hw3_submission.md

Homework 3

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Question 1

1 a)

Objective is to find a rank-one matrix which is closest to the incomplete matrix M, where:

```
M = [[0, 1, x], [1, x, 1], [x, 1, 2]]
```

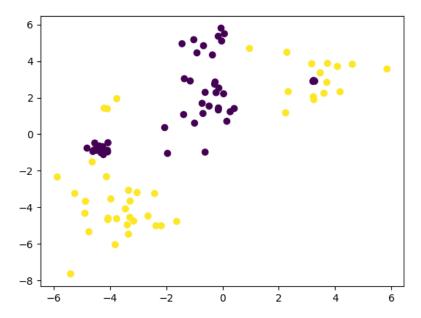
Code:

```
import numpy as np
# using alternating least squares method for collaborative filtering:
# http://www.quuxlabs.com/blog/2010/09/matrix-factorization-a-simple-tutorial-and-implementation-in-python/
def get_error(Q, X, Y, W):
    return np.sum((W * (Q - np.dot(X, Y)))**2)
def matrix_factorization(R, P, Q, K, steps=10000, alpha=0.0002, beta=0.02):
    Q = Q.T
    for step in range(steps):
        for i in range(len(R)):
            for j in range(len(R[i])):
                if R[i][j] > 0:
                    eij = R[i][j] - np.dot(P[i, :], Q[:, j])
                    for k in range(K):
                        P[i][k] = P[i][k] + alpha * (2 * eij * Q[k][j] - beta * P[i][k])
                        Q[k][j] = Q[k][j] + alpha * (2 * eij * P[i][k] - beta * Q[k][j])
        eR = np.dot(P, Q)
        e = 0
        for i in range(len(R)):
            for j in range(len(R[i])):
                if R[i][j] > 0:
                    e = e + pow(R[i][j] - np.dot(P[i, :], Q[:, j]), 2)
                    for k in range(K):
                        e = e + (beta/2) * (pow(P[i][k], 2) + pow(Q[k][j], 2))
        if e < 0.0001:
           break
    return P, Q.T
def initialiseVariables():
    R = np.array(
        [[0, 1, np.nan],
         [1, np.nan, 1],
         [np.nan, 1, 2]]
```

```
N = len(R)
      M = len(R[0])
      K = 1 # number of rows
      P = np.random.rand(N, K)
      Q = np.random.rand(M, K)
      return M, N, K, P, Q, R
  def checkAgainst(_nR):
      desired_matrix = np.array(
          [[0, 1, np.nan],
           [1, np.nan, 1],
           [np.nan, 1, 2]]
      for i in range(len(desired_matrix)):
          for j in range(len(desired_matrix[0])):
              # skip these numbers
              if i == 0 and j == 2 or i == 1 and j == 1 or i == 2 and j == 0:
              else:
                  if round(_nR[i][j]) != desired_matrix[i][j]:
                      return False
      return True
  if __name__ == '__main__':
      M, N, K, P, Q, R = initialiseVariables()
      nP, nQ = matrix_factorization(R, P, Q, K)
      nR = np.dot(nP, nQ.T)
      print(nR)
      print(nP)
      print(nQ)
      print(checkAgainst(nR))
Results:
  [[1.02515492 0.82214388 1.35229942]
  [0.85242192 0.68361713 1.12444436]
  [1.43113499 1.14772787 1.88783469]]
  [[0.97078532]
  [0.8072133]
   [1.35523404]]
  [[1.05600579]
  [0.84688536]
   [1.39299533]]
```

Question 2

2 a)



Data plotted:

Code:

```
import numpy as np
  import matplotlib.pyplot as plt
  from sklearn import svm
  def showGraph(_plt):
      _plt.show()
  def plotGraphData():
      csv = 'kernel.csv'
      data = np.genfromtxt(csv, delimiter=',')
      X = data[:, 1:]
      Y = data[:, 0]
      plt.scatter(X[:, 0], X[:, 1], c=Y)
      return X, Y, plt
  def part1():
      _, _, plt = plotGraphData()
      showGraph(plt)
  # function to train SVM based on scikit package
  # set gamma to 0.5, kernel to rbf
  def trainSVM():
      # part a
      clf = svm.SVC(gamma=0.5, kernel='rbf')
      X, Y, plt = plotGraphData()
      clf.fit(X, Y)
      return clf, X, Y
Result:
  clf:
  {\tt SVC(C=1.0, cache\_size=200, class\_weight=None, coef0=0.0,}\\
    decision_function_shape='ovr', degree=3, gamma=0.5, kernel='rbf',
```

```
max_iter=-1, probability=False, random_state=None, shrinking=True,
tol=0.001, verbose=False)
```

2 b)

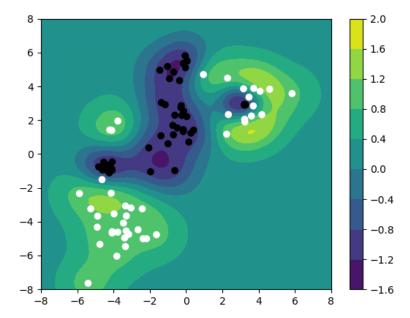
Code:

```
# this is for part b
def decision(_x1, _x2, _clf):
    x = np.array([[_x1, _x2]])
    return _clf.decision_function(x)[0]
```

2 c)

Code:

