Mirror and Preconditioned Gradient Descent in Wasserstein Space

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Motivations

Let $\mathcal{P}_2(\mathbb{R}^d) = \{ \mu \in \mathcal{P}(\mathbb{R}^d), \int ||x||_2^2 d\mu(x) < \infty \}, \ \mathcal{F} : \mathcal{P}_2(\mathbb{R}^d) \to \mathbb{R}.$

Goal:

$$\min_{\mu \in \mathcal{P}_2(\mathbb{R}^d)} \ \mathcal{F}(\mu)$$

Applications:

- Sampling from $\nu \propto e^{-V}$ (Wibisono, 2018)
- Generative modeling
- Learning neural networks (Mei et al., 2018; Chizat and Bach, 2018)
- Modeling dynamic of populations of cells (Schiebinger et al., 2019)

Example of functionals

- Free energies: $\mathcal{F}(\mu) = \int V d\mu + \iint W(x,y) d\mu(x) d\mu(y) + \mathcal{H}(\mu)$ where $\mathcal{H}(\mu) = \int \log (\mu(x)) d\mu(x)$ for $\mu \ll \text{Leb}$
- $\mathcal{F}(\mu) = \mathrm{KL}(\mu||\nu) = \int V d\mu + \mathcal{H}(\mu) \; (+C)$ for sampling from $\nu \propto e^{-V(x)}$
- $\mathcal{F}(\mu) = D(\mu, \nu)$ for sampling from ν

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Gradient Descent on \mathbb{R}^d

Let $f: \mathbb{R}^d \to \mathbb{R}$.

Goal: $\min_{x \in \mathbb{R}^d} f(x)$ via gradient flow

$$\frac{\mathrm{d}x_t}{\mathrm{d}t} = -\nabla f(x_t), \quad x_0 = x_0$$

Gradient Descent on \mathbb{R}^d

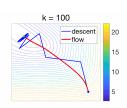
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$$\frac{\mathrm{d}x_t}{\mathrm{d}t} = -\nabla f(x_t), \quad x_0 = x_0$$

Main algorithm: Gradient Descent (GD)

$$\begin{split} \forall k \geq 0, \ x_{k+1} &= x_k - \tau \nabla f(x_k) \\ &= \underset{x \in \mathbb{R}^d}{\operatorname{argmin}} \ \frac{1}{2} \|x - x_k\|_2^2 + \tau \langle \nabla f(x_k), x - x_k \rangle \end{split}$$



Gradient Descent on \mathbb{R}^d

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Main algorithm: Gradient Descent (GD)

$$\forall k \geq 0, \ x_{k+1} = x_k - \tau \nabla f(x_k)$$
 From (Bach, 2020)
$$= \underset{x \in \mathbb{R}^d}{\operatorname{argmin}} \ \frac{1}{2} \|x - x_k\|_2^2 + \tau \langle \nabla f(x_k), x - x_k \rangle$$

Convergence Analysis

- f β -smooth $\implies f(x_{k+1}) \leq f(x_k) \frac{1}{2\beta} \|\nabla f(x_k)\|_2^2 = f(x_k) \frac{\beta}{2} \|x_{k+1} x_k\|_2^2$
- $f \beta$ -smooth and α -convex $\implies f(x_k) f(x^*) \leq \frac{\beta \alpha}{2k} ||x_0 x^*||_2^2$

Reminder:

- $f \beta$ -smooth $\iff \forall x,y \in \mathbb{R}^d, \ f(x) f(y) \langle \nabla f(y), x y \rangle \leq \frac{\beta}{2} \|x y\|_2^2$
- $f \alpha$ -convex $\iff f \alpha \frac{\|\cdot\|_2^2}{2}$ convex

If f not β -smooth: no guarantees for $\mathsf{GD} \to \mathsf{change}$ geometry

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Definition (Bregman Divergence)

Let $\phi:\mathbb{R}^d \to \mathbb{R}$ be strictly convex, then the Bregman divergence is defined as

$$\forall x, y \in \mathbb{R}^d, \ d_{\phi}(x, y) = \phi(x) - \phi(y) - \langle \nabla \phi(y), x - y \rangle.$$

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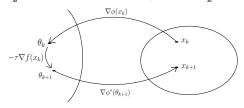
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Mirror Descent algorithm:

$$\forall k \ge 0, \ x_{k+1} = \underset{x \in \mathbb{R}^d}{\operatorname{argmin}} \ d_{\phi}(x, x_k) + \tau \langle \nabla f(x_k), x - x_k \rangle$$
$$= \nabla \phi^* \big(\nabla \phi(x_k) - \tau \nabla f(x_k) \big).$$

Remark: For $\phi(x) = \frac{1}{2} \|x\|_2^2$, MD = GD and $d_{\phi}(x, y) = \frac{1}{2} \|x - y\|_2^2$



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Convergence analysis (Lu et al., 2018)

- f β -smooth relative to ϕ , i.e. $d_f(x,y) \leq \beta d_\phi(x,y)$ (equivalently $\beta \phi f$ convex) $\implies f(x_{k+1}) \leq f(x_k) \beta d_\phi(x_k, x_{k+1})$
- f β -smooth and α -convex relative to ϕ , i.e. $\alpha d_{\phi}(x,y) \leq d_{f}(x,y)$ (equivalently $f \alpha \phi$ convex) $\implies f(x_{k}) f(x^{*}) \leq \frac{\beta \alpha}{k} d_{\phi}(x^{*}, x_{0})$

Proof of convergence

<u>Lemma</u> (Three-Point Inequality)

