### Lecture 3: Algorithmic Meta-Theorems

(A Short Introduction to Parameterized Complexity)

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### Course overview

Monday, June 10 10.30 – 12.30	Tuesday, June 11	Wednesday, June 12 10.30 – 12.30	Thursday, June 13	Friday, June 14
Introduction & basic FPT results		Algorithmic Meta-Theorems		
motivation for FPT kernelization, Crown Lemma, Sunflower Lemma	GDA	1st-order logic, monadic 2nd-order logic, FPT-results by Courcelle's Theorems for tree and clique-width	GDA	GDA
Algorithmic Techniques		Formal-Method & Algorithmic Techniques		
	14.30 – 16.30 Notions of bounded graph width			14.30 – 16.30  FPT-Intractability  Classes & Hierarchies
	path-, tree-, clique width, FPT-results by dynamic programming, transferring FPT results betw. widths	GDA	GDA	motivation for FP-intractability results, FPT-reductions, class XP (slicewise polynomial), W- and A-Hierarchies, placing problems on these hierarchies

### Overview

- logic preliminaries
  - first-order logic
    - expressing graph problems by f-o formulas
  - monadic second-order logic (MSO)
    - expressing graph problems by MSO formulas
  - complexity of evaluation and model checking problems
- Courcelle's theorem
  - FPT-results by model-checking MSO-formulas
    - for graphs / structures with bounded tree-width
    - for maximization problems over graphs of bounded tree-width
    - for graphs of bounded clique-width
  - applications to concrete problems
- graph minors
- meta-theorems for first-order model-checking: an example

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## Meta-theorems: idea, benefits and limitations

#### idea:

- express a problem P by a logical formula  $\varphi_P$  (of 'short' size)
- use model checking of  $\varphi_P$  on logical structures of bounded width k (tree-, clique-width, ...)
  - is time bounded depending on k, size of  $\varphi_P$ , size of the structure
  - this often facilitates FPT-results

#### benefits:

- a quick and easy way to show that [some problems] are fixed-parameter tractable,
- without working out the tedious details of a dynamic programming algorithm.

#### limitations:

- algorithms obtained by meta-theorems cannot be expected to be optimal.
- a careful analysis of a specific problem at hand will usually yield more efficient fpt-algorithms

# Logical preliminaries

## First-order logic (formula example)

$$\varphi_{3} := \exists x_{1} \exists x_{2} \exists x_{3} \left( \neg(x_{1} = x_{2}) \land \neg E(x_{1}, x_{2}) \land \neg(x_{1} = x_{3}) \land \neg E(x_{1}, x_{3}) \land \neg(x_{2} = x_{3}) \land \neg E(x_{2}, x_{3}) \right)$$

 $A(G) \models \varphi_3 \iff G$  has a 3-element independent set.

$$\varphi_{\mathbf{k}} := \exists x_1 \dots \exists x_{\mathbf{k}} \Big( \bigwedge_{1 \le i < j \le \mathbf{k}} (\neg (x_i = x_j) \land \neg E(x_i, x_j)) \Big)$$

 $\mathcal{A}(\mathcal{G}) \vDash \varphi_k \iff \mathcal{G} \text{ has a } k\text{-element independent set.}$ 

$$S \subseteq V$$
 is independent set in  $\mathcal{G} = \langle V, E \rangle$ :  $\iff \forall e = \{u, v\} \in E \ (\neg(u \in S \land v \in S))$   $\iff \forall u, v \in S \ (u \neq v \Rightarrow \{u, v\} \notin E)$ 

# First-order logic: syntax (language)

- language based on:
  - a vocabulary  $\tau = \{R_1, \dots, R_n\}$  of predicate symbols  $R_i$  together with arity  $ar(R_i) \in \mathbb{N}$
  - the binary equality predication =
  - (first-order) variable symbols:  $x, y, z, w, x_1, y_1, z_1, w_1, x_2, \dots$
  - propositional connectives: ∧, ∨, ¬, →, ↔
  - ▶ existential quantifier ∃, universal quantifier ∀
- ▶ atomic formulas (atoms): a formula x = y or  $R(x_1 ... x_n)$  for  $R \in \tau$
- quantifier-free formula: atoms, literals (= negated atoms), formulas built up from atoms by using propositional connectives
- quantifications over (first-order variables):
  - existential quantifications  $\exists x$  and universal quantifications  $\forall x$
- formulas:

$$\varphi ::= x = y \mid R(x_1, \dots, x_{ar(R)}) \quad \text{(where } R \in \tau)$$
$$\mid \neg \varphi \mid \varphi_1 \land \varphi_2 \mid \varphi_1 \lor \varphi_2 \mid \varphi_1 \to \varphi_2 \mid \varphi_1 \leftrightarrow \varphi_2$$
$$\mid \exists x \varphi \mid \forall x \varphi$$

sentences: formulas without free variables.

## First-order logic: semantics (structures)

#### Definition

Let  $\tau = \{R_1, \dots, R_n\}$  be a vocabulary.

A  $\tau$ -structure is a tuple  $\mathcal{A} = \langle A; R_1^{\mathcal{A}}, \dots R_n^{\mathcal{A}} \rangle$  consisting of:

- $\blacktriangleright$  the *universe* A,
- ▶ interpretations  $R_i^A \subseteq A^{ar(R_i)} = \overbrace{A \times \ldots \times A}$  for each of the relation symbols  $R_i$  in  $\tau$ , where  $i \in \{1, \ldots, n\}$ .

### Examples

Let  $\tau_G = \{E/2\}$  vocabulary with binary edge relation.

The *standard structure* for a graph  $\mathcal{G} = \langle V, E \rangle$ :

$$\mathcal{A}_{\tau_{\mathbf{G}}}(\mathcal{G}) \coloneqq \langle V; E^{\mathsf{symm}} \rangle$$
.

### Example

Let  $\tau_{HG} = \{VERT/1, EDGE/1, INC/2\}$  vocabulary (for hypergraphs). The *hypergraph structure* for a graph  $\mathcal{G} = \langle V, E \rangle$ :

$$\mathcal{A}_{\mathsf{THO}}(\mathcal{G}) \coloneqq \langle V \cup E; V, E, \{\langle v, e \rangle \mid v \in V, e \in E, v \in e \} \rangle.$$

## Interpretation of first-order formulas in structures

Let  $\mathcal{A} = \langle A; \{R^{\mathcal{A}}\}_{R \in \tau} \rangle$  be a  $\tau$ -structure. For a  $\tau$ -formula  $\varphi(x_1, \dots, x_k)$  its interpretation  $\varphi(\mathcal{A}) \subseteq A^k$  in  $\mathcal{A}$  is defined by:

