

Example. A (simplified) 3-wheels slot machine

$$S = \{0, \dots, n+1\} \quad \& \quad I = \{0\}$$

$$Act = \{bet, win, loose, pull, payout\}$$

Fix an interval  $W = [i, j]$  with  $2 \leq i \leq j \leq n$

$$\rightarrow = \{(0, bet, 1)\} \cup \{1\} \times \{pull\} \times [2, n] \cup \{(n+1, payout, 0)\}$$

$$\cup W \times \{win\} \times \{n+1\} \cup S \setminus W \times \{loose\} \times \{0\}$$

3-wheels machine  $\rightarrow_3$

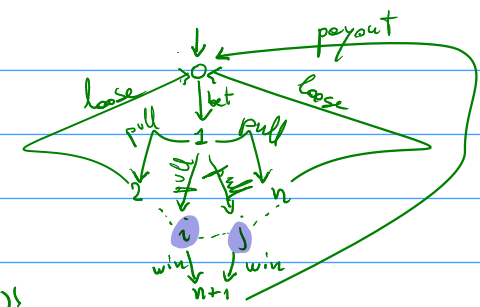
$$AP = \bigcup_{i=1}^3 \{w_i = f \mid f \in Fruits\} \cup \bigcup_{h \in W} \{price = h\} \quad \text{where } Fruits = \{apple, pear, banana, \dots\}$$

$$L: h \mapsto \bigcup_{i=1}^3 \{w_i = c_i(h)\} \cup \{price = p(h)\}$$

$$\text{where } c_1, c_2, c_3: S \rightarrow Fruit \quad p: S \rightarrow \mathbb{N} \text{ s.t. } \forall h \in S: p(h) > 0 \Leftrightarrow h \in W$$

Exercise: the cardinality of  $S$  should be much bigger than the cardinality of  $W$

for the TS above to be realistic. Why? (Hint: think of a possible implementation)



## NON-DETERMINISM

is crucial modelling mechanism

- under-specification
- to abstract away from low level details
- to model uncontrollable behaviour of the environment

(e.g., transitions from 1 in the slot machine)

Deterministic TS  $|I| = 1$

- action deterministic  $\forall q \in S, a \in Act: |\text{Post}(q, a)| \leq 1$

- AP deterministic  $\forall q \in S, A \in 2^{AP}: |\{q' \in \text{Post}(q) \mid L(q') = A\}| \leq 1$

$$q \xrightarrow{a} q_1 \wedge q \xrightarrow{a} q_2 \Rightarrow q_1 = q_2$$

$$q \xrightarrow{a} q_1 \wedge L(q_1) = L(q_2) \Rightarrow q_1 = q_2$$

## Executions & Traces

Execution fragment are sequences  $p \in S(ActS)^* \cup S(ActS)^\omega$  s.t.

$$p = q_0 a_1 q_1 a_2 q_2 \dots a_n q_n \dots \Rightarrow q_i \xrightarrow{a_{i+1}} q_{i+1} \text{ for all } i$$

$p$  initial if  $q_0 \in I$

$p$  maximal if  $\begin{cases} p \text{ infinite} \\ \text{or} \\ p = q_0 a_1 q_1 a_2 q_2 \dots a_n q_n \text{ \& Post}(q_n) = \emptyset \end{cases}$

An execution is an initial & maximal execution fragment

The set  $\text{Reach}(TS)$  of reachable states of TS is the set of states  $q$  of TS s.t. there is an initial execution fragment ending in  $q$

A note inspired by Duncan Atterd's question (27/2/21)

"Why do we need both labelling & actions to express properties?" :

Verification can be  $\begin{cases} \text{action based} \\ \text{state based} \\ \text{action + state based} \end{cases}$  (the most complex case)

Execution fragments are used for action-based verification; this approach is commonplace for modelling communication.

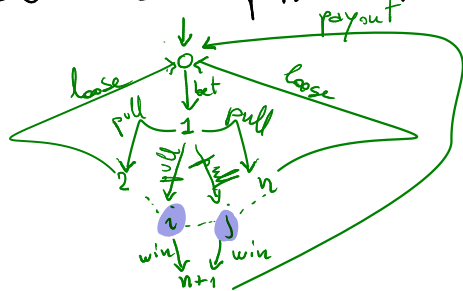
We now devote our attention to a state-based approach, where algorithms are oblivious of actions. Formally:

the **state graph**  $G(TS)$  of  $TS = (S, Act, \rightarrow, I, AP, L)$  is defined as

$$G(TS) = \langle S, \bigcup_{q \in S} \{q\} \times \text{Post}(q) \rangle$$

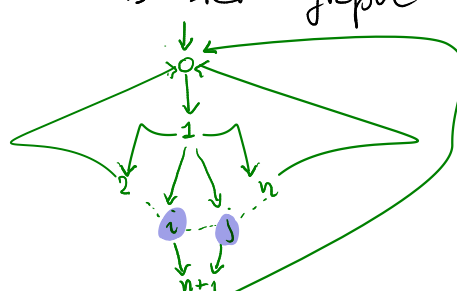
intuitively  $G(TS)$  is obtained by "removing" the actions from the transitions of  $TS$

