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Program transformation implemented in the OCAML compiler.

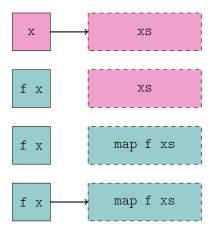
Formalize the transformation and its soundness.

Prove soundness using an adequate IRIS binary logical relation à la SIMULIRIS.

The map problem: natural implementation

```
let rec map f xs =
  match xs with
   \mathsf{I} \quad \mathsf{\Gamma} \mathsf{I} \quad \to \quad
  \mid x :: xs \rightarrow
        let y = f x in
        y :: map f xs
# List.init 250 000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
Stack overflow during evaluation (looping recursion?).
```

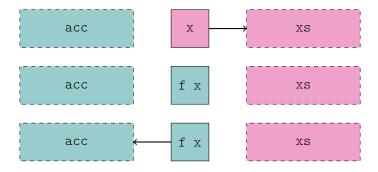
The map problem: natural implementation



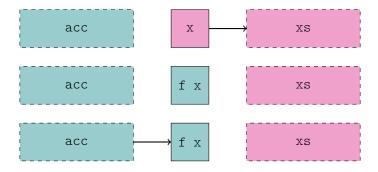
The map problem: APS implementation

```
let rec map ys f xs =
  match xs with
  I \quad [] \quad \rightarrow
    List.rev ys
  \mid x :: xs \rightarrow
       let y = f x in
       map (y :: ys) f xs
let map xs =
  map [] f xs
# List.init 250_000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
 ; ;
-: unit = ()
```

The map problem: APS implementation



The map problem: DPS implementation



The map problem: DPS implementation

```
let rec map dps dst f xs = let map f xs =
  match xs with
                                    match xs with
  I \quad \Gamma \rceil \quad \rightarrow
                                     I \quad [] \quad \rightarrow
   set field dst 1 []
  | x :: xs \rightarrow
                                    | x :: xs \rightarrow
       let y = f x in
                                         let y = f x in
       let dst' = y :: [] in let dst = y :: [] in
       set field dst 1 dst';
                                     map dps dst f xs ;
       map dps dst' f xs
                                        dst
# List.init 250 000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
  ;;
-: unit = ()
```

The map problem: TMC

```
let[@tail_mod_cons] rec map f xs =
  match xs with
  I \quad [] \quad \rightarrow
       Γ٦
  | x :: xs \rightarrow
       let y = f x in
       y :: map f xs
# List.init 250_000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
  ;;
-: unit = ()
```

DATALANG: syntax

```
Index \ni i ::= 0 \mid 1 \mid 2
Tag \ni t
\mathbb{F} \qquad \ni \qquad f
\mathbb{X} \qquad \ni \quad x, y
Val \qquad \ni \quad v, w \quad ::= \quad () \mid i \mid t \mid b \mid \ell \mid \mathbf{0} \mathbf{f}
Expr \ni e := v \mid x \mid \text{let } x = e_1 \text{ in } e_2 \mid e_1 \overline{e_2}
                                    e_1 = e_2 | if e_0 then e_1 else e_2
                                           \{t, e_1, e_2\}
                                           e_1.(e_2) \mid e_1.(e_2) \leftarrow e_3
Def \ni d ::= rec \overline{x} = e
\operatorname{Prog} \quad \ni \quad p \quad := \quad \mathbb{F} \stackrel{\operatorname{fin}}{\rightharpoonup} \operatorname{Def}
State \ni \sigma := \mathbb{L} \stackrel{\text{fin}}{\rightharpoonup} \text{Val}
Config \ni \rho := \operatorname{Expr} \times \operatorname{State}
```

DATALANG: map

TMC transformation

$$e_s \overset{\xi}{\underset{\text{dir}}{\leftrightarrow}} e_t \qquad d_s \overset{\xi}{\underset{\text{dir}}{\leftrightarrow}} d_t$$

$$(e_{dst}, e_{idx}, e_s) \overset{\xi}{\underset{\text{dps}}{\leftrightarrow}} e_t \qquad d_s \overset{\xi}{\underset{\text{dps}}{\leftrightarrow}} d_t$$

 $p_s \leadsto p_t$

TMC transformation: map

Transformation soundness

$$p_s \leadsto p_t$$
 program p_s transforms into program p_t



$$p_s \supseteq p_t$$

program p_t refines program p_t (termination-preserving refinement)

