

# 3D Cloud Classification : PointNet apply to ModelNet10

```
In [21]: #import all the necessary stuffs
import torch
import os
import numpy as np
from matplotlib import pyplot as plt
import random
import math
from torch.utils.data import Dataset, DataLoader, TensorDataset
from torchvision import transforms, utils
import torch.nn as nn
import torch.nn.functional as F
if torch.cuda.is_available():
    dev = "cuda:0"
else:
    dev = "cpu"
device = torch.device(dev)
global device
print(device)
```

cuda:0

```
In [22]: from torch.utils.tensorboard import SummaryWriter
```

```
#
#
#      0=====0
#      |   PLY files reader/writer   |
#      0=====0
#
#
#-----
#
#      function to read/write .ply files
#
#-----
#
#      Hugues THOMAS - 10/02/2017
#
#
#-----
#
#      Imports and global variables
#      \*****/
#
# Basic libs
import numpy as np
import sys

# Define PLY types
ply_dtypes = dict([
    (b'int8', 'i1'),
    (b'char', 'i1'),
    (b'uint8', 'u1'),
    (b'uchar', 'b1'),
```

```

    (b'uchar', 'u1'),
    (b'int16', 'i2'),
    (b'short', 'i2'),
    (b'uint16', 'u2'),
    (b'ushort', 'u2'),
    (b'int32', 'i4'),
    (b'int', 'i4'),
    (b'uint32', 'u4'),
    (b'uint', 'u4'),
    (b'float32', 'f4'),
    (b'float', 'f4'),
    (b'float64', 'f8'),
    (b'double', 'f8')
])

# Numpy reader format
valid_formats = {'ascii': '', 'binary_big_endian': '>',
                  'binary_little_endian': '<'}

#-----
#
#           Functions
#       \*****/
#

def parse_header(plyfile, ext):

    # Variables
    line = []
    properties = []
    num_points = None

    while b'end_header' not in line and line != b'':
        line = plyfile.readline()
        if b'element' in line:
            line = line.split()
            num_points = int(line[2])

            elif b'property' in line:
                line = line.split()
                properties.append((line[2].decode(), ext + ply_dtypes[line[1]]))

    return num_points, properties

def read_ply(filename):
    """
    Read ".ply" files

    Parameters
    -----
    filename : string
        the name of the file to read.

    Returns
    -----
    result : array
        data stored in the file

    Examples
    -----
    Store data in file

    >>> points = np.random.rand(5, 3)
    >>> values = np.random.randint(2, size=10)

```

```
>>> write_ply('example.ply', [points, values], ['x', 'y', 'z', 'values'])
```

Read the file

```
>>> data = read_ply('example.ply')
```

```
>>> values = data['values']
```

```
array([0, 0, 1, 1, 0])
```

```
>>> points = np.vstack((data['x'], data['y'], data['z'])).T
```

```
array([[ 0.466  0.595  0.324]
       [ 0.538  0.407  0.654]
       [ 0.850  0.018  0.988]
       [ 0.395  0.394  0.363]
       [ 0.873  0.996  0.092]])
```

```
"""
```

```
with open(filename, 'rb') as plyfile:
```

```
    # Check if the file start with ply
```

```
    if b'ply' not in plyfile.readline():
```

```
        raise ValueError('The file does not start with the word ply')
```

```
    # get binary_little/big or ascii
```

```
    fmt = plyfile.readline().split()[1].decode()
```

```
    if fmt == "ascii":
```

```
        raise ValueError('The file is not binary')
```

```
    # get extension for building the numpy dtypes
```

```
    ext = valid_formats[fmt]
```

```
    # Parse header
```

```
    num_points, properties = parse_header(plyfile, ext)
```

```
    # Get data
```

```
    data = np.fromfile(plyfile, dtype=properties, count=num_points)
```

```
    return data
```

```
def header_properties(field_list, field_names):
```

```
    # List of lines to write
```

```
    lines = []
```

```
    # First line describing element vertex
```

```
    lines.append('element vertex %d' % field_list[0].shape[0])
```

```
    # Properties lines
```

```
    i = 0
```

```
    for fields in field_list:
```

```
        for field in fields.T:
```

```
            lines.append('property %s %s' % (field.dtype.name, field_names[i]))
```

```
            i += 1
```

```
    return lines
```

```
def write_ply(filename, field_list, field_names):
```

```
    """
```

```
    Write ".ply" files
```

```
    Parameters
```

```
    -----
```

```
    filename : string
```

```
        the name of the file to which the data is saved. A '.ply' extension will  
        be appended to the file name if it does not already have one.
```

