

Lecture Notes:

THE NEWTON-RAPHSON METHOD

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Quadratic Model

Example 0.1:

Problem Statement:

We aim to model the distance a baseball travels as a function of the hitting angle using a quadratic equation.

Model Specification:

Let

- Y_i denote the random variable for distance traveled by the baseball (in feet) for which the observed value is y_i .
- X_i denote the random variable of the hitting angle (in degrees) for which the observed value is x_i

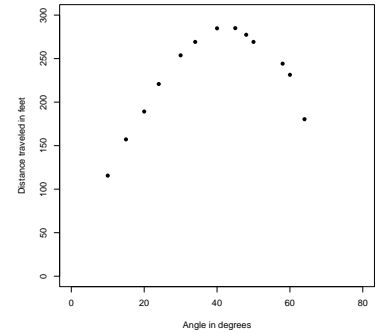
We consider that the relationship between the distance travelled and the hitting angle is modeled as the quadratic equation: $Y_i = \alpha + \beta X_i + \gamma X_i^2 + \epsilon_i$,

where

- α, β, γ are the parameters to be estimated, and
- ϵ_i is the error term, assumed to be normally distributed with mean 0 and variance σ^2 , i.e., $\epsilon_i \sim N(0, \sigma^2)$.

Objective:

Given a dataset $\{(y_i, x_i)\}_{i=1}^n$, our goal is to estimate the parameters α, β, γ , and σ^2 .



Because of $Y_i \sim N(\alpha + \beta X_i + \gamma X_i^2, \sigma^2)$, the probability density function of $Y_i = y_i$ is:

$$P(Y_i = y_i | x_i, \alpha, \beta, \gamma, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2\sigma^2} (y_i - \alpha - \beta x_i - \gamma x_i^2)^2}.$$

Having the observed data, the likelihood function of $(\alpha, \beta, \gamma, \sigma^2)$ can be written as:

$$\begin{aligned}
L(\alpha, \beta, \gamma, \sigma^2 | \{(y_i, x_i)\}_{i=1}^n) &= \prod_{i=1}^n P(Y_i = y_i | x_i, \alpha, \beta, \gamma, \sigma^2) \\
&= \left(\frac{1}{\sigma\sqrt{2\pi}} \right)^n e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2)^2} \\
&= (2\pi)^{-\frac{n}{2}} (\sigma^2)^{-\frac{n}{2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2)^2}.
\end{aligned}$$

Taking the log on both sides of the equation yields the following log-likelihood function:

$$l(\alpha, \beta, \gamma, \sigma^2) = \ln L(\alpha, \beta, \gamma, \sigma^2) = -\frac{n}{2} \ln(2\pi) - \frac{n}{2} \ln(\sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2)^2. \quad (1)$$

We want to approximate the value of $(\alpha, \beta, \gamma, \sigma^2)$ by maximizing the likelihood function (Eq. 1).

Newton-Raphson Algorithm:

1. **Gradient Vector:** The vector of first derivatives with respect to the parameters of $l(\alpha, \beta, \gamma, \sigma^2)$ is:

$$\nabla l(\Theta) = \begin{pmatrix} \frac{\partial l}{\partial \alpha} \\ \frac{\partial l}{\partial \beta} \\ \frac{\partial l}{\partial \gamma} \\ \frac{\partial l}{\partial \sigma^2} \end{pmatrix}, \quad \text{where } \Theta = \begin{pmatrix} \alpha \\ \beta \\ \gamma \\ \sigma^2 \end{pmatrix},$$

and

$$\begin{aligned}
\frac{\partial l}{\partial \alpha} &= -\frac{1}{2\sigma^2} \sum_{i=1}^n 2(y_i - \alpha - \beta x_i - \gamma x_i^2)(-1) \\
&= \frac{1}{\sigma^2} \sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2); \\
\frac{\partial l}{\partial \beta} &= -\frac{1}{2\sigma^2} \sum_{i=1}^n 2(y_i - \alpha - \beta x_i - \gamma x_i^2)(-x_i) \\
&= \frac{1}{\sigma^2} \sum_{i=1}^n (x_i)(y_i - \alpha - \beta x_i - \gamma x_i^2) \\
&= \frac{1}{\sigma^2} \left(\sum_{i=1}^n x_i y_i - \alpha \sum_{i=1}^n x_i - \beta \sum_{i=1}^n x_i^2 - \gamma \sum_{i=1}^n x_i^3 \right); \\
\frac{\partial l}{\partial \gamma} &= -\frac{1}{2\sigma^2} \sum_{i=1}^n 2(y_i - \alpha - \beta - \gamma x_i^2)(-x_i^2) \\
&= \frac{1}{\sigma^2} \sum_{i=1}^n (x_i^2)(y_i - \alpha - \beta - \gamma x_i^2) \\
&= \frac{1}{\sigma^2} \left(\sum_{i=1}^n x_i^2 y_i - \alpha \sum_{i=1}^n x_i^2 - \beta \sum_{i=1}^n x_i^3 - \gamma \sum_{i=1}^n x_i^4 \right); \\
\frac{\partial l}{\partial \sigma^2} &= -\frac{n}{2\sigma^2} - \frac{(-1)(\sigma^2)^{-2}}{2} \sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2)^2 \\
&= -\frac{n}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2)^2
\end{aligned}$$