Transformation soundness

$p_s \leadsto p_t$	program p_s transforms into program p_t
#	
$p_s \gtrsim p_t$	program p_t simulates program p_s (relational separation logic, SIMULIRIS)
\downarrow	
$p_s \supseteq p_t$	program p_t refines program p_t (termination-preserving refinement)

Specification in separation logic

$$\frac{\{???\}}{\texttt{Omap}\, \textcolor{red}{v_s} \gtrsim \texttt{Omap}\, \textcolor{red}{v_t}}{\{???\}}$$

$$\frac{\{???\}}{\texttt{Omap}\, \textcolor{red}{v_s} \gtrsim \texttt{Omap_dps}\, \textcolor{red}{\ell}\, i\, \textcolor{red}{v_t}}{\{???\}}$$

Direct transformation

$$\frac{\{v_s \approx v_t\}}{\texttt{@map } v_s \gtrsim \texttt{@map } v_t}}{\{w_s, w_t. w_s \approx w_t\}}$$

Reldir (Simuliris)
$$f \in \text{dom}(p_s)$$

$$v_s \approx v_t$$

$$\forall w_s, w_t. w_s \approx w_t \twoheadrightarrow \Phi(w_s, w_t)$$

$$0f v_s \gtrsim 0f v_t [\Phi]$$

DPS transformation

$$\begin{array}{c|c} \{v_s \approx v_t * (\ell+i) \mapsto_t \blacksquare \} \\ \hline \text{@map } v_s \gtrsim \text{@map_dps } \ell \ i \ v_t \\ \hline \{(), w_t. \ \exists \ w_t. \ w_s \approx w_t * (\ell+i) \mapsto_t w_t \} \end{array}$$

RELDPS

$$\xi[f] = f_{dps}$$

$$\overline{v_s} \approx \overline{v_t}$$

$$\ell \mapsto_t \overline{v}$$

$$\forall w_s, w_t. w_s \approx w_t \twoheadrightarrow \ell \mapsto_t \overline{v}[i \mapsto w_t] \twoheadrightarrow \Phi(w_s, ())$$

$$@f \overline{v_s} \gtrsim @f_{dps} \ \ell \ i \ \overline{v_t} \ [\Phi]$$

RelProtocol

$$\frac{\mathbf{X}(e_s, e_t, \Psi)}{\mathbf{X}(e_s, e_t, \Psi)} \quad \forall e_s', e_t', \Psi(e_s', e_t') \rightarrow e_s' \gtrsim e_t' \langle \mathbf{X} \rangle \ [\Phi]$$

$$e_s \gtrsim e_t \langle \mathbf{X} \rangle \ [\Phi]$$

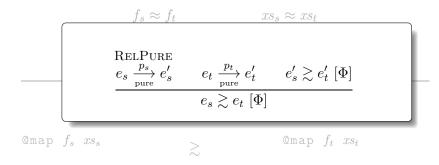
$$f_s \approx f_t$$

$$xs_s \approx xs_t$$

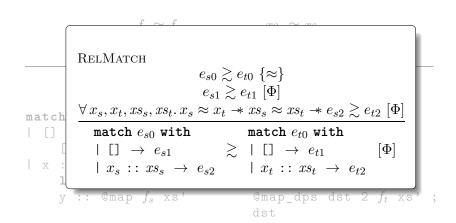
Omap f_s xs_s

 \gtrsim

 $\texttt{Omap} \ f_t \ xs_t$



$$f_s \approx f_t$$
 $xs_s \approx xs_t$



[]

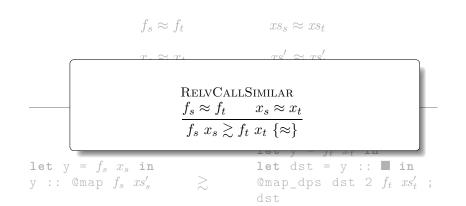
$$f_s \approx f_t$$
 $xs_s \approx xs_t$

[]

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx xs_t$ $xs_s' \approx xs_t'$

let
$$y = f_s x_s$$
 in $y :: @map f_s xs'_s$

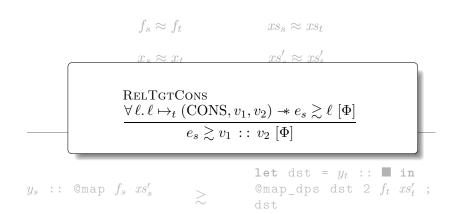
let $y = f_t x_t$ in let $dst = y :: \blacksquare$ in $@map_dps dst 2 f_t xs'_t$; dst



