

# Modeling Terms by Graphs with Structure Constraints (Two Illustrations)

Clemens Grabmayer

Department of Computer Science  
Vrije Universiteit Amsterdam  
The Netherlands

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# Overview

- ▶ timeline of my career
- ▶ research
  - Milner's problems for star expressions
  - maximal sharing for functional programs
- ▶ teaching
  - master course Models of Computation
  - first-year course Logic and Sets
- ▶ management
- ▶ plans and collaborations
  - the  $\lambda$ -calculus with generalized letrec
  - with group, department, other departments

# Maximal sharing

# Process interpretation of regular expressions

- ▶ Milner's questions for **star expressions**
  - results and partial answers
- ▶ Modeling expressible process graphs
  - examples

# Language interpretation $\llbracket \cdot \rrbracket_L$

$$0 \xrightarrow{\llbracket \cdot \rrbracket_L} \text{empty set } \emptyset$$

$$1 \xrightarrow{\llbracket \cdot \rrbracket_P} \{\epsilon\} \quad (\epsilon \text{ the empty word})$$

$$a \xrightarrow{\llbracket \cdot \rrbracket_P} \{a\}$$

$$e + f \xrightarrow{\llbracket \cdot \rrbracket_L} \text{union of } \llbracket e \rrbracket_L \text{ and } \llbracket f \rrbracket_L$$

$$e \cdot f \xrightarrow{\llbracket \cdot \rrbracket_L} \text{element-wise concatenation of } \llbracket e \rrbracket_L \text{ and } \llbracket f \rrbracket_L$$

$$e^* \xrightarrow{\llbracket \cdot \rrbracket_L} \text{set of words over } \llbracket e \rrbracket_L$$

# Process interpretation $\llbracket \cdot \rrbracket_P$

$0 \xrightarrow{\llbracket \cdot \rrbracket_P}$  deadlock  $\delta$ , no termination

$1 \xrightarrow{\llbracket \cdot \rrbracket_P}$  empty process  $\epsilon$ , then terminate

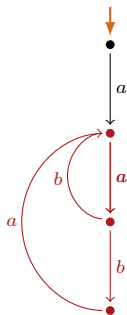
$a \xrightarrow{\llbracket \cdot \rrbracket_P}$  atomic action  $a$ , then terminate

$e + f \xrightarrow{\llbracket \cdot \rrbracket_P}$  alternative composition between  $\llbracket e \rrbracket_P$  and  $\llbracket f \rrbracket_P$

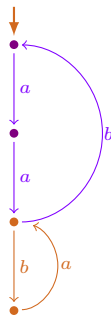
$e \cdot f \xrightarrow{\llbracket \cdot \rrbracket_P}$  sequential composition of  $\llbracket e \rrbracket_P$  and  $\llbracket f \rrbracket_P$

$e^* \xrightarrow{\llbracket \cdot \rrbracket_P}$  unbounded iteration of  $\llbracket e \rrbracket_P$ , option to terminate

# Process interpretation of regular expressions

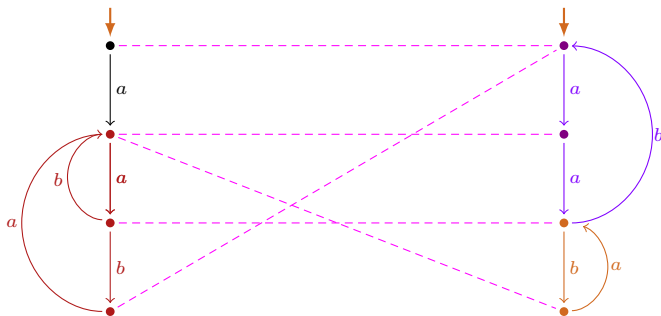


$$\llbracket a \cdot (a \cdot (b + b \cdot a))^* \cdot 0 \rrbracket_P$$



$$\llbracket (a \cdot a \cdot (b \cdot a)^* \cdot b)^* \cdot 0 \rrbracket_P$$

# Process interpretation of star expressions



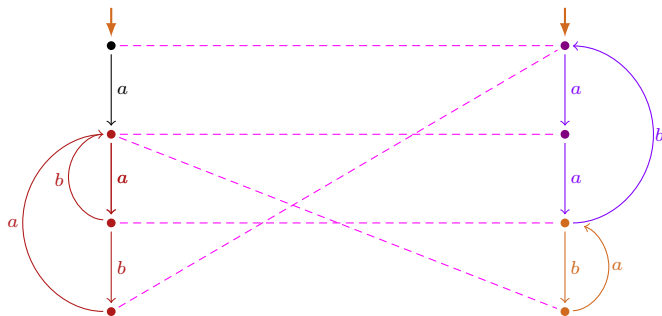
$$\llbracket a(a(b + ba))^*0 \rrbracket_P$$

$$\Leftrightarrow$$

$$\llbracket (aa(ba)^*b)^*0 \rrbracket_P$$



# Process interpretation of star expressions

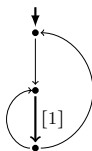
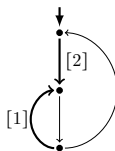
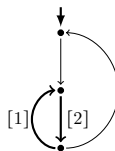


