

CTL

$\Phi ::= \text{true} \mid \overset{\text{Act}}{a} \mid \Phi_1 \wedge \Phi_2 \mid \neg \Phi \mid \exists \varphi \mid \forall \varphi$ (state formulas)
 $\varphi ::= \bigcirc \Phi \mid \Phi_1 \cup \Phi_2$ (path formulas)

CTL⁺

$\Phi ::= \text{true} \mid \overset{\text{Act}}{a} \mid \Phi_1 \wedge \Phi_2 \mid \neg \Phi \mid \exists \varphi \mid \forall \varphi$ (state)
 $\varphi ::= \varphi_1 \wedge \varphi_2 \mid \neg \varphi \mid \bigcirc \Phi \mid \Phi_1 \cup \Phi_2$ (path)

Lecture 7

11-02-2025

$\forall \varphi ::= \neg \exists \neg \varphi$ could be used to drop clause $\forall \varphi$ from the state formulas

CTL*

$\Phi ::= \text{true} \mid \overset{\text{Act}}{a} \mid \Phi_1 \wedge \Phi_2 \mid \neg \Phi \mid \exists \varphi$ (state forms)
 $\varphi ::= \Phi \mid \varphi_1 \wedge \varphi_2 \mid \neg \varphi \mid \bigcirc \varphi \mid \varphi_1 \cup \varphi_2$ (path forms)

$\forall \varphi ::= \neg \exists \neg \varphi$

LTL

$\varphi ::= \text{true} \mid \overset{\text{Act}}{a} \mid \varphi_1 \wedge \varphi_2 \mid \neg \varphi \mid \bigcirc \varphi \mid \varphi_1 \cup \varphi_2$

CTL ENF

Existential Normal Form

$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg \Phi \mid \exists \bigcirc \Phi \mid \exists (\Phi_1 \cup \Phi_2) \mid \exists \square \Phi$

CTL PNF

Positive Normal Form

$\Phi ::= \text{true} \mid \text{false} \mid a \mid \neg a \mid \Phi_1 \wedge \Phi_2 \mid \Phi_1 \vee \Phi_2 \mid \exists \varphi \mid \forall \varphi$ (state forms)
 $\varphi ::= \bigcirc \Phi \mid \Phi_1 \cup \Phi_2 \mid \Phi_1 W \Phi_2$

Thm. For every CTL-formula there exists an equivalent CTL-ENF formula.

Proof. $\forall \bigcirc \Phi \equiv \neg \exists \bigcirc \neg \Phi$
 $\forall (\Phi \cup \Psi) \equiv \neg \exists (\neg \Phi \cup (\neg \Phi \wedge \neg \Psi))$
 $\quad \quad \quad \wedge \neg \exists \square \neg \Psi$

 $\forall \square \Phi \equiv \neg \exists \square \neg \Phi$
 $\forall \square \Phi \equiv \neg \exists \square \neg \Phi$
 $\quad \quad \quad \equiv \neg \exists (\text{true} \cup \neg \Phi)$

Thm. For every CTL-formula there exists an equivalent CTL-PNF formula.

Proof. $\neg \text{true} \equiv \text{false}$
 $\neg \neg \Phi \equiv \Phi$
 $\neg (\Phi \wedge \Psi) \equiv \neg \Phi \vee \neg \Psi$
 $\neg \forall \bigcirc \Phi \equiv \exists \bigcirc \neg \Phi$
 $\neg \exists \bigcirc \Phi \equiv \forall \bigcirc \neg \Phi$
 $\neg \forall (\Phi \cup \Psi) \equiv \exists ((\neg \Phi \wedge \neg \Psi) W (\neg \Phi \wedge \neg \Psi))$
 $\neg \exists (\Phi \cup \Psi) \equiv \forall ((\neg \Phi \wedge \neg \Psi) W (\neg \Phi \wedge \neg \Psi))$

Aspect	Linear time	Braiding time
"behaviour" in states	path-based: trace(s)	state-based computation tree of s
temporal logic	LTL: path formula φ $SF\varphi \Leftrightarrow \Leftrightarrow \forall \pi \in \text{Paths}(s): \pi \models \varphi$	CTL: state formulae existential path quantification universal path quantification
complexity of model checking problems	PSPACE-complete $O(TS \cdot \exp(\varphi))$	PTIME $O(TS \cdot \varphi)$
adequate subsumption and equivalence relations	trace inclusion and trace equivalence (can be checked in PSPACE-complete)	bisimulation subsumption bisimulation equivalence (can be checked in polynomial time)
fairness	no special techniques needed	special techniques needed

Normal Forms

CTL-formulas Φ and Ψ are equivalent (denoted $\Phi \equiv \Psi$) if $\text{Sat}(\Phi) = \text{Sat}(\Psi)$ for all transition systems TS over AP.

Existential Normal Form (ENF)

$$\Phi ::= \text{true} \mid \neg \alpha \mid \Phi \wedge \Phi \mid \neg \Phi \mid \exists \alpha \Phi \mid \exists (\Phi \cup \Phi) \mid \exists \square \Phi$$

Thm. For every CTL-formula there is an equivalent CTL-formula in ENF.