`field_list`: list, tuple, numpy array  
the fields to be saved in the ply file. Either a numpy array, a list of numpy arrays or a tuple of numpy arrays. Each 1D numpy array and each column of 2D numpy arrays are considered as one field.

`field_names`: list  
the name of each fields as a list of strings. Has to be the same length as the number of fields.

### Examples

-----

```
>>> points = np.random.rand(10, 3)
>>> write_ply('example1.ply', points, ['x', 'y', 'z'])

>>> values = np.random.randint(2, size=10)
>>> write_ply('example2.ply', [points, values], ['x', 'y', 'z', 'values'])

>>> colors = np.random.randint(255, size=(10,3), dtype=np.uint8)
>>> field_names = ['x', 'y', 'z', 'red', 'green', 'blue', 'values']
>>> write_ply('example3.ply', [points, colors, values], field_names)
```

"""

*# Format list input to the right form*

```
field_list = list(field_list) if (type(field_list) == list or type(field_list) ==
for i, field in enumerate(field_list):
    if field is None:
        print('WRITE_PLY ERROR: a field is None')
        return False
    elif field.ndim > 2:
        print('WRITE_PLY ERROR: a field have more than 2 dimensions')
        return False
    elif field.ndim < 2:
        field_list[i] = field.reshape(-1, 1)
```

*# check all fields have the same number of data*

```
n_points = [field.shape[0] for field in field_list]
if not np.all(np.equal(n_points, n_points[0])):
    print('wrong field dimensions')
    return False
```

*# Check if field\_names and field\_list have same nb of column*

```
n_fields = np.sum([field.shape[1] for field in field_list])
if (n_fields != len(field_names)):
    print('wrong number of field names')
    return False
```

*# Add extension if not there*

```
if not filename.endswith('.ply'):
    filename += '.ply'
```

*# open in text mode to write the header*

```
with open(filename, 'w') as plyfile:
```

*# First magical word*

```
header = ['ply']
```

*# Encoding format*

```
header.append('format binary_' + sys.byteorder + '_endian 1.0')
```

*# Points properties description*

```
header.extend(header_properties(field_list, field_names))
```

*# End of header*

```
header.append('end_header')
```



```

        rot_pointcloud = torch.matmul(pointcloud, rot_matrix)
        return rot_pointcloud

class RandomNoise(object):
    def __call__(self, pointcloud):

        noise = torch.rand(pointcloud.size(0), pointcloud.size(1)).to(device)*0.02
        noisy_pointcloud = pointcloud + noise
        return noisy_pointcloud

class ShufflePoints(object):
    def __call__(self, pointcloud):
        index = torch.randperm(pointcloud.size(0))
        pointcloud[:, :] = pointcloud[index]
        return pointcloud

class AxisReducer(object):
    def __call__(self, pointcloud):
        pointcloud[:, 0] = torch.sqrt(torch.square(pointcloud[:, 0]) + torch.square(pointcloud[:, 1]))
        pointcloud[:, 1] = 0
        return pointcloud

class NormalizePoints(object):
    def __call__(self, pointcloud):
        return pointcloud / (torch.max(torch.min(pointcloud), torch.max(pointcloud)))

class PointsToVoxel(object):
    def __call__(self, pointcloud, voxel_size = 8):
        pointcloud = ((pointcloud + 1) / 2.01) * voxel_size
        return pointcloud

class VoxelToBool(object): #to visualize the result of PointsToVoxel
    def __call__(self, pointcloud, voxel_size = 8):
        bool_array = torch.zeros((voxel_size, voxel_size, voxel_size), dtype=bool)
        for i in range(pointcloud.size(0)):
            bool_array[pointcloud[i][0], pointcloud[i][1], pointcloud[i][2]] = True
        return bool_array

def default_transforms():
    return transforms.Compose([
        ToTensor(),
        RandomRotation_z(),
        RandomNoise(),
        ShufflePoints(),
    ])

def customize_transforms():
    return transforms.Compose([
        ToTensor(),
        RandomRotation_z(),
        RandomNoise(),
        AxisReducer(),
        ShufflePoints(),
    ])

def customize_transforms_voxel():
    return transforms.Compose([
        ToTensor(),
        RandomRotation_z(),
        RandomNoise(),
        NormalizePoints(),
        PointsToVoxel(),
        ShufflePoints(),
    ])

