$

~~from Initial~~
 ~~$\text{Initial} \rightarrow \text{Goal}$~~

Then the fluent for who will will change.



Wumpus World: Axioms



$go(x, y)$

- Possibility axioms: Move, grab, release

Situation

$$At(\text{Agent}, x, s) \wedge \text{Adjacent}(x, y) \rightarrow Poss(\text{Go}(x, y), s)$$

$$Gold(g) \wedge At(\text{Agent}, x, s) \wedge At(g, x, s) \rightarrow Poss(\text{Grab}(g), s)$$

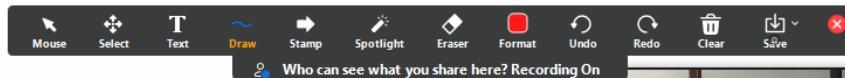
$$Holding(g, s) \rightarrow Poss(\text{Release}(g), s)$$

- Effect axioms: Move, Grab, Release

$$Poss(\text{Go}(x, y), s) \rightarrow At(\text{Agent}, y, \text{Result}(\text{Go}(x, y), s))$$

$$Poss(\text{Grab}(g), s) \rightarrow Holding(g, \text{Result}(\text{Grab}(g), s))$$

$$Poss(\text{Release}(g), s) \rightarrow \neg Holding(g, \text{Result}(\text{Release}(g), s))$$



Wumpus World: Axioms

- Possibility axioms: Move, grab, release

$$\begin{aligned}
 & At(\text{Agent}, x, s) \wedge \text{Adjacent}(x, y) \rightarrow \text{Poss}(\text{Go}(x, y), s) \\
 & \underline{\text{Gold}(g)} \wedge \underline{\text{At}(\text{Agent}, x, s)} \wedge \underline{\text{At}(g, x, s)} \rightarrow \text{Poss}(\text{Grab}(g), s) \\
 & \underline{\text{Holding}(g, s)} \rightarrow \text{Poss}(\text{Release}(g), s)
 \end{aligned}$$

Handwritten annotations with arrows and circles:

- A red curved arrow points from the first premise's x to the second premise's x .
- A red curved arrow points from the second premise's g to the third premise's g .
- A green curved arrow points from the first premise's y to the third premise's s .
- Blue circles highlight $\text{At}(\text{Agent}, x, s)$, $\text{At}(g, x, s)$, and $\text{Holding}(g, s)$.
- Red circles highlight $\text{Gold}(g)$ and s in the second premise.

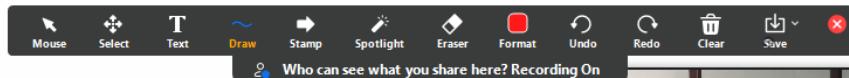
- Effect axioms: Move, Grab, Release

$$\text{Poss}(\text{Go}(x, y), s) \rightarrow \text{At}(\text{Agent}, y, \text{Result}(\text{Go}(x, y), s))$$

$$\text{Poss}(\text{Grab}(g), s) \rightarrow \text{Holding}(g, \text{Result}(\text{Grab}(g), s))$$

$$\text{Poss}(\text{Release}(g), s) \rightarrow \neg \text{Holding}(g, \text{Result}(\text{Release}(g), s))$$

In the precondition in the post condition. Right.



Wumpus World: Axioms

- Possibility axioms: Move, grab, release

$$At(\text{Agent}, x, s) \wedge \text{Adjacent}(x, y) \rightarrow \text{Poss}(\text{Go}(x, y), s)$$

$$\text{Gold}(g) \wedge At(\text{Agent}, x, s) \wedge At(g, x, s) \rightarrow \text{Poss}(\text{Grab}(g), s)$$

$$\text{Holding}(g, s) \rightarrow \text{Poss}(\text{Release}(g), s)$$

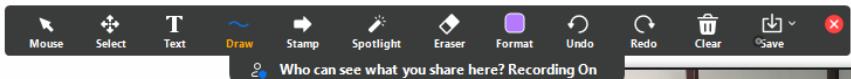
- Effect axioms: Move, Grab, Release

$$\text{Poss}(\text{Go}(x, y), s) \rightarrow At(\text{Agent}, y, \text{Result}(\text{Go}(x, y), s))$$

$$\text{Poss}(\text{Grab}(g), s) \rightarrow \text{Holding}(g, \text{Result}(\text{Grab}(g), s))$$

$$\text{Poss}(\text{Release}(g), s) \rightarrow \neg \text{Holding}(g, \text{Result}(\text{Release}(g), s))$$

What are the results, resulting changes dependent on the action.