Positive Normal Form

$$\Phi ::= \text{true} \mid \text{false} \mid \alpha \mid \neg \alpha \mid \Phi_1 \wedge \Phi_2 \mid \Phi_1 \vee \Phi_2 \mid \exists \varphi \mid \forall \varphi$$

$$\varphi ::= \bigcirc \Phi \mid \Phi_1 \cup \Phi_2 \mid \Phi_1 \text{ W } \Phi_2$$

weak until

Thm. For each CTL-formula there is an equivalent CTL-formula in PNF.

Weak Until:

intuitively not yet a definition

$$\pi \models \Phi \text{ W } \Psi \Leftrightarrow \pi \models \Phi \cup \Psi \text{ or } \pi \models \square (\Phi \wedge \Psi)$$

$$\Leftrightarrow \pi \models \Phi \cup \Psi \text{ or } \pi \models \square \Phi$$

Can be obtained by defining:

$$\exists (\Phi \text{ W } \Psi) := \neg \forall (\Phi \wedge \neg \Psi) \cup (\neg \Phi \wedge \neg \Psi)$$

$$\forall (\Phi \text{ W } \Psi) := \neg \exists ((\Phi \wedge \neg \Psi) \cup (\neg \Phi \wedge \neg \Psi))$$

CTL⁺

Extending CTL with Boolean Connectives

Syntax

$\Phi ::= \text{True} \mid \text{False} \mid \Phi_1 \wedge \Phi_2 \mid \neg \Phi \mid \exists \Phi \mid \forall \Phi$
 $\varphi ::= \varphi_1 \wedge \varphi_2 \mid \neg \varphi \mid \bigcirc \Phi \mid \Phi_1 \cup \Phi_2$

Same as for CTL

(CTL⁺ path formulas)

CTL⁺ formula

Examples

$\exists \neg(\Phi_1 \cup \Phi_2)$
 $\equiv \exists ((\Phi_1 \wedge \Phi_2) \cup (\neg \Phi_1 \wedge \neg \Phi_2))$
 $\vee \exists \neg \Phi_2$
 CTL-formula

$\exists (a W b) \equiv \exists ((a \cup b) \vee \bigcirc a)$
 CTL-formula (after using the definition of W)
 CTL⁺-formula but not a CTL-formula

$\exists \neg \bigcirc \Phi \equiv \exists \bigcirc \neg \Phi$
 CTL⁺ form CTL-form

$\exists (\bigcirc a \wedge \bigcirc b) \equiv \exists \bigcirc (a \wedge \exists \bigcirc b) \vee \exists \bigcirc (b \wedge \exists \bigcirc a)$
 CTL⁺-formula CTL-formula

Thm. Every CTL⁺-formula is equivalent to a CTL-formula.

Incomparable expressiveness of LTL and CTL

Lemma. Φ a CTL-formula, φ a LTL-formula that results by eliminating all path quantifiers from Φ .

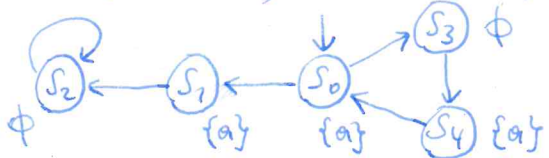
Then: $\Phi \equiv \varphi$ or there is no LTL-formula that is equivalent to Φ .
 For all TS: $TS \models \Phi \Leftrightarrow TS \models \varphi$

Examples:

$\forall \bigcirc a \equiv \bigcirc a$, $\forall (a \cup b) \equiv a \cup b$, $\forall \bigcirc a \equiv \bigcirc a$, $\forall \square a \equiv \square a$
 $\forall \square \forall \bigcirc a \equiv \square \bigcirc a$

Proposition. $\forall \bigcirc \forall \square a \not\equiv \square \bigcirc a$

$\forall \bigcirc (a \wedge \forall \bigcirc a) \not\equiv \square \bigcirc (a \wedge \bigcirc a)$



Proof
 $s_0 \models_{CTL} \square \bigcirc a$ because $\pi = s_0 \dots$
 $s_0 \not\models_{CTL} \forall \bigcirc \forall \square a$ because $s_0^w \not\models \square \bigcirc a$, $s_0 \not\models \forall \square a$
 $\pi = s_0 \xrightarrow{a} s_1 \xrightarrow{a} s_2 \dots$
 $\pi = s_0^* s_1 s_2^w \models \square \bigcirc a$

$s_0 s_1 s_2^w \models_{CTL} \square \bigcirc (a \wedge \bigcirc a)$ since $s_0 s_1 s_2^w \models a \wedge \bigcirc a$

$s_0 s_1 s_2^w \not\models_{CTL} \square \bigcirc (a \wedge \forall \bigcirc a)$ since $s_0 \not\models_{CTL} \forall \bigcirc a$, $s_1 \not\models_{CTL} \forall \bigcirc a$, $s_2 \not\models_{CTL} \forall \bigcirc a$

