

Diversity as a management tool for forest ecosystem services

A theoretical exploration using control theory and viability analyses

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1 Summary

Defining optimal forest management strategies in a changing world is a challenge in the field of forest ecology. The complexity of forest ecosystems, coupled with the uncertainty of future climate conditions, makes it difficult to determine the best course of action. The concept of forest diversity is a key consideration in this debate, as it is believed to be a significant factor in the resilience of forest ecosystems. This study aims to explore whether diversity can be used as a management tool to maintain the ecosystem in a desirable state. To this end, we will use a theoretical model of a mixed-species, multi-layered forest, and apply control theory and viability analyses to assess the relationship between diversity and management trajectories, considering both species and vertical diversity at the stand level. RESULTS

Keywords: forest management, diversity, control theory, viability theory

2 Intro

2.1 Forest and management, new practices for new challenges

Forest covers 31% of the territory in France, however forest health metrics show rapid degradation marked by an alarming +80% increased mortality rate, a 4% decline in growth and a deceleration in carbon storage due to the growing number of health crises combined with more frequent droughts (*IGN* 2024). This impacts forest composition, structure, dynamics and the provisioning of ecosystem services to human populations (Climate regulation, water purification, wood production, air quality, cultural leisure...) (Grammatikopoulou and Vačkářová 2021). Notably, 94% of these forests are designated as productive, emphasizing the critical need to adapt management

strategies to address these emerging challenges. New adaptative policy actions are studied to robustly sustain the state of these forests as the adaptation from monospecific forests stand with clear-cutting into mixed species and uneven aged forest stand with a diversity of selective logging practices (REFSautre; Raymond et al. 2009). Knowledge of these new practices is still limited but they are already implemented relying on the idea that diversification is a way to increase multiple ecosystem services (Tilman 1996).

For obvious economic constraints sustainable wood extraction has been the primary driver of forest management practices. With this approach diversity indices are treated as auxiliary metrics, preventing interference with the core objective of wood extraction. The pivotal question that emerges is whether we can redefine this paradigm and choose diversity as our primary constraints to explore potential benefits and differences in our management approaches. This paradigm shift is motivated, firstly, by the insights from Biodiversity-Ecosystem Functioning (BEF) studies, which highlight diversity as a critical component for overall ecosystem health. Our study's second motivation is the indicating that forest management can function as a tool to actively enhance diversity within ecosystems. But given the many uncertainties in climate and the complex response of forest systems to management actions, new methods (using models and decision science) are needed to assist their design.

2.2 Diversity and ecosystem functioning

Work on composition diversification and its effects is mainly driven by the first work on BEF from grassland studies (Tilman 1996) showing a positive link between biodiversity and ecosystem functioning. But even though numerous hypotheses were made to explain this link (competitive exclusion, niche complementary, sampling effect, etc.) the mechanisms behind this link are still not well understood (Ali 2023). This uncertainty makes it difficult to predict the impact of biodiversity loss. While the hypothesis of BEF relationship, and its relevance is still debated, it fuels an entire segment of research. In forest, the study of BEF is more recent and mainly focused on the link between species diversity and productivity. A positive relationship has been demonstrated at a global scale (Liang et al. 2016), but also in specific forest (Morin, Fahse, et al. 2011; Paquette and Messier 2011; Jourdan et al. 2021). But the interaction is not positive in every forest type. (Forrester and Bauhus 2016). This may suggest that the biodiversity-productivity interaction is context dependant, the relationship seems to be mostly positive in harsh climate and low tree density but negative in suitable environment (Jucker et al. 2016).

It is also reductive to consider productivity as the only function of forest ecosystems, and other should be accounted for: flora and fauna biodiversity, carbon storage, water and biochemical cycle

that provide multiple services to human populations (SEE : Aerts). To gain a comprehensive understanding of the diverse impacts of biodiversity on forest functioning, it is essential to simultaneously investigate multiple functions, as they may not be affected in uniform ways (Korboulewsky, Perez, and Chauvat 2016). It introduces a level of complexity not observed when studying individual functions like the jack-of-all-trades and master of none mechanism (Van Der Plas et al. 2016) blindly increasing biodiversity can increase forest multi-functionality without optimizing any of them and leading sometimes to trade-offs. It is thus important to define the functions that we want to preserve as well as threshold for each of them. Forests exhibit different functions not solely tied to species identity but also emerging from distinct life stages within the same species. Noteworthy trade-offs can be observed in the comparison between young and old grown forests, if the former are more productive, they store less carbon than the latter (Caspersen and Pacala 2001). Recognizing the diverse advantages of both young and old forests could involve reintroducing vertical diversity through uneven forest management to enhance overall ecosystem resilience and functionality (Guldin 1996). However, despite its promise, the implementation of such practices remains limited, with only 25% of managed forests in Europe currently comprising uneven-aged stands (foresteurope.org). This limitation is accentuated by a notable gap in our understanding of the ecological consequences of uneven-aged stages within forest ecosystems. The complex interplay of factors makes it challenging to draw definitive conclusions regarding the comparative ecological effects of even-aged and uneven-aged silviculture (Nolet et al. 2018). Consequently, the full scope of benefits and potential drawbacks associated with fostering vertical diversity in forest management is not yet well comprehended. This dual challenge of limited implementation and incomplete understanding underscores the importance of further research to inform and refine forest management practices. Even if the advantages of diversity in forests are convincingly demonstrated, implementing management strategies to promote it is no straightforward task. This requires a profound understanding of forest dynamics and the short, medium, and long-term responses to interventions within the forest ecosystem.

2.3 Management for diversity

While diversity is not always a priority in forest management— with a significant portion (1/3) of forests in Europe still mono-specific and the majority (3/4) being even-aged (foresteurope.org) various practice philosophies have been proposed to reintroduce diversity into managed forests. Two prominent approaches include retention forestry and the Irregular Shelterwood System. Retention forestry aims to maintain forest structure and composition by leaving a certain proportion of trees in the stand after harvesting (Gustafsson et al. 2012; Rosenvald and Löhmus 2008). Similarly, the

Irregular Shelterwood System, also known as uneven-aged forestry or continuous cover forestry, focuses on sustaining a continuous cover of trees in the stand, promoting both structural and vertical diversity (Sinha et al. 2017; Schall et al. 2018; Nyland 2003; Nolet et al. 2018; Duduman 2011). However, a notable gap exists in the understanding of the long-term dynamics and consequences of these practices, with limited predictive studies on system dynamics.