- ▶ If  $\varphi(x_1, \dots, x_k) \equiv R(x_{i_1}, \dots, x_{i_r})$  with  $i_1, \dots, i_r \in [k]$ , then:  $\varphi(\mathcal{A}) \coloneqq \left\{ (a_1, \dots, a_k) \in A^k \mid (a_{i_1}, \dots, a_{i_k}) \in R^{\mathcal{A}} \right\}$
- $\text{If } \varphi(\boldsymbol{x}_1,\ldots,\boldsymbol{x}_k) \equiv \varphi_1(\boldsymbol{x}_{i_1},\ldots,\boldsymbol{x}_{i_l}) \land \varphi_2(\boldsymbol{x}_{j_1},\ldots,\boldsymbol{x}_{j_m}) \text{ with } \\ i_1,\ldots,i_l,j_1,\ldots,j_m \in [k], \text{ then:}$

$$\varphi(\mathcal{A}) \coloneqq \left\{ (a_1, \dots, a_k) \in A^k \mid (a_{i_1}, \dots, a_{i_l}) \in \varphi_1(\mathcal{A}) \right\}$$
$$\cap \left\{ (a_1, \dots, a_k) \in A^k \mid (a_{j_1}, \dots, a_{j_m}) \in \varphi_2(\mathcal{A}) \right\}$$

- ▶ If  $\varphi(x_1, \dots, x_k) \equiv \exists x_{k+1} \varphi_0(x_{i_1}, \dots, x_{i_\ell})$  with  $i_1, \dots, i_\ell \in [k+1]$ , then:  $\varphi(\mathcal{A}) \coloneqq \left\{ \langle a_1, \dots, a_k \rangle \in A^k \middle| \text{ there exists } a_{k+1} \in A \right.$ such that  $\langle a_{i_1}, \dots, a_{i_\ell} \rangle \in \varphi_0(\mathcal{A}) \right\}$ 
  - ightharpoonup igh
  - ▶ For a sentence  $\varphi$ ,  $\mathcal{A} \models \varphi$  will mean  $\varphi(\mathcal{A}) \neq \emptyset$  (then  $\varphi(\mathcal{A}) = \{\langle \rangle \}$ ).

# Expressing graph properties by first-order formulas

#### Exercise

For given formulas  $\varphi(x)$  and for all  $k \in \mathbb{N}$ ,  $k \ge 1$  define formulas  $\exists^{\ge k} x \, \varphi(x)$ ,  $\exists^{< k} x \, \varphi(x)$ ,  $\exists^{=k} x \, \varphi(x)$ , such that in a given  $\tau$ -structure  $\mathcal{A} = \langle A; \{R^{\mathcal{A}}\}_{Per} \rangle$ :

$$\mathcal{A} \vDash \exists^{\geq k} x \, \varphi(x) \iff |\{a \in A \mid \mathcal{A} \vDash \varphi(a)\}| \geq k$$

$$\mathcal{A} \vDash \exists^{< k} x \, \varphi(x) \iff |\{a \in A \mid \mathcal{A} \vDash \varphi(a)\}| < k$$

$$\mathcal{A} \vDash \exists^{= k} x \, \varphi(x) \iff |\{a \in A \mid \mathcal{A} \vDash \varphi(a)\}| = k$$

# Expressing graph properties by first-order formulas

#### Exercise

Express by a first-order formula with the vocabulary  $\tau_G = \{E/2\}$  for graphs that:

- (i) a graph  $\mathcal{G}$  contains a clique with precisely k elements,
- (ii) a graph  $\mathcal{G}$  has a dominating set with less or equal to k elements,
- (iii) a graph  $\mathcal{G}$  has a dominating set with precisely k elements,

#### Recall:

$$\varphi_{\mathbf{k}} := \exists x_1 \dots \exists x_{\mathbf{k}} \Big( \bigwedge_{1 \le i \le j \le \mathbf{k}} (\neg (x_i = y_i) \land \neg E(x_i, x_j)) \Big)$$

$$\mathcal{A}_{\tau_{G}}(\mathcal{G}) \models \varphi_{k} \iff \mathcal{G} \text{ has a } k\text{-element independent set.}$$

# Expressing graph properties by first-order formulas

#### Exercise

Express by a first-order formula with the vocabulary with vocabulary  $\tau_{HG} = \{ VERT/_1, EDGE/_1, INC/_2 \}$  for hypergraphs that:

- (i) a graph  $\mathcal{G}$  contains a clique with precisely k elements,
- (ii) a graph  $\mathcal{G}$  has a dominating set with less or equal to k elements,
- (iii) a graph  $\mathcal{G}$  has a dominating set with precisely k elements.

# Evaluation and model checking (first-order logic)

Let  $\Phi$  be a class of first-order formulas.

The *evaluation problem* for  $\Phi$ :

### $\mathsf{EVAL}(\Phi)$

**Instance:** A structure A and a formula  $\varphi \in \Phi$ .

**Problem:** Compute  $\varphi(A)$ .

### The *model checking problem* for $\Phi$ :

### $MC(\Phi)$

**Instance:** A structure  $\mathcal{A}$  and a formula  $\varphi \in \Phi$ .

**Problem:** Decide whether  $A \models \varphi$  (that is,  $\varphi(A) \neq \emptyset$ ).

*Width* of formula  $\varphi$ : maximal number of free variables in a subformula of  $\varphi$ .

#### Theorem

EVAL(FO) and MC(FO) can be solved in time  $O(|\varphi| \cdot |A|^w \cdot w)$ , where w is the width of the input formula  $\varphi$ .

## Monadic second-order logic (formula example)

$$\psi_{3} := \exists C_{1} \exists C_{2} \exists C_{3} \left( \left( \forall x \left( \bigvee_{i=1}^{3} C_{i}(x) \right) \right) \land \forall x \left( \bigwedge_{1 \leq i < j \leq 3} \neg \left( C_{i}(x) \land C_{j}(x) \right) \right) \right)$$

$$\land \forall x \forall y \left( E(x, y) \rightarrow \bigwedge_{i=1}^{3} \neg \left( C_{i}(x) \land C_{i}(y) \right) \right) \right)$$

$$\equiv \exists C_{1} \exists C_{2} \exists C_{3} \left( \forall x \left( C_{1}(x) \lor C_{2}(x) \lor C_{3}(x) \right) \right)$$

$$\land \forall x \left( \neg \left( C_{1}(x) \land C_{2}(x) \right) \land \neg \left( C_{1}(x) \land C_{3}(x) \right) \right)$$

$$\land \forall x \forall y \left( E(x, y) \rightarrow \neg \left( C_{1}(x) \land C_{1}(y) \right) \right)$$

$$\land \neg \left( C_{2}(x) \land C_{2}(y) \right)$$

$$\land \neg \left( C_{3}(x) \land C_{3}(y) \right) \right) \right)$$

$$\mathcal{A}(\mathcal{G}) \models \psi_3 \iff \mathcal{G} \text{ has is } 3\text{-colorable}.$$