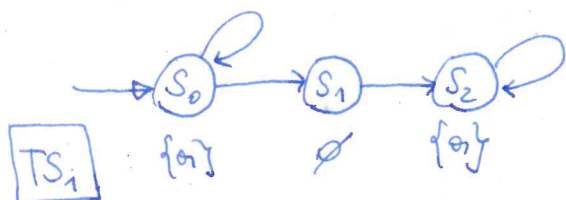
Hence $s_0 \not\models_{CTL} \forall \bigcirc (a \wedge \forall \bigcirc a)$, yet $s_0 \models_{CTL} \square \bigcirc (a \wedge \bigcirc a)$

Thm. Incomparable Expressiveness LTL/CTL (Since $(s_0 s_3 s_4)^* s_1 s_2^w \models \square \bigcirc (a \wedge \bigcirc a)$
 $(s_0 s_3 s_4)^w \models \square \bigcirc (a \wedge \bigcirc a)$)

(a) There are LTL-formulas for which no equivalent CTL-formula exists
 e.g. $\square \bigcirc a$ and $\square \bigcirc (a \wedge \bigcirc a)$.

(b) There are CTL-formulas for which no equivalent LTL-formula exists
 e.g. $\forall \bigcirc \forall \square a$ and $\forall \bigcirc (a \wedge \forall \bigcirc a)$ and $\forall \square \bigcirc a$

Proposition. (i) $\forall \Diamond \forall \Box a \neq \Diamond \Box a$ ^{eventually always!} \Rightarrow there is no LTL-formula that is equivalent with $\forall \Diamond \Box a$



$$S_0 \not\models_{CTL} \forall \Diamond \forall \Box a$$

because $S_0^w \not\models \Diamond \forall \Box a$

$$S_0 \not\models \forall \Box a \text{ since } S_0^* S_1 S_2^w \not\models \Box a$$

$$S_0 \models_{LTL} \Diamond \Box a$$

because $\pi = S_0 \dots$

$$TS_1 \models_{LTL} \Diamond \Box a$$

$$TS_1 \not\models_{CTL} \forall \Diamond \forall \Box a$$

$$\pi = S_0^w \models \Diamond \Box a$$

$$S_0^w \models a$$

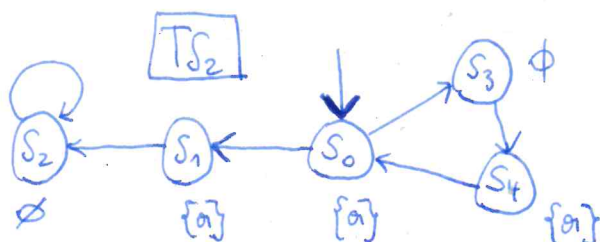
$$S_0^w \models \Box a$$

$$\pi = S_0^* S_1 S_2^w \models \Diamond \Box a$$

$$S_2^w \models a$$

$$S_2^w \models \Box a$$

(ii) $\forall \Diamond (a \wedge \forall \Diamond a) \neq \Diamond (a \wedge \Box a) \Rightarrow$ there is no LTL-formula that is equivalent with $\forall \Diamond (a \wedge \forall \Diamond a)$



$$S_0 \not\models_{CTL} \forall \Diamond (a \wedge \forall \Diamond a)$$

because $S_0 S_1 S_2^w \not\models \Diamond (a \wedge \forall \Diamond a)$

$$S_0 \not\models \forall \Diamond a$$

$$S_1 \not\models \forall \Diamond a$$

$$S_2 \not\models \forall \Diamond a$$

$$S_0 \models_{LTL} \Diamond (a \wedge \Box a)$$

because $\pi = S_0 \dots$

$$TS_2 \models_{LTL} \Diamond (a \wedge \Box a)$$

$$TS_2 \not\models_{CTL} \forall \Diamond (a \wedge \forall \Diamond a)$$

$$(S_0 S_3 S_4)^* S_1 S_2^w \models \Diamond (a \wedge \Box a)$$

$$S_1 S_2^w \models a \wedge \Box a$$

$$(S_0 S_3 S_4)^w \models \Diamond (a \wedge \Box a)$$

$$S_4 (S_0 S_3 S_4)^w \models a \wedge \Box a$$

Lemma. Φ a CTL-formula, Ψ the LTL formula that arises by deleting all path quantifiers from Φ .

