Verifying Tail Modulo Cons using Relational Separation Logic

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Program transformation implemented in the OCAML compiler.

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Formalize the transformation and its soundness.

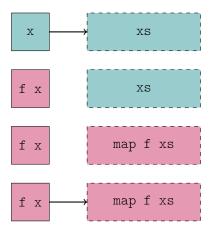
Verifying Tail Modulo Cons using Relational Separation Logic

Prove soundness using an adequate IRIS binary logical relation à la SIMULIRIS.

The map problem: natural implementation

```
let rec map f xs =
  match xs with
   \mathsf{I} \quad \mathsf{\Gamma} \mathsf{I} \quad \to \quad
  \mid x :: xs \rightarrow
        let y = f x in
        y :: map f xs
# List.init 250 000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
Stack overflow during evaluation (looping recursion■).
```

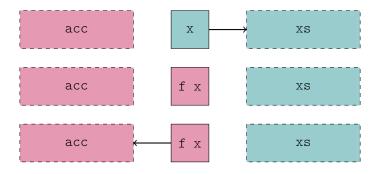
The map problem: natural implementation



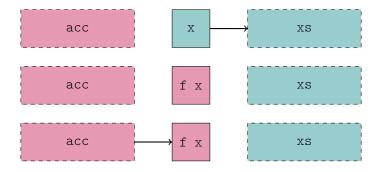
The map problem: APS implementation

```
let rec map ys f xs =
  match xs with
  I \quad [] \quad \rightarrow
    List.rev ys
  \mid x :: xs \rightarrow
       let y = f x in
       map (y :: ys) f xs
let map xs =
  map [] f xs
# List.init 250_000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
 ; ;
-: unit = ()
```

The map problem: APS implementation



The map problem: DPS implementation



The map problem: DPS implementation

```
let rec map dps dst f xs = let map f xs =
  match xs with
                                    match xs with
  I \quad \Gamma \rceil \quad \rightarrow
                                     I \quad [] \quad \rightarrow
   set field dst 1 []
  | x :: xs \rightarrow
                                    | x :: xs \rightarrow
       let y = f x in
                                         let y = f x in
       let dst' = y :: [] in let dst = y :: [] in
       set field dst 1 dst';
                                     map dps dst f xs ;
       map dps dst' f xs
                                        dst
# List.init 250 000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
  ;;
-: unit = ()
```

The map problem: TMC

```
let[@tail_mod_cons] rec map f xs =
  match xs with
  I \quad [] \quad \rightarrow
       Γ٦
  | x :: xs \rightarrow
       let y = f x in
       y :: map f xs
# List.init 250_000 (fun \rightarrow ())
  |> map Fun.id
  |> ignore
  ;;
-: unit = ()
```

DATALANG: syntax

```
Index \ni i := 0 | 1 | 2
Tag \ni t
\mathbb{B}
        \ni \ell
\mathbb{L}
        \ni f
\mathbb{F}
\mathbb{X} \qquad \ni \quad x, y
Val \qquad \ni \quad v, w \quad ::= \quad () \mid i \mid t \mid b \mid \ell \mid @f
Expr
         \ni e ::= v \mid x \mid \mathtt{let} \ x = e_1 \ \mathtt{in} \ e_2 \mid e_1 \ \overline{e_2}
                                       e_1 = e_2 | if e_0 then e_1 else e_2
                                       \{t, e_1, e_2\}
                                        e_1.(e_2) \mid e_1.(e_2) \leftarrow e_3
Def \ni d ::= rec \overline{x} = e
                              := \mathbb{F} \stackrel{\text{fin}}{\rightharpoonup} \text{Def}
Prog \ni p
State \ni \sigma := \mathbb{L} \stackrel{\text{fin}}{\rightharpoonup} \text{Val}
Config
                                := \operatorname{Expr} \times \operatorname{State}
              \ni \rho
```

