

Assigned Nov 2nd, 2025

Due: Nov 8, 2025

1. Modern Robotics: Exercise 4.6
2. Modern Robotics: Exercise 4.9
3. Modern Robotics: Exercise 5.8 - (a)

Note: in modern robotics, body screw axis \mathcal{B}_i means the screw axis of joint i expressed in frame b, i.e. ${}^b\mathcal{S}_i$ in our notation.