```

In [24]: *#define our and verify our dataset*

```
class PointCloudData(Dataset):
    def __init__(self,
                  root_dir,
                  folder="train",
                  transform=default_transforms()):
        self.root_dir = root_dir
        folders = [dir for dir in sorted(os.listdir(root_dir))
                   if os.path.isdir(root_dir + "/" + dir)]
        self.classes = {folder: i for i, folder in enumerate(folders)}
        self.transforms = transform
        self.files = []
        for category in self.classes.keys():
            new_dir = root_dir+"/"+category+"/"+folder
            for file in os.listdir(new_dir):
                if file.endswith('.ply'):
                    sample = {}
                    sample['ply_path'] = new_dir+"/"+file
                    sample['category'] = category
                    self.files.append(sample)

    def __len__(self):
        return len(self.files)

    def __getitem__(self, idx):
        ply_path = self.files[idx]['ply_path']
        category = self.files[idx]['category']
        data = read_ply(ply_path)
        pointcloud = self.transforms(np.vstack((data['x'],
                                                data['y'],
                                                data['z'])).T)

        return {'pointcloud': pointcloud, 'category': self.classes[category]}

def slice_dataset(dataset_input):
    dataset = []
    for i in range(10):
        dataset.append([])

    for obj in dataset_input:
        index = obj["category"]
        dataset[index].append(obj["pointcloud"])
    torch_dataset = []
    for data in dataset:
        #print(torch.cat(data))

        torch_dataset.append(torch.stack(data))

    return torch_dataset

NUM_POINTS = 1024
NUM_CLASSES = 10
BATCH_SIZE = 32

train_ds = PointCloudData("./data/ModelNet10_PLY")
test_ds = PointCloudData("./data/ModelNet10_PLY", folder='test')

dataloader_train = DataLoader(train_ds, batch_size=BATCH_SIZE, shuffle=True)
dataloader_test = DataLoader(test_ds, batch_size=BATCH_SIZE, shuffle=True)
```

```

train_ds_augment = PointCloudData("./data/ModelNet10_PLY",transform=customize_transfo
test_ds_augment = PointCloudData("./data/ModelNet10_PLY", folder='test',transform=cus

dataloader_train_augment = DataLoader(train_ds_augment, batch_size=BATCH_SIZE, shuffl
dataloader_test_augment = DataLoader(test_ds_augment, batch_size=BATCH_SIZE, shuffle=

train_ds_augment_voxel = PointCloudData("./data/ModelNet10_PLY",transform=customize_t
test_ds_augment_voxel = PointCloudData("./data/ModelNet10_PLY", folder='test',transfo

dataloader_train_augment_voxel = DataLoader(train_ds_augment_voxel, batch_size=BATCH_
dataloader_test_augment_voxel = DataLoader(test_ds_augment_voxel, batch_size=BATCH_SI

index =800

plt.figure(1)
points = train_ds[index]["pointcloud"].cpu()

plt.figure(1)
fig = plt.figure(figsize=(5, 5))
ax = fig.add_subplot(111, projection="3d")
ax.scatter(points[:, 0], points[:, 1], points[:, 2],s=5)
ax.set_axis_off()
plt.show()

points = train_ds_augment_voxel[index]["pointcloud"].cpu()

voxel_to_bool = VoxelToBool()

voxelarray = voxel_to_bool(points)
print(voxelarray.shape)

plt.rcParams["figure.figsize"] = [5,5]
plt.rcParams["figure.autolayout"] = True
ax = plt.figure(2).add_subplot(projection='3d')

#ax.voxels(voxelarray, edgecolor="k",facecolors="red")
ax.voxels(voxelarray, edgecolor='k')

plt.show()
print(voxelarray.shape)