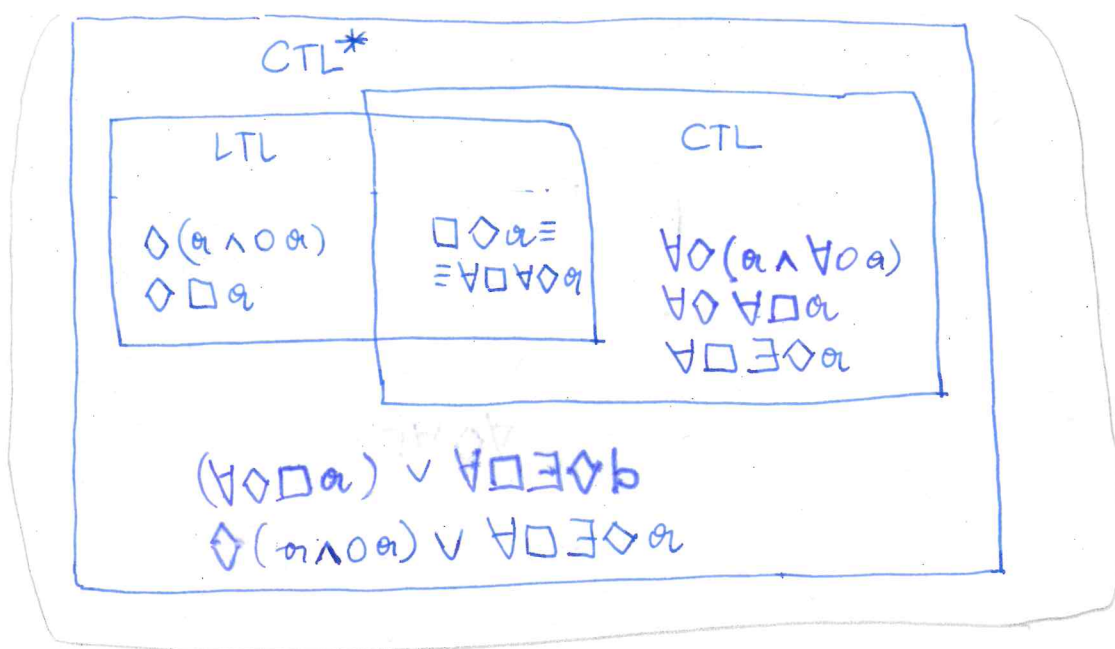
Then: $\Psi \equiv_{LTL} \Phi$ or there is no LTL-formula that is equivalent to Φ .

Examples: $\forall \Diamond a \equiv \Diamond a$, $\forall (a \cup b) \equiv a \cup b$, $\forall \Diamond a \equiv \Diamond a$, $\forall \Box a \equiv \Box a$
 $\forall \Box \forall \Diamond a \equiv \Box \Diamond a$.

Theorem. Incomparable Expressiveness LTL/CTL

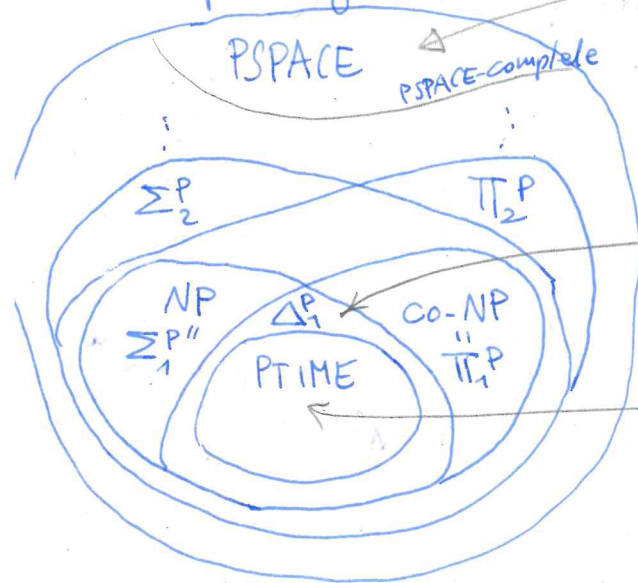
(a) There are LTL formulas for which no equivalent CTL-formulas exist. E.g. $\Diamond \Box a$, and $\Diamond (a \wedge \forall \Diamond a)$.

(b) There are CTL-formulas for which no equivalent LTL-formulas exist. E.g. $\forall \Diamond \forall \Box a$, $\forall \Diamond (a \wedge \forall \Diamond a)$, $\forall \Box \exists \Diamond a$



μ -calculus

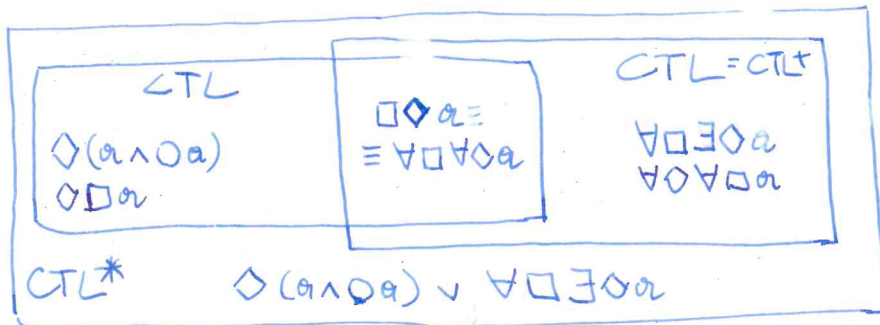
Complexity.