Let $g: \mathbb{R}^d \to \mathbb{R}$ be a convex function, $\phi: \mathbb{R}^d \to \mathbb{R}$ strictly convex. Let $z_0 \in \mathbb{R}^d$ and $z^* = \operatorname{argmin}_z \ \mathrm{d}_{\phi}(z, z_0) + g(z)$. Then, for all $z \in \mathbb{R}^d$,

$$g(z) + d_{\phi}(z, z_0) \ge g(z^*) + d_{\phi}(z^*, z_0) + d_{\phi}(z, z^*).$$

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Using smoothness, Three-point inequality on $g(x)=\frac{1}{\beta}\langle \nabla f(x_k),x-x_k\rangle$ and strong convexity we get for all $x\in\mathbb{R}^d$,

$$f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \beta d_{\phi}(x_{k+1}, x_k)$$

$$\leq f(x_k) + \langle \nabla f(x_k), x - x_k \rangle + \beta d_{\phi}(x, x_k) - \beta d_{\phi}(x, x_{k+1})$$

$$\leq f(x) + (\beta - \alpha) d_{\phi}(x, x_k) - \beta d_{\phi}(x, x_{k+1}).$$

By induction and using the monotonicity of f, and taking $x=x^*$, we get the desired rates: $f(x_k)-f(x) \leq \frac{\alpha \mathrm{d}_\phi(x,x_0)}{\left(1+\frac{\alpha}{R-\alpha}\right)^k-1} \leq \frac{\beta-\alpha}{k} \mathrm{d}_\phi(x,x_0)$.

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By induction and using the monotonicity of f, and taking $x=x^*$, we get the desired rates: $f(x_k) - f(x) \leq \frac{\alpha d_\phi(x,x_0)}{(1+\frac{\alpha}{2})^k-1} \leq \frac{\beta-\alpha}{k} d_\phi(x,x_0)$.

Remarks: (1) the proof works replacing β with $1/\tau$ if $\tau \leq 1/\beta$, (2) we need smoothness and convexity in specific directions.

Preconditioned Gradient Descent (Maddison et al., 2021)

Let $h: \mathbb{R}^d \to \mathbb{R}$ strictly convex, $g: \mathbb{R}^d \to \mathbb{R}$.

Preconditioned Gradient Descent scheme:

$$\forall k \ge 0, \ y_{k+1} = y_k - \tau \nabla h^* \left(\nabla g(y_k) \right)$$
$$= \underset{y \in \mathbb{R}^d}{\operatorname{argmin}} \ h \left(\frac{y_k - y}{\tau} \right) \tau + \left\langle \nabla g(y_k), y - y_k \right\rangle$$

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Closely related to MD (Kim et al., 2023) as for $g=\phi^*$, $h^*=f$, $y=\nabla\phi(x)$,

$$\nabla \phi(x_{k+1}) = \nabla \phi(x_k) - \tau \nabla f(x_k) \iff x_{k+1} = \nabla \phi^* (\nabla \phi(x_k) - \tau \nabla f(x_k)).$$

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Convergence analysis (Maddison et al., 2021)

- h^* β -smooth relative to $g^* \implies h^*(\nabla g(y_{k+1})) \leq h^*(\nabla g(y_k)) \beta d_g(y_{k+1}, y_k)$
- h^* β -smooth and α -convex relative to g^* $\implies \forall k \geq 1, \ h^* \big(\nabla g(y_k) \big) h^*(0) \leq \frac{\alpha \beta}{k} \big(g(y_0) g(y^*) \big)$
 - $\implies \forall k \ge 0, \ g(y_k) g(y^*) \le (1 \alpha/\beta)^k (g(y_0) g(y^*))$

Relation between MD and Preconditioned GD



Dual Space Preconditioning for Gradient Descent

Chris J. Maddison^{1,4,*}, Daniel Paulin^{2,*}, Yee Whye Teh³, and Arnaud Doucet³



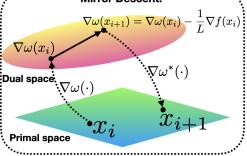


 $egin{align*} \overline{ ext{Algorithm}} & ext{Mirror descent} \ &
abla \omega(x_{i+1}) =
abla \omega(x_i) - rac{1}{L}
abla f(x_i) \ &
abla w(x_i) - rac{1}{L}
abla f(x_i) - rac{1}{L}
abla f(x_i)$

Algorithm 1.1 Dual preconditioned gradient descent $x_{i+1} = x_i - \frac{1}{L^*} \nabla k(\nabla f(x_i))$



Mirror Descent:



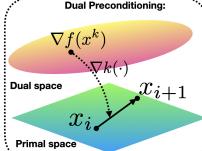


Figure: Taken from a tweet of Konstantin Mishchenko ¹

¹https://mobile.x.com/konstmish/status/1431983100561592323/photo/1

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Wasserstein Geometry

Definition (Wasserstein distance)

Let $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d)$ and denote by $\Pi(\mu, \nu)$ the set of coupling between μ, ν . Then, the Wasserstein distance is

$$W_2^2(\mu, \nu) = \inf_{\gamma \in \Pi(\mu, \nu)} \int ||x - y||_2^2 d\gamma(x, y).$$

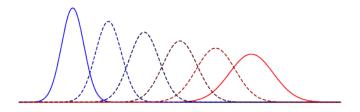
Properties:

- W₂ distance, $(\mathcal{P}_2(\mathbb{R}^d), W_2)$: Wasserstein space
- Brenier's theorem: If $\mu \ll \mathrm{Leb}$, then there exists a unique T^{ν}_n such that
- 1. $(T_{\mu}^{\nu})_{\#}\mu = \nu \left(T_{\#}\mu(A) = \mu(T^{-1}(A))\right)$ for all $A \subset \mathbb{R}^d$
- 2. $W_2^2(\mu, \nu) = \int \|x T_\mu^\nu(x)\|_2^2 d\mu(x) = \|Id T_\mu^\nu\|_{T^2(\mu)}^2$
- Riemannian structure

Riemannian Structure of the Wasserstein Space

• Geodesics between $\mu \ll \mathrm{Leb}$ and $\nu \in \mathcal{P}_2(\mathbb{R}^d)$:

$$\forall t \in [0,1], \ \mu_t = ((1-t)\mathrm{Id} + t\mathrm{T}^{\nu}_{\mu})_{\#}\mu$$