On the other hand theoretical ecology, studies species coexistence providing insights into enhancing diversity by controlling various aspects of the forest ecosystem (Wilson 2011). The Intermediate Disturbance Hypothesis, for example, suggests that maintaining intermediate levels of disturbance allows for the coexistence of species with different disturbance tolerances (Connell 1978; Sheil and Burslem 2013). Another strategy involves cutting dominant species to promote the development of other species (Pichancourt et al. 2014). Despite these approaches offering valuable insights into managing biological diversity, challenges persist. The applicability of these theories to real-world forest management scenarios is limited, and they face contestations within the scientific community (Mackey and Currie 2000; Fox 2013).

These studies emphasize the need for a comprehensive understanding of forest management beyond traditional cutting practices. They strive to provide guidance for managing biological diversity thanks to different management practices. However extracting an optimal management trajectory proves challenging due to the current limitations in our understanding, coupled with the added complexity of simultaneously maximizing multiple ecological functions. Exploring the possibility of new forest management focused on mitigating drawbacks on diversity and not optimisation could open new perspectives.

2.4 Hypothesis and objectives of the study

Given the understanding that diversity holds significance for optimal forest functioning and recognizing management as a pivotal tool in shaping this diversity, our main hypothesis is that using diversity as a constraints for management instead of productivity could bring forth new management strategies. To test this, we developed a simple theoretical model of multi-species/layers forest ecosystem dynamics. The model was parameterized for two species with different vital rates (growth, survival, reproduction) and competition for light between three vertical storeys (upper, mid, under). The model was used to predict annual Shannon diversity index of species, vertical structure, above-ground biomass, and timber extraction every ten years. Algorithm from viability theory were used to deduce the the set of states and controls that respect our constraints. With this approach we where able to compare the management trajectories that respect diversity con-

straints with the ones that respect wood extraction constraints.

3 Methods

3.1 Forest model

3.1.1 Choice of model

Forest models are very diverse, they evolved with need, understanding of ecosystem processes, and technological innovations. They are applied at different spacial scales from tree, to stand to landscape level. They integrate different processes as growth, regeneration, mortality, management, photosynthesis, evapotranspiration, disturbances with more or less details. Numerous types of forest model classification exist (Porté and Bartelink 2002), but for this short exploration only a simple classification in two groups will be useful (Fontes et al. 2011) : first there are the empirical models that are developed on experimental data (and then theoretical models which are the continuous equivalent with differential equation), secondly there are the process based models (PBM) that infer dynamics from underlying processes at community, individual or cellular level.

Amongst PBM, the biggest family is formed by Gap-models (Bugmann 2001), built upon the assumption that most of forest dynamic is the result of competition for light. Although gap models show promise, a significant drawback is their complexity, especially when defining the system state. This complexity surpasses our capacity for analysis. However, it is possible to reduce dimensions (and runtime to 5%) while making minimal assumptions with model aggregation, achieved through tools like DisCForM and TreeMig (Lischke, Löffler, and Fischlin 1998; Lischke, Zimmermann, et al. 2006) by height discretization.

On the other hand theoretical models are derived from theoretical considerations, and not from detailed mathematical models of tree population dynamics such as gap models. However both of this approach show a remarkable congruence in their formulation (Bugmann 2001).

The limit of the viability analyses is its computational cost, and the need for a simple model, which means a compromise between complexity and realism. The model had to be simple enough to be summarized by a small number of state variables, but also complex enough to be able to test different management strategies. We hypothesize that we can use a simple theoretical model to explore the effect of diversity on ecosystem services, and that the some results will then be transferable to more complex models. The advantages of this approach is that we can explore a large range of possibilities and test new hypothesis that could not be tested with more complex

models.

For this study the needs for stand-level mixed-species size structured forest with a limited number of state variables and the possibility to apply management strategies, led us to the choice of a theoretical model. The model is based on the work of Kohyama and associates (Kohyama and Takada 2009; Kohyama and Takada 2012).

3.1.2 Model description

The theoretical model described below comes from the study of multiple articles from Kohyama and associates (Kohyama and Takada 2009; Kohyama and Takada 2012). It is a compartment based model with multi species and multi layers structure Figure 1. The dynamic is influenced by growth, regeneration, mortality as well as competition for light from the layers above. There are some differences between the models present in Kohyama 2009 and 2012, in particular definition of birth and competition. We chose to define birth as in Kohyama 2009 as a negative linear, or Verhulst function (and not as a negative exponential, or Ricker function in Koyama 2012). The only difference is that birth in our study is considere on independant from the number of adult tree. Even if Kohyama 2009 propose a way to add competition for resources by layers below, we chose a strictly one-sided competition from the above layers as in Kohyama 2012.

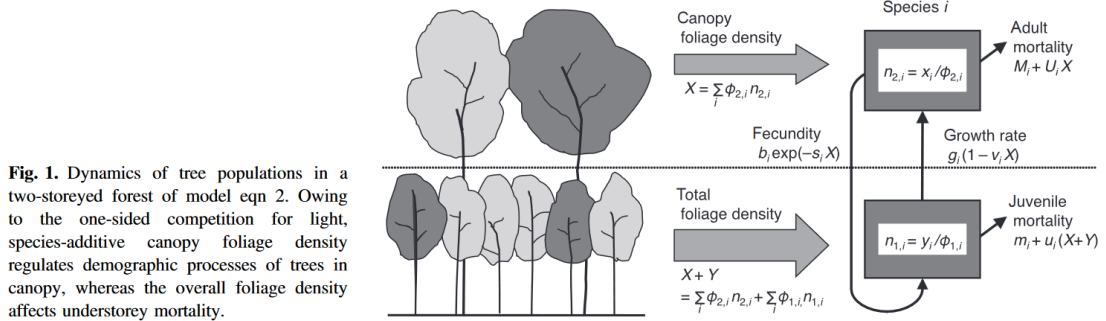


Figure 1: Figure from (Kohyama and Takada 2012)

Dynamic of each layer is driven by the competition from above layers foliage density (assimilated to the basal area) $\sum_{i=1}^L X_i$ with X_i being the foliage density of layer i defined by the number of tree $n_{sp,i}$ and the mean basal area of tree $\phi_{sp,i}$ of each species (sp) in layer i :

$$X_i = \sum_{sp} \phi_{sp,i} n_{sp,i} \quad (1)$$

The various processes are influenced by competition, with a linear negative relationship. Op-

timal probabilities are determined for each processes (birth b , growth g and mortality m) without competition. These probabilities are then adjusted based on the process sensitivity (Cb , Cg , Cm) of the layer and species to foliage density.

