

1. matrix decomposition

singular value decomposition:

$$A = U\Sigma V^T$$

$$Ax = U\Sigma V^T x$$

2. eigenvalue decomposition

For $A = A^T$:Let S^n be the set of real symmetric matrices of size n . $Av = \lambda v \implies \lambda$ is an eigenvalue of A , v is an eigenvector of A $A = Q\Sigma Q^T$, Q is a matrix with columns of eigenvectors

3. real symmetric matrices have real eigenvalues:

proof:

$$\begin{aligned} Av &= \lambda v \\ v^* Av &= v^* \lambda v = \lambda \|v\|_2^2 \\ (v^* Av)^* &= v^* A^* v = \lambda^* \|v\|_2^2 \\ &\implies \lambda = \lambda^* \end{aligned}$$

4. positive (semi)-definite: $A \geq 0$ A real symmetric, $(\forall v) v^T Av \geq 0 \implies A$ PSD A real symmetric, $(\forall v) v^T Av > 0 \implies A$ PD5. $A \in S_+^n$ iff all eigenvalues are non-negative

proof:

$$\begin{aligned} v^T Av &= v^T Q\Sigma Q^T v \\ v^T Av &= \tilde{v}^T \Sigma \tilde{v} = \sum \lambda_i \|v_i\|^2 \\ (\forall i) \lambda_i \geq 0 &\implies (\forall v) v^T Av \geq 0 \end{aligned}$$

6. for PSD matrices, we can take square root

$$A^{\frac{1}{2}} = Q\Sigma^{\frac{1}{2}}Q^T, A^{\frac{1}{2}}A^{\frac{1}{2}} = A = Q\Sigma Q^T$$

7. functions of matrices $f : S_{++}^n \rightarrow \mathbb{R}$
 how to compute gradient
 $f(x) = \log(\det X)$

$$\begin{aligned}
 f(X + \delta X) &= \log \det(X + \delta X) \\
 &= \log \det((X^{\frac{1}{2}}(I + X^{-\frac{1}{2}})\delta X X^{-\frac{1}{2}})X^{\frac{1}{2}}) \\
 &= \log \det(X) + \log \det(I + X^{-\frac{1}{2}}\delta X X^{-\frac{1}{2}}) \\
 \text{let } M &= X^{-\frac{1}{2}}\delta X X^{-\frac{1}{2}} \\
 &= \log \det(X) + \log \det(I + M)
 \end{aligned}$$

claim eigenvalues of $I + M$: $1 + \lambda_i$

$$\begin{aligned}
 Mv_i &= \lambda_i v_i \\
 (I + M)v_i &= (1 + \lambda_i)v_i \\
 \det(M) &= \prod_i (1 + \lambda_i) \\
 f(X + \delta X) &= \log \det(X) + \log \prod_i (1 + \lambda_i) \\
 &= \log \det(X) + \sum_i \log(1 + \lambda_i) \\
 &\approx \log \det(X) + \sum_i \lambda_i \text{ since } \delta X \text{ is small} \\
 &\approx \log \det(X) + \text{trace}(X^{-\frac{1}{2}}\delta X X^{\frac{1}{2}}) \\
 &\approx \log \det(X) + \text{trace}(X^{-1}\delta X) \text{ cyclic property of trace} \\
 \text{trace}(X^{-1}\delta X) &= \langle X^{-T}, \delta X \rangle \\
 f(X + \delta X) &= f(X) + \langle \nabla f(X), \delta X \rangle \implies \nabla f(X) = X^{-1} \\
 \log \det(X) &= \log(X) \implies f'(X) = \frac{1}{X}
 \end{aligned}$$

8. 2nd order approximation

$$f(X + \delta X) = f(X) + \langle \nabla f(X), \delta X \rangle + 1/2 \langle \delta X, \nabla^2 f(x) \delta X \rangle$$

first look at first order approximation: $g(X) = X^{-1}$

$$\begin{aligned} g(X + \delta X) &= (X + \delta X)^{-1} = (X^{\frac{1}{2}}(I + X^{-\frac{1}{2}}\delta X X^{-\frac{1}{2}})X^{\frac{1}{2}})^{-1} \\ &= X^{-\frac{1}{2}}(I + X^{-\frac{1}{2}}\delta X X^{-\frac{1}{2}})^{-1}X^{-\frac{1}{2}} \\ &\text{for small } A \text{ (small eigenvalues): } (I + A)^{-1} \approx I - A \\ &= X^{-\frac{1}{2}}(I - X^{-\frac{1}{2}}\delta X X^{-\frac{1}{2}})X^{-\frac{1}{2}} \\ &= X^{-1} - X^{-1}\delta X X^{-1} \end{aligned}$$

$$\log \det(X + \delta X) = \log \det(X) + \text{tr}(X^{-1}\delta X) - \frac{1}{2}\text{tr}(\delta X X^{-1}\delta X X^{-1})$$

analogy:

$$\begin{aligned} g(x) &= \frac{1}{x} \\ g'(x) &= \frac{-1}{x^2} = -x^{-2} \end{aligned}$$

9. convex sets

affine sets: a set $C \subseteq \mathbb{R}^n$ is affine if $(\forall x_1, x_2 \in C)(\forall \theta \in \mathbb{R}) \implies \theta x_1 + (1 - \theta)x_2 \in C$
can use this definition to check sets for convexity property

eg: set of solution to a set of linear equations is affine

affine combination: $\sum_i \theta_i x_i, \forall \theta_i \in \mathbb{R}, \sum_i \theta_i = 1$

10. convex sets

a set $C \subseteq \mathbb{R}^n$ is convex if $(\forall x_1, x_2 \in C)(\forall \theta \in \mathbb{R}) 0 \leq \theta \leq 1 \implies \theta x_1 + (1 - \theta)x_2 \in C$

convex combination: $\sum_i \theta_i x_i, \forall \theta_i \in \mathbb{R}, \sum_i \theta_i = 1, \theta_i \geq 0$

convex hull: the set of all convex combinations of points in C , the hull is convex

any affine set is convex, since convex property is a constrained version of the affine property

11. hyperplane

$$C = \{x : a^T x = b\}, a \in \mathbb{R}^n, a \neq 0, b \in \mathbb{R}$$

12. halfspaces

$$C = \{x : a^T x \leq b\}, a \in \mathbb{R}^n, a \neq 0, b \in \mathbb{R}$$

$$\text{let } a^T x_c = b$$

$$= \{x : a^T (x - x_c) \leq 0\}, a \in \mathbb{R}^n, a \neq 0$$