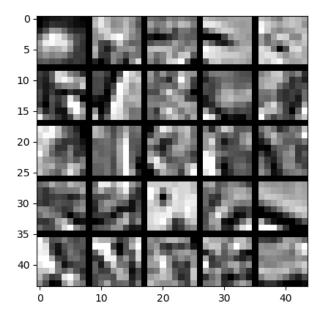
```
# part c
def visualiseClassifier():
    clf, X, Y = trainSVM()
    vdecision = np.vectorize(decision, excluded=[2])
    x1list = np.linspace(-8.0, 8.0, 100)
    x2list = np.linspace(-8.0, 8.0, 100)
    X1, X2 = np.meshgrid(x1list, x2list)
    Z = vdecision(X1, X2, clf)
    cp = plt.contourf(X1, X2, Z)
    plt.colorbar(cp)
    plt.scatter(X[:, 0], X[:, 1], c=Y, cmap='gray')
    plt.show()
```



Graph Plotted:

Question 3

3.



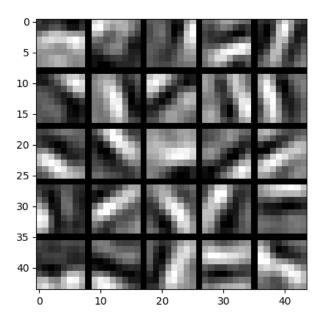
Data matrix X:

3 a)

code:

```
import numpy as np
from numpy.linalg import norm
import matplotlib.pyplot as plt
from scipy.optimize import fmin_l_bfgs_b as minimize
from Homework.Week6.utils import normalize, tile_raster_images, sigmoid, ravelParameters, unravelParameters
from Homework.Week6.utils import initializeParameters, computeNumericalGradient
def initialiseVariables():
    nV = 8 * 8 # number of visible units
    nH = 25 # number of hidden units
    dW = 0.0001 # weight decay term
    sW = 3 # sparsity penalty term
    npy = 'images.npy'
    X = normalize(np.load(npy))
    return nV, nH, dW, sW, X
# part a
def sparseAutoencoderCost(theta,nV,nH,dW,sW,X):
   W1,W2,b1,b2 = unravelParameters(theta,nH,nV)
    n = X.shape[0]
    z2 = np.dot(X, W1) + np.dot(np.ones((n, 1)), b1.T)
    a2 = sigmoid(z2)
    z3 = np.dot(a2, W2) + np.dot(np.ones((n, 1)), b2.T)
    a3 = sigmoid(z3)
    eps = a3-X
    loss = 0.5 * np.sum(eps**2)/n
    decay = 0.5 * (np.sum(W1 ** 2) + np.sum(W2 ** 2))
    # Compute sparsity terms and total cost
    rho = 0.01
    a2mean = np.mean(a2,axis=0).reshape(nH,1)
    kl = np.sum(rho*np.log(rho/a2mean)+ (1-rho)*np.log((1-rho)/(1-a2mean)))
    dkl = -rho/a2mean + (1-rho)/(1-a2mean)
    cost = loss+dW*decay+sW*kl
    d3 = eps * a3 * (1 - a3)
```

```
d2 = (sW*dk1.T+np.dot(d3,W2.T))*a2*(1-a2)
      W1grad = np.dot(X.T, d2)/n + dW * W1
      W2grad = np.dot(a2.T, d3)/n + dW * W2
      b1grad = np.dot(d2.T, np.ones((n, 1)))/n
      b2grad = np.dot(d3.T, np.ones((n, 1)))/n
      grad = ravelParameters(W1grad,W2grad,b1grad,b2grad)
      print(' .',end="")
      return cost,grad
  def checkCostGradFunction():
      nV, nH, dW, sW, X = initialiseVariables()
      theta = initializeParameters(nH, nV)
      cost, grad = sparseAutoencoderCost(theta, nV, nH, dW, sW, X)
      return cost, grad
Running checkCostGradFunction() gives:
  Cost: 54.352568640271166
  Grad: [ 0.76502459  0.94329594  0.79515806 ...  0.02468031  0.00289279
   -0.02947588]
3 b)
code:
  def compareGradients():
      # from previous
      nV, nH, dW, sW, X = initialiseVariables()
      theta = initializeParameters(nH, nV)
      cost, grad = sparseAutoencoderCost(theta, nV, nH, dW, sW, X)
      print('\nComparing numerical gradient with backprop gradient')
      num\_coords = 5
      indices = np.random.choice(theta.size, num_coords, replace=False)
      numgrad = computeNumericalGradient(lambda t: sparseAutoencoderCost(t, nV, nH, dW, sW, X)[\theta], theta, indices)
      subnumgrad = numgrad[indices]
      subgrad = grad[indices]
      diff = norm(subnumgrad - subgrad) / norm(subnumgrad + subgrad)
      print('\n', np.array([subnumgrad, subgrad]).T)
      print('The relative difference is', diff)
Running comapreGradients() gives Result:
  Comparing numerical gradient with backprop gradient
   . . . . . . . . . .
   [[-0.03965281 -0.03965281]
   [ 0.72180184  0.72180184]
   [ 0.85801614  0.85801614]
   [-0.00907039 -0.00907039]
   [ 0.89547885  0.89547885]]
  The relative difference is 4.9672839287460054e-11
3 c)
Code:
```



Output Graph:

Question 4