# Monadic second-order logic

- language based on:
  - a vocabulary  $\tau = \{R_1, \dots, R_n\}$  of predicate symbols  $R_i$  together with arity  $ar(R_i) \in \mathbb{N}$
  - the binary equality predication =
  - first-order variable symbols:  $x, y, z, w, x_1, y_1, z_1, w_1, x_2, \dots$
  - monadic second-order variable symbols (symbolizing variables for unary predicate symbols): X, Y, Z, W, X<sub>1</sub>, Y<sub>1</sub>, Z<sub>1</sub>, W<sub>1</sub>, X<sub>1</sub>,...,
  - propositional connectives: ∧, ∨, ¬, →, ↔
  - existential quantifier ∃, universal quantifier ∀
- ▶ atomic formulas (atoms):  $x = y \mid R(x_1 ... x_n) \mid X(x)$  (for  $R \in \tau$ )
- quantifications:
  - first-order existential quantificiations  $\exists x$  and universal quant.  $\forall x$
  - ▶ second-order existential quantific.  $\exists X$  and universal quantif.  $\forall X$
- formulas:

$$\varphi ::= x = y \mid \frac{R}{R}(x_1, \dots, x_{\mathsf{af}(R)}) \mid \frac{X}{X}(x)$$

$$\mid \neg \varphi \mid \varphi_1 \land \varphi_2 \mid \varphi_1 \lor \varphi_2 \mid \varphi_1 \to \varphi_2 \mid \varphi_1 \leftrightarrow \varphi_2$$

$$\mid \exists x \varphi \mid \forall x \varphi \mid \exists \frac{X}{Y} \varphi \mid \forall X \varphi$$

## Interpretation of MSO-formulas in first-order structures

Let  $\mathcal{A} = \langle A; \left\{ R^{\mathcal{A}} \right\}_{R \in \mathbf{\tau}} \rangle$  be a  $\mathbf{\tau}$ -structure. For a MSO( $\mathbf{\tau}$ )-formula  $\varphi(\mathbf{x}_1, \dots, \mathbf{x}_k, \mathbf{X}_1, \dots, \mathbf{X}_\ell)$  its *interpretation*  $\varphi(\mathcal{A}) \subseteq A^k \times \mathcal{P}(A)^\ell$  in  $\mathcal{A}$  is defined by:

- similar clauses as before, plus:
- ▶ If  $\varphi(x_1, \dots, x_k, X_1, \dots, X_\ell) \equiv X_i(x_j)$  with  $i \in [k]$  and  $j \in [\ell]$ , then:  $\varphi(\mathcal{A}) \coloneqq \left\{ (a_1, \dots, a_k, P_1, \dots, P_\ell) \in A^k \times \mathcal{P}(A)^\ell \mid a_j \in P_i \right\}$
- $\begin{array}{l} \blacktriangleright \ \ \text{If} \ \varphi(\boldsymbol{x}_1,\ldots,\boldsymbol{x}_k,\boldsymbol{X}_1,\ldots,\boldsymbol{X}_\ell) \equiv \exists \boldsymbol{X}_{k+1}\varphi_0(\boldsymbol{x}_{i_1},\ldots,\boldsymbol{x}_{i_{k'}},\boldsymbol{X}_{j_1},\ldots,\boldsymbol{X}_{j_{\ell'}}) \\ \text{with} \ i_1,\ldots,i_{k'} \in [k], \ \text{and} \ j_1,\ldots,j_{\ell'} \in [\ell+1] \ \text{then:} \end{array}$

$$\begin{split} \varphi(\mathcal{A}) \coloneqq \big\{ \langle a_1, \dots, a_k, P_1, \dots, P_\ell \rangle \in A^k \times \mathcal{P}(A)^\ell \big| \\ & \text{there exists } P_{\ell+1} \in \mathcal{P}(A) \text{ such that } \\ & \left\langle a_{i_1}, \dots, a_{i_{k'}}, P_{j_1}, \dots, P_{j_{\ell'}} \right\rangle \in \varphi_0(\mathcal{A}) \big\} \end{split}$$

- $\mathcal{A} \vDash \varphi(a_1, \dots, a_k, P_1, \dots, P_\ell)$ will mean:  $\langle a_1, \dots, a_k, P_1, \dots, P_\ell \rangle \in \varphi(\mathcal{A})$ .
- ▶ For a sentence  $\varphi$ ,  $\mathcal{A} \models \varphi$  will mean  $\varphi(\mathcal{A}) \neq \emptyset$  (then  $\varphi(\mathcal{A}) = \{(\})\}$ ).

## Monadic second-order logic (formula example)

$$\psi_{3} := \exists C_{1} \exists C_{2} \exists C_{3} \left( \left( \forall x \left( \bigvee_{i=1}^{3} C_{i}(x) \right) \right) \land \forall x \left( \bigwedge_{1 \leq i < j \leq 3} \neg \left( C_{i}(x) \land C_{j}(x) \right) \right) \right)$$

$$\land \forall x \forall y \left( E(x, y) \rightarrow \bigwedge_{i=1}^{3} \neg \left( C_{i}(x) \land C_{i}(y) \right) \right) \right)$$

$$\equiv \exists C_{1} \exists C_{2} \exists C_{3} \left( \forall x \left( C_{1}(x) \lor C_{2}(x) \lor C_{3}(x) \right) \right)$$

$$\land \forall x \left( \neg \left( C_{1}(x) \land C_{2}(x) \right) \land \neg \left( C_{1}(x) \land C_{3}(x) \right) \right)$$

$$\land \forall x \forall y \left( E(x, y) \rightarrow \neg \left( C_{1}(x) \land C_{1}(y) \right) \right)$$

$$\land \neg \left( C_{2}(x) \land C_{2}(y) \right)$$

$$\land \neg \left( C_{3}(x) \land C_{3}(y) \right) \right) \right)$$

$$\mathcal{A}(\mathcal{G}) \models \psi_3 \iff \mathcal{G} \text{ has is } 3\text{-colorable}.$$

# Expressing graph properties by MSO formulas (1)

#### Exercise

Express by a monadic second-order formula  $\varphi(X)$  with one free unary predicate variable X over the vocabulary  $\tau_{\mathbf{G}} = \{E/2\}$  for graphs that for all graphs  $\mathcal{G} = \langle V, E \rangle$ :

$$\mathcal{A}_{\tau_{\mathsf{G}}}(\mathcal{G}) \vDash \varphi(S) \iff S \subseteq V \text{ is an independent set in } \mathcal{G}$$

#### Recall:

$$S \subseteq V$$
 is independent set in  $\mathcal{G}$ :  $\iff \forall e = \{u, v\} \in E \ (\neg(u \in S \land v \in S))$   
 $\iff \forall u, v \in S(\ u \neq v \Rightarrow \{u, v\} \notin E)$ 

#### Exercise

Express the independent set property by a  $MSO(\tau_{HG})$  formula  $\psi$  with vocabulary  $\tau_{HG} = \{VERT/_1, EDGE/_1, INC/_2\}$  for hypergraphs:

$$\mathcal{A}_{\mathsf{THG}}(\mathcal{G}) \vDash \psi(S) \iff S \subseteq V \text{ is an independent set in } \mathcal{G}$$

# Expressing graph properties by MSO formulas (2)

#### Exercise

Express by a monadic second-order formula feedback(X) with one free unary predicate variable X over  $\tau_{HG} = \{VERT/_1, EDGE/_1, INC/_2\}$ , the vocabulary for graphs, that for all hypergraphs  $\mathcal{G} = \langle V, E \rangle$ :

$$\mathcal{A}_{\tau_{\mathsf{HG}}}(\mathcal{G}) \vDash \mathit{feedback}(S) \iff S \subseteq V \text{ is a feedback vertex set}$$

(A set  $S \subseteq V$  is a feedback vertex set in  $\mathcal{G}$  if S contains a vertex of every cycle of  $\mathcal{G}$ .)