$$a(a(b + ba))^*0$$

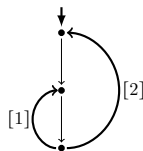
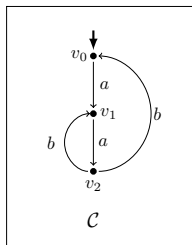
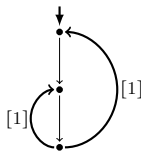
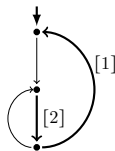
$$\Leftrightarrow_P$$

$$(aa(ba)^*b)^*0$$

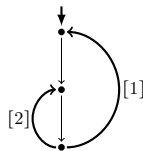
# 7 LEE-witnesses

 $\hat{\mathcal{C}}_1$  $\hat{\mathcal{C}}_2$  $\hat{\mathcal{C}}_3$ 

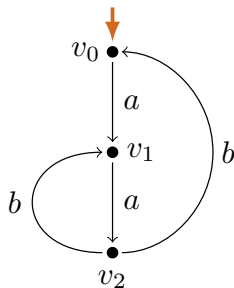
$\Rightarrow$   
make layered

 $\hat{\mathcal{C}}_4$  $\mathcal{C}$  $\hat{\mathcal{C}}_5$  $\hat{\mathcal{C}}_6$ 

$\Rightarrow$   
make layered

 $\hat{\mathcal{C}}_7$

# Layered LEE-witness



loop-branch labeling: marking transitions  $\xrightarrow{a}$  as

- ▶ entry steps  $\xrightarrow{\langle a, [n] \rangle}$
- ▶ branch steps  $\xrightarrow{\langle a, br \rangle}$

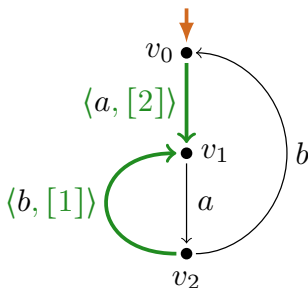
## Definition

A loop-branch labeling is a **layered LEE-witness**, if:

- ▶ no infinite  $\rightarrow_{br}$  paths from start vertex,
- ▶  $\forall n \in \mathbb{N} \forall v \in V \left( \mathcal{L}(v, \rightarrow_{[n]}, \rightarrow_{br}) \text{ is loop chart} \right)$ .

$\mathcal{L}(v, \rightarrow_{[n]}, \rightarrow_{br}) :=$  subchart induced  
by entry steps  $\rightarrow_{[n]}$  from  $v$   
followed by branch steps  $\rightarrow_{br}$ ,

# Layered LEE-witness



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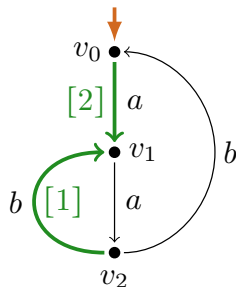
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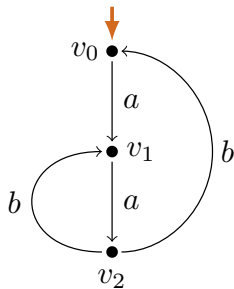
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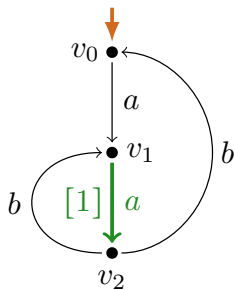
- ▶ no infinite  $\rightarrow_{br}$  paths from start vertex,
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# Extraction (example)



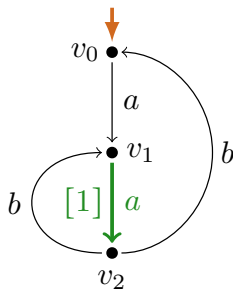
# Extraction (example)



layered  
LEE-witness

# Extraction (example)

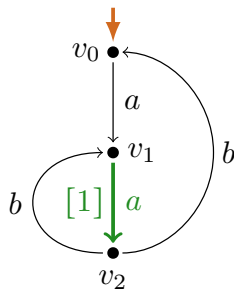
$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



layered  
LEE-witness



# Extraction (example)

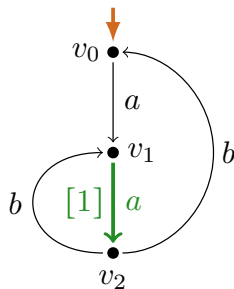


layered  
LEE-witness

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

$$s(v_2) = (a \cdot t(v_2, v_1))^* \cdot 0$$

# Extraction (example)



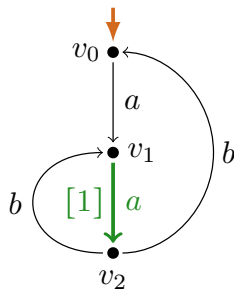
layered  
LEE-witness

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

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$$t(v_2, v_1) = 0^* \cdot (b \cdot t(v_1, v_1) + b \cdot t(v_0, v_1))$$

