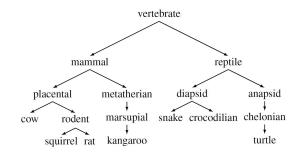


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Graphical Models Belief Propagation Algorithm

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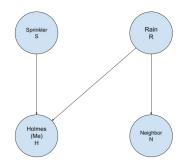
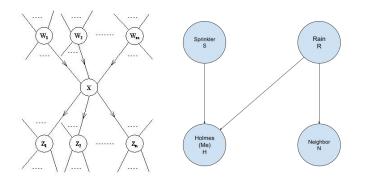
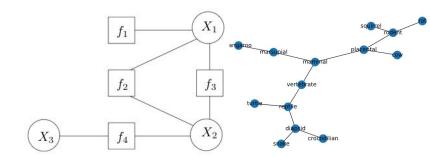


Table of Contents

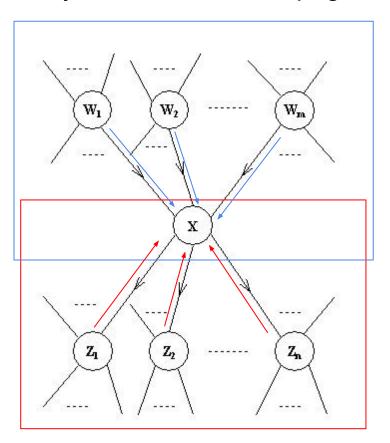
- 1. Belief Propagation on Bayesian Networks
 - a. Theory
 - b. Case Study



- 2. Belief propagation on Factor graphs
 - a. Theory
 - b. Taxonomy project



Bayesian network: Propagation Rules



Acyclic graph, but messages flow in both direction.

 $\lambda(x) = \mathbb{P}(Z_1,...,Z_n|X=x) = \prod_{j=1}^n \overline{\lambda_{Z_j}(x)}$ Likelihood

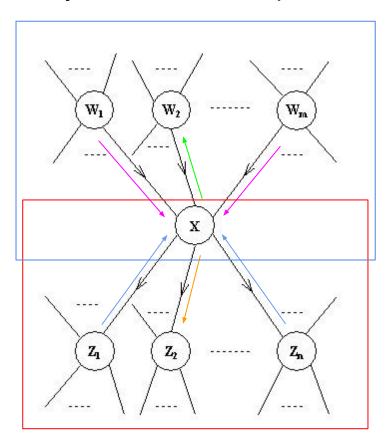
message Parent-> Child

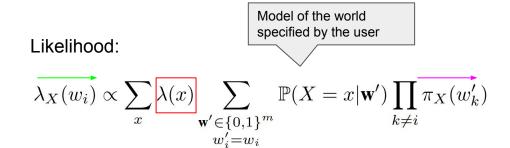
Prior
$$\pi(x) = \sum_{\mathbf{w} \in \{0,1\}^m} \mathbb{P}(X=x|\mathbf{w}) \prod_{k=1}^m \overline{\pi_X(w_k)}$$

Belief
$$BEL(x) \equiv \alpha \lambda(x) \pi(x)$$

= $\alpha \left[\prod_{j=1}^{n} \lambda_{Z_j}(x) \right] \left[\sum_{\mathbf{w}} P(x \mid \mathbf{w}) \prod_{k=1}^{n} \pi_X(w_k) \right]$

Bayesian network: Updates

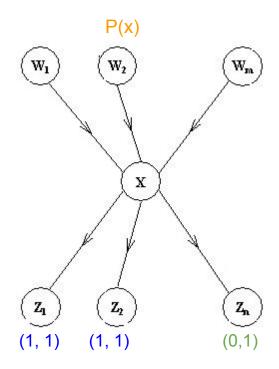




Prior:

$$\pi_{Z_j}(x) \propto \pi(x) \prod_{k \neq j} \lambda_{Z_k}(x)$$

Bayesian network: Boundary Conditions



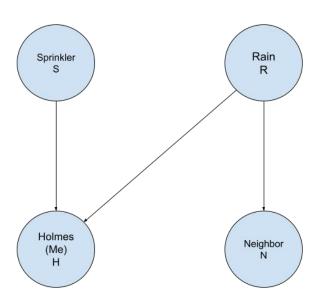
Example for binary states

Root nodes: If w is a node with no parents, we set the prior value π value equal to the prior probabilities of P(x)