2. **The Hessian matrix:** The matrix of second derivatives with respect to the parameters of the log-likelihood function is:

$$\nabla^2 l(\boldsymbol{\Theta}) = \begin{bmatrix} \frac{\partial^2 l}{\partial \alpha^2} & \frac{\partial^2 l}{\partial \alpha \partial \beta} & \frac{\partial^2 l}{\partial \alpha \partial \gamma} & \frac{\partial^2 l}{\partial \alpha \partial \sigma^2} \\ \frac{\partial^2 l}{\partial \beta \partial \alpha} & \frac{\partial^2 l}{\partial \beta^2} & \frac{\partial^2 l}{\partial \beta \partial \gamma} & \frac{\partial^2 l}{\partial \beta \partial \sigma^2} \\ \frac{\partial^2 l}{\partial \gamma \partial \alpha} & \frac{\partial^2 l}{\partial \gamma \partial \beta} & \frac{\partial^2 l}{\partial \gamma^2} & \frac{\partial^2 l}{\partial \gamma \partial \sigma^2} \\ \frac{\partial^2 l}{\partial \sigma^2 \partial \alpha} & \frac{\partial^2 l}{\partial \sigma^2 \partial \beta} & \frac{\partial^2 l}{\partial \sigma^2 \partial \gamma} & \frac{\partial^2 l}{(\partial \sigma^2)^2} \end{bmatrix}$$

3. Calculation of the second-order partial derivatives yields:

$$\begin{aligned}
&\nabla^2 l(\boldsymbol{\Theta}) \\
&= \begin{bmatrix} -\frac{n}{\sigma^2} & -\frac{\sum x_i}{\sigma^2} & -\frac{\sum x_i^2}{\sigma^2} & -\frac{(\sum y_i - n\alpha - \beta \sum x_i - \gamma \sum x_i^2)}{\sigma^4} \\ -\frac{\sum x_i}{\sigma^2} & -\frac{\sum x_i^2}{\sigma^2} & -\frac{\sum x_i^3}{\sigma^2} & -\frac{(\sum x_i y_i - \alpha \sum x_i - \beta \sum x_i^2 - \gamma \sum x_i^3)}{\sigma^4} \\ -\frac{\sum x_i^2}{\sigma^2} & -\frac{\sum x_i^3}{\sigma^2} & -\frac{\sum x_i^4}{\sigma^2} & -\frac{(\sum x_i^2 y_i - \alpha \sum x_i^2 - \beta \sum x_i^3 - \gamma \sum x_i^4)}{\sigma^4} \\ -\frac{(\sum y_i - n\alpha - \beta \sum x_i - \gamma \sum x_i^2)}{\sigma^4} & -\frac{(\sum x_i y_i - \alpha \sum x_i - \beta \sum x_i^2 - \gamma \sum x_i^3)}{\sigma^4} & -\frac{(\sum x_i^2 y_i - \alpha \sum x_i^2 - \beta \sum x_i^3 - \gamma \sum x_i^4)}{\sigma^4} & -\frac{\frac{\partial^2 l}{(\partial \sigma^2)^2}}{\sigma^4} \end{bmatrix}
\end{aligned}$$

where, the last diagonal element is

$$\begin{aligned}\frac{\partial^2 l}{(\partial \sigma^2)^2} &= -\frac{n}{2}(-1)(\sigma^2)^{-2} + \frac{1}{2}(-2)(\sigma^3)^{-3} \sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2)^2 \\ &= \frac{n}{2\sigma^4} - \frac{\sum_{i=1}^n (y_i - \alpha - \beta x_i - \gamma x_i^2)^2}{\sigma^6}.\end{aligned}$$

4. Finally, the iteration formula for Θ is:

$$\Theta^{\text{new}} = \Theta^{\text{old}} - \left(\nabla^2 l(\Theta^{\text{old}}) \right)^{-1} \left(\nabla l(\Theta^{\text{old}}) \right)$$

Application:

1. **Drug discovery:** Finding chemical compounds that are active against a disease from a large chemical library.
2. **Protein homology:** Detecting homologous proteins which is useful to find homologous sequence of proteins.
3. **Predicting housing market:** Is government induced policies impact housing prices?
4. **Genetics:** Detecting genes which are responsible for disease/phenotype in human and plant genetics.
5. **Ecology:** Do human induced disturbances have threshold effects on the natural environment for animals, fish, birds and plants?
6. **Public health:** Determining factors that effect public health in countries across the world.