Example: the TS of the slot machine



&

its state graph



notice that state labels do not "disappear" even though they are not explicitly represented

Notation: given a sequence  $\sigma = \sigma_0 \sigma_1 \dots \sigma_n \dots$

- the length of  $\sigma$  is  $|\sigma|$  (if  $\sigma$  is infinite,  $|\sigma| = \infty$ )
- the  $i$ -th element of  $\sigma$  is  $\sigma[i]$
- the last element of  $\sigma$  is  $\text{last}(\sigma)$ , provided that  $\sigma$  is finite

From now on we assume  $TS$  fixed

# LINEAR TIME BEH & PROPERTIES

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A **PATH FRAGMENT** of TS is a path on its state graph

$$\pi \in S^* \cup S^\omega \text{ s.t. } \forall 0 \leq i \leq |\pi|: \pi[i+1] \in \text{Post}(\pi[i])$$

$\pi$  maximal if  $\pi \in S^*$  &  $\text{Post}(\text{last}(\pi)) = \emptyset$  or  $\pi \in S^\omega$

$\pi$  initial if  $\pi[0] \in I$

$\pi$  path if initial & maximal

$$\bigcup \text{trace}(\pi) \\ \{ \pi \in \text{path}(TS) : \pi[0] = s \}$$

**TRACE** of  $\pi$   $\{L(\pi[i])\}_{0 \leq i < |\pi|}$

$$\text{Traces}(TS) := \bigcup_{s \in I} \text{traces}(s)$$

An **LT property** (on AP) is an element  $P$  of  $2^{(2^{AP})^\omega}$  i.e.  $P \subseteq (2^{AP})^\omega$

Examples. Let  $AP = \{z, g, y\}$  and  $P_{\text{right}} = \text{"the traffic light is infinitely often z"}$

$$P_{\text{right}} \supseteq \{z\} \{z, y\} \{g, y\} \{z\} \{z, y\} \{g, y\}$$

$$\not\supseteq \{z\} \{g\} \emptyset \emptyset \emptyset \dots$$

$$\supseteq \{z\}^\omega$$

$$\supseteq X^\omega \text{ if } z \in X \subseteq AP$$

$$\supseteq \{X_i\}_{i \in \omega} \text{ if } z \in X_i \Leftrightarrow i \text{ prime}$$

thread  $h$  is in the critical section

$$\text{Let } AP = \{c_1, \dots, c_n\}$$

$$P_{\text{mutex}} = \{ \{A_i\}_{i \in \omega} \in (2^{AP})^\omega \mid \forall i \geq 0, 1 \leq h \leq k \leq n: \{c_h, c_k\} \subseteq A_i \Rightarrow h = k \}$$

$$= \bigwedge_{1 \leq h < k \leq n} \{c_h, c_k\} \not\subseteq A_1 \wedge \dots \wedge \bigwedge_{1 \leq h < k \leq n} \{c_h, c_k\} \subseteq A_n$$

Exercise: What does  $P' = \{ \{A_i\}_{i \geq 0} \in (2^{AP})^\omega \mid \forall i \geq 0 \exists k \text{ s.t. } c_k \in A_i \}$  state?

Give two different traces in  $P'$

Exercise: Let  $P_{\text{set}} : \text{"always } (price = 0 \rightarrow \text{eventually } \bigvee_{p \in \text{Price}} price = p) \text{"}$ . Give an example of an element of  $P_{\text{set}}$  and one of  $(2^{AP})^\omega \setminus P_{\text{set}}$

$$\begin{array}{c} TS \\ \omega \\ \pi = \end{array} \quad \begin{array}{c} I \\ \omega \\ s_0 \end{array} \xrightarrow{\alpha_1} \begin{array}{c} s_1 \end{array} \xrightarrow{\alpha_2} \dots \xrightarrow{\alpha_n} \begin{array}{c} s_n \end{array} \xrightarrow{\alpha_{n+1}} \dots$$

$$\downarrow \quad \downarrow \quad \quad \quad \downarrow$$

$$L(s_0) \quad L(s_1) \quad \dots \quad L(s_n) \quad \dots \in P \quad \text{LT property}$$

$$TS \models P$$