

# A framework for the verification of concurrent OCAML 5 programs using separation logic

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The release of OCAML 5, which introduced parallelism into the language, drove the need for safe and efficient concurrent data structures. New libraries like **SATURN** [25] aim at addressing this need. From the perspective of formal verification, this is an opportunity to apply and further state-of-the-art techniques to provide stronger guarantees.

We present a framework for verifying fine-grained concurrent OCAML 5 algorithms. Following a pragmatic approach, we support a limited but sufficient fragment of the language whose semantics has been carefully formalized to faithfully express such algorithms. Source programs are translated to a deeply-embedded language living inside **Coq** where they can be specified and verified using the **IRIS** [8] concurrent separation logic.

## 1 Introduction

Designing concurrent algorithms, in particular *lock-free* algorithms, is a notoriously difficult task. In this paper, we are concerned with proving the correctness of these algorithms. The question of performance is also crucial and requires special expertise; we will not address it here.

**Example 1: physical equality.** Consider, for example, the OCAML implementation of a concurrent stack [1] in **Figure 2**. Essentially, it consists of an atomic reference to a list that is updated atomically using the **Atomic.compare\_and\_set** primitive. While this simple implementation—it is indeed one of the simplest lockfree algorithms—may seem easy to verify, it is actually more subtle than it looks.

Indeed, the semantics of **Atomic.compare\_and\_set** involves *physical equality*: if the content of the atomic reference is physically equal to the expected value, it is atomically updated to the new value. Comparing physical equality is tricky and can be dangerous—this is why *structural equality* is often preferred—because the programmer has few guarantees about the *physical identity* of a value. In particular, the physical identity of a list, or more generally of an inhabitant of an algebraic data type, is not really specified. The only guarantee is: if two values are physically equal, they are also structurally equal. Apparently, we don’t learn anything interesting when two values are physically distinct. Going back to our example, this is fortunately not an issue, since we always retry the operation when **Atomic.compare\_and\_set** returns **false**.

Looking at the standard runtime representation of OCAML values, this makes sense. The empty list is represented by a constant while a non-empty list is represented by pointer to a

```

type 'a t =
  'a list Atomic.t

let create () =
  Atomic.make []

let rec push t v =
  let old = Atomic.get t in
  let new_ = v :: old in
  if not @@ Atomic.compare_and_set t old new_ then (
    Domain.cpu_relax () ;
    push t v
  )

let rec pop t =
  match Atomic.get t with
  | [] -> None
  | v :: new_ as old ->
    if Atomic.compare_and_set t old new_ then (
      Some v
    ) else (
      Domain.cpu_relax () ;
      pop t
    )

```

Figure 1. Implementation of a concurrent stack

tagged memory block. Physical equality for non-empty lists is just pointer comparison. It is clear that two pointers being distinct does not imply the pointed memory blocks are.

From the viewpoint of formal verification, this means we have to carefully design the semantics of the language to be able to reason about physical equality and other subtleties of concurrent programs. Essentially, the conclusion we can draw is that the semantics of physical equality and therefore `Atomic.compare_and_set` is non-deterministic: we cannot determine the result of physical comparison just by looking at the abstract values.

**Example 2: when physical identity matters.** Consider another example given in ??: the `Rcfd.close`<sup>1</sup> function from the `Eio` [26] library. Essentially, it consists in protecting a file descriptor using reference counting. Similarly, it relies on atomically updating the `state` field using `Atomic.Loc.compare_and_set`<sup>2</sup>. However, there is a complication. Indeed, we claim that the correctness of `close` derives from the fact that the `Open` state does not change throughout the lifetime of the data structure; it can be replaced by a `Closing` state but never by another `Open`. In other words, we want to say that 1) this `Open` is *physically unique* and 2) `Atomic.Loc.compare_and_set` therefore detects whether the data structure has flipped into the `Closing` state. In fact, this kind of property appears frequently in lockfree algorithms; it also occurs in the `Kcas` [24] library<sup>3</sup>.

Once again, this argument requires special care in the semantics of physical equality. In short, we have to reveal something about the physical identity of some abstract values. Yet, we cannot reveal too much—in particular, we cannot simply convert an abstract value to a concrete one (a memory location)—, since the OCAML compiler may perform optimizations

<sup>1</sup>[https://github.com/ocaml-multicore/eio/blob/main/lib\\_eio/unix/rcfd.ml](https://github.com/ocaml-multicore/eio/blob/main/lib_eio/unix/rcfd.ml)

<sup>2</sup>Here, we make use of atomic record fields that were recently introduced in OCAML.