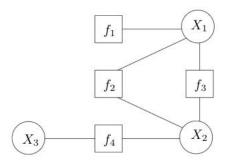
Anticipatory nodes: If X is a childless node that has not been instantiated, we set the λ value as a vector of all 1's

Evidence nodes: If evidence $X=x_i$ is obtained, we set the λ value to (0,...,0,1,0,...0) with 1 at the i_{th} position.

Bayesian network: Case study



Factor Graphs: Theory



Factor Graph = Bipartite Graph

- ___ Factor node
- Variable node

Total likelihood:

$$p(\mathbf{x}) = \prod_{f \in F} \mathbf{f}_f(\mathbf{x}_f)$$

Propagation:

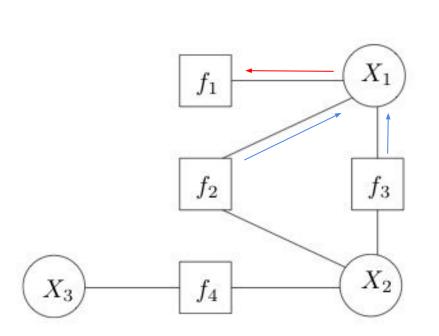
$$\mu_{v \to f}(x_v) = \prod_{f^* \in N(v) \setminus \{f\}} \mu_{f^* \to v}(x_v)$$

$$\mu_{f \to v}(x_{v}) = \sum_{\mathbf{x'}_{f}: x'_{v} = x_{v}} f_{f}(\mathbf{x'}_{f}) \prod_{v^{*} \in N(f) \setminus \{v\}} \mu_{v^{*} \to f}(\mathbf{x'}_{v^{*}})$$

Marginals:

$$p_{X_{v}}(x_{v}) \propto \prod_{f \in N(v)} \mu_{f \to v}(x_{v})$$

Factor Graphs: example of propagation: variable to factor node



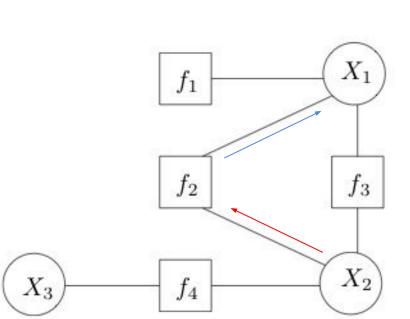
$$\overrightarrow{\mu_{v \to f}(x_v)} = \prod_{f \star \in N(v) \setminus \{f\}} \overrightarrow{\mu_{f \star \to v}(x_v)}$$

Messages from variable X to factor nodes f are vectors of size NbStates(X)

Messages from factor f to variable X are also vectors of size NbStates(X)

We just multiply coordinate by coordinates the two incoming messages

Factor Graphs: example of propagation: factor to variable node



$$\overline{\mu_{f \to v}(x_{v})} = \sum_{\mathbf{x'}_{f}: x'_{v} = x_{v}} f_{f}(\mathbf{x'}_{f}) \prod_{v^{*} \in N(f) \setminus \{v\}} \overline{\mu_{v^{*} \to f}(x'_{v^{*}})}$$

Messages from variable X to factor nodes f are vectors of size NbStates(X)

Messages from factor f to variable X are also vectors of size NbStates(X)

We just multiply coordinate by coordinates the incoming messages

Factor Graphs: Taxonomy Project

From a corpus of abstracts on Wikipedia, and a selection of words (x1, ..., xn), the objective is to discover the taxonomic structure.