$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$

```
y_s :: \texttt{Qmap} \ f_s \ xs_s' \qquad \gtrsim \qquad \begin{array}{c} \texttt{let} \ \texttt{dst} = y_t \ :: \ \blacksquare \ \texttt{in} \\ \texttt{Qmap\_dps} \ \texttt{dst} \ 2 \ f_t \ xs_t' \ ; \\ \texttt{dst} \end{array}
```



$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $xs'_s \approx xs'_t$ $y_s \approx y_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, \blacksquare)$

$$y_s :: \texttt{Qmap} \ f_s \ xs_s' \qquad \gtrsim \qquad \begin{array}{c} \texttt{let} \ \texttt{dst} = \ell_t \ \texttt{in} \\ \texttt{Qmap_dps} \ \texttt{dst} \ 2 \ f_t \ xs_t' \ ; \\ \texttt{dst} \end{array}$$

$$f_spprox f_t$$
 $xs_spprox xs_t$ $xs_s'pprox xs_t'$ $xs_s'pprox xs_t'$ Reltgirule $e_t extstyle rac{p_t}{ ext{pure}} e_t' extstyle e_s \gtrsim e_t' [\Phi]$ $e_s \gtrsim e_t \ [\Phi]$

$$y_s :: \texttt{Qmap} \ f_s \ xs_s' \\ \gtrsim \\ \end{aligned} \qquad \begin{cases} \texttt{let} \ \texttt{dst} = \ell_t \ \texttt{in} \\ \texttt{Qmap_dps} \ \texttt{dst} \ 2 \ f_t \ xs_t' \ ; \\ \texttt{dst} \end{cases}$$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, \blacksquare)$

$$y_s$$
 :: @map f_s xs_s' $>$ @map_dps ℓ_t 2 f_t xs_t' ; ℓ_t

$$f_{s} \approx f_{t} \qquad xs_{s} \approx xs_{t}$$

$$\text{ReldPS2}$$

$$\xi[f] = f_{dps}$$

$$\overline{v_{s}} \approx \overline{v_{t}}$$

$$\ell \mapsto_{t} (t, v_{1}, v_{2})$$

$$\underline{\forall w_{s}, w_{t}. w_{s}} \approx w_{t} \twoheadrightarrow \ell \mapsto_{t} (t, v_{1}, w_{t}) \twoheadrightarrow \Phi(w_{s}, ())}$$

$$\underline{\text{@f } \overline{v_{s}} \gtrsim \text{@} f_{dps} \ \ell \ 2 \ \overline{v_{t}} \ [\Phi]}$$

$$y_{s} :: ys_{s}$$

$$\geq \frac{\text{@map_dps} \ \ell_{t} \ 2 \ f_{t} \ xs'_{t} \ ;}{\ell_{t}}$$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $ys_s \approx ys_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, ys_t)$

$$y_s$$
 :: ys_s \gtrsim () ; ℓ_t

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $ys_s \approx ys_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, ys_t)$

$$y_s :: ys_s > \ell_t$$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx xs_t$ $xs_s' \approx xs_t'$

$$\frac{\text{RelSrcCons}}{\forall \ell. \ell \mapsto_s (\text{CONS}, v_1, v_2) \twoheadrightarrow \ell \gtrsim e_t \ [\Phi]}{v_1 :: v_2 \gtrsim e_t \ [\Phi]}$$

$$\ell_s$$
 \geq

$$f_s \approx f_t \qquad xs_s \approx xs_t$$

$$x_s \approx x_t \qquad xs_s' \approx xs_t'$$

$$y_s \approx y_t$$

$$ys_s \approx ys_t$$

$$\ell_t \mapsto_t (\text{CONS}, y_t, ys_t)$$

$$\ell_s \mapsto_s (\text{CONS}, y_s, ys_s)$$

$$\ell_s$$
 \geq

$$f_{s} \approx f_{t} \qquad xs_{s} \approx xs_{t}$$

$$\begin{array}{c} \text{RelBijInsert} \\ \ell_{s} \mapsto_{s} \overline{v_{s}} \\ \ell_{t} \mapsto_{t} \overline{v_{t}} \\ \overline{v_{s}} \approx \overline{v_{t}} \\ \underline{\ell_{s} \approx \ell_{t} \twoheadrightarrow e_{s} \gtrsim e_{t} [\Phi]} \\ e_{s} \gtrsim e_{t} [\Phi] \end{array}$$

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$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $xs_s \approx xs_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $ys_s \approx ys_t$ $\ell_s \approx \ell_t$

$$\ell_s$$
 \geq

Thank you for your attention!