1. Batch Normalization Derivation:

$$\begin{split} \hat{x}_{ij} &= \frac{x_{ij} - \mu_j}{(\sigma_j^2 + \epsilon)^2} \\ \mu_j &= \frac{1}{N} \sum_i x_{ij} \\ \sigma_j^2 &= \frac{1}{N} \sum_i (x_{ij} - \mu_j)^2 \\ y_{ij} &= \gamma_j \hat{x}_{ij} + \beta_j \\ \frac{\partial y_{ij}}{\partial x_{ij}} &= \frac{\partial y_{ij}}{\partial \hat{x}_{ij}} \frac{\partial \hat{x}_{ij}}{\partial x_{ij}} + (\sum_i \frac{\partial y_{ij}}{\partial \hat{x}_{ij}} \frac{\partial \hat{x}_{ij}}{\partial \mu_j}) \frac{\partial \mu_j}{\partial x_{ij}} + (\sum_i \frac{\partial y_{ij}}{\partial \hat{x}_{ij}} \frac{\partial \hat{x}_{ij}}{\partial \sigma_j^2}) \frac{\partial \sigma_j^2}{\partial x_{ij}} \\ \frac{\partial \sigma_j^2}{\partial x_{ij}} &= \frac{2}{N} (x_{ij} - \mu_j) - (\sum_i \frac{2}{N} (x_{ij} - \mu_j)) \frac{1}{N} \\ &= \frac{2}{N} (x_{ij} - \mu_j) + \frac{2}{N^2} (\sum_i (x_{ij} - \mu_j)) \\ let \ a_j &= \frac{1}{(\sigma_j^2 + \epsilon)^{0.5}} \\ \frac{\partial y_{ij}}{\partial x_{ij}} &= \partial y_{ij} \gamma_j a_j + (\sum_i \partial y_{ij} \gamma_j (-a_j)) (\frac{1}{D}) + (\sum_i \partial y_{ij} \gamma_j (\frac{-1}{2}) \hat{x}_{ij} a_j^2) (\frac{\partial \sigma_j^2}{\partial x_{ij}}) \\ \frac{\partial y_{ij}}{\partial x_{ij}} &= \partial y_{ij} \gamma_j a_i - \frac{1}{N} (\sum_i \partial y_{ij} \gamma_j a_i) - \frac{a_j}{N} \hat{x}_{ij} (\sum_i \partial y_{ij} \gamma_j \hat{x}_{ij}) + \frac{a_j}{N^2} (\sum_i \partial y_{ij} \gamma_j \hat{x}_{ij}) (\sum_i \hat{x}_{ij}) \end{split}$$

Notes:

 \bullet can omit the last term with $\frac{1}{N^2}$ since it contributes little to the overall sum

```
Forward Pass:
```

```
mode = bn_param['mode']
   eps = bn_param.get('eps', 1e-5)
   momentum = bn_param.get('momentum', 0.9)
   N, D = x.shape
   running_mean = bn_param.get('running_mean', np.zeros(D, dtype=x.dtype))
   running_var = bn_param.get('running_var', np.zeros(D, dtype=x.dtype))
   out, cache = None, None
    if mode == 'train':
        batch_mean = np.sum(x, axis=0) / N
       batch_var = np.sum(np.power(x-batch_mean, 2), axis=0) / N
        running_mean = (1-momentum) * batch_mean + (momentum) * running_mean
        running_var = (1-momentum) * batch_var + (momentum) * running_var
        x_hat = (x - batch_mean) / (np.sqrt(batch_var + eps))
        out = gamma * x_hat + beta
        cache = (x, x_hat, gamma, beta, batch_mean, batch_var, eps)
    elif mode == 'test':
        x_hat = (x - running_mean)/(np.sqrt(running_var + eps))
        out = gamma * x_hat + beta
   else:
        raise ValueError('Invalid forward batchnorm mode "%s"', % mode)
   # Store the updated running means back into bn_param
    bn_param['running_mean'] = running_mean
    bn_param['running_var'] = running_var
Backward Pass:
   N, D = dout.shape
   x, x_hat, gamma, beta, batch_mean, batch_var, eps = cache
   dbeta = np.sum(dout, axis=0)
   dgamma = np.sum(dout * x_hat, axis=0)
   a = 1.0/np.sqrt(batch_var + eps)
   dx = dout * gamma * a
         - 1./N * a * gamma * (np.sum(dout, axis=0))
         - 1./N * a * gamma * x_hat * np.sum(dout * x_hat, axis=0)
         + 1./N**2 * a * gamma *
             np.sum(dout * x_hat, axis=0) * np.sum(x_hat, axis=0)
```