The model can be summarised with one differential equation :

$$\begin{aligned}
n_{sp,l}(t+1) = & n_{sp,l}(t) \\
& + b_{sp,l}(1 - Cb_{sp,l} \sum_{i=1}^L X_i) \} birth \\
& + g_{sp,l-1} n_{sp,l-1}(t)(1 - Cg_{sp,l-1} \sum_{i=l-1}^L X_i) \} growth from lower level \\
& - g_{sp,l} n_{sp,l}(t)(1 - Cg_{sp,l} \sum_{i=l}^L X_i) \} growth to upper level \\
& - m_{sp,l} n_{sp,l}(t)(1 + Cm_{sp,l} \sum_{i=l}^L X_i) \} mortality \\
& - u_{sp,l}(t) \} logging
\end{aligned} \tag{2}$$

And some special cases for lower and upper layers :

$b_{sp,l} = 0$ for $l > 1$, new trees always arrive in the lower level

$g_{sp,L} = 0$, trees cannot grow out of the upper layer

$g_{sp,0} = 0$, trees cannot grow into the lower level

$u_{sp,1:2} = 0$, we chose to only apply logging to the upper level

Population densities and demographic parameters are defined in Table 1 and are all positive.

Abbreviation	Meaning	Unit
l	layer index	
L	number of layer (i.e. maximum layer)	
sp	species index	
SP	number of species	
$n_{sp,l}$	number of trees of species sp in layer l	ha^{-1}
$x_{sp,l}$	foliage density of species sp in layer l	$m^2.ha^{-1}$
$\phi_{sp,l}$	mean basal area of tree from species sp in layer l	m^2
X_l	foliage density of layer l	$m^2.ha^{-1}$
$\sum_{i=l}^L X_i$	foliage density above layer l	$m^2.ha^{-1}$
b_{sp}	optimal birth rate per tree in layer L	
Cb_{sp}	birth susceptibility to superior foliage density	$ha.m^{-2}$
$g_{sp,l}$	growth susceptibility to superior foliage density	
$m_{sp,l}$	probability of intrinsic mortality	
$Cg_{sp,l}$	growth susceptibility to superior foliage density	$ha.m^{-2}$
$Cb_{sp,l}$	mortality susceptibility to superior foliage density	$ha.m^{-2}$
$u_{sp,l}$	number of trees cut from species sp in layer l	ha^{-1}

Table 1: Parameters for the model

3.1.3 Model parametrisation

We are starting with a 3 layers 2 species system with a mixture of possible species : *Abies alba*, *Betula pendula*, *Fagus sylvatica*, *Picea abies*, *Pinus sylvestris*, *Quercus pubescens*. The layers are defined by simplifying the IGN (French National Institute for Geographic and Forestry Information) 4-dimensional wood classification used in national forest inventory into 3 classes : dbh (cm) in $[0,22.5]$ for small wood, $[22.5,67.5]$ for medium and large, and $[67.5, +[$ for very large. We have to define all parameters from the model.

Litterature and ForCEEPS simulations were used to adjust the dynamic of the system on a constant climate. (see appendix on parametrisation (Bugmann 1994; Morin, Bugmann, et al. 2021)). Giving the parameters in Table S.6.

We choose to concentrate our analyses on two species *Abies alba* and *Fagus sylvatica* as their dynamic was the most similar to ForCEEPS (REF to supplementary data) and they can be found together in mixed stand in France.

3.2 Viability theory for defining management strategies

There doesn't seem to be any optimal solution to manage such complicated ecosystems, while taking into account their multi-functionality. Some methods, such as viability theory (Aubin and Da Prato 1990), have been developed to actively discover sequences of actions sustaining multiple objectives within satisfaction constraints. Viability analyses establishes a framework to define control and states that can be combined to stay in our biological constraints for as long as needed (Rougé, Mathias, and Deffuant 2013). Viability theory finds application in scenarios where objectives involve ecosystem services in forest social-ecological systems (Houballah2021; Houballah2023; Mathias et al. 2015). In these studies, biodiversity is leveraged to identify viable control sequences, sustaining forest biodiversity and some ecosystem services through timber extraction control. Nevertheless, it has not yet been employed to comprehend how controlling species diversity and selective cutting targets can lead to viable management trajectories.

Viability theory provides a framework for management of dynamic systems. The challenge lies in finding management strategies ($u(t)$) that perpetually keep the system within a space of chosen constraints K . Rather than fixating on a single optimal state, the approach is to navigate within a spectrum of acceptable outcomes, preventing irreversible negative impacts.

In our case, the control is discrete and happens every ten years (Δt), mathematically, this is articulated as a controlled discrete-time dynamical system:

$$N(t + \Delta t) = g(N(t), u(t), \Delta t), \quad (3)$$

where $N(t)$ is the system state at time t , $u(t)$ is the control applied at time t , and g is the state transition function. In our case the state of the system, $N(t)$, is defined by the matrix of the number of trees in each layer and for each species:

$$N(t) = [n_{sp,l}(t)]_{SP \times L}$$

. And the state transition function is defined as the cut at discrete time t ($u(t)$) and the dynamic following it (described in Equation (2)). The space of possible control is defined by the number of trees that are going to stay after a cut in the higher layer, only very large trees are affected by cuts : (THIS CHOICE WAS MADE FOR CALCUTATION SIMPLICITY BUT CAN ALSO BE SEEN AS A WAY TO SIMULATE CONSEQUENCE DRIVEN CUTTING STRATEGY, AS IT IMPACTS ALSO HOW IT IS GOING TO SHOW IN OUR "TRUE MODEL DYNAMIC")

$$U(\mathbb{N}^{sp}) = \{u \in \mathbb{N}^{sp} \mid \forall sp \in \mathbb{N}_{[1,SP]} \ u_{sp} \leq n_{sp}\} \quad (4)$$

The space of possible control is then all the upper layer compositions such as the number of trees left is inferior or equal to the number of trees present before the cut.

The resulting viability kernel ($Viab(K)$), which includes states where a management strategy can keep the system within desirable states, is formally described as:

$$Viab(K) = \{N_0 \in K \mid \exists U(\cdot), \forall t \in \mathbb{N}_5, N(t) \in K\}, \quad (5)$$

where N_0 denotes an initial state of the system in our constraints K . Within the viability kernel, at least one control strategy $u(\cdot)$ can maintain the system in a desirable state K . After the delimitation of the viability kernel all viable controls (u_v) can be determined and analysed.