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• Tangent space at $\mu \in \mathcal{P}_2(\mathbb{R}^d)$ (Ambrosio et al., 2005):

$$\mathcal{T}_{\mu}\mathcal{P}_{2}(\mathbb{R}^{d}) = \overline{\{\nabla\psi, \ \psi \in C_{c}^{\infty}(\mathbb{R}^{d})\}} \subset L^{2}(\mu),$$

where $L^2(\mu) = \{ f \in \mathbb{R}^d \to \mathbb{R}^d, \int \|f(x)\|_2^2 d\mu(x) < \infty \}.$

$$T_{\mu}\mathcal{P}_2(\mathbb{R}^d)\subset L^2(\mu)$$
 μ

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where $L^2(\mu) = \{ f \in \mathbb{R}^d \to \mathbb{R}^d, \ \int \|f(x)\|_2^2 \ \mathrm{d}\mu(x) < \infty \}.$

$$T_{\mu}\mathcal{P}_2(\mathbb{R}^d)\subset L^2(\mu)$$

$$\mathcal{P}_2(\mathbb{R}^d)$$

• \mathcal{F} is α -geodesically convex if $t \mapsto \mathcal{F}(\mu_t)$ is α -convex, *i.e.* for all $t \in [0,1]$,

$$\mathcal{F}(\mu_t) \le (1-t)\mathcal{F}(\mu_0) + t\mathcal{F}(\mu_1) - \frac{\alpha t(1-t)}{2} W_2^2(\mu_0, \mu_1).$$

Wasserstein Gradient

Definition (Wasserstein gradient (Bonnet, 2019))

Let $\mu \in \mathcal{P}_2(\mathbb{R}^d)$. $\nabla_{W_2}\mathcal{F}(\mu) \in L^2(\mu)$ is a Wasserstein gradient of \mathcal{F} at μ if for any $\nu \in \mathcal{P}_2(\mathbb{R}^d)$ and any optimal coupling $\gamma \in \Pi_o(\mu, \nu)$,

$$\mathcal{F}(\nu) = \mathcal{F}(\mu) + \int \langle \nabla_{\mathbf{W}_2} \mathcal{F}(\mu)(x), y - x \rangle \, d\gamma(x, y) + o(\mathbf{W}_2(\mu, \nu)).$$

If such a gradient exists, then we say that \mathcal{F} is W_2 -differentiable at μ .

Properties:

 $\gamma \in \Pi(\mu, \nu)$,

- There is a unique gradient in $\mathcal{T}_{\mu}\mathcal{P}_{2}(\mathbb{R}^{d})$ (Lanzetti et al., 2022, Proposition 2.5)
- Differential are strong (Lanzetti et al., 2022, Proposition 2.6), *i.e.* for any

$$\mathcal{F}(\nu) = \mathcal{F}(\mu) + \int \langle \nabla_{\mathbf{W}_2} \mathcal{F}(\mu)(x), y - x \rangle \, d\gamma(x, y) + o\left(\sqrt{\int \|x - y\|_2^2 \, d\gamma(x, y)}\right)$$

In particular, for $\gamma = (\mathrm{Id}, \mathrm{T})_{\#} \mu$,

$$\mathcal{F}(\mathrm{T}_{\#}\mu) = \mathcal{F}(\mu) + \langle \nabla_{\mathrm{W}_2}\mathcal{F}(\mu), \mathrm{T} - \mathrm{Id} \rangle_{L^2(\mu)} + o(\|\mathrm{T} - \mathrm{Id}\|_{L^2(\mu)})$$

Wasserstein Gradient

Example of functionals

• Potential energies $\mathcal{V}(\mu) = \int V d\mu$: For V differentiable and smooth,

$$\nabla_{\mathbf{W}_2} \mathcal{V}(\mu) = \nabla V$$

• Interaction energies $\mathcal{W}(\mu) = \iint W(x-y) \ \mathrm{d}\mu(x) \mathrm{d}\mu(y)$: For W even, differentiable and smooth.

$$\nabla_{\mathbf{W}_2} \mathcal{W}(\mu) = \nabla W \star \mu$$

Negative entropy

 $\mathcal{H}(\mu)=\int \log \left(\mu(x)\right)\,\mathrm{d}\mu(x)$ not W_2 -differentiable but can consider subgradients under regularity assumptions:

$$\forall x \in \mathbb{R}^d, \ \nabla_{\mathbf{W}_2} \mathcal{H}(\mu)(x) = \nabla \log \mu(x)$$

Wasserstein Gradient Flows (Ambrosio et al., 2005)

Wasserstein gradient flow of \mathcal{F} : curve $t \mapsto \mu_t$ satisfying (weakly)

$$\partial_t \mu_t = \operatorname{div} (\mu_t \nabla_{\mathbf{W}_2} \mathcal{F}(\mu_t)).$$

Particles:
$$x_t \sim \mu_t \iff \frac{\mathrm{d}x_t}{\mathrm{d}t} = -\nabla_{\mathrm{W}_2} \mathcal{F}(\mu_t)(x_t)$$
.