Dataland: semantics

$$\begin{split} & \text{STEPCALL} \\ & \underbrace{p[f] = (\text{rec } \overline{x} = e)}_{\text{(@}f \ \overline{v}, \sigma) \xrightarrow{\text{head}} (e[\overline{x} \backslash \overline{v}], \sigma)} \end{split}$$

StepBlock
$$\forall i \in \text{Index}, \ell + i \notin \text{dom}(\sigma)$$

$$(\{\,t\,,\,v_1\,,\,v_2\,\},\sigma)\xrightarrow[\mathrm{head}]{p} (\ell,\sigma[\ell\mapsto t,v_1,v_2])$$

$$\begin{array}{ll} \text{STEPLOAD} & \text{STEPSTORE} \\ \frac{\sigma[\ell] = v}{(\ell.\,(i),\sigma)^{\frac{p}{\text{head}}}\,(v,\sigma)} & \frac{\ell+i \in \text{dom}(\sigma)}{(\ell.\,(i)\leftarrow v,\sigma)^{\frac{p}{\text{head}}}\,((),\sigma[\ell+i\mapsto v])} \end{array}$$

DATALANG: map

```
map → rec f xs =
  match xs with
  | [] →
        []
  | x :: xs →
        let y = f x in
        y :: @map f xs
```

TMC transformation

$$e_s \overset{\xi}{\underset{\text{dir}}{\rightleftharpoons}} e_t \qquad d_s \overset{\xi}{\underset{\text{dir}}{\rightleftharpoons}} d_t$$

$$(e_{dst}, e_{idx}, e_s) \overset{\xi}{\underset{\text{dps}}{\rightleftharpoons}} e_t \qquad d_s \overset{\xi}{\underset{\text{dps}}{\rightleftharpoons}} d_t$$

 $p_s \leadsto p_t$

TMC transformation: map

Transformation soundness

TODO

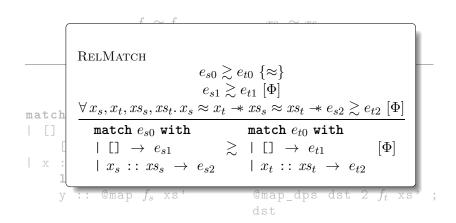
Separation logic

TODO quote original TMC article main ideas, specifications (direct and DPS)

Protocols

TODO

$$f_s \approx f_t$$
 $xs_s \approx xs_t$

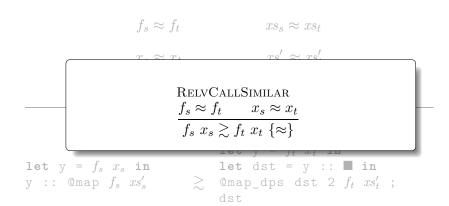


[]

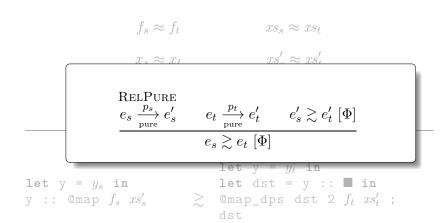
$$f_s \approx f_t$$
 $xs_s \approx xs_t$

[]

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx xs_t$ $xs_s' \approx xs_t'$



$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$



$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$

```
y_s :: \texttt{Qmap} \ f_s \ xs_s' \qquad \qquad \underbrace{\texttt{Qmap\_dps} \ \text{dst} \ 2}_{\texttt{dst}} \ f_t \ xs_t' \ ;
```

$$f_spprox f_t$$
 $xs_spprox xs_t$ $xs_spprox xs_t$ $xs_spprox xs_t$ RELTGTCONS $orall \ell.\ell\mapsto_t (ext{CONS},v_1,v_2) woheadrightarrow e_s\gtrsim \ell\ [\Phi]$ $e_s\gtrsim v_1::v_2\ [\Phi]$ let $ext{dst}=y_t::\ lacksquare$ in $ext{gmap_dps}$ $ext{dst}$ $ext{in}$ $ext{gmap_dps}$ $ext{dst}$; $ext{dst}$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, \blacksquare)$