```

<Figure size 640x480 with 0 Axes>

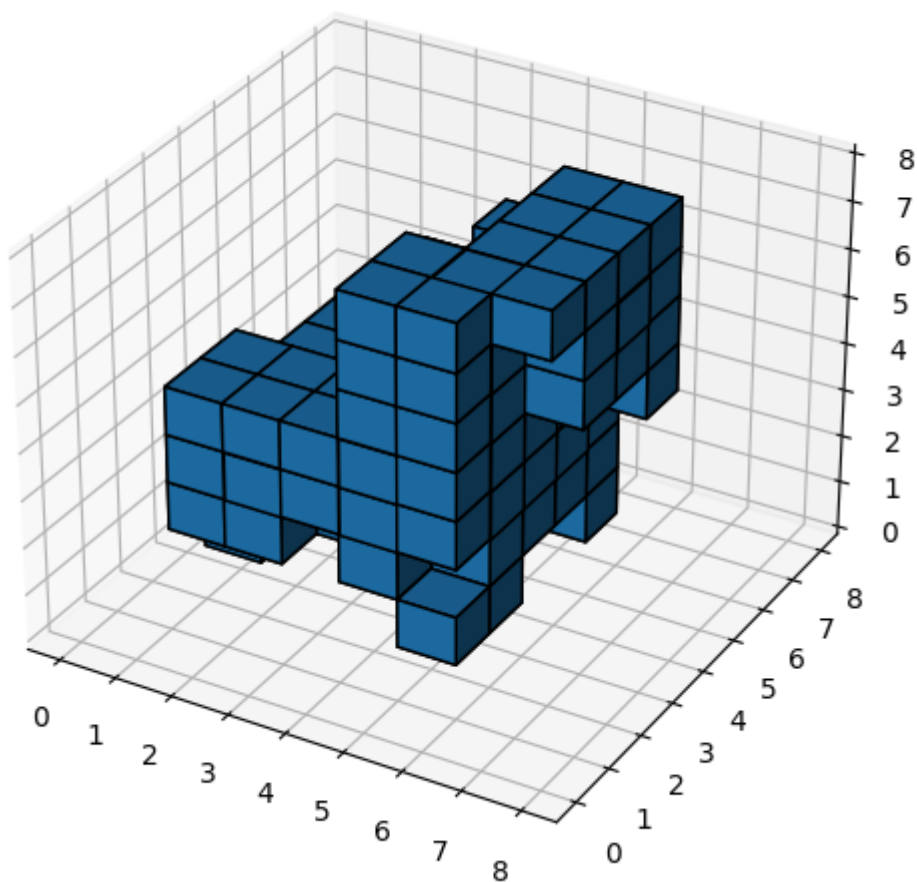




```
torch.Size([8, 8, 8])
```

/home/a/.local/lib/python3.8/site-packages/IPython/core/pylabtools.py:152: UserWarning: This figure includes Axes that are not compatible with tight\_layout, so results might be incorrect.

```
fig.canvas.print_figure(bytes_io, **kw)
```



```
torch.Size([8, 8, 8])
```

```
In [25]: # show an example of each object
num_classes = 10
titles_object = []
for key in train_ds_augment.classes:
    titles_object.append(key)
```

```

# fig, ax = plt.subplots(num_classes, 5, figsize=(10,20))
fig = plt.figure(figsize=(14,20))

sliced_dataset = slice_dataset(train_ds)
sliced_dataset_test = slice_dataset(test_ds)

size_x = 7
for i in range(num_classes):
    for j in range(size_x):
        points = sliced_dataset[i][j].cpu()

        ax = fig.add_subplot(num_classes, size_x, 1+i*size_x+j, projection='3d')
        plt.title(titles_object[i]+" : "+str(j))

        ax.scatter(points[:, 0], points[:, 1], points[:, 2], s=1)

        ax.set_axis_off()

plt.legend()
plt.show()

print("Numbers of each object")
for i in range(num_classes):
    print(i, len(sliced_dataset[i]), len(sliced_dataset_test[i]))

del sliced_dataset, sliced_dataset_test

```

No artists with labels found to put in legend. Note that artists whose label start with an underscore are ignored when legend() is called with no argument.