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Time discretization of the flow:

• Implicit/Backward (JKO) scheme (Jordan et al., 1998):

$$\mu_{k+1} = \underset{\mu \in \mathcal{P}_2(\mathbb{R}^d)}{\operatorname{argmin}} \frac{1}{2} W_2^2(\mu, \mu_k) + \tau \mathcal{F}(\mu)$$

If $\mu_k \ll \text{Leb}$, $\mu_{k+1} = T_{\#}\mu_k$ with

$$T = \underset{T \in L^{2}(\mu_{k})}{\operatorname{argmin}} \ \frac{1}{2} \|T - \operatorname{Id}\|_{L^{2}(\mu_{k})}^{2} + \tau \mathcal{F}(T_{\#}\mu_{k})$$

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Time discretization of the flow: • Implicit/Backward (JKO) scheme (Jordan et al., 1998):

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$$\mu_{k+1} = \underset{\mu \in \mathcal{P}_2(\mathbb{R}^d)}{\operatorname{argmin}} \frac{1}{2} W_2^2(\mu, \mu_k) + \tau \mathcal{F}(\mu)$$

If $\mu_k \ll \text{Leb}$, $\mu_{k+1} = T_\# \mu_k$ with

$$T = \underset{T \in L^2(\mu_k)}{\operatorname{argmin}} \frac{1}{2} \|T - \operatorname{Id}\|_{L^2(\mu_k)}^2 + \tau \mathcal{F}(T_{\#}\mu_k)$$

Explicit/Forward scheme

$$\begin{cases} \mathbf{T}_{k+1} = \operatorname{argmin}_{\mathbf{T} \in L^{2}(\mu_{k})} \ \frac{1}{2} \|\mathbf{T} - \operatorname{Id}\|_{L^{2}(\mu_{k})}^{2} + \tau \langle \nabla_{\mathbf{W}_{2}} \mathcal{F}(\mu_{k}), \mathbf{T} - \operatorname{Id} \rangle_{L^{2}(\mu_{k})} \\ \mu_{k+1} = (\mathbf{T}_{k+1})_{\#} \mu_{k} \end{cases}$$

Taking the FOC: $T_{k+1} = Id - \tau \nabla_{W_2} \mathcal{F}(\mu_k)$

Wasserstein Gradient Descent

$$T_{\mu_k}\mathcal{P}_2(\mathbb{R}^d)\subset L^2(\mu_k)$$

$$\mu_k$$

$$T_{k+1}=\operatorname{Id}-\tau\nabla_{\operatorname{W}_2}\mathcal{F}(\mu_k)$$

$$\mu_{k+1}=(\operatorname{T}_{k+1})_\#\mu_k$$

$$\mathcal{P}_2(\mathbb{R}^d)$$

Wasserstein Gradient Descent:

$$\begin{cases} \mathbf{T}_{k+1} = \operatorname{argmin}_{\mathbf{T} \in L^{2}(\mu_{k})} \ \frac{1}{2} \|\mathbf{T} - \operatorname{Id}\|_{L^{2}(\mu_{k})}^{2} + \tau \langle \nabla_{\mathbf{W}_{2}} \mathcal{F}(\mu_{k}), \mathbf{T} - \operatorname{Id} \rangle_{L^{2}(\mu_{k})} \\ \mu_{k+1} = (\mathbf{T}_{k+1})_{\#} \mu_{k} \end{cases}$$

Taking the FOC: $T_{k+1} = Id - \tau \nabla_{W_2} \mathcal{F}(\mu_k)$

Particle approximation: $\hat{\mu}_k^n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i^k}$, $x_i^{k+1} = T_{k+1}(x_i^k)$ for all $i \in \{1, \dots, n\}$.

Contributions

Study schemes of the form

$$\begin{cases} T_{k+1} = \operatorname{argmin}_{T \in L^2(\mu_k)} \ d(T, Id) + \tau \langle \nabla_{W_2} \mathcal{F}(\mu_k), T - Id \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (T_{k+1})_{\#} \mu_k, \end{cases}$$

and provide convergence conditions.

Considered divergences:

- For $d(T, Id) = \frac{1}{2} ||T Id||_{L^2(\mu)}^2$: Wasserstein gradient descent
- For $d_{\phi_{\mu}}(T, Id) = \phi_{\mu}(T) \phi_{\mu}(Id) \langle \nabla \phi_{\mu}(Id), T Id \rangle_{L^{2}(\mu)}$ (Bregman divergence on $L^{2}(\mu)$): extends Mirror Descent (Beck and Teboulle, 2003) to $\mathcal{P}_{2}(\mathbb{R}^{d})$.
- For $d(T, Id) = \int h(T(x) x) d\mu(x)$: extends **Preconditioned Gradient Descent** (Maddison et al., 2021) to $\mathcal{P}_2(\mathbb{R}^d)$.

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Background on $L^2(\mu)$

Definition (Bregman Divergence (Frigyik et al., 2008))

Let $\phi_{\mu}: L^2(\mu) \to \mathbb{R}$ be convex. The Bregman divergence is defined for all $T, S \in L^2(\mu)$ as

$$d_{\phi_{\mu}}(T, S) = \phi_{\mu}(T) - \phi_{\mu}(S) - \langle \nabla \phi_{\mu}(S), T - S \rangle_{L^{2}(\mu)}.$$

• If $\phi_{\mu}(T) = \frac{1}{2} \|T\|_{L^{2}(\mu)}^{2}$, $d_{\phi_{\mu}}(T, S) = \frac{1}{2} \|T - S\|_{L^{2}(\mu)}^{2}$ • We call ϕ_{μ} pushforward compatible if there exists $\phi : \mathcal{P}_{2}(\mathbb{R}^{d}) \to \mathbb{R}$ such that

$$\forall \mu \in \mathcal{P}_2(\mathbb{R}^d), \ \forall \mathbf{T} \in L^2(\mu), \ \phi_{\mu}(\mathbf{T}) = \phi(\mathbf{T}_{\#}\mu).$$

In this case, if ϕ is W_2 -differentiable, then ϕ_μ is Fréchet differentiable and $\nabla \phi_\mu(T) = \nabla_{W_2} \phi(T_\# \mu) \circ T$.

- Let $\phi_{\mu}, \psi_{\mu} : L^{2}(\mu) \to \mathbb{R}$ convex. • ϕ_{μ} is β -smooth relative to ψ_{μ} if for all $T, S \in L^{2}(\mu), d_{\phi_{\mu}}(T, S) \leq \beta d_{\psi_{\mu}}(T, S)$.
 - ϕ_{μ} is β -smooth relative to ψ_{μ} if for all $1, S \in L^{-}(\mu)$, $d_{\phi_{\mu}}(1, S) \leq \beta d_{\psi_{\mu}}(1, S)$. • ϕ_{μ} is α -convex relative to ψ_{μ} if for all $T, S \in L^{2}(\mu)$, $d_{\phi_{\mu}}(T, S) \geq \alpha d_{\psi_{\mu}}(T, S)$.