To approach the viability kernel we used an algorithm inspired by Saint-Pierre (Saint-Pierre 1994)).

To define the desirable states we chose constraints on wood extraction and diversity. The first one allow to take into account the economic aspect of forest management. The metrics for diversity were included as a way to take into account the diversity aspect of forest management and it's impact on other services. We chose to use the Shannon index as a measure of species and vertical diversity, as it is a common metric in ecology and combine information about diversity

and evenness.

After defining the viability kernel for : species... The algorithm rely on a discretisation of all possible states into a grid in order to analyse the space of possible states. With our technical constraints we were able to define a grid with n points for the blabla dimension and n points for the 2 othe layers and the control for each species. Which provides the analyses of n states with n different control combinations that can be applied. Everything ran with R n a machine with 720 Giga RAM and 60 core, turning for Around 5 hours time we get the viability kernel, code accessible at github. All the following analyses where also done with R (REF) using packages (REF) and (REF) for PCA analyses. We got the results :

4 Results

4.1 Sensibility and Compatibility of the constraints

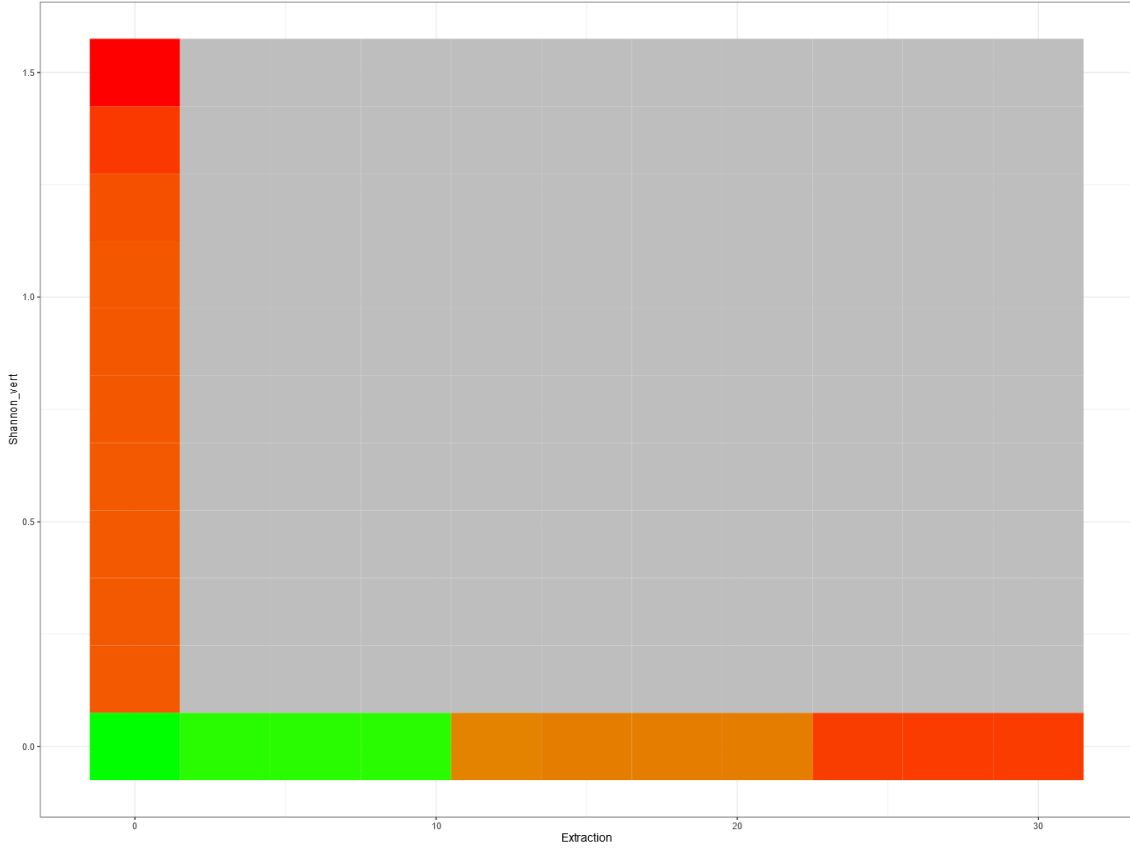


Figure 2: Figure : Volume of viability kernel function of constraints

Conclusion : If it is possible to stay inside a constraints of diversity both specific and vertical, as well as in a constraint of wood extraction, it is not possible to stay in a constraint of diversity and wood extraction at the same time.

Realistic constraints we chose to study : ... (But we already know that common constraints is not actually possible)

So we are going to compare the two

The question is then : what are the characteristic of the two different viability kernel and what are the controls that can be applied to stay in one or the other ?.

