

Mirror and Preconditioned Gradient Descent in Wasserstein Space

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Motivations

Let $\mathcal{P}_2(\mathbb{R}^d) = \{\mu \in \mathcal{P}(\mathbb{R}^d), \int \|x\|_2^2 d\mu(x) < \infty\}$, $\mathcal{F} : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$.

Goal:

$$\min_{\mu \in \mathcal{P}_2(\mathbb{R}^d)} \mathcal{F}(\mu)$$

Applications:

- Sampling from $\nu \propto e^{-V}$ ([Wibisono, 2018](#))
- Generative modeling
- Learning neural networks ([Mei et al., 2018](#); [Chizat and Bach, 2018](#))

Example of functionals

- Free energies: $\mathcal{F}(\mu) = \int V d\mu + \iint W(x, y) d\mu(x)d\mu(y) + \mathcal{H}(\mu)$ where $\mathcal{H}(\mu) = \int \log(\mu(x)) d\mu(x)$ for $\mu \ll \text{Leb}$
- $\mathcal{F}(\mu) = \text{KL}(\mu||\nu) = \int V d\mu + \mathcal{H}(\mu) + \text{cst}$ for sampling from $\nu \propto e^{-V(x)}$
- $\mathcal{F}(\mu) = D(\mu, \nu)$ for sampling from ν

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Applications

Gradient Descent on \mathbb{R}^d

Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$.

Goal: $\min_{x \in \mathbb{R}^d} f(x)$ via gradient flow

$$\frac{dx_t}{dt} = -\nabla f(x_t), \quad x_0 = x_0$$

Gradient Descent on \mathbb{R}^d

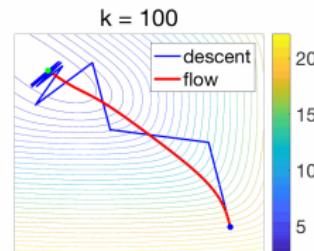
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$$\frac{dx_t}{dt} = -\nabla f(x_t), \quad x_0 = x_0$$

Main algorithm: **Gradient Descent (GD)**

$$\forall \tau > 0, \quad \forall k \geq 0, \quad x_{k+1} = x_k - \tau \nabla f(x_k)$$



From (Bach, 2020)

$$= \operatorname{argmin}_{x \in \mathbb{R}^d} \frac{1}{2} \|x - x_k\|_2^2 + \tau \langle \nabla f(x_k), x - x_k \rangle$$

Gradient Descent on \mathbb{R}^d

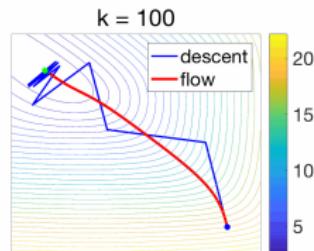
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Convergence Analysis

- f β -smooth $\implies f(x_{k+1}) \leq f(x_k) - \frac{1}{2\beta} \|\nabla f(x_k)\|_2^2 = f(x_k) - \frac{\beta}{2} \|x_{k+1} - x_k\|_2^2$
- f β -smooth and α -convex $\implies f(x_k) - f(x^*) \leq \frac{\beta - \alpha}{2k} \|x_0 - x^*\|_2^2$

Reminder:

- f β -smooth $\iff \forall x, y \in \mathbb{R}^d, \quad f(x) - f(y) - \langle \nabla f(y), x - y \rangle \leq \frac{\beta}{2} \|x - y\|_2^2$
- f α -convex $\iff f - \alpha \frac{\|\cdot\|_2^2}{2}$ convex

Mirror Descent on \mathbb{R}^d (Beck and Teboulle, 2003)

If f not β -smooth: no guarantees for GD → change geometry

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Definition (Bregman Divergence)

Let $\phi : \mathbb{R}^d \rightarrow \mathbb{R}$ be convex, then the Bregman divergence is defined as

$$\forall x, y \in \mathbb{R}^d, d_\phi(x, y) = \phi(x) - \phi(y) - \langle \nabla \phi(y), x - y \rangle.$$

Properties:

- ϕ convex $\implies d_\phi(x, y) \geq 0$ for all $x, y \in \mathbb{R}^d$
- ϕ strictly convex $\implies d_\phi(x, y) = 0 \iff x = y$