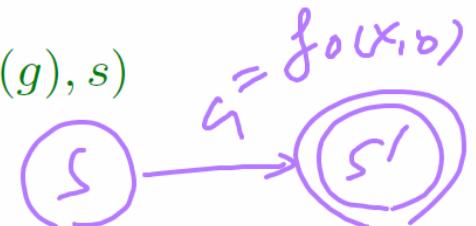


Wumpus World: Axioms

- Possibility axioms: Move, grab, release

$$At(\text{Agent}, x, s) \wedge \text{Adjacent}(x, y) \rightarrow Poss(\text{Go}(x, y), s)$$

$$Gold(g) \wedge At(\text{Agent}, x, s) \wedge At(g, x, s) \rightarrow Poss(\text{Grab}(g), s)$$

$$Holding(g, s) \rightarrow Poss(\text{Release}(g), s)$$


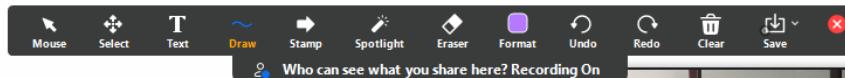
- Effect axioms: Move, Grab, Release

$$Poss(\text{Go}(x, y), s) \rightarrow At(\text{Agent}, y, Result(\text{Go}(x, y), s))$$

$$Poss(\text{Grab}(g), s) \rightarrow Holding(g, Result(\text{Grab}(g), s))$$

$$Poss(\text{Release}(g), s) \rightarrow \neg Holding(g, Result(\text{Release}(g), s))$$

this so that makes sense.



Wumpus World: Axioms

- Possibility axioms: Move, grab, release

$\text{At}(\text{Agent}, x, s) \wedge \text{Adjacent}(x, y) \rightarrow \text{Poss}(\text{Go}(x, y), s)$

$\text{Gold}(g) \wedge \text{At}(\text{Agent}, x, s) \wedge \text{At}(g, x, s) \rightarrow \text{Poss}(\text{Grab}(g), s)$

$\text{Holding}(g, s) \rightarrow \text{Poss}(\text{Release}(g), s)$

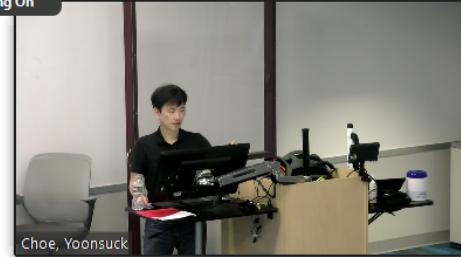
- Effect axioms: Move, Grab, Release

$\text{Poss}(\text{Go}(x, y), s) \rightarrow \text{At}(\text{Agent}, y, \text{Result}(\text{Go}(x, y), s))$

$\checkmark \text{Poss}(\text{Grab}(g), s) \rightarrow \text{Holding}(g, \text{Result}(\text{Grab}(g), s))$

$\text{Poss}(\text{Release}(g), s) \rightarrow \neg \text{Holding}(g, \text{Result}(\text{Release}(g), s))$

And we're precondition of releasing it is your way of holding on to it. So unless you're holding it. You can release it.



Frame Problem

- In the previous slide, we cannot deduce if the following can be proven (G_1 represents a particular lump of gold):

$$At(G_1, [1, 1], Result([Go([1, 1], [1, 2]), Grab(G_1), Go([1, 2], [1, 1])], S_0))$$
- It is because the effect axioms say only *what should change*, but not *what does not change when actions are taken*.
- Initial solution: *Frame axioms*

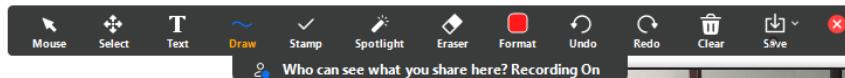
$$At(o, x, s) \wedge (o \neq Agent) \wedge \neg Holding(o, s)$$

$$\rightarrow At(o, x, Result(Do(y, z), s)).$$

This says moving does not affect the gold when it is not held.