Convexity on $\mathcal{P}_2(\mathbb{R}^d)$

Let $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$, $\mu_0 \ll \text{Leb}$, and $\mu_t = ((1-t)\text{Id} + tT_{\mu_0}^{\mu_1})_{\#}\mu_0$.

• \mathcal{F} is α -geodesically convex if $t \mapsto \mathcal{F}(\mu_t)$ is α -convex, i.e. for all $t \in [0,1]$,

$$\mathcal{F}(\mu_t) \le (1-t)\mathcal{F}(\mu_0) + t\mathcal{F}(\mu_1) - \frac{\alpha t(1-t)}{2}W_2^2(\mu_0, \mu_1),$$

or equivalently

$$\frac{\alpha}{2} W_2^2(\mu_0, \mu_1) = \frac{\alpha}{2} \|T_{\mu_0}^{\mu_1} - Id\|_{L^2(\mu_0)}^2 \le \mathcal{F}(\mu_1) - \mathcal{F}(\mu_0) - \langle \nabla_{W_2} \mathcal{F}(\mu_0), T_{\mu_0}^{\mu_1} - Id \rangle_{L^2(\mu_0)}
= d_{\tilde{\mathcal{F}}_{\mu_0}}(T_{\mu_0}^{\mu_1}, Id)$$

with $\tilde{\mathcal{F}}_{\mu}(T) = \mathcal{F}(T_{\#}\mu)$.

Convexity on $\mathcal{P}_2(\mathbb{R}^d)$

• \mathcal{F} is α -geodesically convex if $t\mapsto \mathcal{F}(\mu_t)$ is α -convex, i.e. for all $t\in[0,1]$,

Let $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$, $\mu_0 \ll \text{Leb}$, and $\mu_t = ((1-t)\text{Id} + tT_{\mu_0}^{\mu_1})_{\#}\mu_0$.

$$\mathcal{F}(\mu_t) \le (1-t)\mathcal{F}(\mu_0) + t\mathcal{F}(\mu_1) - \frac{\alpha t(1-t)}{2}W_2^2(\mu_0, \mu_1),$$

or equivalently

$$\frac{\alpha}{2} W_2^2(\mu_0, \mu_1) = \frac{\alpha}{2} \|T_{\mu_0}^{\mu_1} - Id\|_{L^2(\mu_0)}^2 \le \mathcal{F}(\mu_1) - \mathcal{F}(\mu_0) - \langle \nabla_{W_2} \mathcal{F}(\mu_0), T_{\mu_0}^{\mu_1} - Id \rangle_{L^2(\mu_0)}
= d_{\tilde{\mathcal{F}}_{\mu_0}}(T_{\mu_0}^{\mu_1}, Id)$$

with $\tilde{\mathcal{F}}_{\mu}(\mathrm{T}) = \mathcal{F}(\mathrm{T}_{\#}\mu)$.

Definition

Let $\mathcal{F}, \mathcal{G}: \mathcal{P}_2(\mathbb{R}^d) \to \mathbb{R}$, $\mu \in \mathcal{P}_2(\mathbb{R}^d)$, $T, S \in L^2(\mu)$, $\mu_t = (T_t)_{\#}\mu$ with $T_t = (1-t)S + tT$ for all $t \in [0,1]$.

• \mathcal{F} β -smooth relative to \mathcal{G} along $t \mapsto \mu_t$ if $\forall s, t \in [0, 1]$, $d_{\tilde{\mathcal{F}}_{\mu}}(T_s, T_t) \leq \beta d_{\tilde{\mathcal{G}}_{\mu}}(T_s, T_t)$.

• \mathcal{F} α -convex relative to \mathcal{G} along $t \mapsto \mu_t$ if $\forall s, t \in [0, 1]$, $d_{\tilde{\mathcal{F}}_{\mu}}(T_s, T_t) \ge \alpha d_{\tilde{\mathcal{G}}_{\mu}}(T_s, T_t)$.

Mirror Descent on the Wasserstein Space

Let $\phi_{\mu}: L^2(\mu) \to \mathbb{R}$ be strictly convex, proper and differentiable.

Mirror Descent scheme:

$$\begin{cases} T_{k+1} = \operatorname{argmin}_{T \in L^2(\mu_k)} \ d_{\phi_{\mu_k}}(T, Id) + \tau \langle \nabla_{W_2} \mathcal{F}(\mu_k), T - Id \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (T_{k+1})_{\#} \mu_k. \end{cases}$$

By FOC: $\nabla \phi_{\mu_k}(\mathbf{T}_{k+1}) = \nabla \phi_{\mu_k}(\mathrm{Id}) - \tau \nabla_{\mathbf{W}_2} \mathcal{F}(\mu_k)$

Computing the scheme:

- For $\phi_{\mu}(T) = \int V \circ T \, d\mu$, $T_{k+1} = \nabla V^* \circ (\nabla V \tau \nabla_{W_2} \mathcal{F}(\mu_k))$
- For ϕ_{μ} pushforward compatible:

$$\nabla_{\mathbf{W}_2} \phi(\mu_{k+1}) \circ \mathbf{T}_{k+1} = \nabla_{\mathbf{W}_2} \phi(\mu_k) - \tau \nabla_{\mathbf{W}_2} \mathcal{F}(\mu_k)$$

In general: implicit in $T_{k+1} \rightarrow N$ ewton method

• Other particular cases with closed-forms, e.g. $\phi_{\mu}(T) = \frac{1}{2} \|P_{\mu}T\|_{L^{2}(\mu)}^{2}$ recovers SVGD (Liu and Wang, 2016) or EKS (Garbuno-Inigo et al., 2020).