bathtub : 0



bathtub : 1



bathtub : 2



bathtub : 3



bathtub : 4



bathtub : 5



bathtub : 6



bed : 0



bed : 1



bed : 2



bed : 3



bed : 4



bed : 5



bed : 6



chair : 0



chair : 1



chair : 2



chair : 3



chair : 4



chair : 5



chair : 6



desk : 0



desk : 1



desk : 2



desk : 3



desk : 4



desk : 5



desk : 6



dresser : 0



dresser : 1



dresser : 2



dresser : 3



dresser : 4



dresser : 5



dresser : 6



monitor : 0



monitor : 1



monitor : 2



monitor : 3



monitor : 4



monitor : 5



monitor : 6



night\_stand : 0



night\_stand : 1



night\_stand : 2



night\_stand : 3



night\_stand : 4



night\_stand : 5



night\_stand : 6



sofa : 0



sofa : 1



sofa : 2



sofa : 3



sofa : 4



sofa : 5



sofa : 6



table : 0



table : 1



table : 2



table : 3



table : 4



table : 5



table : 6



toilet : 0



toilet : 1



toilet : 2



toilet : 3



toilet : 4



toilet : 5



toilet : 6



Numbers of each object

0	106	50
1	515	100
2	889	100
3	200	86
4	200	86
5	465	100
6	200	86
7	680	100
8	392	100
9	344	100

```
In [26]: #define plot, loss and train loop of our dataset
def plot_all(accuracy_train_array, accuracy_test_array, loss_train_array, loss_test_array):
    plt.figure(1)
    plt.xlabel("Epochs")
    plt.ylabel("Accuracy in %")
    plt.plot(accuracy_train_array, label="Accuracy train")
    plt.plot(accuracy_test_array, label="Accuracy test")

    plt.legend()
    plt.show()
    plt.figure(2)
    plt.xlabel("Epochs")
    plt.ylabel("Loss")

    plt.plot(loss_train_array, label="Loss train")
    plt.plot(loss_test_array, label="Loss test")

    plt.legend()
    plt.show()
def basic_loss(outputs, labels):
    #outputs, labels = torch.Tensor(outputs, dtype=torch.long), torch.Tensor(labels, dtype=torch.long)
    #criterion = torch.nn.NLLLoss()
    criterion = torch.nn.CrossEntropyLoss()
    #criterion = torch.nn.CrossEntropyLoss()
    bsize = outputs.size(0)
    #outputs = torch.transpose(outputs, 0, 1)
    return criterion(outputs, labels)

def pointnet_full_loss(outputs, labels, m1, m2, loss_func, alpha=0.001):
    #criterion = torch.nn.NLLLoss()
    criterion = loss_func
    #criterion = torch.nn.CrossEntropyLoss()
    bsize = outputs.size(0)

    id_1 = torch.eye(m1.size(1), requires_grad=True).repeat(bsize, 1, 1).to(device)
    diff1 = id_1 - torch.bmm(m1, m1.transpose(1, 2))

    id_2 = torch.eye(m2.size(1), requires_grad=True).repeat(bsize, 1, 1).to(device)
    diff2 = id_2 - torch.bmm(m2, m2.transpose(1, 2))

    return criterion(outputs, labels) + alpha * (torch.norm(diff1)) / float(bsize) +

def get_accuracy(labels_predict, labels_true):
    _, predicted = torch.max(labels_predict.data, 1)