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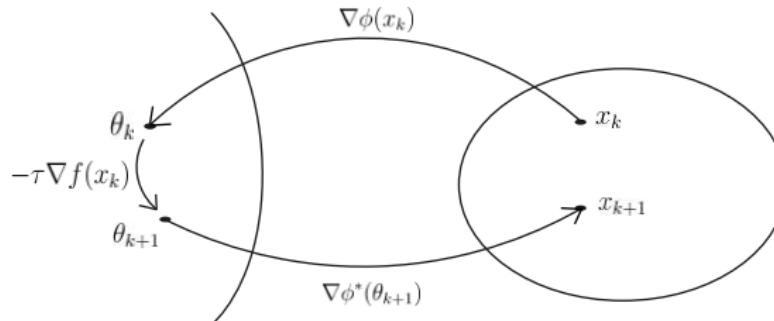
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Mirror Descent (MD) algorithm:

$$\begin{aligned}\forall k \geq 0, x_{k+1} &= \operatorname{argmin}_{x \in \mathbb{R}^d} d_\phi(x, x_k) + \tau \langle \nabla f(x_k), x - x_k \rangle \\ &= \nabla \phi^*(\nabla \phi(x_k) - \tau \nabla f(x_k))\end{aligned}$$

with $\phi^*(y) = \sup_x \langle x, y \rangle - \phi(x)$, $\nabla \phi^* = (\nabla \phi)^{-1}$.



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Convergence analysis (Lu et al., 2018)

- f β -smooth relative to ϕ , i.e. $d_f(x, y) \leq \beta d_\phi(x, y)$ (equivalently $\beta\phi - f$ convex)
 $\implies f(x_{k+1}) \leq f(x_k) - \beta d_\phi(x_k, x_{k+1})$
- f β -smooth and α -convex relative to ϕ , i.e. $\alpha d_\phi(x, y) \leq d_f(x, y)$ (equivalently $f - \alpha\phi$ convex) $\implies f(x_k) - f(x^*) \leq \frac{\beta - \alpha}{k} d_\phi(x^*, x_0)$

Remark: For $\phi(x) = \frac{1}{2} \|x\|_2^2$, MD = GD and $d_\phi(x, y) = \frac{1}{2} \|x - y\|_2^2$

Preconditioned Gradient Descent (Maddison et al., 2021)

Let $h : \mathbb{R}^d \rightarrow \mathbb{R}$ strictly convex, $g : \mathbb{R}^d \rightarrow \mathbb{R}$ convex.

Preconditioned Gradient Descent scheme for $\min_y g(y)$:

$$\begin{aligned}\forall k \geq 0, \quad & y_{k+1} = y_k - \tau \nabla h^*(\nabla g(y_k)) \\ &= \operatorname{argmin}_{y \in \mathbb{R}^d} h\left(\frac{y_k - y}{\tau}\right) \tau + \langle \nabla g(y_k), y - y_k \rangle\end{aligned}$$

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Closely related to MD (Kim et al., 2023) as for $g = \phi^*$, $h^* = f$, $y = \nabla \phi(x)$,

$$\nabla \phi(x_{k+1}) = \nabla \phi(x_k) - \tau \nabla f(x_k) \iff x_{k+1} = \nabla \phi^*(\nabla \phi(x_k) - \tau \nabla f(x_k)).$$

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Convergence analysis (Maddison et al., 2021)

- h^* β -smooth relative to g^* $\implies h^*(\nabla g(y_{k+1})) \leq h^*(\nabla g(y_k)) - \beta d_g(y_{k+1}, y_k)$
- h^* β -smooth and α -convex relative to g^*
 $\implies \forall k \geq 1, \quad h^*(\nabla g(y_k)) - h^*(0) \leq \frac{\alpha - \beta}{k} (g(y_0) - g(y^*))$
 $\implies \forall k \geq 0, \quad g(y_k) - g(y^*) \leq (1 - \alpha/\beta)^k (g(y_0) - g(y^*))$

Relation between MD and Preconditioned GD



Dual Space Preconditioning for Gradient Descent



Chris J. Maddison^{1,4,*}, Daniel Paulin^{2,*}, Yee Whye Teh³, and Arnaud Doucet³