Descent Lemma

Let $\phi_{\mu}: L^2(\mu) \to \mathbb{R}$ be strictly convex, proper and differentiable.

Mirror Descent scheme:

$$\begin{cases} \mathbf{T}_{k+1} = \operatorname{argmin}_{\mathbf{T} \in L^2(\mu_k)} \ d_{\phi_{\mu_k}}(\mathbf{T}, \operatorname{Id}) + \tau \langle \nabla_{\mathbf{W}_2} \mathcal{F}(\mu_k), \mathbf{T} - \operatorname{Id} \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (\mathbf{T}_{k+1})_{\#} \mu_k. \end{cases}$$

Proposition (Descent Lemma)

Assumptions:

• For all $k \ge 0$, \mathcal{F} is β -smooth relative to ϕ along $t \mapsto \left((1-t)\operatorname{Id} + t\operatorname{T}_{k+1}\right)_{\#}\mu_k$ Then, for all k > 0.

$$\mathcal{F}(\mu_{k+1}) \le \mathcal{F}(\mu_k) - \beta d_{\phi_{\mu_k}}(\mathrm{Id}, \mathrm{T}_{k+1}).$$

Remark: β -smoothness implies $\beta d_{\phi_{\mu_k}}(T_{k+1}, Id) \ge d_{\tilde{\mathcal{F}}_{\mu_k}}(T_{k+1}, Id)$

Sketch of the proof:

- 1. Apply β -smoothness
- 2. Apply 3-point inequality

Convergence

Proposition

Assumptions: Let $\beta > 0, \alpha \geq 0$ and $T_{\phi_{\mu_k}}^{\mu_k, \mu^*} = \operatorname{argmin}_{T_{\#}\mu_k = \mu^*} d_{\phi_{\mu_k}}(T, \operatorname{Id}).$

- \mathcal{F} eta-smooth relative to ϕ along $t\mapsto ig((1-t)\mathrm{Id}+t\mathrm{T}_{k+1}ig)_{\mu}\mu_k$
- \mathcal{F} α -convex relative to ϕ along $t \mapsto \left((1-t) \mathrm{Id} + t \mathrm{T}_{\phi_{uv}}^{\mu_k, \mu^*} \right)_{\#} \mu_k$
- Assume $d_{\phi_{\mu_k}}(T_{\phi_{\mu_k}}^{\mu_k,\mu^*},T_{k+1}) \geq d_{\phi_{\mu_{k+1}}}(T_{\phi_{\mu_{k+1}}}^{\mu_{k+1},\mu^*},\mathrm{Id})$

Then, for all $k \geq 1$, $\mathcal{F}(\mu_k) - \mathcal{F}(\mu^*) \leq \frac{\beta - \alpha}{k} d_{\phi_{\mu_0}}(T_{\phi_{\mu_0}}^{\mu_0, \mu^*}, \mathrm{Id})$. If $\alpha > 0$, for all $k \geq 0$, $d_{\phi_{\mu_k}}(T_{\phi_{\mu_k}}^{\mu_k, \mu^*}, \mathrm{Id}) \leq \left(1 - \frac{\alpha}{\beta}\right)^k d_{\phi_{\mu_0}}(T_{\phi_{\mu_0}}^{\mu_0, \mu^*}, \mathrm{Id})$.

Let
$$\phi_\mu$$
 be pushforward compatible. Define the OT problem:

$$W_{\phi}(\nu,\mu) = \inf_{\gamma \in \Pi(\nu,\mu)} \phi(\nu) - \phi(\mu) - \int \langle \nabla_{W_2} \phi(\mu)(y), x - y \rangle \, d\gamma(x,y)$$

$$\gamma \in \Pi(\nu,\mu)$$
 J
 $\leq d_{\phi_n}(T,S)$ for $(T,S)_{\#}\eta \in \Pi(\nu,\mu)$

Property: If $\mu \ll \text{Leb}$ and $\nabla_{W_2}\phi(\mu)$ is invertible, then $\gamma^* = (T^{\mu,\nu}_{\phi_\mu}, \text{Id})_\#\mu$, and $W_{\phi}(\nu,\mu) = d_{\phi_\mu}(T^{\mu,\nu}_{\phi_\mu}, \text{Id})$.

Continuous Formulation

Informally, for ϕ_{μ} pushforward compatible:

$$\begin{cases} \varphi(\mu_k) = \nabla_{W_2} \phi(\mu_k) \\ \varphi(\mu_{k+1}) \circ T_{k+1} = \varphi(\mu_k) - \tau \nabla_{W_2} \mathcal{F}(\mu_k) \end{cases} \xrightarrow{\tau \to 0} \begin{cases} \varphi(\mu_t) = \nabla_{W_2} \phi(\mu_t) \\ \frac{d}{dt} \varphi(\mu_t) = -\nabla_{W_2} \mathcal{F}(\mu_t). \end{cases}$$

Continuous Formulation

Informally, for ϕ_{μ} pushforward compatible:

$$\begin{cases} \varphi(\mu_k) = \nabla_{W_2} \phi(\mu_k) \\ \varphi(\mu_{k+1}) \circ T_{k+1} = \varphi(\mu_k) - \tau \nabla_{W_2} \mathcal{F}(\mu_k) \end{cases} \xrightarrow{\tau \to 0} \begin{cases} \varphi(\mu_t) = \nabla_{W_2} \phi(\mu_t) \\ \frac{d}{dt} \varphi(\mu_t) = -\nabla_{W_2} \mathcal{F}(\mu_t). \end{cases}$$

$$\frac{d}{dt} \varphi(\mu_t) = \frac{d}{dt} \nabla_{W_2} \phi(\mu_t) = H \phi_{\mu_t}(v_t),$$

with $H\phi_{\mu_t}: L^2(\mu_t) \to L^2(\mu_t)$ Hessian operator defined such that