    total = labels_true.size(0)
    correct = (predicted == labels_true).sum().item()
    val_acc = 100. * correct / total
    return val_acc

def evaluation_model(model, dataloader_test, loss_func):
    correct = total = 0
```

```

loss_test=0
val_acc_test=0
size=0
with torch.no_grad():
    for id_batch, data in enumerate(dataloader_test):
        inputs, labels = data['pointcloud'].float(), data['category']
        size+=1
        predicted, rotation_1, rotation_2 = model(inputs)
        # outputs, __ = model(inputs.transpose(1,2))

        predicted, labels = torch.Tensor(predicted).type(torch.FloatTensor), torch
        #loss_test = basic_loss(predicted, labels)
        loss_test += pointnet_full_loss(predicted, labels, rotation_1, rotation_2, l
        val_acc_test += get_accuracy(predicted, labels)

    return loss_test/size, val_acc_test/size

def train(
    model,
    dataloader_train,
    dataloader_test,
    epochs=100,
    loss_func=torch.nn.NLLLoss()
):
    optimizer = torch.optim.Adam(model.parameters(), lr=0.001)
    scheduler = torch.optim.lr_scheduler.StepLR(optimizer,
                                                step_size=20, gamma=0.5)

    (loss_train_array, accuracy_train_array, loss_test_array, accuracy_test_array,) = [],

    for epoch in range(epochs):

        for id_batch, data in enumerate(dataloader_train):
            inputs, labels = data['pointcloud'].float(), data['category']

            optimizer.zero_grad()
            labels_predict, rotation_1, rotation_2 = model(inputs)
            labels_predict, labels = torch.Tensor(labels_predict).type(torch.FloatTensor)
            #loss_train = basic_loss(labels_predict, labels)

            loss_train = pointnet_full_loss(labels_predict, labels, rotation_1, rotation_2)

            loss_train.backward()
            optimizer.step()
            #print(id_batch)
            if id_batch==0:

                acc_train = get_accuracy(labels_predict, labels)
                loss_train_array.append(loss_train.cpu().detach().numpy())
                accuracy_train_array.append(acc_train)
                scheduler.step()
                loss_test, acc_test=evaluation_model(model, dataloader_test, loss_func)
                loss_test_array.append(loss_test.cpu().detach().numpy())
                accuracy_test_array.append(acc_test)

                print('Epoch: %d, Loss_train: %.3f, Accuracy_train: %.1f %, Loss_test: %.3f, Accuracy_test: %.1f %' % (epoch, loss_train, acc_train, loss_test, acc_test))

    return loss_train_array, accuracy_train_array, loss_test_array, accuracy_test_array

```

In [27]: *#define our different model*

```

class PointMLP(nn.Module):
    def __init__(self, input_size, classes=10):