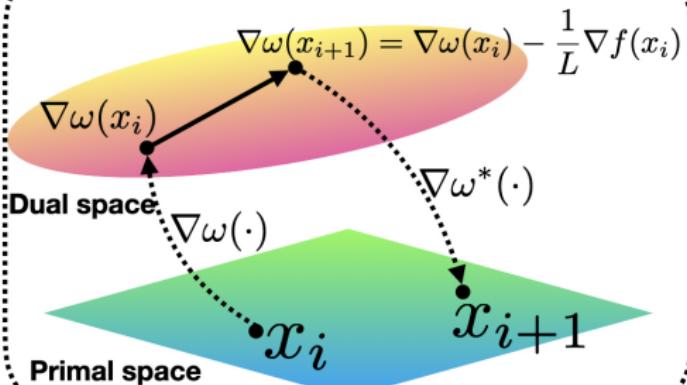


Algorithm	Mirror descent
	$\nabla \omega(x_{i+1}) = \nabla \omega(x_i) - \frac{1}{L} \nabla f(x_i)$

Algorithm	1.1 Dual preconditioned gradient descent
	$x_{i+1} = x_i - \frac{1}{L^*} \nabla k(\nabla f(x_i))$



Mirror Descent:



Dual Preconditioning:

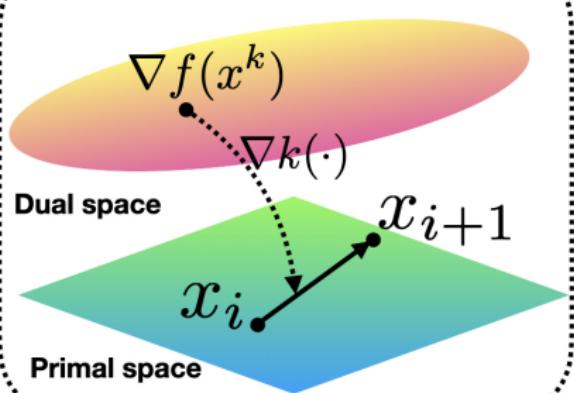


Figure: Taken from a tweet of Konstantin Mishchenko ¹

¹<https://mobile.x.com/konstmish/status/1431983100561592323/photo/1>

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Wasserstein Geometry (Ambrosio et al., 2005)

Endow $\mathcal{P}_2(\mathbb{R}^d)$ with the Wasserstein distance,

$$\forall \mu, \nu \in \mathcal{P}_2(\mathbb{R}^d), \quad W_2^2(\mu, \nu) = \inf_{\gamma \in \Pi(\mu, \nu)} \int \|x - y\|_2^2 \, d\gamma(x, y)$$

Wasserstein Geometry (Ambrosio et al., 2005)

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Properties:

- W_2 distance, $(\mathcal{P}_2(\mathbb{R}^d), W_2)$: Wasserstein space
- Riemannian structure (with geodesics and tangent space $\mathcal{T}_\mu \mathcal{P}_2(\mathbb{R}^d) \subset L^2(\mu)$)

Wasserstein gradient $\nabla_{W_2} \mathcal{F}(\mu) : \mathbb{R}^d \rightarrow \mathbb{R}^d \in \mathcal{T}_\mu \mathcal{P}_2(\mathbb{R}^d)$ of \mathcal{F} at μ satisfies

$$\forall T \in L^2(\mu), \quad \mathcal{F}(T_\# \mu) = \mathcal{F}(\mu) + \langle \nabla_{W_2} \mathcal{F}(\mu), T - \text{Id} \rangle_{L^2(\mu)} + o(\|T - \text{Id}\|_{L^2(\mu)})$$

with $T_\# \mu(A) = \mu(T^{-1}(A))$ for all $A \in \mathcal{B}(\mathbb{R}^d)$.

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with $T_\# \mu(A) = \mu(T^{-1}(A))$ for all $A \in \mathcal{B}(\mathbb{R}^d)$.

Example

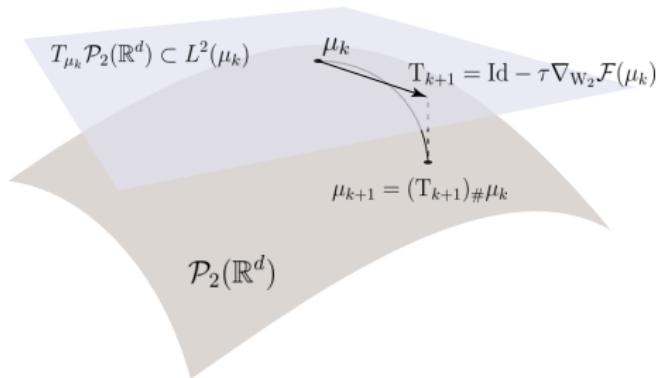
- $\mathcal{V}(\mu) = \int V \, d\mu, \quad \nabla_{W_2} \mathcal{V}(\mu) = \nabla V$
- $\mathcal{W}(\mu) = \frac{1}{2} \iint W(x - y) \, d\mu(x) d\mu(y), \quad \nabla_{W_2} \mathcal{W}(\mu) = \nabla W \star \mu$