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2}\phi(\mu_t) = \langle \mathrm{H}\phi_{\mu_t}(v_t), v_t \rangle_{L^2(\mu_t)} \quad \text{with} \quad \partial_t \mu_t + \mathrm{div}(\mu_t v_t) = 0.$$

Mirror flow:

$$\partial_t \mu_t - \operatorname{div} \left(\mu_t (H \phi_{\mu_t})^{-1} \nabla_{W_2} \mathcal{F}(\mu_t) \right) = 0.$$

Related works:

- For $\phi(\mu) = \int V d\mu$, $\mathcal{F}(\mu) = \mathrm{KL}(\mu||\mu^*)$, coincides with continuous formulation of Mirror Langevin (Ahn and Chewi, 2021)
- For $\phi = \mathcal{F}$, coincides with Information Newton's flows (Wang and Li, 2020)
- For $\phi(\mu) = \frac{1}{2}W_2^2(\mu,\nu)$, $\mathcal{F}(\mu) = KL(\mu||\mu^*)$, coincides with Sinkhorn flows (Deb et al., 2023)

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Preconditioned GD

Let $h: \mathbb{R}^d \to \mathbb{R}$ strictly convex, proper and differentiable.

Preconditioned Gradient Descent scheme: Let $\phi_{\mu}^{h}(T) = \int h \circ T \ d\mu$,

$$\begin{cases} \mathbf{T}_{k+1} = \operatorname{argmin}_{\mathbf{T} \in L^2(\mu_k)} \ \phi_{\mu_k}^h \left(\frac{\mathbf{Id} - \mathbf{T}}{\tau} \right) \tau + \langle \nabla_{\mathbf{W}_2} \mathcal{F}(\mu_k), \mathbf{T} - \mathbf{Id} \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (\mathbf{T}_{k+1})_{\#} \mu_k \end{cases}$$

By FOC:
$$T_{k+1} = Id - \tau \nabla h^* \circ \nabla_{W_2} \mathcal{F}(\mu_k)$$

Preconditioned GD

Let $h: \mathbb{R}^d \to \mathbb{R}$ strictly convex, proper and differentiable.

Preconditioned Gradient Descent scheme: Let $\phi_{\mu}^{h}(T) = \int h \circ T d\mu$,

$$\begin{cases} \mathbf{T}_{k+1} = \operatorname{argmin}_{\mathbf{T} \in L^2(\mu_k)} \ \phi_{\mu_k}^h \left(\frac{\mathbf{Id} - \mathbf{T}}{\tau} \right) \tau + \langle \nabla_{\mathbf{W}_2} \mathcal{F}(\mu_k), \mathbf{T} - \mathbf{Id} \rangle_{L^2(\mu_k)} \\ \mu_{k+1} = (\mathbf{T}_{k+1})_{\#} \mu_k \end{cases}$$

By FOC: $T_{k+1} = Id - \tau \nabla h^* \circ \nabla_{W_2} \mathcal{F}(\mu_k)$

Proposition (Descent Lemma)

Assumptions: For all $k \geq 0$,

• \mathcal{F} convex along $t \mapsto ((1-t)\mathrm{T}_{k+1} + t\mathrm{Id})_{\#}\mu_k$

 $\#^{\mu k}$

ullet ϕ^{h^*} eta-smooth relative to \mathcal{F}^* along a suitable curve

Then, for all
$$k \geq 0$$
,

$$\phi_{\mu_{k+1}}^{h^*} \left(\nabla_{\mathbf{W}_2} \mathcal{F}(\mu_{k+1}) \right) \le \phi_{\mu_k}^{h^*} \left(\nabla_{\mathbf{W}_2} \mathcal{F}(\mu_k) \right) - \beta \mathbf{d}_{\tilde{\mathcal{F}}_{u_k}} \left(\mathbf{T}_{k+1}, \mathrm{Id} \right).$$

Preconditioned GD

Let $h: \mathbb{R}^d \to \mathbb{R}$ strictly convex, proper and differentiable.

Preconditioned Gradient Descent scheme: Let $\phi_u^h(T) = \int h \circ T \ d\mu$,

$$\begin{cases} T_{k+1} = \operatorname{argmin}_{T \in L^{2}(\mu_{k})} \phi_{\mu_{k}}^{h} \left(\frac{\operatorname{Id} - T}{\tau} \right) \tau + \langle \nabla_{W_{2}} \mathcal{F}(\mu_{k}), T - \operatorname{Id} \rangle_{L^{2}(\mu_{k})} \\ \mu_{k+1} = (T_{k+1})_{\#} \mu_{k} \end{cases}$$

By FOC: $T_{k+1} = Id - \tau \nabla h^* \circ \nabla_{W_2} \mathcal{F}(\mu_k)$

Proposition

Assumptions: For all $k \geq 0$, denoting $\bar{T} = \operatorname{argmin}_{T,T_{\#}\mu_k = \mu^*} d_{\tilde{\mathcal{F}}_{\mu_k}}(Id,T)$,

- \mathcal{F} convex along $t \mapsto ((1-t)\mathrm{T}_{k+1} + t\mathrm{Id})_{\#}\mu_k$
- ϕ^{h^*} β -smooth relative to \mathcal{F}^* along a suitable curve
- ϕ^{h^*} α -convex relative to \mathcal{F}^* along a suitable curve

Then, for all $k \geq 1$, $\phi_{\mu_k}^{h^*} \left(\nabla_{W_2} \mathcal{F}(\mu_k) \right) - h^*(0) \leq \frac{\beta - \alpha}{k} \left(\mathcal{F}(\mu_0) - \mathcal{F}(\mu^*) \right)$. Moreover, assuming that h^* attains its minimum at 0 and $\alpha > 0$, for all $k \geq 0$,

 $\mathcal{F}(\mu_k) - \mathcal{F}(\mu^*) \leq (1 - \tau \alpha)^k \left(\mathcal{F}(\mu_0) - \mathcal{F}(\mu^*) \right).$

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Showing Relative Smoothness and Convexity

Relative smoothness of $\mathcal{F}:\mathcal{P}_2(\mathbb{R}^d)\to\mathbb{R}$ relative to $\phi:\mathcal{P}_2(\mathbb{R}^d)\to\mathbb{R}$?