2. Layer Normalization Derivation:

$$\begin{split} \hat{x}_{ij} &= \frac{x_{ij} - \mu_i}{(\sigma_i^2 + \epsilon)^2} \\ \mu_i &= \frac{1}{D} \sum_j x_{ij} \\ \sigma_i^2 &= \frac{1}{D} \sum_j (x_{ij} - \mu_i)^2 \\ y_{ij} &= \gamma_j \hat{x}_{ij} + \beta_j \\ \frac{\partial y_{ij}}{\partial x_{ij}} &= \frac{\partial y_{ij}}{\partial \hat{x}_{ij}} \frac{\partial \hat{x}_{ij}}{\partial x_{ij}} + (\sum_j \frac{\partial y_{ij}}{\partial \hat{x}_{ij}} \frac{\partial \mu_i}{\partial \mu_i}) \frac{\partial \mu_i}{\partial x_{ij}} + (\sum_j \frac{\partial y_{ij}}{\partial \hat{x}_{ij}} \frac{\partial \hat{x}_{ij}}{\partial \sigma_i^2}) \frac{\partial \sigma_i^2}{\partial x_{ij}} \\ \frac{\partial \sigma_i^2}{\partial x_{ij}} &= \frac{2}{D} (x_{ij} - \mu_i) - (\sum_j \frac{2}{D} (x_{ij} - \mu_i)) \frac{1}{D} \\ &= \frac{2}{D} (x_{ij} - \mu_i) + \frac{2}{D^2} (\sum_j (x_{ij} - \mu_i)) \\ let \ a_i &= \frac{1}{(\sigma_i^2 + \epsilon)^{0.5}} \\ \frac{\partial y_{ij}}{\partial x_{ij}} &= \partial y_{ij} \gamma_j a_i + (\sum_j \partial y_{ij} \gamma_j (-a_i)) (\frac{1}{D}) + (\sum_j \partial y_{ij} \gamma_j (\frac{-1}{2}) \hat{x}_{ij} a_i^2) (\frac{\partial \sigma_i^2}{\partial x_{ij}}) \\ \frac{\partial y_{ij}}{\partial x_{ij}} &= \partial y_{ij} \gamma_j a_i - \frac{1}{D} (\sum_i \partial y_{ij} \gamma_j a_i) - \frac{a_i}{D} \hat{x}_{ij} (\sum_i \partial y_{ij} \gamma_j \hat{x}_{ij}) + \frac{a_i}{D^2} (\sum_i \partial y_{ij} \gamma_j \hat{x}_{ij}) (\sum_i \hat{x}_{ij}) \end{split}$$

Notes:

• can omit the last term with $\frac{1}{D^2}$ since it contributes little to the overall sum

Forward Pass:

```
N, D = x.shape
    sample_mean = np.sum(x, axis=1) / D
    sample_var = np.sum(np.power(x-np.expand_dims(sample_mean, axis=1), 2),
                     axis=1) / D
   x_hat = (x - np.expand_dims(sample_mean, axis=1)) /
                (np.sqrt(np.expand_dims(sample_var, axis=1) + eps))
    out = gamma * x_hat + beta
    cache = (x, x_hat, gamma, beta, sample_mean, sample_var, eps)
Backward Pass:
   N, D = dout.shape
   x, x_hat, gamma, beta, sample_mean, sample_var, eps = cache
   dbeta = np.sum(dout, axis=0)
   dgamma = np.sum(dout * x_hat, axis=0)
   a = 1.0/np.sqrt(sample_var + eps) #dim: (N)
   dx = dout * np.expand_dims(gamma, axis=0) * np.expand_dims(a, axis=1)
         - 1./D * np.sum(dout * np.expand_dims(a,axis=1) *
             np.expand_dims(gamma, axis=0), axis=1, keepdims=True)
         - 1./D * np.expand_dims(a, axis=1) * x_hat *
             np.sum(dout * np.expand_dims(gamma, axis=0) * x_hat,
                    axis=1, keepdims=True)
         + 1./D**2 * np.expand_dims(a, axis=1) *
             np.sum(dout * np.expand_dims(gamma, axis=0) * x_hat,
                    axis=1, keepdims=True)
             * np.sum(x_hat, axis=1, keepdims=True)
```