Problem is that you need $O(AF)$ such axioms for all *(action, fluent)* pair (A : num of actions, F : num of fluent predicates).

This cannot be deduced properly.



Who can see what you share here? Recording On



Prolog 3/5

- you can insert

- `write('string')`
- `write(X)`
- etc. anywhere in the rule to printout a message or the content of a variable.
- It can be chained:

- `write('string: '), write(X), write('string2: '), write(Y)`

- enter [user]. to begin manual entry:

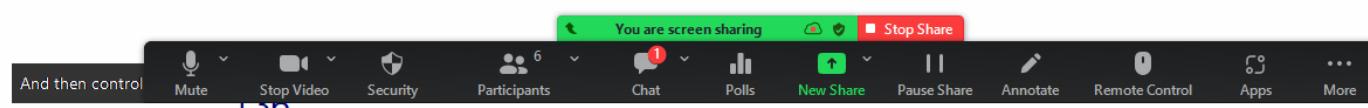
② Facts

- {
- loves(john,jane).
- loves(jane,john).

③ Rules

- {
- couple(X,Y) :- loves(X,Y) , loves(Y,X).
- CTRL-D to end

④





Frame Problem

- In the previous slide, we cannot deduce if the following can be proven (G_1 represents a particular lump of gold):

$$At(G_1, [1, 1], Result([Go([1, 1], [1, 2]), Grab(G_1), Go([1, 2], [1, 1])], S_0)$$

- It is because the effect axioms say only *what should change*, but not *what does not change when actions are taken*.

- Initial solution: *Frame axioms*

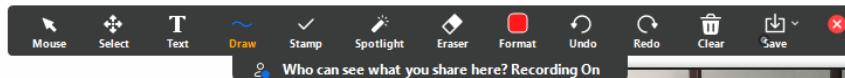
locally *not held*

$$\boxed{\boxed{At(o, x, s) \wedge (o \neq Agent) \wedge \neg Holding(o, s)} \rightarrow At(o, x, Result(At(y, z, s), s))}$$

This says moving does not affect the gold when it is not held.

Problem is that you need $O(AF)$ such axioms for all *(action, fluent)* pair (A : num of actions, F : num of fluent predicates).

And I'll see you next Thursday.



Who can see what you share here? Recording On



Prolog 3/5

- you can insert

- `write('string')`
- `write(X)`
- etc. anywhere in the rule to printout a message or the content of a variable.
- It can be chained:

- `write('string: '), write(X), write('string2: '), write(Y)`

- enter [user]. to begin manual entry:

② Facts

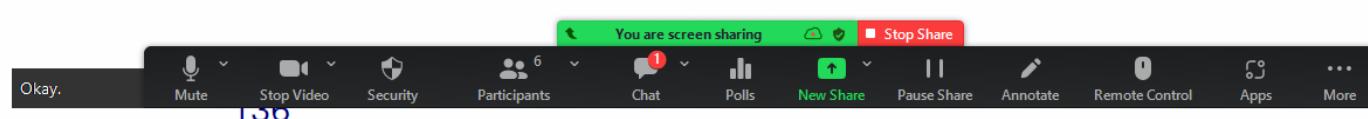
- loves(john,jane).
- loves(jane,john).

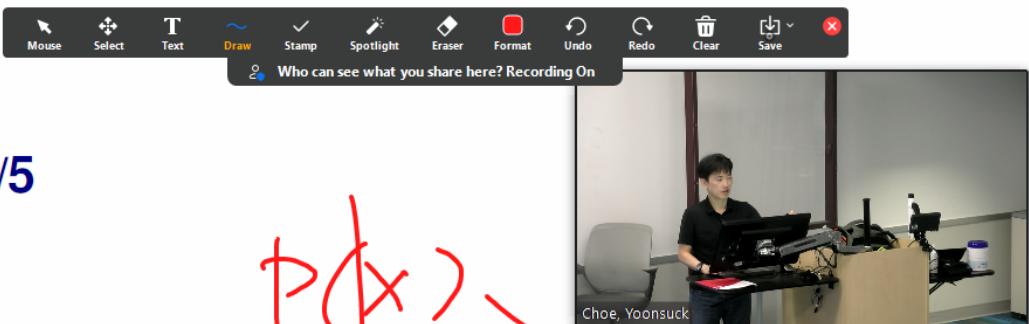
③ Rules

- `couple(X,Y) :- loves(X,Y) , loves(Y,X).`
- CTRL-D to end

④

building the
KB.