Wasserstein Gradient Descent

Wasserstein Gradient Descent:

$$\begin{cases} T_{k+1} = \operatorname{argmin}_{T \in L^2(\mu_k)} \frac{1}{2} \|T - \text{Id}\|_{L^2(\mu_k)}^2 + \tau \langle \nabla_{W_2} \mathcal{F}(\mu_k), T - \text{Id} \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (T_{k+1})_\# \mu_k \end{cases}$$

Taking the FOC: $T_{k+1} = \text{Id} - \tau \nabla_{W_2} \mathcal{F}(\mu_k)$

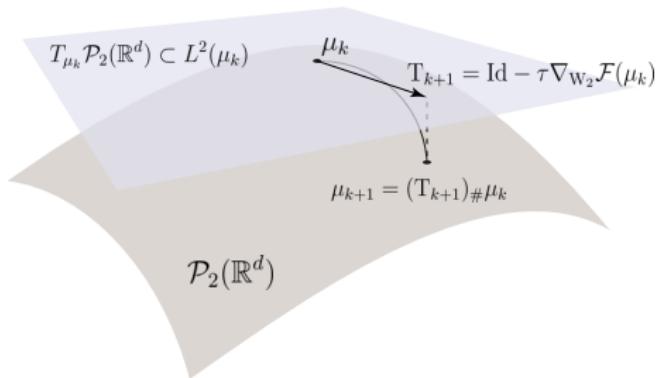


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Taking the FOC: $T_{k+1} = \operatorname{Id} - \tau \nabla_{W_2} \mathcal{F}(\mu_k)$



Particle approximation: $\hat{\mu}_k^n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i^k}$, $x_i^{k+1} = T_{k+1}(x_i^k)$ for all $i \in \{1, \dots, n\}$.

Contributions

Study schemes of the form

$$\begin{cases} T_{k+1} = \operatorname{argmin}_{T \in L^2(\mu_k)} d(T, \text{Id}) + \tau \langle \nabla_{W_2} \mathcal{F}(\mu_k), T - \text{Id} \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (T_{k+1})_\# \mu_k, \end{cases}$$

and provide **convergence conditions**.

Considered divergences:

- For $d(T, \text{Id}) = \frac{1}{2} \|T - \text{Id}\|_{L^2(\mu)}^2$: **Wasserstein gradient descent**
- For $d_{\phi_\mu}(T, \text{Id}) = \phi_\mu(T) - \phi_\mu(\text{Id}) - \langle \nabla \phi_\mu(\text{Id}), T - \text{Id} \rangle_{L^2(\mu)}$ (**Bregman divergence** on $L^2(\mu)$): extends **Mirror Descent** (Beck and Teboulle, 2003) to $\mathcal{P}_2(\mathbb{R}^d)$.
- For $d(T, \text{Id}) = \int h(T(x) - x) d\mu(x)$: extends **Preconditioned Gradient Descent** (Maddison et al., 2021) to $\mathcal{P}_2(\mathbb{R}^d)$.

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Background on $L^2(\mu)$

Definition (Bregman Divergence (Frigyik et al., 2008))

Let $\phi_\mu : L^2(\mu) \rightarrow \mathbb{R}$ be convex. The Bregman divergence is defined for all $T, S \in L^2(\mu)$ as

$$d_{\phi_\mu}(T, S) = \phi_\mu(T) - \phi_\mu(S) - \langle \nabla \phi_\mu(S), T - S \rangle_{L^2(\mu)}.$$

- If $\phi_\mu(T) = \frac{1}{2}\|T\|_{L^2(\mu)}^2$, $d_{\phi_\mu}(T, S) = \frac{1}{2}\|T - S\|_{L^2(\mu)}^2$
- We call ϕ_μ **pushforward compatible** if there exists $\phi : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$ such that

$$\forall \mu \in \mathcal{P}_2(\mathbb{R}^d), \forall T \in L^2(\mu), \phi_\mu(T) = \phi(T \# \mu).$$

In this case,

$$\nabla \phi_\mu(T) = \nabla_{W_2} \phi(T \# \mu) \circ T$$

Relative Convexity and Smoothness

Let $\phi_\mu, \psi_\mu : L^2(\mu) \rightarrow \mathbb{R}$ convex, $\mathcal{F}, \mathcal{G} : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$.