$$y_s :: \texttt{Qmap} \ f_s \ xs_s' \qquad \begin{tabular}{ll} & \texttt{let} \ \texttt{dst} \ = \ \ell_t \ \texttt{in} \\ & \texttt{Qmap_dps} \ \texttt{dst} \ 2 \ f_t \ xs_t' \ ; \\ & \texttt{dst} \end{tabular}$$

$$f_spprox f_t$$
 $xs_spprox xs_t$ $xs_s'pprox xs_t'$ $xs_s'pprox xs_t'$ Reltgirule $e_t extstyle rac{p_t}{ extstyle exts$

$$y_s :: \texttt{Qmap} \ f_s \ xs_s' \\ \underset{\sim}{>} \ \text{Qmap_dps dst 2} \ f_t \ xs_t' \ ;$$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, \blacksquare)$

$$f_{s} \approx f_{t} \qquad xs_{s} \approx xs_{t}$$

$$\begin{cases}
ELDPS2 & \xi[f] = f_{dps} \\
\overline{v_{s}} \approx \overline{v_{t}} \\
\ell \mapsto_{t} (t, w_{1}, w_{2}) \\
\forall w_{s}, w_{t}. w_{s} \approx w_{t} * \ell \mapsto_{t} (t, w_{1}, w_{t}) * w_{s} \gtrsim () \ [\Phi]
\end{cases}$$

$$f \ \overline{v_{s}} \gtrsim f_{dps} \ \ell \ 2 \ \overline{v_{t}} \ [\Phi]$$

$$y_{s} :: @map \ f_{s} \ xs'_{s} & & \ell_{t} \end{cases}$$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $ys_s \approx ys_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, ys_t)$

$$y_s$$
 :: ys_s \gtrsim (); ℓ_t

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $ys_s \approx ys_t$ $\ell_t \mapsto_t (\text{CONS}, y_t, ys_t)$

$$y_s :: ys_s > \ell_s$$

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx xs_t$ $xs_s' \approx xs_t'$

$$\frac{\text{RELSRCCONS}}{\forall \ell. \ell \mapsto_s (\text{CONS}, v_1, v_2) \twoheadrightarrow \ell \gtrsim e_t \ [\Phi]}{v_1 :: v_2 \gtrsim e_t \ [\Phi]}$$

$$y_s :: ys_s > \ell$$

$$f_s \approx f_t \qquad xs_s \approx xs_t$$

$$x_s \approx x_t \qquad xs_s' \approx xs_t'$$

$$y_s \approx y_t$$

$$ys_s \approx ys_t$$

$$\ell_t \mapsto_t (\text{CONS}, y_t, ys_t)$$

$$\ell_s \mapsto_s (\text{CONS}, y_s, ys_s)$$

$$\ell_s$$
 \gtrsim ℓ_t

$$f_s pprox f_t$$
 $xs_s pprox xs_t$ RelbijInsert $\ell_s \mapsto_s \overline{v_s}$ $\ell_t \mapsto_t \overline{v_t}$ $\overline{v_t}$ $\overline{v_s} pprox \overline{v_t}$

$$\frac{\ell_s \approx \ell_t \twoheadrightarrow e_s \gtrsim e_t \ [\Phi]}{e_s \gtrsim e_t \ [\Phi]}$$

$$\ell_s$$
 \geq ℓ

$$f_s \approx f_t$$
 $xs_s \approx xs_t$ $x_s \approx x_t$ $xs_s' \approx xs_t'$ $y_s \approx y_t$ $ys_s \approx ys_t$ $\ell_s \approx \ell_t$

$$\ell_s$$
 \geq ℓ

Thank you for your attention!