<sup>3</sup><https://github.com/ocaml-multicore/kcas/blob/main/doc/gkmz-with-read-only-cmp-ops.md>

```

type state =
  | Open of Unix.file_descr
  | Closing of (unit -> unit)
type t =
  { mutable ops: int [@atomic];
    mutable state: state [@atomic];
  }

let close t =
  match t.state with
  | Open fd as prev ->
    let next = Closing (fun () -> Unix.close fd) in
    if Atomic.Loc.compare_and_set [%atomic.loc t.state] prev next then (
      if t.ops == 0
      && Atomic.Loc.compare_and_set [%atomic.loc t.state] next closed
      then
        close () ;
        true
      ) else (
        false
      )
  | Closing _ ->
    false

```

Figure 2. `Rcfd.close` function from the `Eio` [26] library

like sharing of immutable values and hash-consing.

**A formalized OCAML fragment for the verification of concurrent algorithms.** These subtle aspects, illustrated through two realistic examples, justify the need for a faithful formal semantics of a fragment of OCAML tailored for the verification of concurrent algorithms. Ideally, of course, this fragment would include most of the language. However, the direct practical aim of this work—the verification of real-life libraries like `SATURN` [25]—led us to the following design philosophy: only include what is actually needed to express and reason about concurrent algorithms in a convenient way.

In this paper, we show how we have designed a practical framework, `Zoo`, following this guideline. We review the works related to the verification of OCAML programs in Section 2; we describe our framework in Section 3; we detail the important features, including the treatment of physical equality, in Section 4 before concluding.

## 2 Related work

The idea of applying formal methods to verify OCAML programs is not new. Generally speaking, there are mainly two ways:

**Semi-automated verification.** The verified program is annotated by the user to guide the verification tool: preconditions, postconditions, invariants, *etc.* Given this input, the tool generates proof obligations that are mostly automatically discharged. One may further distinguish two types of semi-automated systems: *foundational* and *non-foundational*.

In *non-foundational* automated verification, the tool and the external solvers it may rely on are part of the trusted computing base. It is the most common approach and has been

widely applied in the literature [5, 7, 3, 18, 17, 4], including to OCAML by CAMELEER [15], which uses the GOSPEL specification language [12] and WHY3 [4].

In *foundational* automated verification, the proofs are checked by a proof assistant like COQ, meaning the automation does not have to be trusted. To our knowledge, it has been applied to C [16] and RUST [23].

**Non-automated verification.** The verified program is translated, manually or in an automated way, into a representation living inside a proof assistant. The user has to write specifications and prove them.

The representation may be primitive, like Gallina for COQ. For pure programs, this is rather straightforward, *e.g.* in `hs-to-coq` [10]. For imperative programs, this is more challenging. One solution is to use a monad, *e.g.* in `coq-of-ocaml` [21], but it does not support concurrency.

The representation may be embedded, meaning the semantics of the language is formalized in the proof assistant. This is the path taken by some recent works [19, 20, 11] harnessing the power of separation logic, in particular the IRIS [8] concurrent separation logic. IRIS is a very important work for the verification of concurrent algorithms. It allows for a rich, customizable ghost state that makes it possible to design complex *concurrent protocols*. In our experience, for the lockfree algorithms we considered, there is simply no alternative.

The tool closest to our needs so far is CFML [19], which targets OCAML. However, CFML does not support concurrency and is not based on IRIS. The OSIRIS [22] framework, still under development, also targets OCAML and is based on IRIS. However, it does not support concurrency and it is arguably non-trivial to introduce it since the semantics uses interaction trees [13]—the question of how to handle concurrency in this context is a research subject. Furthermore, OSIRIS is not usable yet; its ambition to support a large fragment of OCAML makes it a challenge.

### 3 Zoo in practice

Before describing the salient features of our language, ZOO, in Section 4, we give an overview of the framework.

**From OCAML to Zoo.** First, OCAML source files are translated into Zoo by the `ocaml2zoo` tool. The Zoo syntax is given in Figure 3<sup>4</sup>, omitting mutually recursive toplevel functions that are treated specifically. Essentially, Zoo is an untyped, ML-like, imperative, concurrent programming language. The supported OCAML fragment includes: shallow `match`, ADTs, records, inline records, atomic record fields, unboxed types, toplevel mutually recursive functions.