Relative smoothness/convexity on $L^2(\mu)$

- ϕ_μ is β -smooth relative to ψ_μ if for all $T, S \in L^2(\mu)$, $d_{\phi_\mu}(T, S) \leq \beta d_{\psi_\mu}(T, S)$.
- ϕ_μ is α -convex relative to ψ_μ if for all $T, S \in L^2(\mu)$, $d_{\phi_\mu}(T, S) \geq \alpha d_{\psi_\mu}(T, S)$.

Relative Convexity and Smoothness

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- ϕ_μ is α -convex relative to ψ_μ if for all $T, S \in L^2(\mu)$, $d_{\phi_\mu}(T, S) \geq \alpha d_{\psi_\mu}(T, S)$.

Define $\tilde{\mathcal{F}}_\mu(T) = \mathcal{F}(T \# \mu)$, $\tilde{\mathcal{G}}_\mu(T) = \mathcal{G}(T \# \mu)$.

Relative smoothness/convexity on $\mathcal{P}_2(\mathbb{R}^d)$

Relative smoothness/convexity along a curve $\mu_t = (T_t) \# \mu$ with $T_t = (1-t)S + tT$ for all $t \in [0, 1]$, $T, S \in L^2(\mu)$.

- \mathcal{F} β -smooth relative to \mathcal{G} along $t \mapsto \mu_t$ if $\forall s, t \in [0, 1]$,

$$d_{\tilde{\mathcal{F}}_\mu}(T_s, T_t) \leq \beta d_{\tilde{\mathcal{G}}_\mu}(T_s, T_t)$$

- \mathcal{F} α -convex relative to \mathcal{G} along $t \mapsto \mu_t$ if $\forall s, t \in [0, 1]$,

$$d_{\tilde{\mathcal{F}}_\mu}(T_s, T_t) \geq \alpha d_{\tilde{\mathcal{G}}_\mu}(T_s, T_t)$$

Mirror Descent on the Wasserstein Space

Let $\phi_\mu : L^2(\mu) \rightarrow \mathbb{R}$ be strictly convex, proper and differentiable.

Mirror Descent scheme:

$$\begin{cases} T_{k+1} = \operatorname{argmin}_{T \in L^2(\mu_k)} d_{\phi_{\mu_k}}(T, \operatorname{Id}) + \tau \langle \nabla_{W_2} \mathcal{F}(\mu_k), T - \operatorname{Id} \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (T_{k+1})_{\#} \mu_k. \end{cases}$$

By FOC: $\nabla \phi_{\mu_k}(T_{k+1}) = \nabla \phi_{\mu_k}(\operatorname{Id}) - \tau \nabla_{W_2} \mathcal{F}(\mu_k)$

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By FOC: $\nabla \phi_{\mu_k}(T_{k+1}) = \nabla \phi_{\mu_k}(\text{Id}) - \tau \nabla_{W_2} \mathcal{F}(\mu_k)$

Computing the scheme:

- For $\phi_\mu(T) = \int V \circ T \, d\mu$, $T_{k+1} = \nabla V^* \circ (\nabla V - \tau \nabla_{W_2} \mathcal{F}(\mu_k))$
- For ϕ_μ pushforward compatible (i.e. $\phi_\mu(T) = \phi(T_{\#} \mu)$ with $\phi : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$):

$$\nabla_{W_2} \phi(\mu_{k+1}) \circ T_{k+1} = \nabla_{W_2} \phi(\mu_k) - \tau \nabla_{W_2} \mathcal{F}(\mu_k)$$

In general: implicit in $T_{k+1} \rightarrow$ Newton method

Descent Lemma

Let $\phi_\mu : L^2(\mu) \rightarrow \mathbb{R}$ be strictly convex, proper and differentiable.

Mirror Descent scheme:

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Proposition (Descent Lemma)

Assumptions:

- For all $k \geq 0$, \mathcal{F} is β -smooth relative to ϕ along $t \mapsto ((1-t)\text{Id} + tT_{k+1})_{\#} \mu_k$.
Then, for all $k \geq 0$,

$$\mathcal{F}(\mu_{k+1}) \leq \mathcal{F}(\mu_k) - \beta d_{\phi_{\mu_k}}(\text{Id}, T_{k+1}).$$

Convergence

Proposition

Assumptions: Let $\beta > 0, \alpha \geq 0$ and $T_{\phi_{\mu_k}}^{\mu_k, \mu^*} = \operatorname{argmin}_{T \# \mu_k = \mu^*} d_{\phi_{\mu_k}}(T, \operatorname{Id})$.