### Steps:

- Construct a formula cycle-family(X) that expresses the property of a set being the union of cycles.
- ▶ Using *cycle-family*(X), construct *feedback*(X).

# MSO for graphs and hypergraphs

- MSO(τ<sub>G</sub>): MSO with vocabulary τ<sub>G</sub> = {E/₂}
   MSO(τ<sub>HG</sub>): MSO with vocab. τ<sub>HG</sub> = {VERT/₁, EDGE/₁, INC/₂}
   MSO₁:
   vocabulary: {INC/₂}
- ► MSO<sub>2</sub>:
  - vocabulary: { INC/2}
  - quantifications:  $\exists_{(\text{vert})} x / \forall_{(\text{vert})} x$ ,  $\exists_{(\text{edge})} x / \forall_{(\text{edge})} x$ ,  $\exists_{(\text{vert})} X / \forall_{(\text{vert})} X$ ,  $\exists_{(\text{edge})} X / \forall_{(\text{edge})} X$

• quantifications:  $\exists_{(\text{vert})} x / \forall_{(\text{vert})} x$ ,  $\exists_{(\text{edge})} x / \forall_{(\text{edge})} x$ ,  $\exists_{(\text{vert})} X / \forall_{(\text{vert})} X$ 

### Correspondences

```
MSO(\tau_G) corresponds to MSO_1

MSO(\tau_{HG}) corresponds to MSO_2
```

where 'corresponds to' means: 'is equally expressive as'.

#### Note:

We use MSO for either logic, restrict to  $MSO(\tau_G)$  /  $MSO_1$  if needed.

# Expressing graph properties by MSO formulas (5)

#### Exercise

Express by a  $\mathsf{MSO}(\tau_{\mathsf{HG}})$  formula  $\mathit{conn}(X)$  with one free unary predicate variable X over  $\tau_{\mathsf{HG}} = \{\mathit{VERT/1}, \mathit{EDGE/1}, \mathit{INC/2}\}$ , the vocabulary for graphs, that for all hypergraphs  $\mathcal{G} = \langle V, E \rangle$ :

 $\mathcal{A}_{\tau_{\mathsf{HG}}}(\mathcal{G}) \vDash \mathit{hamiltonian} \iff \mathsf{there} \; \mathsf{is} \; \mathsf{a} \; \mathsf{Hamiltonian} \; \mathsf{path} \; \mathsf{in} \; \mathcal{G}.$ 

#### Note:

- ▶ This property is not expressible by a (single)  $MSO(\tau_G)$  formula.
- ▶ Other property that are not  $MSO(\tau_G)$  expressible:
  - balanced bipartite graphs
  - existence of a perfect matching
  - simple graphs
  - existence of spanning trees with maximum degree 3

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# Expressing graph properties by MSO formulas (5)

#### Exercise

 $A_{\tau_{HG}}(\mathcal{G}) \models hamiltonian \iff \text{there is a Hamiltonian path in } \mathcal{G}.$ 

# Evaluation and model checking (MSO)

The *model checking problem* for MSO-formulas on labeled, ordered unranked trees:

```
MC(MSO, TREE_{lo})
```

**Instance:** A labeled, ordered, unranked  $\Sigma$ -tree  $\mathcal{T}$ ,

and a MSO( $\tau_{\Sigma}^{u}$ )-formula  $\varphi$ 

**Problem:** Decide whether  $\mathcal{T} \models \varphi$ .

where for given alphabet  $\Sigma$ ,  $\tau_{\Sigma}^{u} := \{E/2, N/2\} \cup \{P_a/1 \mid a \in \Sigma\}.$ 

#### **Theorem**

 $MC(MSO, TREE_{lo}) \in FPT$ .

More precisely, there is a computable function  $f: \mathbb{N} \to \mathbb{N}$  such that  $MC(MSO, TREE_{lo})$  can be decided in time  $\leq O(f(|\varphi|) + ||\mathcal{T}||)$ .

Note that here:  $f(k) \ge 2^{-\frac{k^2}{2}} k$  (a non-elementary function).

### Courcelle's Theorem

## Courcelle's Theorem for graphs

```
p^*-tw-MC(MSO)
```

**Instance:** A graph  $\mathcal{G}$  and an MSO( $\tau_{HG}$ )-sentence  $\varphi$ .

**Parameter:**  $tw(\mathcal{G}) + |\varphi|$  (where  $tw(\mathcal{G})$  the tree-width of  $\mathcal{G}$ )

**Problem:** Decide whether  $A(\mathcal{G}) \models \varphi$ .

### Theorem (special case of Courcelle's Theorem)

 $p^*$ -tw-MC(MSO)  $\in$  FPT. More precisely, the problem is decidable, for some computable and non-decreasing function  $f: \mathbb{N} \times \mathbb{N} \to \mathbb{N}$  by an algorithm in time:

```
f(k_1, k_2) \cdot n, where k_1 := tw(\mathcal{A}), k_2 := |\varphi|, n := |V(\mathcal{G})|
```

# Courcelle's Theorem: applications (1)

 $p^*$ -tw-Colorability  $\in FPT$ 

**Instance:** A graph  $\mathcal{G}$  and  $\ell \in \mathbb{N}$ .

Parameter: tw(C)

**Problem:** Decide whether is  $\mathcal{G}$   $\ell$ -colorable.

### Example

- ▶  $p^*$ -tw-3-Colorability  $\in$  FPT.
- ▶  $p^*$ -tw-Colorability  $\in$  FPT.

# Courcelle's Theorem: applications (2)

*p\*-tw*-Hamiltonicity

Instance: A graph  $\mathcal{G}$  Parameter:  $tw(\mathcal{C})$ 

**Problem:** Decide whether G is a hamiltonian (that is, contains

a cyclic path that visits every vertex precisely once).

### Example

 $p^*$ -tw-Hamiltonicity  $\in$  FPT.