LTL-model checking¹⁰
 CTL*-model-checking
 upper bound: $O(|TS| \cdot 2^{|\Phi|})$

μ -Calculus

CTL-model checking
 $O(|TS| \cdot |\Phi|)$



	CTL	LTL	CTL*
model checking	P TIME	PSPACE-complete	PSPACE-complete
without fairness	$size(TS) \cdot \Phi $	$size(TS) \cdot exp(\Phi)$	$size(TS) \cdot exp(\Phi)$
with fairness	$size(TS) \cdot \Phi \cdot fair $	$size(TS) \cdot exp(\Phi) \cdot fair $	$size(TS) \cdot exp(\Phi) \cdot fair $
for fixed specifications	$O(size(TS))$	$O(size(TS))$	$O(size(TS))$
satisfiability check	EXPTIME	PSPACE-complete	2EXPTIME
best known technique upper bound	$O(exp(\Phi))$	$exp(\Phi)$	$exp(exp(\Phi))$

Syntax $\Phi ::= \text{true} \mid \overset{\text{AP}}{a} \mid \Phi \wedge \Phi \mid \neg \Phi \mid \exists \Psi$
 $\Psi ::= \Phi \mid \Psi \wedge \Psi \mid \neg \Psi \mid \bigcirc \Psi \mid \Psi \cup \Psi$

(CTL*-formulas)
 state formulas
 path formulas

defined: $\Diamond \Psi := \text{true} \cup \Psi$ $\forall \Psi := \neg \exists \neg \Psi$
 $\Box \Psi := \neg \Diamond \neg \Psi$

Example $\forall \Box (\bigcirc \Diamond a \wedge \neg (b \cup \Box c))$,
 $\forall \bigcirc \Box \neg a \wedge \exists \Diamond \Box (a \vee \forall (b \cup \neg a))$

not CTL-formulas

Semantics

For $a \in \text{AP}$ and $TS = \langle S, \text{Act}, \rightarrow, I, \text{AP}, L \rangle$ a transition system,
 and all $s \in S$:

$s \models a \iff a \in L(s)$
 $s \models \neg \Phi \iff \text{not } s \models \Phi$ (i.e. $s \not\models \Phi$)
 $s \models \Phi \wedge \Psi \iff (s \models \Phi) \text{ and } (s \models \Psi)$
 $s \models \exists \Psi \iff \pi \models \Psi \text{ for some } \pi \in \text{Paths}(s)$

} same as
 for
 CTL

For all paths π in S :

$\pi \models \Phi \iff \pi[0] \models \Phi$ } NEW for CTL*
 $\pi \models \Psi_1 \wedge \Psi_2 \iff \pi \models \Psi_1 \text{ and } \pi \models \Psi_2$ } same as
 $\pi \models \neg \Psi \iff \pi \not\models \Psi$ } for CTL+
 $\pi \models \bigcirc \Psi \iff \pi_{\geq 1} \models \Psi$ } same as for CTL
 $\pi \models \Psi_1 \cup \Psi_2 \iff \exists j \geq 0. (\pi_{\geq j} \models \Psi_2$
 $\wedge \forall 0 \leq k < j : \pi_{\geq k} \models \Psi_1)$

$\text{Sat}(\Phi) := \{s \in S \mid s \models \Phi\}$

$TS \models \Phi \iff \forall s_0 \in I : s_0 \models \Phi$

Embedding of LTL in CTL*

Thm. $TS = \langle S, \text{Act}, \rightarrow, I, \text{AP}, L \rangle$ a transition system without terminal states.

For every LTL-formula φ and for each $s \in S$:

$s \models \varphi$ \iff $s \models \forall \varphi$
 LTL-semantics CTL*-semantics

$TS \models \varphi$ \iff $TS \models \forall \varphi$
 CTL CTL*

Exercises from Last time

Ex 5.24(d) $\Phi := \Box a \cup \Diamond b \rightarrow \Box (a \cup \Diamond b)$ valid/satisfiable?

Φ is satisfiable: $\underbrace{\phi\phi\phi\dots}_{\phi^\omega \in (2AP)^\omega} \models \Phi$ because $\phi^\omega \models \Diamond b$
 $\phi^\omega \models \Box a \cup \Diamond b$
 hence $\phi^\omega \models \Box a \cup \Diamond b \rightarrow \dots$

Φ is not valid: $\sigma = \{b\}\phi\phi\dots \not\models \Phi$ because $\sigma = \{b\}\phi^\omega \models \Diamond b$
 $\sigma = \{b\}\phi^\omega \models \Box a \cup \Diamond b$
 $\sigma \not\models \Box (a \cup \Diamond b)$
 since $\sigma \not\models a$ and $\sigma \not\models \Diamond b$

Marokhi's argumentation: $\psi \cup \Diamond \Phi \equiv \Diamond \Phi$ for all Φ, ψ ! which is obviously not valid!
 Hence $(\Box a \cup \Diamond b \rightarrow \Box (a \cup \Diamond b)) \equiv \Diamond b \rightarrow \Box \Diamond b$