4.2 Viable state with diversity or wood extraction constraints : Volume and visualization, what in common ?

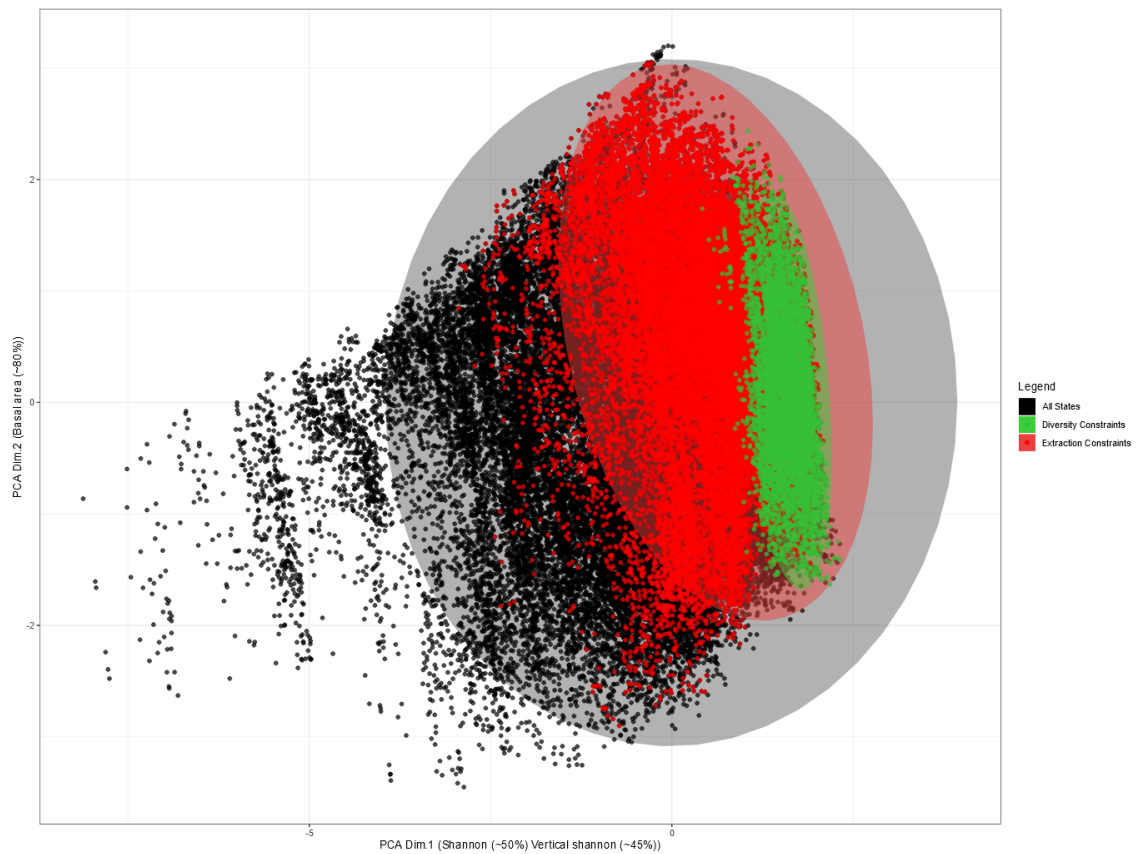


Figure 3: Figure : Viable state in the PCA space (see appendix for PCA)

Volume of viability kernel :

Constraints	State	Post control state	Control state	Association
Diversity	6 285	1 455	320	106 735
Extraction	11 899	8 756	622	349 037
Shared	6 121	1 193	1 317	61 144
Total	15 625	15 625	625	1.3 Million

Table 2: Volume of the viable space

Conclusion : A lot of common state even though there is an incompatibility between the two constraints. Perhaps on a limited timeline it is possible to stay in both constraints.

4.3 Viable state with diversity or wood extraction constraints : characteristic comparison

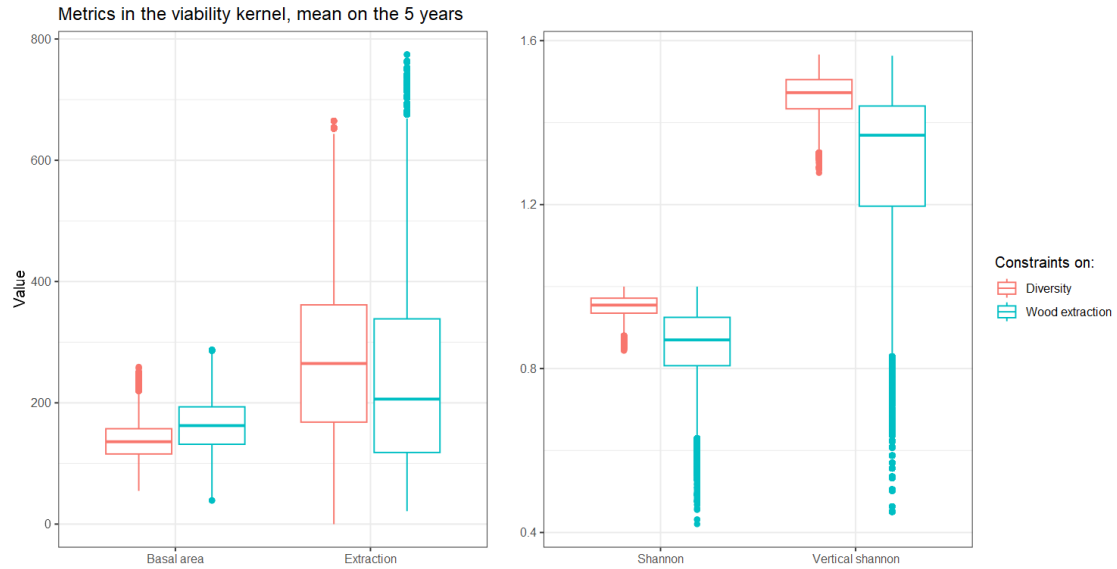


Figure 4: Figure : Metric in the viable state

Conclusion : Questions on volume, is it possible to cut so much (necessity of an upper limit + verif of formula for wood volume). Seems that there is no huge sacrifice of wood extraction for diversity, but mean doesn't take into account potential attraction inside the viability kernel.

4.4 Viable control with diversity or wood extraction constraints

Control as in state and what we extract ? Different between both, nb of viable control : diversity () and extraction ()

Characteristic of common state and/or control ?

5 Discussion

In order to be able to draw accurate conclusions from our results a few limits must be addressed. The first one being the computational cost of the analyses, it limited the number of forest states we were able to emulate. Meaning that the dynamic of our model is not perfectly reproduced by the dynamic of the grid we studied, some trajectories may differ and be viable only in one of two cases. Secondly parametrisation of the model we chose could have been more thorough, by using data, conducting a sensibility analyses on every parameter. This would allow to use more species in the following analyses. We also based our parametrisation on a model (ForCEEPS) which himself is not a perfect representation of reality and possesses its own biases. Finally we chose to limit our constraints to diversity and wood extraction which does not cover the ecosystem services that are provided by forest. In order to put constraints on multi-functionality we would need to define metrics that can be used as proxy for different services. Even only on diversity there are a lot of other metrics that could have been chosen and in order to confirm this choice we would need to test the sensibility of our results to the choice of metrics.

MORE DISCUSSION ON THE METRICS

The conclusions drawn, whether related to composition or vertical diversity, are highly dependent on the metric chosen as a proxy for diversity species richness (Jucker et al. 2016; Guldin 1996; Nolet et al. 2018). This complexity adds an additional layer of intricacy to understanding the connections between these metrics and the potential services the forests could offer.

DISCUSSION DES RESULTATS

WHAT NEXT ?

The most interesting thing to do after this work would be the application of the control trajectories we found to a mecanistic model as Forceeps and see if those conclusion are transferable.