- \mathcal{F} β -smooth relative to ϕ along $t \mapsto ((1-t)\operatorname{Id} + tT_{k+1})_{\#} \mu_k$
- \mathcal{F} α -convex relative to ϕ along $t \mapsto ((1-t)\operatorname{Id} + tT_{\phi_{\mu_k}}^{\mu_k, \mu^*})_{\#} \mu_k$
- Assume $d_{\phi_{\mu_k}}(T_{\phi_{\mu_k}}^{\mu_k, \mu^*}, T_{k+1}) \geq d_{\phi_{\mu_{k+1}}}(T_{\phi_{\mu_{k+1}}}^{\mu_{k+1}, \mu^*}, \operatorname{Id})$

Then, for all $k \geq 1$, $\mathcal{F}(\mu_k) - \mathcal{F}(\mu^*) \leq \frac{\beta - \alpha}{k} d_{\phi_{\mu_0}}(T_{\phi_{\mu_0}}^{\mu_0, \mu^*}, \operatorname{Id})$.

Convergence

Proposition

Assumptions: Let $\beta > 0, \alpha \geq 0$ and $T_{\phi_{\mu_k}}^{\mu_k, \mu^*} = \operatorname{argmin}_{T \# \mu_k = \mu^*} d_{\phi_{\mu_k}}(T, \text{Id})$.

- \mathcal{F} β -smooth relative to ϕ along $t \mapsto ((1-t)\text{Id} + tT_{k+1})_{\#} \mu_k$
- \mathcal{F} α -convex relative to ϕ along $t \mapsto ((1-t)\text{Id} + tT_{\phi_{\mu_k}}^{\mu_k, \mu^*})_{\#} \mu_k$
- Assume $d_{\phi_{\mu_k}}(T_{\phi_{\mu_k}}^{\mu_k, \mu^*}, T_{k+1}) \geq d_{\phi_{\mu_{k+1}}}(T_{\phi_{\mu_{k+1}}}^{\mu_{k+1}, \mu^*}, \text{Id})$

Then, for all $k \geq 1$, $\mathcal{F}(\mu_k) - \mathcal{F}(\mu^*) \leq \frac{\beta - \alpha}{k} d_{\phi_{\mu_0}}(T_{\phi_{\mu_0}}^{\mu_0, \mu^*}, \text{Id})$.

Let ϕ_μ be pushforward compatible. Define the OT problem:

$$\begin{aligned} W_\phi(\nu, \mu) &= \inf_{\gamma \in \Pi(\nu, \mu)} \phi(\nu) - \phi(\mu) - \int \langle \nabla_{W_2} \phi(\mu)(y), x - y \rangle \, d\gamma(x, y) \\ &\leq d_{\phi_\eta}(T, S) \quad \text{for } (T, S) \# \eta \in \Pi(\nu, \mu) \end{aligned}$$

Property: If $\mu_{k+1} \ll \text{Leb}$ and $\nabla_{W_2} \phi(\mu_{k+1})$ is invertible, then

$$d_{\phi_{\mu_k}}(T_{\phi_{\mu_k}}^{\mu_k, \mu^*}, T_{k+1}) \geq d_{\phi_{\mu_{k+1}}}(T_{\phi_{\mu_{k+1}}}^{\mu_{k+1}, \mu^*}, \text{Id}) = W_\phi(\mu^*, \mu_{k+1})$$

Preconditioned GD

Let $h : \mathbb{R}^d \rightarrow \mathbb{R}$ strictly convex, proper and differentiable.

Preconditioned Gradient Descent scheme: Let $\phi_\mu^h(T) = \int h \circ T \, d\mu$,

$$\begin{cases} T_{k+1} = \operatorname{argmin}_{T \in L^2(\mu_k)} \phi_{\mu_k}^h \left(\frac{\operatorname{Id} - T}{\tau} \right) \tau + \langle \nabla_{W_2} \mathcal{F}(\mu_k), T - \operatorname{Id} \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (T_{k+1})_\# \mu_k \end{cases}$$

By FOC: $T_{k+1} = \operatorname{Id} - \tau \nabla h^* \circ \nabla_{W_2} \mathcal{F}(\mu_k)$