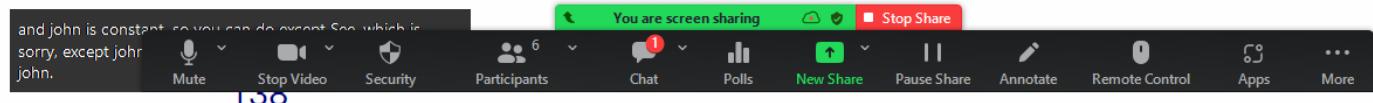
Prolog 5/5

- You can also test unification

- At the "?-" prompt
 - $p(X) = p(john).$
 - $p(X,Y) = p(g(Z),Z).$
 - $p(X) = p(f(X)).$ <-- this will give an error
 - etc.

$p(\cancel{x})$
 $p(\cancel{john}) \rightarrow p(\underline{\text{joh}\cancel{n}})$
 $D = \{ \cancel{x}, \underline{\text{john}} \}$
 v c.

~~\cancel{x}/c~~
 \cancel{x}/\cancel{john}



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```
Action (; for next solution, a for all solutions, RET to stop) ? p
Action (; for next solution, a for all solutions, RET to stop) ?
Action (; for next solution, a for all solutions, RET to stop) ? ;
no
| ?- couple(jane,john).

true ? ;

no
| ?- couple(john,jill).

no
| ?- couple(jane,X).

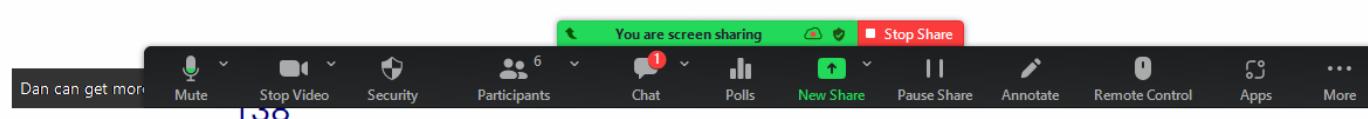
X = john ? ;
no
| ?- p(X) = p(john).

X = john
yes
| ?- 
```

■ etc.

$p(x)$
 $p(john)$ → $p(\underline{john})$
 $D = \{x, \underline{john}\}$
 v c.

s will give an error



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```
Action (; for next solution, a for all solutions, RET to stop) ? p
Action (; for next solution, a for all solutions, RET to stop) ?
Action (; for next solution, a for all solutions, RET to stop) ? ;
no
| ?- couple(jane,john).

true ? ;

no
| ?- couple(john,jill).

no
| ?- couple(jane,X).

X = john ? ;

no
| ?- p(X) = p(john).

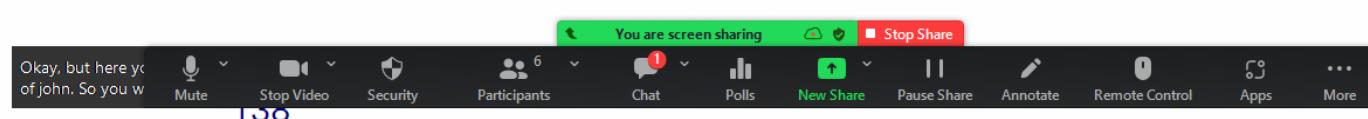
X = john
yes
| ?- p(f(g(john))) = p(f(y)).
```

■ etc.

$$\begin{array}{c} \rightarrow | \rightarrow \\ P(f(g(john))) \\ P(f(y)) \end{array}$$

s will give an error

$$P = \{ y, \underline{g(john)} \}$$



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```

no
| ?- couple(john,jill).

no
| ?- couple(jane,X).

X = john ? ;

no
| ?- p(X) = p(john).

X = john

yes
| ?- p(f(g(john))) = p(f(y)).

no
| ?- p(f(g(john))) = p(f(Y)).