To expand this work :

Forest management encompasses more than just harvesting; it involves considerations such as plantation practices, which can directly address questions related to species choice and turnover in the face of climate change. The intricate dynamics of species selection become a crucial consideration, presenting a potential advantage in the context of forest plantation management ((Brockerhoff

et al. 2008)). Furthermore, the exploration extends to the conversion to uneven shelterwood practices, prompting research inquiries into the optimal methodologies involved ((Sinha et al. 2017; Duduman 2011; Nyland 2003)).

Landscape diversity

And also test the hypothesis made with this kind of study on other, more descriptive model as for example mechanistic ones.

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Appendix

A Kohyama model parametrisation

We are starting with a 3 layers 3 species system with a mixture of possible species : *Abies alba*, *Betula pendula*, *Fagus sylvatica*, *Picea abies*, *Pinus sylvestris*, *Quercus pubescens*. The layers are defined by dbh (cm) interval : $[0,22.5]$, $[22.5,67.5]$, $[67.5,+]$. We have to define all parameters in Table 3.

By species, sp		
$b_{sp,1}$	optimal birth probability	$ha^{-1}.year^{-1}$
$Cb_{sp,1}$	birth susceptibility to superior foliage density	$ha.m^{-2}$
m_{sp}	probability of intrinsic mortality	$year^{-1}$
Cg_{sp}	growth susceptibility to superior foliage density	$ha.m^{-2}$
Cm_{sp}	mortality susceptibility to superior foliage density	$ha.m^{-2}$
By layer l		
ϕ_l	mean basal area per tree in layer l	$m^2.ha^{-1}$
By species sp and layer l		
$g_{sp,l}$	optimal probability of transition from layer l to the next	$.year^{-1}$

Table 3: Parameters that we have to define numerically

A.1 Parameters deduced form litterature of ForCEEPS and ForClim

A.1.1 Basal area

Basal area is defined as the area of the cross subsection of the tree at breast height (1.3m). It is a good indicator of the density of the forest. It is defined as :

$$\phi_l = \frac{\pi}{4} * \overline{D_l}^2 \quad (6)$$

With $\overline{D_l}$ the mean diameter in layer l . (i.e. 11.25, 45, 100 cm).

A.1.2 Intrinsic Mortality

Mortality was defined exactly as in ForCEEPS, as the inverse of the life expectancy of the species (A_{max}) multiplied by a factor $c_{mort} = 4.605$.

$$m_s = \frac{c_{mort}}{A_{max_s}} \quad (7)$$

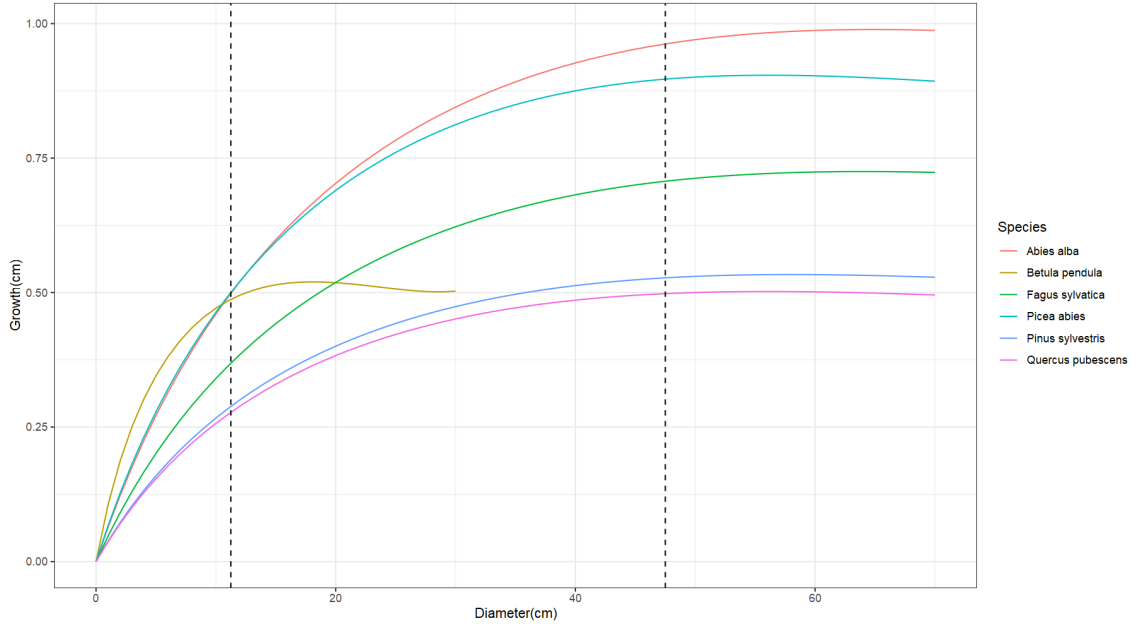


Figure 5: Growth as a function of diameter for the 5 species

A_{max} can be found in the thesis on ForClim (**bugmannEcologyMountainousForests1965**) or the supplementary data of ForCEEPS (Morin, Bugmann, et al. 2021)

A.1.3 Optimal Growth

Optimal growth is defined in ForCEEPS (Morin, Bugmann, et al. 2021) as :

$$\Delta D_{\text{opt}_i}(t+1) = g_s \frac{D_i(t) \left(1 - \frac{H_i(t)}{H_{\max_s}}\right)}{2H_{\max_s} - b_{\max_s} \times \exp\left(\left(\frac{-s_s}{b_{\max_s}} D_i(t)\right) \times \left(\frac{-s_s}{b_{\max_s}} D_i(t) + 2\right)\right)} \quad (8)$$

With g_s the growth rate, D_i the diameter of the tree, H_i the height of the tree, H_{\max_s} the maximum height of the species, b_{\max_s} the maximum height of the species above breast ($b_{\max_s} = H_{\max_s} - 1.37$), and s_s the shape parameter of the species. g_s , H_{\max_s} , and s_s can be found in the appendix (Morin, Bugmann, et al. 2021). H_i is also defined as a function of D_i :

$$H_i(t) = b + b_{\max_s} \left(1 - \exp\left(-\frac{s_s}{b_{\max_s}} D_i(t)\right)\right) \quad (9)$$

This gives a function $f(D_i) = \Delta D_{\text{opt}_i}(t+1)$, which is the growth of the tree as a function of its diameter.