## Tree decompositions, and tree-width for graphs

### Definition (recalling tree-width for graphs)

A *tree decomposition* of a graph  $\mathcal{G} = \langle V, E \rangle$  is a pair  $\langle \mathcal{T}, \{B_t\}_{t \in T} \rangle$  where  $\mathcal{T} = \langle T, F \rangle$  a (undirected, unrooted) tree, and  $B_t \subseteq V$  for all  $t \in T$  such that:

- (T1)  $A = \bigcup_{t \in T} B_t$  (every vertex of  $\mathcal{G}$  is in some bag).
- (T2)  $(\forall \{u,v\} \in E) (\exists t \in T) [\{u,v\} \subseteq B_t]$ (the vertices of every edge of  $\mathcal{G}$  are realized in some bag).
- (T3)  $(\forall v \in V)$  [subgraph of  $\mathcal{T}$  defd. by  $\{t \in T \mid v \in B_t\}$  is connected] (the tree vertices (in  $\mathcal{T}$ ) whose bags contain some vertex of  $\mathcal{G}$  induce a subgraph of  $\mathcal{T}$  that is connected).

The *width* of a tree dec.  $\langle \mathcal{T}, \{B_t\}_{t \in T} \rangle$  is  $\max\{|B_t| - 1 \mid t \in T\}$ .

The *tree-width tw*( $\mathcal{A}$ ) of a  $\tau$ -structure  $\mathcal{A}$  is defined by:

tw(A) := minimal width of a tree decomposition of A.

## Tree decompositions, and tree-width for structures

### Definition (extension of tree-width to structures)

A tree decomposition of a  $\tau$ -structure  $\mathcal{A} = \langle A; \left\{ R^{\mathcal{A}} \right\}_{R \in \tau} \rangle$  is a pair  $\langle \mathcal{T}, \left\{ B_t \right\}_{t \in T} \rangle$  where  $\mathcal{T} = \langle T, F \rangle$  a (undirected, unrooted) tree, and  $B_t \subseteq V$  for all  $t \in T$  such that:

- (T1)  $A = \bigcup_{t \in T} B_t$  (every element of the universe of A is in some bag).
- (T2)  $(\forall R \in \tau) (\forall (a_1, \dots, a_r) \in R^A) (\exists t \in T) [\{a_1, \dots, a_r\} \subseteq B_t]$  (the vertices of every 'hyperedge' in  $R^A$  are realized in some bag).
- (T3)  $(\forall v \in V)$  [ subgraph of  $\mathcal{T}$  defd. by  $\{t \in T \mid v \in B_t\}$  is connected ] (the tree vertices (in  $\mathcal{T}$ ) whose bags contain some vertex of  $\mathcal{G}$  induce a subgraph of  $\mathcal{T}$  that is connected).

The *width* of a tree dec.  $\langle \mathcal{T}, \{B_t\}_{t \in T} \rangle$  is  $\max \{|B_t| - 1 \mid t \in T\}$ .

The *tree-width tw*( $\mathcal{A}$ ) of a  $\tau$ -structure  $\mathcal{A}$  is defined by:

tw(A) := minimal width of a tree decomposition of A.

### Courcelle's Theorem

### $p^*$ -tw-MC(MSO)

**Instance:** A structure  $\mathcal{A}$  and an MSO-sentence  $\varphi$ .

Parameter:  $tw(A) + |\varphi|$ .

**Problem:** Decide whether  $A \models \varphi$ .

### Theorem ([Courcelle, 1990])

 $p^*$ -tw-MC(MSO)  $\in$  FPT. More precisely, the problem is decidable by an algorithm in time:

 $f(k_1, k_2) \cdot |A| + O(\|A\|)$ , where  $k_1 := tw(A)$ , and  $k_2 := |\varphi|$ , f computable and non-decreasing

$$\begin{split} f(k_1,k_2)\cdot|A| + O(\|\mathcal{A}\|) &\leq f(k_1,k_2)\cdot|A| + c\cdot\|\mathcal{A}\| &\quad \text{with some } c > 0 \\ &\leq (f(k_1,k_2)+c)\cdot\|\mathcal{A}\| \\ &\leq g(k)\cdot(\|\mathcal{A}\|+|\varphi|) &\quad \text{for } g(x)\coloneqq f(x,x)+c \\ &\quad k\coloneqq k_1+k_2 \\ &\leq g(k)\cdot n &\quad \text{where } n\coloneqq \|\mathcal{A}\|+|\varphi| \end{split}$$

# Vertex Cover (first attempt)

```
Let \mathcal{G} = \langle V, E \rangle a graph. For all S \subseteq V:
 S is a vertex cover of \mathcal{G} : \iff \forall e = \{u, v\} \in E \ (u \in S \lor v \in S))
```

```
p*-tw-VERTEX-COVER
```

**Instance:** A graph  $\mathcal{G} = \langle V, E \rangle$ , and  $\ell \in \mathbb{N}$ .

Instance:  $tw(\mathcal{G})$ .

**Problem:** Does  $\mathcal{G}$  have a vertex cover of size at most  $\ell$ ?

### Courcelle's Theorem: Refinement 1

#### Refinement 1 of Courcelle's Theorem

 $p^*$ -tw-MC $\leq$ (MSO)  $\in$  FPT. More precisely, the problem is decidable by an algorithm in time:

```
f(k_1, k_2) \cdot |A| + O(\|A\|), where k_1 := tw(A), and k_2 := |\varphi|, f computable and non-decreasing
```

### Vertex Cover

```
Let \mathcal{G} = \langle V, E \rangle a graph. For all S \subseteq V:
 S is a vertex cover of \mathcal{G} : \iff \forall e = \{u, v\} \in E \ (u \in S \lor v \in S))
```

p\*-tw-VERTEX-COVER

**Instance:** A graph  $\mathcal{G} = \langle V, E \rangle$ , and  $\ell \in \mathbb{N}$ .

Instance:  $tw(\mathcal{G})$ .

**Problem:** Does  $\mathcal{G}$  have a vertex cover of size at most  $\ell$ ?

### Example

 $p^*$ -tw-Vertex-Cover  $\in$  FPT.

### Vertex Cover

```
Let \mathcal{G} = \langle V, E \rangle a graph. For all S \subseteq V:
 S is a vertex cover of \mathcal{G} :\iff \forall e = \{u, v\} \in E \ (u \in S \lor v \in S))
```

#### p\*-tw-VERTEX-COVER

**Instance:** A graph  $\mathcal{G} = \langle V, E \rangle$ , and  $\ell \in \mathbb{N}$ .

Instance: tw(G).

**Problem:** Does  $\mathcal{G}$  have a vertex cover of size at most  $\ell$ ?

#### Example

p\*-tw-Vertex-Cover  $\in$  FPT.

### Courcelle's Theorem: Refinement 2

```
p^*-tw-MC^=(MSO)
```

**Instance:** A structure A, an MSO-sentence  $\varphi(X)$ , and  $m \in \mathbb{N}$ .

Parameter:  $tw(A) + |\varphi(X)|$ .