• Let $\mathcal{F}(\mu) = \int V d\mu$ and $\phi(\mu) = \int U d\mu$:

$$V$$
 β -smooth relative to $U \Longrightarrow \mathcal{F}$ β -smooth relative to ϕ V α -convex relative to $U \Longrightarrow \mathcal{F}$ α -convex relative to ϕ

• Let $\mathcal{F}(\mu) = \iint W(x-y) d\mu(x) d\mu(y)$ and $\phi(\mu) = \iint K(x-y) d\mu(x) d\mu(y)$:

$$W$$
 β -smooth relative to $K \Longrightarrow \mathcal{F}$ β -smooth relative to ϕ W α -convex relative to $K \Longrightarrow \mathcal{F}$ α -convex relative to ϕ

- For $\mathcal{F}=\mathcal{G}+\mathcal{H}$, $\mathrm{d}_{\tilde{\mathcal{F}}_{u}}=\mathrm{d}_{\tilde{\mathcal{G}}_{u}}+\mathrm{d}_{\tilde{\mathcal{H}}_{u}}$ and \mathcal{F} 1-convex relative to \mathcal{G} and \mathcal{H}
- In general: look at the Hessian

Mirror Descent on Interaction Energy

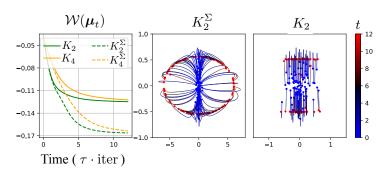
Goal: Let $\Sigma \in S_d^{++}(\mathbb{R})$ possibly ill-conditioned,

$$\min_{\mu} \ \mathcal{W}(\mu) = \iint W(x-y) \ \mathrm{d}\mu(x) \mathrm{d}\mu(y) \quad \text{with} \quad W(z) = \frac{1}{4} \|z\|_{\Sigma^{-1}}^4 - \frac{1}{2} \|z\|_{\Sigma^{-1}}^2$$

Bregman potential: $\phi_{\mu}(T) = \iint K(T(x) - T(y)) d\mu(x) d\mu(y)$ with

$$K_2(z) = \frac{1}{2} \|z\|_2^2, \quad K_2^{\Sigma}(z) = \frac{1}{2} \|z\|_{\Sigma^{-1}}^2,$$

$$K_4(z) = \frac{1}{4} \|z\|_2^4 + \frac{1}{2} \|z\|_2^2, \quad K_4^{\Sigma}(z) = \frac{1}{4} \|z\|_{\Sigma^{-1}}^4 + \frac{1}{2} \|z\|_{\Sigma^{-1}}^2.$$



Mirror Descent on Gaussian

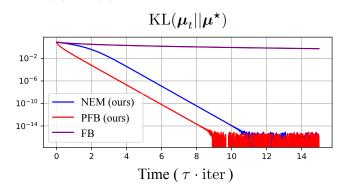
Goal:

$$\min_{\mu} \mathcal{F}(\mu) = \int V d\mu + \mathcal{H}(\mu) \quad \text{with} \quad V(x) = \frac{1}{2} x^T \Sigma^{-1} x$$

 $\rightarrow \text{ minimum } \mu^{\star} = \mathcal{N}(0, \Sigma).$

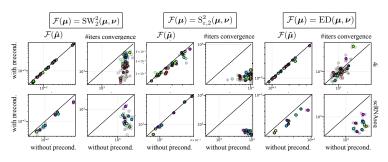
Comparison between:

- Forward-Backward (FB) on the Bures-Wasserstein space (Diao et al., 2023)
- Preconditioned Forward-Backward (PFB) scheme with $\phi(\mu) = \int V d\mu$
- NEM: MD with $\phi(\mu) = \mathcal{H}(\mu)$ and restriction to Gaussian



Preconditioned GD on Single-Cells

 $\begin{array}{l} \textbf{Goal}\colon \min_{\mu} \ \mathcal{F}(\mu) = D(\mu,\nu) \ \text{with} \ \mu_0 \ \text{untreated cell and} \ \nu \ \text{perturbed cell} \\ \text{Use PGD with} \ h^*(x) = (\|x\|_2^a + 1)^{1/a} - 1 \ \text{with} \ a \in \{1.25, 1.5, 1.75\}, \ \text{which is well} \\ \text{suited to minimize functions growing in} \ \|x - x^*\|^{a/(a-1)} \ \text{near} \ x^*. \\ \end{array}$



- Rows: 2 profiling technologies
- ullet Columns/subcolumns: Different objectives $\mathcal{F}/\text{measure}$ of convergence and number of iterations to converge
- Points: For treatment $i, z_i = (x_i, y_i)$ with x_i value of $\mathcal{F}(\hat{\mu}) = D(\hat{\mu}, \nu)$ (1st subcolumn) or number of iterations (2nd subcolumn) without preconditioning and y_i with preconditioning
- Colors: treatments
 - \rightarrow Points below the diagonal: PGD provides a better minimum or converges faster

Conclusion

Conclusion:

- Mirror Descent on $\mathcal{P}_2(\mathbb{R}^d)$
- Preconditioned Gradient Descent on $\mathcal{P}_2(\mathbb{R}^d)$
- Convergence analysis of the discrete schemes
- Also in the paper: analysis of the Bregman Forward-Backward scheme

Perspectives:

- Better understand sufficient conditions of convergence for PGD
- Find more examples satisfying the conditions
- Analyze the Gaussian MD scheme

Conclusion

Conclusion:

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Perspectives:

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- Analyze the Gaussian MD scheme

Thank you for your attention!

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