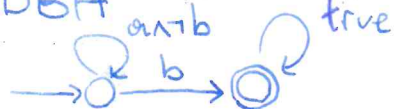
nondeterministic Büchi automaton

NBA for $a \cup b$ with 2 states

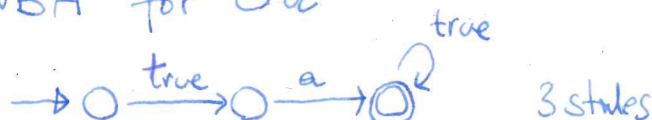


deterministic Büchi-automaton with

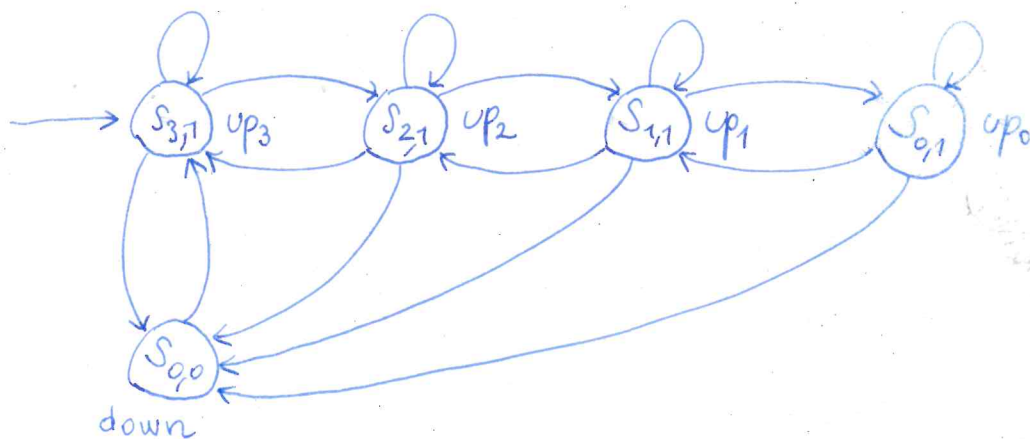
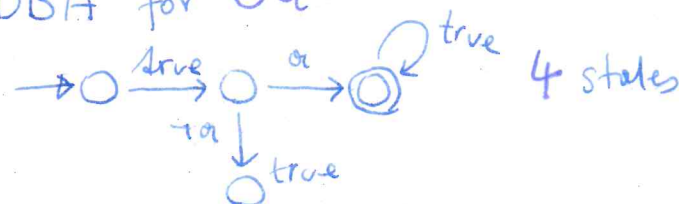
DBA $a \cup b$ 2 states



NBA for $\Box a$



DBA for $\Box a$



Possibly the system never goes down $\exists \Box \neg \text{down}$

Invariantly the system never goes down $\forall \Box \neg \text{down}$

It is always possible to start as new $\forall \Box \exists \Diamond \text{up}_3$

The system always eventually goes down
 and is operational until going down

$\forall ((\text{up}_3 \vee \text{up}_2) \cup \text{down})$

CTL Model Checking

CTL Model Checking Problem

Input: a transition system TS , and a CTL formula Φ
 Question: does $TS \models \Phi$ hold?

TS is assumed to be finite, with no terminal states.

Recall: $Sat(\Phi) := \{s \in S \mid s \models \Phi\}$... states of S in which Φ is satisfied.

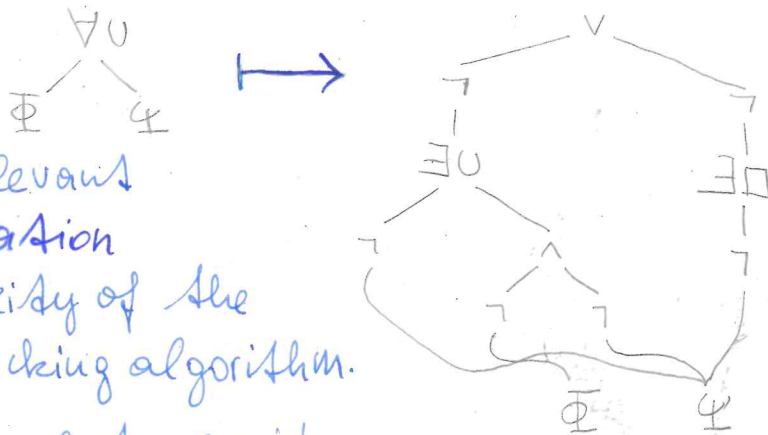
We will use CTL-formulas in ENF existential normal form

CTL-ENF $\Phi ::= \text{true} \mid a \mid \bigwedge_{Act} (\Phi_1 \wedge \Phi_2) \mid \neg \Phi \mid \exists \bigcirc \Phi \mid \exists (\Phi_1 \cup \Phi_2) \mid \exists \square \Phi$

Recall: every CTL-formula can be transformed into an equivalent CTL-ENF formula (although with an exponential overhead)

e.g. $\forall (\Phi \cup \Psi) \mapsto \neg \exists (\neg \Psi \cup (\neg \Phi \wedge \neg \Psi)) \vee \neg \exists \square \neg \Psi$
 (3 occurrences of Ψ)

This overhead could be avoided by using dag-representations of formulas.



The overhead is relevant for the determination of the complexity of the CTL-model checking algorithm.

A different approach to avoid the complexity increase due to this transformation, is to extend the CTL-model checking algorithm to deal also with formulas $\forall \bigcirc \Phi$, $\forall (\Phi \cup \Psi)$, and $\forall \square \Phi$.