As our model does not account for a change of growth with diameter we took the growth from the mean diameter of our two interval : $[0, 22.5]$ and $[22.5, 67.5]$ (i.e. 11.25 and 45). It gives :

Species	Growth 1	Growth 2
<i>Abies alba</i>	0.5	0.96
<i>Betula pendula</i>	0.5	0
<i>Fagus sylvatica</i>	0.37	0.71
<i>Picea abies</i>	0.5	0.9
<i>Pinus sylvestris</i>	0.29	0.53
<i>Quercus pubescens</i>	0.28	0.5

Table 4: Growth for the 5 species and two below layers

Growth is the number of cm added to the diameter of the tree each year. To get the transition probability to the next layer with the assumption that tree dbh are uniformly distributed in each layer we need to divide this value by the diameter difference of the layer (See Tab. ??).

A.1.4 Optimal Establishment

Establishment is a process that is still not well understood. In ForCEEPS optimal establishment (if all the threshold for establishment are met) is the same for every species : 0.006 individu/m²/year. We will use this value for our model for every species.

A.1.5 Light competition

Proportionality between the species is known (see ForClim Ly (growth) and La(birth)), as mortality due to light competition is due to the absence of growth we used the same proportionality between species.

Species	Ly (growth, mortality)	La (birth)
<i>Abies alba</i>	0.05	1
<i>Betula pendula</i>	0.3	9
<i>Fagus sylvatica</i>	0.05	1
<i>Picea abies</i>	0.1	5
<i>Pinus sylvestris</i>	0.3	9
<i>Quercus pubescens</i>	0.3	7

Table 5: Sensitivity for light competition

If we have a relative sensitivity of our species to light availability we still have to get the global coefficient linked to this sensitivity for growth, birth and mortality. We cannot extract the parameters from a simplification as we used a negative linear function, which is not the case in ForCEEPS. We will use the data from ForCEEPS to fit our parameters.

A.2 ForCEEPS input data and results

ForCEEPS simulations were used to adjust the dynamic of the system. 6 species were chosen to do so : *Abies alba*, *Betula pendula*, *Fagus sylvatica*, *Picea abies*, *Pinus sylvestris*. We chose a constant climate for 300 years drawn randomly from meteorologic data from Bern between 1950 and 2000 (resulting climate can be found in Fig. 6). We used the same initial forest structure for all simulations : 10 trees per species per layer. We did 20 simulations of 1000m² patch for each species association. We then took the mean of the 20 simulations and multiplied it by 10 to get the number of trees per hectare. We then fitted the parameters of the model to get the same dynamic as the ForCEEPS simulations.

A.2.1 Climate

Climate was taken randomly for each month in the climate data from 1950 to 2000 (Bern), to get a constant climate. To be sure to have non limiting precipitation they were all multiplied by a factor 10.

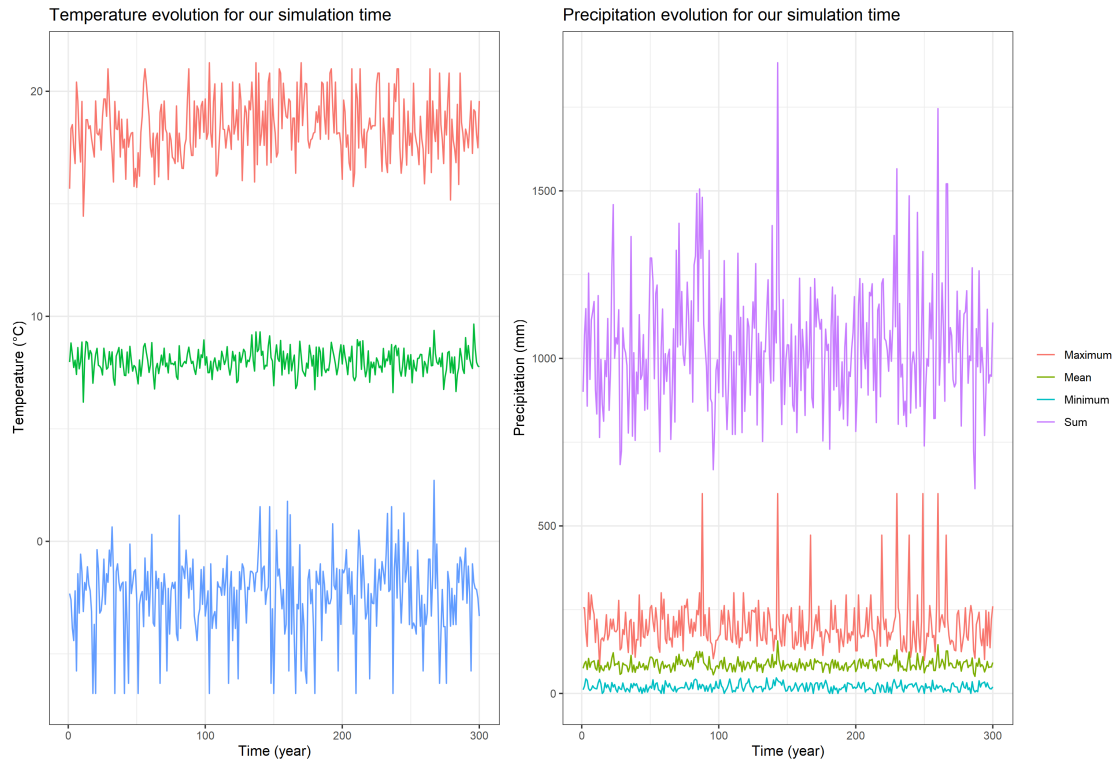


Figure 6: Climate for our ForCEEPS simulation

A.2.2 setup parameters

For the setup parameters we used non limiting values for water and nitrogen. The parameters can be found in the github documents (file Basic.setup), and are the same for all simulations.

Result of the simulation are in color in Fig. 7.

A.2.3 Fitting the parameters

To fit the parameter we used the function `optim` in R with the following parameters :

```
result <- optimParallel(start point, function to minimize, lower = rep(0,3), upper =  
rep(0.1,3), method = "L-BFGS-B")
```

Method "L-BFGS-B" (see `optim` documentation <https://www.rdocumentation.org/packages/stats/versions/3.6.2/topics/optim>) allows box constraints, that is each variable can be given a lower and/or upper bound. The initial value must satisfy the constraints. This uses a limited-memory modification of the BFGS quasi-Newton method. "BFGS" is a quasi-Newton method (also known as a variable metric algorithm), specifically that published simultaneously in 1970 by Broyden, Fletcher, Goldfarb and Shanno. This uses function values and gradients to build up a picture of the surface to be optimized.