Under relative smoothness and convexity of $\phi_\mu^{h^*}$ relative to \mathcal{F}^* :

$$\forall k \geq 0, \phi_{\mu_{k+1}}^{h^*} (\nabla_{W_2} \mathcal{F}(\mu_{k+1})) \leq \phi_{\mu_k}^{h^*} (\nabla_{W_2} \mathcal{F}(\mu_k)) - \beta d_{\tilde{\mathcal{F}}_{\mu_k}}(T_{k+1}, \operatorname{Id}),$$

$$\forall k \geq 1, \phi_{\mu_k}^{h^*} (\nabla_{W_2} \mathcal{F}(\mu_k)) - h^*(0) \leq \frac{\beta - \alpha}{k} (\mathcal{F}(\mu_0) - \mathcal{F}(\mu^*)).$$

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→ In general: look at the hessian

Showing Relative Smoothness and Convexity

Smoothness and convexity of $\mathcal{F} : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$ relative to $\phi : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$?

→ In general: look at the hessian

Particular cases where it is simpler: For $V, U, W, K : \mathbb{R}^d \rightarrow \mathbb{R}$,

- Let $\mathcal{F}(\mu) = \int V d\mu$ and $\phi(\mu) = \int U d\mu$:

V β -smooth relative to $U \implies \mathcal{F}$ β -smooth relative to ϕ

V α -convex relative to $U \implies \mathcal{F}$ α -convex relative to ϕ

- Let $\mathcal{F}(\mu) = \iint W(x - y) d\mu(x)d\mu(y)$ and $\phi(\mu) = \iint K(x - y) d\mu(x)d\mu(y)$:

W β -smooth relative to $K \implies \mathcal{F}$ β -smooth relative to ϕ

W α -convex relative to $K \implies \mathcal{F}$ α -convex relative to ϕ

- For $\mathcal{F} = \mathcal{G} + \mathcal{H}$, $d_{\tilde{\mathcal{F}}_\mu} = d_{\tilde{\mathcal{G}}_\mu} + d_{\tilde{\mathcal{H}}_\mu}$ and \mathcal{F} 1-convex relative to \mathcal{G} and \mathcal{H}

Mirror Descent on Interaction Energy

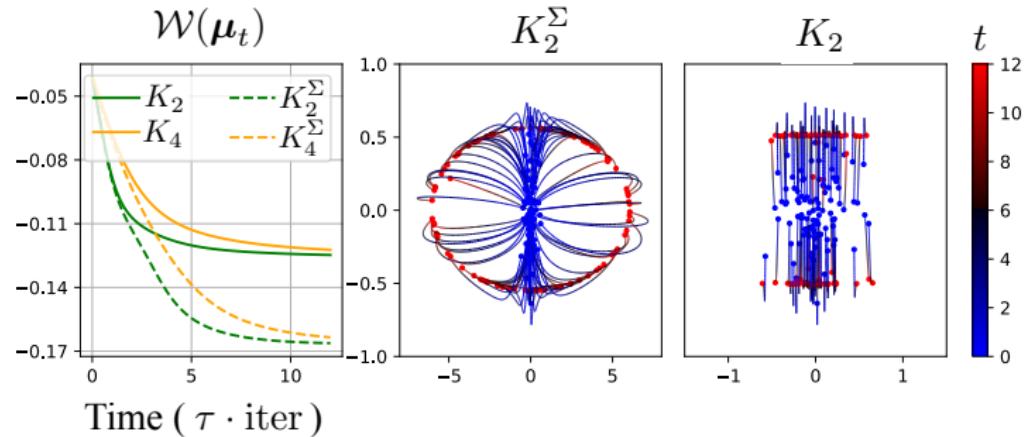
Goal: Let $\Sigma \in S_d^{++}(\mathbb{R})$ possibly ill-conditioned,

$$\min_{\mu} \mathcal{W}(\mu) = \iint W(x - y) \, d\mu(x)d\mu(y) \quad \text{with} \quad W(z) = \frac{1}{4}\|z\|_{\Sigma^{-1}}^4 - \frac{1}{2}\|z\|_{\Sigma^{-1}}^2$$

Bregman potential: $\phi_{\mu}(T) = \iint K(T(x) - T(y)) \, d\mu(x)d\mu(y)$ with

$$K_2(z) = \frac{1}{2}\|z\|_2^2, \quad K_2^{\Sigma}(z) = \frac{1}{2}\|z\|_{\Sigma^{-1}}^2,$$

$$K_4(z) = \frac{1}{4}\|z\|_2^4 + \frac{1}{2}\|z\|_2^2, \quad K_4^{\Sigma}(z) = \frac{1}{4}\|z\|_{\Sigma^{-1}}^4 + \frac{1}{2}\|z\|_{\Sigma^{-1}}^2.$$