Basic idea of the model-checking algorithm for CTL:

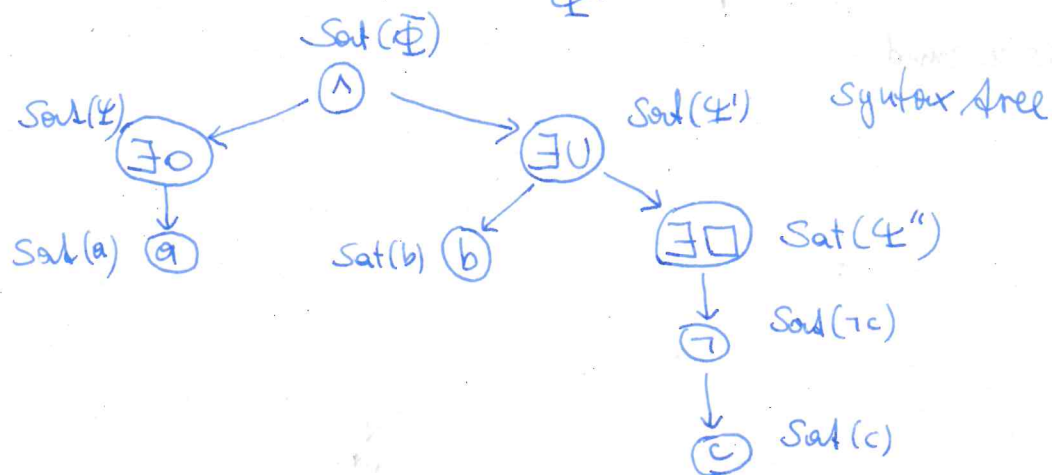
(i) Compute $Sat(\Phi)$ by induction on subformulas of Φ

(ii) ^{Then} $TS \models \Phi \iff \underbrace{I}_{\text{initial states of } \Phi} \subseteq Sat(\Phi)$

Example:

$AP = \{a, b, c\}$

$$\Phi = \underbrace{\exists o a}_{\Phi} \wedge \underbrace{\exists (b \vee \exists \square \neg c)}_{\Phi'}$$



we calculate the satisfaction sets $Sat(\tilde{\Phi})$ for all subformulas $\tilde{\Phi}$ of Φ by induction over the syntax tree

Characterization of $\text{Sat}(\cdot)$ for CTL formulae in ENF

Theorem. Let $TS = \langle S, Act, \rightarrow, I, AP, L \rangle$ be a transition system.
For all CTL-formulae Φ, Ψ over AP :

- (a) $\text{Sat}(\text{true}) = S$,
- (b) $\text{Sat}(a) = \{s \in S \mid a \in L(s)\}$ for all $a \in Act$.
- (c) $\text{Sat}(\Phi \wedge \Psi) = \text{Sat}(\Phi) \cap \text{Sat}(\Psi)$.
- (d) $\text{Sat}(\neg \Phi) = S \setminus \text{Sat}(\Phi)$
- (e) $\text{Sat}(\exists \bigcirc \Phi) = \{s \in S \mid \text{Post}(s) \cap \text{Sat}(\Phi) \neq \emptyset\}$
- (f) $\text{Sat}(\exists \Phi \cup \Psi) =$ the smallest subset $T \subseteq S$ such that
 - (i) $\text{Sat}(\Psi) \subseteq T$, and (ii) $s \in \text{Sat}(\Phi)$ and $\text{Post}(s) \cap T \neq \emptyset \Rightarrow s \in T$
- (g) $\text{Sat}(\exists \square \Phi) =$ the largest subset $T \subseteq S$ such that
 - (i) $T \subseteq \text{Sat}(\Phi)$, and (ii) $s \in T \Rightarrow \text{Post}(s) \cap T \neq \emptyset$.

Theorem. Time Complexity of CTL-model checking

For transition system TS with N states and K transitions,
and CTL-formula Φ , the CTL-model checking problem
 $TS \models \Phi$ can be determined in time $O((N+K) \cdot |\Phi|)$.

Derived characterizations for CTL-formulae of the forms
 $\forall \bigcirc \Phi$, $\forall \Phi \cup \Psi$, $\forall \square \Phi$:

- (h) $\text{Sat}(\forall \bigcirc \Phi) = \{s \in S \mid \text{Post}(s) \subseteq \text{Sat}(\Phi)\}$
- (i) $\text{Sat}(\forall \Phi \cup \Psi)$ is the smallest set $T \subseteq S$ such that
 $\text{Sat}(\Psi) \cup \{s \in \text{Sat}(\Phi) \mid \text{Post}(s) \subseteq T\} \subseteq T$
- (j) $\text{Sat}(\forall \square \Phi)$ is the largest set $T \subseteq S$ such that
 $T \subseteq \{s \in \text{Sat}(\Phi) \mid \text{Post}(s) \subseteq T\}$.

Alternative Formulation of $\text{Sat}(\exists\Phi\vee\psi)$ and $\text{Sat}(\exists\Box\psi)$

$$\exists\Phi\vee\psi \equiv \psi \vee (\Phi \wedge \exists\Box(\exists\Phi\vee\psi)).$$

Thus $\exists\Phi\vee\psi$ is a fixed point of:

$$F \equiv \psi \vee (\Phi \wedge \exists\Box(F)). \quad (*)$$

But also $\exists(\Phi\vee\psi)$ is a solution, but it is larger in the sense that $\text{Sat}(\exists\Box(\Phi\vee\psi)) \supseteq \text{Sat}(\exists\Box(\exists\Phi\vee\psi))$.

