6.2. Analytical Ray Tracing - Matrix Method

11. Ray Vector
$$\vec{r}_i = \begin{pmatrix} N_i \alpha_i \\ Y_i \end{pmatrix}$$

12.1 Free Space

 $\alpha_2 = \alpha_1 \Leftrightarrow n\alpha_2 = n\alpha_1$

$$y_2 = y_1 + d \tan \alpha_1 = y_1 + d \alpha_1 = y_1 + \frac{d}{n} n \alpha_1 = \frac{d}{n} n \alpha_1 + y_1$$

$$\Rightarrow \begin{bmatrix} n\alpha_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 10 \end{bmatrix} \begin{bmatrix} n\alpha_1 \\ y_1 \end{bmatrix} \Leftrightarrow \vec{r}_2 = \vec{T}_2, \vec{r}_1$$

Transfer Matrix
$$T_{21} = \begin{bmatrix} 1 & 0 \\ \frac{d}{n} & 1 \end{bmatrix}$$

$$M_1 S m \alpha_1 = M_2 S m \alpha_2$$

$$h_1 \propto_1 = n_2 \propto_2$$

$$n_2\alpha_2 = n_1\alpha_1$$

$$\Rightarrow \vec{r}_2 = \vec{r}_1 = \vec{r}_1$$

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$T = \begin{bmatrix} 1 & 0 \\ \frac{d_1}{n_1} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{d_1}{n_1} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ \frac{d_1}{n_1} + \frac{d_2}{n_2} \end{bmatrix}$$

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$$\frac{N_i}{Q_i} = \frac{N_t}{Q_i} = \frac{N_t}{Q_t}$$

$$\frac{N_i}{Q_i} = \frac{N_t}{Q_t} = \frac{N_t}{Q_t}$$

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$$N_i \theta_i = N_t \theta_t$$

 $N_i (\alpha_i + \beta) = N_t (\alpha_t + \beta)$

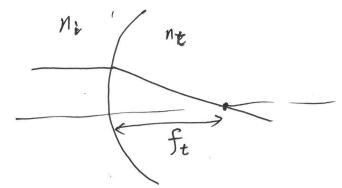
$$\beta = \frac{y_1}{R}$$

$$\Rightarrow n_i \alpha_i + \frac{n_i}{R} y_i = n_t \alpha_t + \frac{n_t}{R} y_i$$

$$\Rightarrow \begin{pmatrix} \dot{N}_{t} & \dot{\chi}_{t} \\ \dot{\gamma}_{2} \end{pmatrix} = \begin{pmatrix} 1 & -\left(\frac{M_{t} - N_{i}}{R}\right) \end{pmatrix} \begin{pmatrix} \dot{N}_{i} & \dot{\chi}_{i} \\ \dot{\gamma}_{1} \end{pmatrix}$$

Refraction Matrix
$$R = \begin{bmatrix} 1 & -\left(\frac{Mt-Mi}{R}\right) \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -D \\ 0 & 1 \end{bmatrix}$$

Pover of Refration surface
$$D = \frac{M_t - M_i}{R}$$



$$H = TR = \begin{bmatrix} 1 & 0 \\ \frac{d}{n_t} & 1 \end{bmatrix} \begin{bmatrix} 1 & -D \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -D \\ \frac{d}{n_t} & 1 - \frac{Dd}{n_t} \end{bmatrix}$$

Let
$$y_i = y_i$$

 $\alpha_i = 0$

$$\begin{bmatrix}
N_t \alpha_2 \\
Y_2
\end{bmatrix} = \begin{bmatrix}
1 & -D \\
\frac{d}{N_t} & 1 - \frac{Dd}{N_t}
\end{bmatrix}
\begin{bmatrix}
0 \\
Y_I
\end{bmatrix} = \begin{bmatrix}
-D \\
(1 - \frac{Dd}{N_t})Y_I
\end{bmatrix} = \begin{bmatrix}
-D \\
1 - \frac{Dd}{N_t}
\end{bmatrix} Y_I$$

for
$$y_2 = 0$$
 at the foral point:
 $1 - D \stackrel{\text{dol}}{=} 0 \Rightarrow 0 = 0 = 0 = 0 = 0$

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$$1 - D \stackrel{\text{dol}}{=} 0 \Rightarrow 0 \Rightarrow 0 = 0 = 0 = 0 = 0$$

Pewrite
$$R = \begin{bmatrix} 1 & -D \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -\frac{1}{1} & \frac{1}{1} \\ 0 & 1 \end{bmatrix}$$

6.2. Apolytical Ray Tracing - ABCD Matrix Method. 111 Ray Vector $\vec{Y}_i = \begin{cases} N_i d_i \\ Y_i \end{cases}$ Yi Zai 121 Free Space d> = d1 $Y_2 = Y_1 + d \tan \alpha_1$ = y + $d\alpha_1$ X 2 sin x atan X \Rightarrow $ny_2 = ny_1 + nd\alpha_1$ $\Rightarrow \begin{bmatrix} n\alpha_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} n\alpha_1 \\ y_1 \end{bmatrix} \iff \vec{r}_2 = \vec{r}_2$ 17/68 Thin Lens $I = R, R_1$ $= \begin{vmatrix} 1 & -D_2 \\ 0 & 1 \end{vmatrix} \begin{vmatrix} 1 & -D_1 \\ 0 & 1 \end{vmatrix}$ $=\begin{bmatrix} 1 & -(D_1+D_2) \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1/f \\ 0 & 1 \end{bmatrix}$ Let $\alpha_1 = 0$, in $\alpha_1 r$. $\begin{bmatrix} \alpha_2 \\ \gamma_2 \end{bmatrix} = T(d) L \begin{bmatrix} 0 \\ \gamma_1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ d & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ \gamma_1 \end{bmatrix} = \begin{bmatrix} 1 & -1/f \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ \gamma_1 \end{bmatrix} = \begin{bmatrix} 1 & -1/f \\ 0 & 1 - \frac{d}{f} \end{bmatrix} \begin{bmatrix} 0 \\ \gamma_1 \end{bmatrix} = \begin{bmatrix} 1 & -\frac{d}{f} \\ 1 & -\frac{d}{f} \end{bmatrix} \begin{bmatrix} 0 \\ 1 & -\frac{d}{$

$$R_{2}$$
 R_{2}
 R_{2}

$$L = R_2 T(\frac{d}{n}) R_1$$

$$= \begin{bmatrix} 1 & -D_2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{d}{n} & 1 \end{bmatrix} \begin{bmatrix} 1 & -D_1 \\ 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 - \frac{D_2 d}{n} & -D_2 \\ \frac{d}{n} & 1 \end{bmatrix} \begin{bmatrix} 1 & -D_1 \\ 0 & 1 \end{bmatrix}$$

$$=\begin{bmatrix} 1-\frac{D_2d}{n} & -D_1-D_2-\frac{D_1D_2d}{n} \\ \frac{d}{n} & \frac{-D_1d}{n}+1 \end{bmatrix}$$