```

```

    super(PointMLP, self).__init__()
    l_1 = 512
    l_2 = 256

    self.fc_1 = nn.Linear(NUM_POINTS*3, l_1).to(device)
    self.bn_1 = nn.BatchNorm1d(l_1).to(device)
    self.fc_2 = nn.Linear(l_1, l_2).to(device)
    self.dropout_1 = nn.Dropout(0.3).to(device)
    self.bn_2 = nn.BatchNorm1d(l_2).to(device)

    self.fc_3 = nn.Linear(l_2, classes).to(device)
    self.bn_3 = nn.BatchNorm1d(classes).to(device)

    self.eye_1 = torch.eye(1, requires_grad=False)
    self.eye_2 = torch.eye(1, requires_grad=False)

def forward(self, x):
    x = x.to(device)

    x = torch.flatten(x, start_dim=1)
    x = self.fc_1(x)
    x = self.bn_1(x)
    x = F.relu(x)
    x = self.fc_2(x)
    x = self.dropout_1(x)
    x = self.bn_2(x)
    x = F.relu(x)
    x = self.fc_3(x)
    x = self.bn_3(x)
    x = F.relu(x)
    return x, self.eye_1.repeat(x.size(0), 1, 1).to(device), self.eye_2.repeat(x.size(0), 1, 1).to(device)

class Tnet(nn.Module):
    def __init__(self, input_size, kernel_size):
        super(Tnet, self).__init__()
        #l_1 = 64
        #l_2 = 128
        #l_3 = 1024
        #l_4 = 512
        #l_5 = 256

        l_1 = 32
        l_2 = 64
        l_3 = 256
        l_4 = 128
        l_5 = 64

        self.kn_size = kernel_size

        self.fc_1 = nn.Conv1d(kernel_size, l_1, 1).to(device)
        self.bn_1 = nn.BatchNorm1d(l_1).to(device)
        self.fc_2 = nn.Conv1d(l_1, l_2, 1).to(device)
        self.bn_2 = nn.BatchNorm1d(l_2).to(device)
        self.fc_3 = nn.Conv1d(l_2, l_3, 1).to(device)
        self.bn_3 = nn.BatchNorm1d(l_3).to(device)

        self.mp = nn.MaxPool1d(l_3).to(device)
        self.fc_4 = nn.Linear(input_size, l_4).to(device)
        self.bn_4 = nn.BatchNorm1d(l_4).to(device)
        self.fc_5 = nn.Linear(l_4, l_5).to(device)
        self.bn_5 = nn.BatchNorm1d(l_5).to(device)
        self.fc_6 = nn.Linear(l_5, self.kn_size*self.kn_size).to(device)

def forward(self, x):

```

```

x = x.to(device)

#x = torch.flatten(x,start_dim=-2)
x = x.transpose(2, 1)
x = self.fc_1(x)
x = self.bn_1(x)
x = F.relu(x)
x = self.fc_2(x)
x = self.bn_2(x)
x = F.relu(x)
x = self.fc_3(x)
x = self.bn_3(x)
x = F.relu(x)

x = self.mp(x)
x = torch.flatten(x,start_dim=1)
x = self.fc_4(x)
x = self.bn_4(x)
x = F.relu(x)
x = self.fc_5(x)
x = self.bn_5(x)
x = F.relu(x)
x = self.fc_6(x)
x = x.view(-1,self.kn_size,self.kn_size)
return x

```

```

class InputTransform(nn.Module):
    def __init__(self,input_size, kernel_size):
        super(InputTransform, self).__init__()
        self.kn_size = kernel_size

        self.t_net = Tnet(input_size, kernel_size).to(device)

    def forward(self, x):
        x = x.to(device)
        kern = self.t_net(x)
        x = torch.matmul(x,kern)
        return x,kern

```

```

class PointNetBasic(nn.Module):
    def __init__(self, input_size,classes=10):
        super(PointNetBasic, self).__init__()
        #l_1 = 64
        #l_2 = 64
        #l_3 = 64
        #l_4 = 128
        #l_5 = 1024
        #l_6 = 512
        #l_7 = 256

        l_1 = 32
        l_2 = 32
        l_3 = 32
        l_4 = 128
        l_5 = 512
        l_6 = 256
        l_7 = 128

        self.fc_1 = nn.Conv1d(3,l_1,1).to(device)
        self.bn_1 = nn.BatchNorm1d(l_1).to(device)
        self.fc_2 = nn.Conv1d(l_1,l_2,1).to(device)
        self.bn_2 = nn.BatchNorm1d(l_2).to(device)
        self.fc_3 = nn.Conv1d(l_2,l_3,1).to(device)
        self.bn_3 = nn.BatchNorm1d(l_3).to(device)
        self.fc_4 = nn.Conv1d(l_3,l_4,1).to(device)