For instance, the `push` function from Section 1 is translated into:

```
Definition stack_push : val :=
  rec: "push" "t" "v" =>
    let: "old" := !"t" in
    let: "new_" := "v" :: "old" in
    ifnot: CAS "t".[contents] "old" "new_" then (
      Yield ;;
      "push" "t" "v"
    ).
```

<sup>4</sup>More precisely, it is the syntax of the surface language, including many COQ notations.

Coq term	$t$	
constructor	$C$	
projection	$proj$	
record field	$fld$	
identifier	$s, f$	$\in \text{String}$
integer	$n$	$\in \mathbb{Z}$
boolean	$b$	$\in \mathbb{B}$
binder	$x$	$::= \langle \rangle \mid s$
unary operator	$\oplus$	$::= \sim \mid -$
binary operator	$\otimes$	$::= + \mid - \mid * \mid 'quot' \mid 'rem'$ $\mid <= \mid < \mid >= \mid > \mid = \mid \neq \mid == \mid !=$ $\mid \text{and} \mid \text{or}$
expression	$e$	$::= t \mid s \mid \#n \mid \#b$ $\mid \text{fun: } x_1 \dots x_n \Rightarrow e \mid \text{rec: } f \ x_1 \dots x_n \Rightarrow e$ $\mid \text{let: } x := e_1 \text{ in } e_2 \mid e_1 ;; e_2$ $\mid \text{let: } f \ x_1 \dots x_n := e_1 \text{ in } e_2 \mid \text{letrec: } f \ x_1 \dots x_n := e_1 \text{ in } e_2$ $\mid \text{let: } 'C \ x_1 \dots x_n := e_1 \text{ in } e_2 \mid \text{let: } x_1, \dots, x_n := e_1 \text{ in } e_2$ $\mid \oplus e \mid e_1 \otimes e_2$ $\mid \text{if: } e_0 \text{ then } e_1 \text{ (else } e_2)^? \mid \text{ifnot: } e_0 \text{ then } e_1$ $\mid \text{for: } x := e_1 \text{ to } e_2 \text{ begin } e_3 \text{ end}$ $\mid \S C \mid 'C \ (e_1, \dots, e_n) \mid (e_1, \dots, e_n) \mid e.<proj>$ $\mid [] \mid e_1 :: e_2$ $\mid \text{Alloc } e_1 \ e_2 \mid \text{ref } e \mid !e \mid e_1 <- e_2$ $\mid 'C \ \{e_1, \dots, e_n\} \mid \{e_1, \dots, e_n\} \mid e.\{fld\} \mid e_1 <- \{fld\} \ e_2$ $\mid \text{Reveal } e \mid \text{GetTag } e \mid \text{GetSize } e$ $\mid \text{match: } e_0 \text{ with } br_1 \mid \dots \mid br_n \mid \_ \text{ (as } s)^? \Rightarrow e)^? \text{ end}$ $\mid \text{Fork } e \mid \text{Yield}$ $\mid e.[fld] \mid \text{Xchg } e_1 \ e_2 \mid \text{CAS } e_1 \ e_2 \ e_3 \mid \text{FAA } e_1 \ e_2$ $\mid \text{Proph} \mid \text{Resolve } e_0 \ e_1 \ e_2$
branch	$br$	$::= C \ (x_1 \dots x_n)^? \text{ (as } s)^? \Rightarrow e$ $\mid [] \text{ (as } s)^? \Rightarrow e \mid x_1 :: x_2 \text{ (as } s)^? \Rightarrow e$
toplevel value	$v$	$::= t \mid \#n \mid \#b$ $\mid \text{fun: } x_1 \dots x_n \Rightarrow e \mid \text{rec: } f \ x_1 \dots x_n \Rightarrow e$ $\mid \S C \mid 'C \ (v_1, \dots, v_n) \mid (v_1, \dots, v_n)$ $\mid [] \mid v_1 :: v_2$

Figure 3. Zoo syntax (omitting mutually recursive toplevel functions)

**Specifications and proofs.** Second, the user writes specifications for the translated functions and prove them using the **IRIS** proof mode [9].

For instance, the specification for the `stack_push` function would be:

```
Lemma stack_push_spec t ι v :
  <<<
    stack_inv t ι
  | ∀ vs, stack_model t vs
  >>>
    stack_push t v @ ↑ι
  <<<
    stack_model t (v :: vs)
  | RET (); True
  >>>.
Proof.
  ...
Qed.
```

Here, we use a *logically atomic specification* [6], which has been proven [14] to be equivalent to *linearizability* [2] in sequentially consistent memory models.

## 4 Zoo features

## 5 Conclusion and future work

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