However: $\exists(\Phi\vee\psi)$ is the least solution of (*):

(f)' $\text{Sat}(\exists(\Phi\vee\psi))$ is the smallest set $T \subseteq S$ such that

$$\text{Sat}(\psi) \cup \{s \in \text{Sat}(\Phi) \mid \text{Post}(s) \cap T \neq \emptyset\} \subseteq T.$$

With μ -Calculus notation:

$$\exists(\Phi\vee\psi) \approx \underbrace{\mu F. (\psi \vee (\Phi \wedge \exists\Box F))}_{\mu\text{-Calculus notation.}}$$

Also:

$$\exists\Box\Phi \equiv \Phi \wedge \exists\Box(\exists\Box\Phi)$$

Hence $\exists\Box\Phi$ is a fixed point of

$$F \equiv \Phi \wedge \exists\Box F.$$

Indeed it is the Largest fixed point w.r.t. "measure" $\text{Sat}(\cdot)$.

(g)' $\text{Sat}(\exists\Box\Phi)$ is the Largest set $T \subseteq S$ such that

$$T \subseteq \{\Phi\} \cup \{s \in \text{Sat}(\Phi) \mid \text{Post}(s) \cap T \neq \emptyset\}.$$

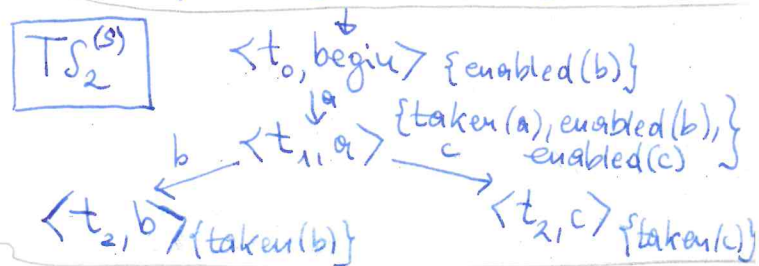
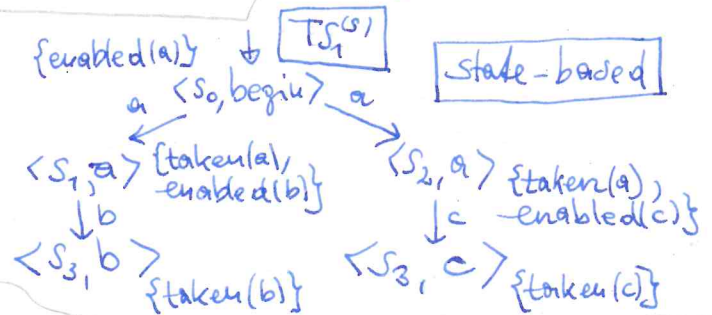
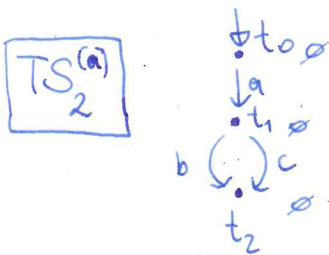
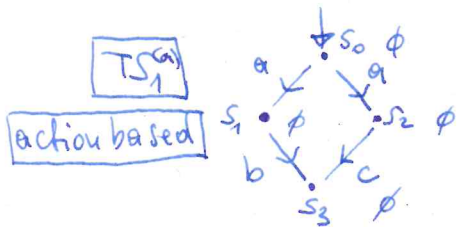
With μ -Calculus notation:

$$\exists\Box\Phi \approx \underbrace{\nu F. (\Phi \wedge \exists\Box F)}_{\mu\text{-Calculus notation.}}$$

MOTIVATION for CTL (Shortcoming of LTL)

CTL permits finer distinctions between transition systems:

- ① LTL-satisfiability of formulas ^{in a TS} does not distinguish between trace-equivalent systems.
- ② CTL-satisfiability ^{in a TS} does not distinguish between bisimilar systems.
(bisimilarity is a finer equivalence than trace equivalence).



TS₁^(s) and TS₂^(s) have the same traces!

⇒ they satisfy the same formulas (due to ①)

Hence: "After taken a-step, always a b-step is enabled" is not expressible ^{correctly}.

Attempt: $\Box (\text{taken}(a) \rightarrow \text{enabled}(b)) =: \Phi$

Yet: TS₁^(s) $\not\models \Phi$, and TS₂^(s) $\not\models \Phi$, because: $s_0, s_2, s_3 \not\models \Phi$, $t_0, t_1, t_2 \not\models \Phi$

However CTL can make a distinction between TS₁ and TS₂.

$\Phi := \forall \Box (\text{taken}(a) \rightarrow \text{enabled}(b))$

"On all paths, after taking an a-step, a b-step is possible"

TS₁^(s) $\not\models \Phi$, but TS₂^(s) $\models \Phi$.

We note that TS₁ and TS₂ are not bisimilar. (Hence ② is not applicable.)

if TS₁, TS₂ image-finite