I only fit three non specific parameters LCg (light competition for growth), LCm (light competition for mortality) and LCb (light competition for birth). In the model they are then multiplied by the sensitivity of the species to light competition (see Tab. 5).

A.2.4 Results

Species	b (/ha/an)	m (/year)	g1 (/year)	g2 (/year)	LCb	LCm	LCg
<i>Abies alba</i>	60	0.013	0.022	0.021	0.0059	0.0046	0.0059
<i>Betula pendula</i>	60	0.031	0.022	0	0.0295	0.0229	0.0295
<i>Fagus sylvatica</i>	60	0.012	0.016	0.016	0.0531	0.0413	0.0531
<i>Picea abies</i>	60	0.015	0.022	0.02	0.0531	0.0413	0.0531
<i>Pinus sylvestris</i>	60	0.023	0.013	0.012	0.0059	0.0046	0.0059
<i>Quercus pubescens</i>	60	0.008	0.012	0.011	0.0413	0.0321	0.0413

Table 6: Parameters found for the 5 species

A.3 Volume allometry

Volume was calculated with the formula from (Deleuze et al. 2014) :

$$\text{VolTot} = \frac{h_{\text{tot}} \cdot c_{130}^2}{4\pi \left(1 - \frac{1.3}{h_{\text{tot}}}\right)^2} \left(a + b \cdot \frac{\sqrt{c_{130}}}{h_{\text{tot}}} + c \cdot \frac{h_{\text{tot}}}{c_{130}} \right) \quad (10)$$

With h_{tot} the total height of the tree, c_{130} the diameter at 130cm, and a , b , and c the coefficients for each species. The coefficients can be found in (Deleuze et al. 2014). h_{tot} was defined as a function of c_{130} like in equation 9.

Species	Volume layer 1	Volume layer 2	Volume layer 3
<i>Abies alba</i>	0.007624415	0.2518305	1.724068
<i>Picea abies</i>	0.009195898	0.2779880	1.697751
<i>Pinus sylvestris</i>	0.005440307	0.1669922	1.134001
<i>Betula pendula</i>	0.004805793	0.1585726	0.947111
<i>Fagus sylvatica</i>	0.005384323	0.2140528	1.681878
<i>Quercus pubescens</i>	0.004872535	0.1729537	1.281115

Table 7: Volume of the 6 species in the 3 layers (m3/tree)

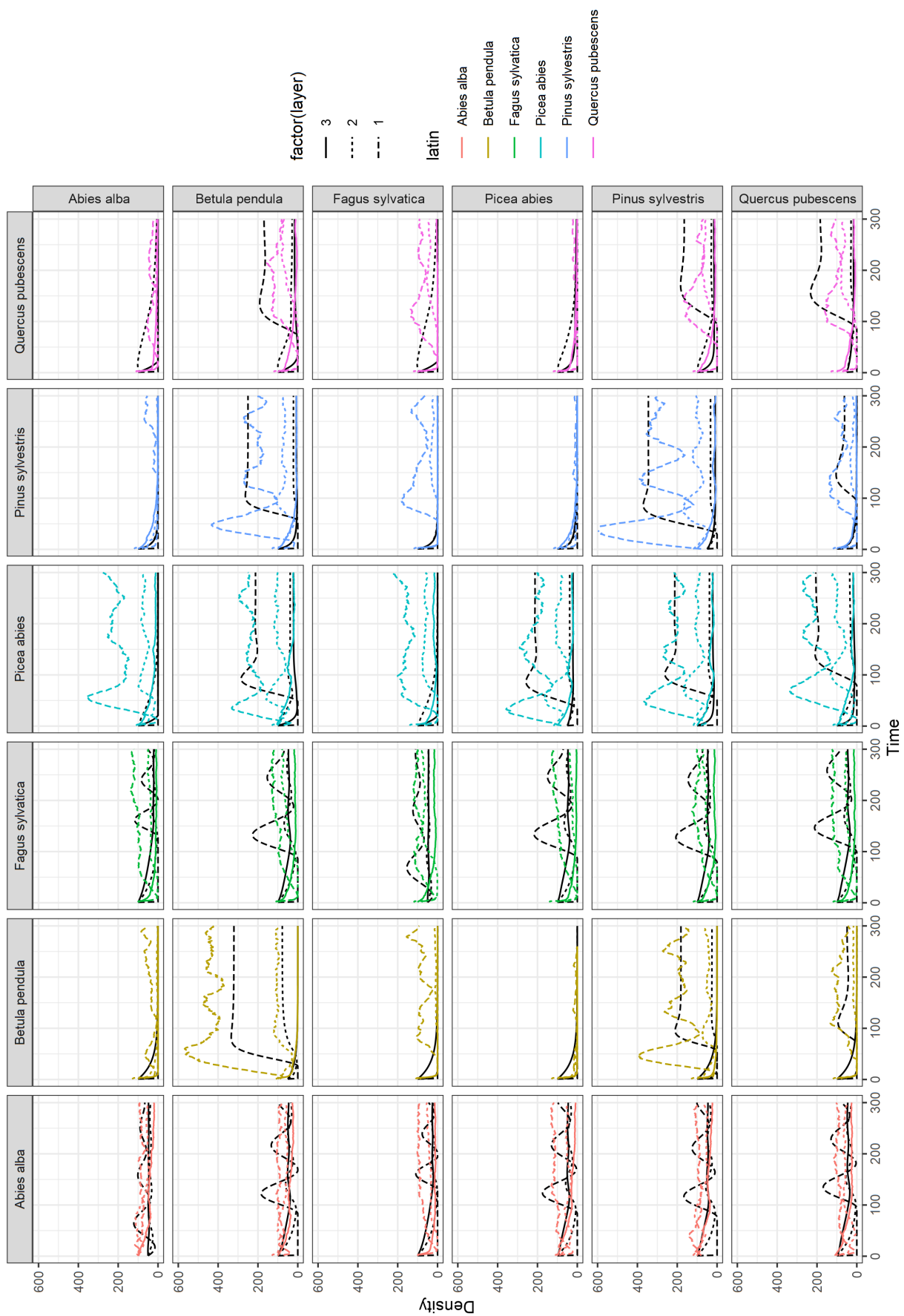


Figure 7: Fit Kohyama model (color) on ForCEEPS simulation (black) for individual species