Mirror Descent on Gaussian

Goal:

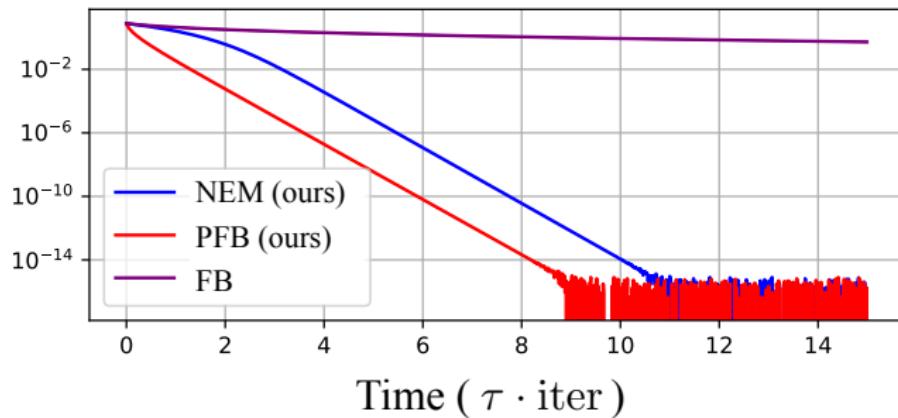
$$\min_{\mu} \mathcal{F}(\mu) = \int V d\mu + \mathcal{H}(\mu) \quad \text{with} \quad V(x) = \frac{1}{2} x^T \Sigma^{-1} x$$

→ minimum $\mu^* = \mathcal{N}(0, \Sigma)$.

Comparison between:

- Forward-Backward (FB) on the Bures-Wasserstein space ([Diao et al., 2023](#))
- Preconditioned Forward-Backward (PFB) scheme with $\phi(\mu) = \int V d\mu$
- NEM: MD with $\phi(\mu) = \mathcal{H}(\mu)$ and restriction to Gaussian

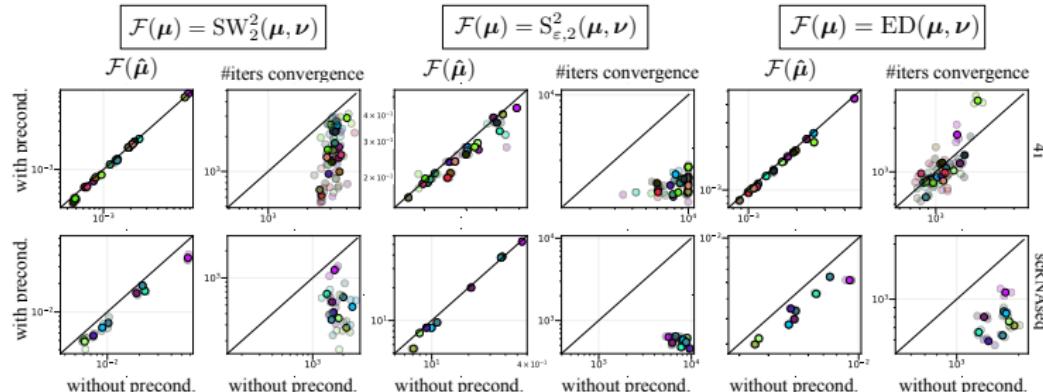
$$\text{KL}(\mu_t || \mu^*)$$



Preconditioned GD on Single-Cells

Goal: $\min_{\mu} \mathcal{F}(\mu) = D(\mu, \nu)$ with μ_0 untreated cell and ν perturbed cell

Use PGD with $h^*(x) = (\|x\|_2^a + 1)^{1/a} - 1$ with $a \in \{1.25, 1.5, 1.75\}$



- Rows: 2 profiling technologies
 - Columns: Different objectives \mathcal{F}
 - Subcolumns: Measure of convergence and number of iterations to converge
- Points below the diagonal: PGD provides a better minimum or converges faster

Conclusion

Conclusion:

- Mirror Descent on $\mathcal{P}_2(\mathbb{R}^d)$
- Preconditioned Gradient Descent on $\mathcal{P}_2(\mathbb{R}^d)$
- Convergence analysis of the discrete schemes
- Also in the paper: analysis of the Bregman Forward-Backward scheme

Perspectives:

- Find more examples satisfying the conditions
- Analyze the Gaussian MD scheme

Conclusion

Thank you!

Paper: <https://arxiv.org/abs/2406.08938>



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