**Problem:** Decide whether  $A = \exists X (card^{=m}(X) \land \varphi(X)).$ 

#### Refinement 2 of Courcelle's Theorem

 $p^*$ -tw-MC<sup>=</sup>(MSO)  $\in$  FPT. More precisely, the problem is decidable by an algorithm in time:

```
f(k_1, k_2) \cdot |A|^2 + O(\|A\|), where k_1 := tw(A), and k_2 := |\varphi|, f computable and non-decreasing
```

# Courcelle's Theorem Ref. 3: Optimization version

```
\begin{split} p^*\text{-}\textit{tw}\text{-}\mathsf{opt}\text{-}\mathsf{MC}(\mathsf{MSO}) \\ & \textbf{Instance:} \ \mathsf{A} \ \mathsf{graph} \ \mathcal{G} = \langle V, E \rangle, \ \mathsf{an} \ \mathsf{MSO}\text{-}\mathsf{sentence} \ \varphi(X_1, \dots, X_p). \\ & \textbf{Parameter:} \ \textit{tw}(\mathcal{G}) + |\varphi(X_1, \dots, X_p)|. \\ & \textbf{Compute:} \ \max_{\substack{\mathsf{min} \\ \mathsf{min}}} \big\{ \alpha(|X_1|, \dots, |X_p|) \mid \begin{matrix} X_1, \dots, X_p \subseteq V \cup E \\ \mathcal{A}(\mathcal{G}) \vDash \varphi(X_1, \dots, X_p). \end{matrix} \big\}. \\ & \text{where} \ \alpha \ \mathsf{is} \ \mathsf{an} \ \mathsf{affine} \ \mathsf{function} \ \alpha(x_1, \dots, x_p) = a_0 + \sum_{i=1}^p a_i \cdot x_i. \end{split}
```

### Optimization version of Courcelle's Theorem

```
p^*-tw-opt-MC(MSO) \epsilon FPT, and it is decidable by an algorithm in time: f(tw(\mathcal{G}), |\varphi|) \cdot |V|, where f computable and non-decreasing.
```

# Maximum 2-edge colorable subgraphs

 $p^*$ -tw-max-2-edge-colorable-subgraph

**Instance:** A graph  $\mathcal{G} = \langle V, E \rangle$ .

Parameter:  $tw(\mathcal{G})$ .

Compute: Maximum number of edges

in a 2-edge colored subgraph of G.

### Example [AA & Vahan Mkrtchyan]

 $p^*$ -tw-max-2-edge-colorable-subgraph  $\in$  FPT.

# Maximum 2-edge colorable subgraphs

 $p^*$ -tw-max-2-edge-colorable-subgraph

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Parameter:  $tw(\mathcal{G})$ .

Compute: Maximum number of edges

in a 2-edge colored subgraph of G.

#### Example [AA & Vahan Mkrtchyan]

 $p^*$ -tw-max-2-edge-colorable-subgraph  $\in$  FPT.

# Courcelle's Theorem: applications (3)

*p\*-tw-*INDEPENDENT-SET

**Instance:** A graph  $\mathcal{G}$ , a number  $\ell \in \mathbb{N}$ .

Parameter:  $tw(\mathcal{G})$ 

**Problem:** Decide whether  $\mathcal{G}$  has an independent set of  $\ell$  ele-

ments.

## Example

 $p^*$ -tw-Independent-Set  $\in$  FPT.

# Courcelle's Theorem: applications (4)

*p\*-tw-*FEEDBACK-VERTEX-SET

**Instance:** A graph  $\mathcal{G}$  and  $\ell \in \mathbb{N}$ .

Parameter: tw(C)

**Problem:** Decide whether  $\mathcal{G}$  has a feedback vertex set of  $\ell$ 

elements.

### Example

 $p^*$ -tw-FEEDBACK-VERTEX-SET  $\in$  FPT.

# Courcelle's Theorem: applications (5)

```
p*-tw-Crossing-Number
```

**Instance:** A graph  $\mathcal{G}$ , and  $k \in \mathbb{N}$ 

Parameter:  $tw(\mathcal{G}) + k$ 

**Problem:** Decide whether the crossing number of  $\mathcal{G}$  is k.

### Example

 $p^*$ -tw-Crossing-Number  $\in$  FPT.

The *crossing number* is the least number of edge crossings required to draw the graph in the plane such that at each point at most two edges cross.

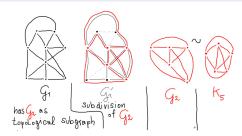
# Courcelle's Theorem: applications (5)

### Definition

Let  $\mathcal{G}_1 = \langle V_1, E_1 \rangle$  and  $\mathcal{G}_2 = \langle V_2, E_2 \rangle$  be graphs.  $\mathcal{G}_1$  is a *subdivision* of  $\mathcal{G}_2$  if:

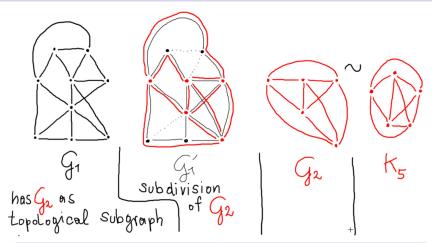
G<sub>1</sub> arises by splitting the edges of G<sub>2</sub>
into paths with intermediate vertices.

 $\mathcal{H}$  is a *topological subgraph* of  $\mathcal{G}$  if  $\mathcal{G}$  has a subgraph that is a subdivision of  $\mathcal{H}$ .



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# Courcelle's Theorem: applications (5)



## Theorem (Kuratowski)

A graph is planar if and only if it contains neither  $K_5$  nor  $K_{3,3}$  as topological subgraph.

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# Courcelle's Theorem: applications (5)

### Theorem (Kuratowski)

A graph is planar if and only if it contains neither  $K_5$  nor  $K_{3,3}$  as topological subgraph.

#### Lemma

There is a  $MSO(\tau_{HG})$  formula top-sub<sub>H</sub> such that for every graph G:

$$\mathcal{A}_{\mathsf{THG}}(\mathcal{G}) \vDash top\text{-}sub_{\mathcal{H}} \iff \mathcal{H} \text{ is a topological subgraph of } \mathcal{G}.$$

Using  $MSO(\tau_{HG})$  formula path(x, y, Z) that Z is a path from x to y.

### Lemma

There is a  $MSO(\tau_{HG})$  formula  $cross_k$  such that for every graph  $\mathcal{G}$ :

$$\mathcal{A}_{\mathsf{THG}}(\mathcal{G}) \vDash \mathsf{cross}_k \iff \mathsf{the\ crossing\ number\ of\ } \mathcal{G} \mathsf{\ is\ at\ most\ } k.$$

*Proof:* By induction, where  $cross_0 := \neg top - sub_{K_5} \land \neg top - sub_{K_{3,3}}$ .