Y = g(john)

```

■ etc.

The video feed shows a person at a desk with a computer monitor. The video feed is overlaid with red and green handwritten annotations explaining a Prolog query. The annotations show the query $p(f(g(john)))$ being expanded to $p(f(y))$. A green oval highlights the variable y in the query, and a green arrow points from it to the variable y in the expansion. The text "will give an error" is written next to the expansion. Below the expansion, a green arrow points down to the term $\lambda / f(john)$.

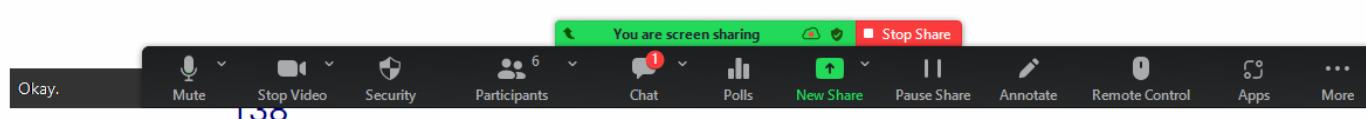
$p(f(g(john)))$

$p(f(y))$

s will give an error

$p = \{ y, \underline{f(john)} \}$

$\lambda / f(john)$



yschoe@brain: ~/teaching/src/prover

Run `fwupdmgr get-upgrades` for more information.

You have new mail.

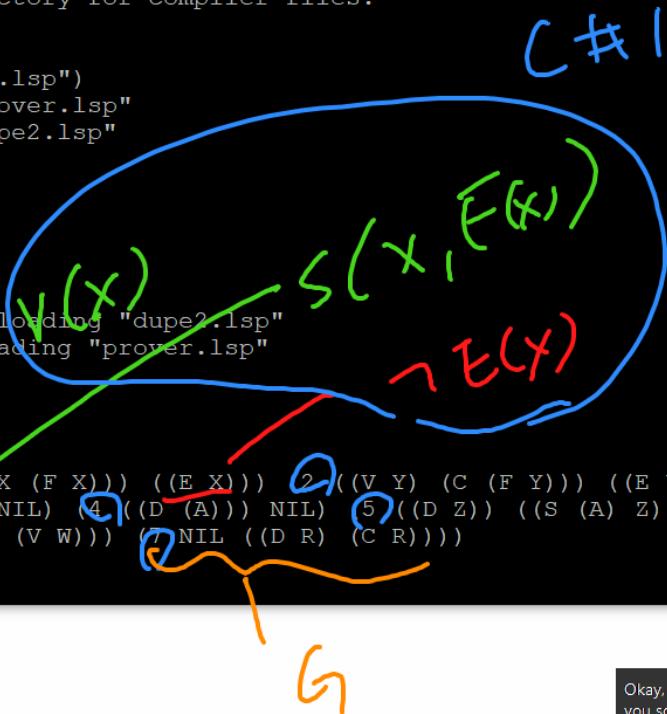
Last login: Thu Sep 22 11:07:58 2022 from 128.194.120.224
yschoe@brain:~\$ cd teaching/src/prover/
yschoe@brain:~/teaching/src/prover\$ ls
dupe2.lsp dupe.lsp prover.lsp
yschoe@brain:~/teaching/src/prover\$ gcl
GCL (GNU Common Lisp) 2.6.12 CLtL1 Fri Apr 22 15:51:11 UTC 2016
Source License: LGPL(gcl,gmp), GPL(unexec,bfd,xgcl)
Binary License: GPL due to GPL'ed components: (XGCL UNEXEC)
Modifications of this banner must retain notice of a compatible license
Dedicated to the memory of W. Schelter

Use (help) to get some basic information on how to use GCL.

Temporary directory for compiler files:

/tmp/

```
>(load "prover.lsp")
;; Loading "prover.lsp"
;; Loading "dupe2.lsp"
"[1] T
"
"[2] NIL
"
"[3] NIL
" ; Finished loading "dupe2.lsp"
;; Finished loading "prover.lsp"
T
>*customs*
((1 ((V X) (S X (F X))) ((E X)))
 (2 ((V Y) (C (F Y))) ((E Y)))
 (3 ((E (A))) NIL)
 (4 ((D (A))) NIL)
 (5 ((D Z)) ((S (A) Z)))
 (6 NIL ((D W) (V W)))
 (7 NIL ((D R) (C R))))
```



(# (pos) (neg))

s will give an error

Okay, so you don't need to know any of this. I'm just giving you some orientation on how to understand what's.

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You are screen sharing Stop Share