# Extraction (example)



layered  
LEE-witness

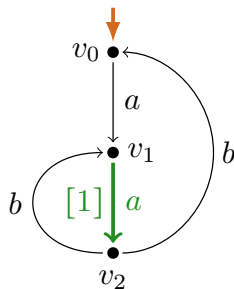
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$$t(v_1, v_1) = 1$$

# Extraction (example)



layered  
LEE-witness

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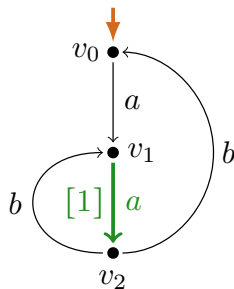
$$s(v_2) = (a \cdot t(v_2, v_1))^* \cdot 0$$

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# Extraction (example)



layered  
LEE-witness

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

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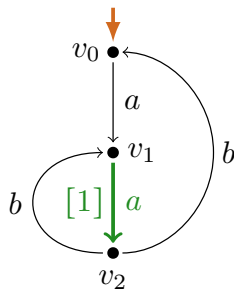
$$t(v_2, v_1) = 0^* \cdot (b \cdot t(v_1, v_1) + b \cdot t(v_0, v_1))$$

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$$t(v_0, v_1) = 0^* \cdot a \cdot t(v_1, v_1)$$

$$= 0^* \cdot a \cdot 1$$

# Extraction (example)



layered  
LEE-witness

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

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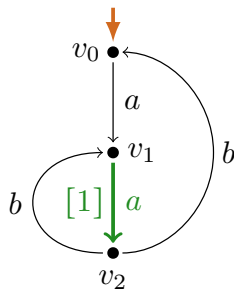
$$t(v_1, v_1) = 1$$

$$t(v_0, v_1) = 0^* \cdot a \cdot t(v_1, v_1)$$

$$= 0^* \cdot a \cdot 1$$

$$=_{\text{Mil}} a$$

# Extraction (example)



layered  
LEE-witness

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

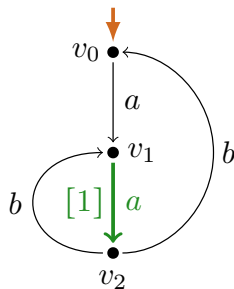
$$s(v_2) = (a \cdot t(v_2, v_1))^* \cdot 0$$

$$\begin{aligned} t(v_2, v_1) &= 0^* \cdot (b \cdot t(v_1, v_1) + b \cdot t(v_0, v_1)) \\ &=_{\text{Mil}^-} 0^* \cdot (b \cdot 1 + b \cdot a) \end{aligned}$$

$$t(v_1, v_1) = 1$$

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layered  
LEE-witness

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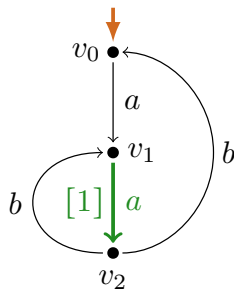
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# Extraction (example)



layered  
LEE-witness

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

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$$=_{\text{Mil}^-} (a \cdot (b + b \cdot a))^* \cdot 0$$

$$t(v_2, v_1) = 0^* \cdot (b \cdot t(v_1, v_1) + b \cdot t(v_0, v_1))$$

$$=_{\text{Mil}^-} 0^* \cdot (b \cdot 1 + b \cdot a)$$

$$=_{\text{Mil}^-} b + b \cdot a$$

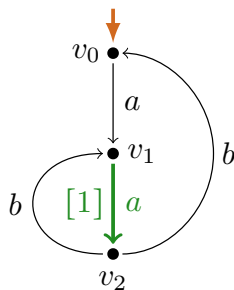
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# Extraction (example)



layered  
LEE-witness

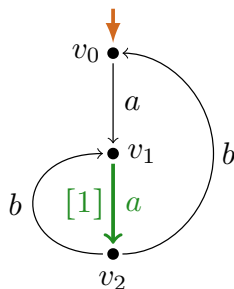
$$\begin{aligned} s(v_0) &= 0^* \cdot a \cdot s(v_1) \\ &=_{\text{Mil}^-} a \cdot s(v_1) \end{aligned}$$

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# Extraction (example)



layered  
LEE-witness

$$\begin{aligned}
 s(v_0) &= 0^* \cdot a \cdot s(v_1) \\
 &=_{\text{Mil}^-} a \cdot s(v_1) \\
 &=_{\text{Mil}^-} a \cdot (a \cdot (b + b \cdot a))^* \cdot 0
 \end{aligned}$$

$$\begin{aligned}
 s(v_2) &= (a \cdot t(v_2, v_1))^* \cdot 0 \\
 &=_{\text{Mil}^-} (a \cdot (b + b \cdot a))^* \cdot 0
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 t(v_2, v_1) &= 0^* \cdot (b \cdot t(v_1, v_1) + b \cdot t(v_0, v_1)) \\
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 t(v_1, v_1) &= 1 \\
 t(v_0, v_1) &= 0^* \cdot a \cdot t(v_1, v_1) \\
 &= 0^* \cdot a \cdot 1 \\
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