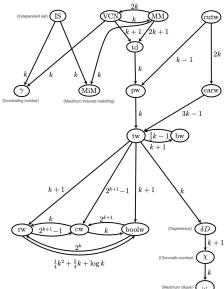
## Computably boundedness between notions of width

(from Sasák, [Sásak, 2010])  $g(wd_1) \succeq wd_2 : \Leftrightarrow wd_1 \stackrel{g}{\to} wd_2$ 

- ► FPT-results

  transfer upwards

  (and conversely to → )
- (∉ FPT)-results transfer downwards (and along <sup>g</sup>→)



# Comparing parameterizations

### Definition (computably bounded below)

Let  $\kappa_1, \kappa_2 : \Sigma^* \to \mathbb{N}$  parameterizations.

- ▶  $\kappa_1 \succeq \kappa_2 : \iff \exists g : \mathbb{N} \to \mathbb{N} \text{ computable } \forall x \in \Sigma^* \Big[ g(\kappa_1(x)) \geq \kappa_2(x) \Big].$

### Proposition

For all parameterized problems  $(Q, \kappa_1)$  and  $(Q, \kappa_2)$  with parameterizations  $\kappa_1, \kappa_2 : \Sigma^* \to \mathbb{N}$  with  $\kappa_1 \succeq \kappa_2$ :

$$\langle Q, \kappa_1 \rangle \in \mathsf{FPT} \iff \langle Q, \kappa_2 \rangle \in \mathsf{FPT}$$
  
 $\langle Q, \kappa_1 \rangle \notin \mathsf{FPT} \implies \langle Q, \kappa_2 \rangle \notin \mathsf{FPT}$ 

## Courcelle's Theorem for clique-width

Recall that  $MSO(\tau_G) \sim MSO_1$  (quantification over sets of vertices, but not sets of edges).

```
p^*-clw-MC(MSO(\tau_{\sf G})/MSO<sub>1</sub>)
```

**Instance:** A graph  $\mathcal{G}$  and an  $MSO(\tau_G)$ -sentence  $\varphi$ .

Parameter:  $c/w(\mathcal{G}) + |\varphi|$ .

**Problem:** Decide whether  $\mathcal{A}(\mathcal{G}) \vDash \varphi$ .

```
Theorem ([Courcelle et al., 2000]) p^*-c/w-MC(MSO(\tau_G)/MSO<sub>1</sub>) \in FPT.
```

Also, there is a maximization version of this theorem.

## Courcelle's Theorem for clique-width (example)

```
Let \mathcal{G} = \langle V, E \rangle a graph. For all S \subseteq V:
 S is a vertex cover of \mathcal{G} : \iff \forall e = \{u, v\} \in E \ (u \in S \lor v \in S))
```

```
p*-c/w-Vertex-Cover
```

**Instance:** A graph  $\mathcal{G} = \langle V, E \rangle$ , and  $\ell \in \mathbb{N}$ .

Instance:  $clw(\mathcal{G})$ .

**Problem:** Does  $\mathcal{G}$  have a vertex cover of size at most  $\ell$ ?

### Example

```
p^*-c/w-VERTEX-COVER \in FPT.
```

# Application to maximum 2-edge colorable subgraphs?

p\*-c/w-max-2-edge-colorable-subgraph

**Instance:** A graph  $\mathcal{G} = \langle V, E \rangle$ .

Parameter:  $c/w(\mathcal{G})$ .

Compute: Maximum number of edges

in a 2-edge colored subgraph of G.

### Open problem [AA, Vahan Mkrtchyan]

 $p^*$ -c/w-max-2-edge-colorable-subgraph  $\in$  FPT ?

We saw that there is a  $MSO_2$  formula  $\varphi(X)$  such that:

$$\mathcal{A}_{\mathsf{THG}}(\mathcal{G}) \vDash \varphi(S) \iff S \subseteq E \text{ is an 2-colorable set of edges in } \mathcal{G}$$

But there seems not to be such an MSO<sub>1</sub> formula.

## Courcelle's Theorem for clique-width (non-example)

```
p^*-c/w-Hamiltonicity
```

Instance: A graph  $\mathcal{G}$  Parameter:  $c/w(\mathcal{C})$ 

**Problem:** Decide whether G is a hamiltonian (that is, contains

a cyclic path that visits every vertex precisely once).

### Recall

There is no  $MSO_1$  formula that expresses Hamiltonicity.

Hence we cannot apply Courcelle's Theorem for clique-width. Indeed:

### **Theorems**

- (T1)  $p^*$ -c/w-HAMILTONICITY  $\notin$  FPT, since it is not decidable in time  $\notin n^{o(clw(\mathcal{C}))}$  (Fomin et al, 2014).
- (T2)  $p^*$ -c/w-HAMILTONICITY  $\in O(n^{o(clw(\mathcal{C}))})$  (Bergougnoux, Kanté, Kwon, 2020).

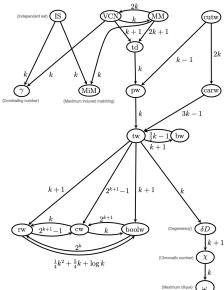
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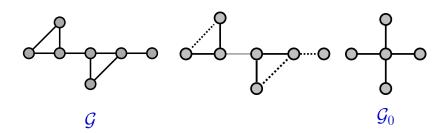
# **Graph Minors**

# Graph minors

### Definition

A graph  $\mathcal{G}_0$  is a *minor* of a graph  $\mathcal{G}$  if  $\mathcal{G}_0$  is obtained by:

- deleting some edges,
- deleting arising isolated vertices,
- $\triangleright$  contracting edges in  $\mathcal{G}$ .



## **Excluded minors**

### Definition (minor closed)

A class  $\mathcal{G}$  is *minor closed* if for every  $\mathcal{G} \in \mathcal{G}$  all minors of  $\mathcal{G}$  are in  $\mathcal{G}$ .

We say that a class G is characterized by excluded minors in H if:

$$\mathcal{G} := \mathsf{Excl}(\mathcal{H}) := \{ \mathcal{G} \mid \mathcal{G} \text{ does not have a minor in } \mathcal{H} \}$$

## Theorem (Graph Minor Theorem (Robertson-Seymour, 1983–2004))

Every class of graphs that is minor closed can be characterized by finitely many excluded minors. That is, for every class  $\mathcal{G}$  of minor closed graphs there are graphs  $\mathcal{H}_1, \ldots, \mathcal{H}_m$  such that:

$$\boldsymbol{\mathcal{G}} = \mathsf{Excl}(\{\boldsymbol{\mathcal{H}}_1,\ldots,\boldsymbol{\mathcal{H}}_m\}).$$

## Deciding minor closed classes

### *p*-MINOR

**Instance:** Graphs  $\mathcal{G}$  and  $\mathcal{H}$ .

Parameter:  $\|\mathcal{G}\|$ 

**Problem:** Decide whether  $\mathcal{G}$  is a minor of  $\mathcal{H}$ .

### **Theorem**

p-MINOR  $\in$  FPT, decidable in time  $f(k) \cdot n^3$  where  $k = ||\mathcal{G}||$ , and n is the number of vertices of  $\mathcal{H}$ .

## Corollary

Every minor-closed class of graphs is decidable in cubic time.

### Corollary

Let  $\langle Q, \kappa \rangle$  be a parameterized problem on graphs such that for every  $\mathbf{k} \in \mathbb{N}$ , either  $\{ \mathcal{G} \in Q \mid \kappa(\mathcal{G}) = \mathbf{k} \}$  or  $\{ \mathcal{G} \notin Q \mid \kappa(\mathcal{G}) = \mathbf{k} \}$  is minor closed.

Then every slice  $\langle Q, \kappa \rangle_k$  is decidable in cubic time. In this case we can say that  $\langle Q, \kappa \rangle$  is nonuniformly fixed-parameter tractable.

# Non-uniformly fixed-parameter tractable

A parameterized problem  $(Q, \Sigma, \kappa)$  is *fixed-parameter tractable* if:

```
\begin{split} \exists f: \mathbb{N} \to \mathbb{N} \text{ computable } \exists p \in \mathbb{N}[X] \text{ polynomial} \\ \exists \mathbb{A} \text{ algorithm, takes inputs in } \Sigma^* \\ \forall x \in \Sigma^* \big[ \, \mathbb{A} \text{ decides whether } x \in Q \text{ holds} \\ \text{ in time } \leq f(\kappa(x)) \cdot p(|x|) \, \big] \end{split}
```

#### Definition

A parameterized problem  $\langle Q, \Sigma, \kappa \rangle$  is *non-uniformly fixed-parameter tractable* (in nu-FPT) if:

```
\exists f: \mathbb{N} \to \mathbb{N} \text{ computable } \exists p \in \mathbb{N}[X] \text{ polynomial} \\ \exists \left\{ \mathbb{A}_k \right\}_{k \in \mathbb{N}} \text{ algorithms, takes inputs in } \Sigma^* \\ \forall x \in \Sigma^* \Big[ \mathbb{A}_{\kappa(x)} \text{ decides whether } x \in Q \text{ holds} \\ \text{ in time } \leq f(\kappa(x)) \cdot p(|x|) \Big]
```

## Using minor-closed classes for FPT results

### Corollary

Let  $\langle Q, \kappa \rangle$  be a parameterized problem on graphs such that for every  $k \in \mathbb{N}$ , either  $\{\mathcal{G} \in Q \mid \kappa(\mathcal{G}) = k\}$  or  $\{\mathcal{G} \notin Q \mid \kappa(\mathcal{G}) = k\}$  is minor closed. Then  $\langle Q, \kappa \rangle$  is non-uniformly fixed-parameter tractable (in nu-FPT).

### Applications:

- p-Vertex-Cover ∈ nu-FPT (p-Vertex-Cover is minor closed).
- p-FEEDBACK-VERTEX-SET ∈ nu-FPT (problem is minor closed).
- p-DISJOINT-CYCLES

**Instance:** A graph  $\mathcal{G}$ , and  $k \in \mathbb{N}$ .

Parameter: k.

**Problem:** Decide whether  $\mathcal{G}$  has k disjoint cycles.

p-DISJOINT-CYCLES  $\in$  nu-FPT, since the class of graphs that do not have k disjoint cycles is minor closed.

# First-Order Meta-Theorem (example)

## Seese's theorem

A class  $\mathcal{G}$  of graphs has bounded degree if there is  $d \in \mathbb{N}$  such that  $\Delta(\mathcal{G}) \leq d$  for all  $\mathcal{G} \in \mathcal{G}$  (where  $\Delta(\mathcal{G}) = \max$ . degree of vertex in  $\mathcal{G}$ ).

```
p\text{-MC}(\mathsf{FO}, \mathcal{G})
```

**Instance:** A graph  $G \in G$ , and a f-o formula  $\varphi$  over  $\tau_{HG}$ 

Parameter:  $|\varphi|$ .

**Problem:** Decide whether  $A(G) \models \varphi$ .

## Theorem ([Seese, 1995])

 $p ext{-MC}(\mathsf{FO},\mathcal{G}) \in \mathsf{FPT}$  for every class  $\mathcal{G}$  of bounded degree. This model checking problem can be solved in time  $f(|\varphi|) \cdot |\mathcal{G}|$ , (linear in  $|\mathcal{G}|$ ).

### Theorem (for comparison, we saw it earlier)

EVAL(FO) and MC(FO) can be solved in time  $O(|\varphi| \cdot |A|^w \cdot w)$ , where w is the width of the input formula  $\varphi$ .

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## First-order metatheorems: reference

A good reference for other meta-theorems for first-order logic is:

[Kreutzer, 2009]: Stephan Kreutzer: Algorithmic Meta-Theorems.

## Summary

- Logic preliminaries
  - first-order logic
    - expressing graph problems by f-o formulas
  - monadic second-order logic (MSO)
    - expressing graph problems by MSO formulas
  - complexity of evaluation and model checking problems
- Courcelle's theorem
  - FPT-results by model-checking MSO-formulas
    - for graphs with bounded tree-width
    - for structures with bounded tree-width
    - for graphs of bounded clique-width
  - applications to concrete problems
- graph minors
- meta-theorems for first-order model-checking: an example

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# Friday

Monday, June 10 10.30 – 12.30	Tuesday, June 11	Wednesday, June 12 10.30 – 12.30	Thursday, June 13	Friday, June 14
Introduction & basic FPT results		Algorithmic Meta-Theorems		
motivation for FPT kernelization, Crown Lemma, Sunflower Lemma	GDA	1st-order logic, monadic 2nd-order logic, FPT-results by Courcelle's Theorems for tree and clique-width	GDA	GDA
Algorithmic Techniques		Formal-Method & Algorithmic Techniques		
	14.30 – 16.30			14.30 – 16.30
	Notions of bounded graph width			FPT-Intractability Classes & Hierarchies
	path-, tree-, clique width, FPT-results by dynamic programming, transferring FPT results betw. widths	GDA	GDA	motivation for FP-intractability results, FPT-reductions, class XP (slicewise polynomial), W- and A-Hierarchies, placing problems on these hierarchies

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# **Example suggestions**

### Examples

- 1. Find a first-order logic formula over  $\tau_{\mathbf{G}}$  that expresses that a graph has a cycle of length precisely k.
- 2. Find an MSO<sub>1</sub> or MSO( $\tau_G$ ) formula that expresses that a graph has a dominating set of  $\leq k$  elements.
- 3. Find an  $MSO_2$  or  $MSO(\tau_{HG})$  formula *feedback*(S) that expresses that  $S \subseteq V$  is a feedback vertex set.
- 4. (\*) Find an MSO<sub>1</sub> or MSO( $\tau_{\rm G}$ ) formula that expresses that a graph is connected.
- 5. (\*) Find an  $MSO_2$  or  $MSO(\tau_{HG})$  formula *path*(x, y, Z) that expresses that Z is a set of edges that forms a path from x to y.

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