```

```

self.bn_4 = nn.BatchNorm1d(l_4).to(device)
self.fc_5 = nn.Conv1d(l_4,l_5,1).to(device)
self.bn_5 = nn.BatchNorm1d(l_5).to(device)

self.mp = nn.MaxPool1d(l_5).to(device)
self.fc_6 = nn.Linear(input_size,l_6).to(device)
self.bn_6 = nn.BatchNorm1d(l_6).to(device)
self.fc_7 = nn.Linear(l_6,l_7).to(device)
self.dropout_1 = nn.Dropout(0.3).to(device)
self.bn_7 = nn.BatchNorm1d(l_7).to(device)
self.fc_8 = nn.Linear(l_7,classes).to(device)
self.eye_1 = torch.eye(1, requires_grad=False)
self.eye_2 = torch.eye(1, requires_grad=False)

```

```

def forward(self, x):
    x=x.to(device)
    x = x.transpose(2, 1)
    x = self.fc_1(x)
    x = self.bn_1(x)
    x = F.relu(x)
    x = self.fc_2(x)
    x = self.bn_2(x)
    x = F.relu(x)
    x = self.fc_3(x)
    x = self.bn_3(x)
    x = F.relu(x)
    x = self.fc_4(x)
    x = self.bn_4(x)
    x = F.relu(x)
    x = self.fc_5(x)
    x = self.bn_5(x)
    x = F.relu(x)

    x = self.mp(x)
    x = torch.flatten(x,start_dim=1)

    x = self.fc_6(x)
    x = self.bn_6(x)
    x = F.relu(x)
    x = self.fc_7(x)
    x = self.bn_7(x)
    x = F.relu(x)
    x = self.dropout_1(x)
    x = self.fc_8(x)
    return x,self.eye_1.repeat(x.size(0), 1, 1).to(device),self.eye_2.repeat(x.si

```

```

class PointNetFull(nn.Module):
    def __init__(self, input_size,classes=10):
        super(PointNetFull, self).__init__()
        #l_1 = 64
        #l_2 = 64
        #l_3 = 64
        #l_4 = 128
        #l_5 = 1024
        #l_6 = 512
        #l_7 = 256

        l_1 = 32
        l_2 = 32
        l_3 = 32
        l_4 = 128
        l_5 = 512
        l_6 = 256

```



```
l_7 = 128
```

```
#torch.nn.Conv1d(3, 64, 1)
```

```
self.input_transform_1 = InputTransform(input_size,3).to(device)
```

```
self.fc_1 = nn.Conv1d(3,l_1,1).to(device)
```

```
self.bn_1 = nn.BatchNorm1d(l_1).to(device)
```

```
self.fc_2 = nn.Conv1d(l_1,l_2,1).to(device)
```

```
self.bn_2 = nn.BatchNorm1d(l_2).to(device)
```

```
self.fc_3 = nn.Conv1d(l_2,l_3,1).to(device)
```

```
self.bn_3 = nn.BatchNorm1d(l_3).to(device)
```

```
self.fc_4 = nn.Conv1d(l_3,l_4,1).to(device)
```

```
self.bn_4 = nn.BatchNorm1d(l_4).to(device)
```

```
self.fc_5 = nn.Conv1d(l_4,l_5,1).to(device)
```

```
self.bn_5 = nn.BatchNorm1d(l_5).to(device)
```

```
self.mp = nn.MaxPool1d(l_5).to(device)
```

```
self.fc_6 = nn.Linear(input_size,l_6).to(device)
```

```
self.bn_6 = nn.BatchNorm1d(l_6).to(device)
```

```
self.fc_7 = nn.Linear(l_6,l_7).to(device)
```

```
self.dropout_1 = nn.Dropout(0.3).to(device)
```

```
self.bn_7 = nn.BatchNorm1d(l_7).to(device)
```

```
self.fc_8 = nn.Linear(l_7,classes).to(device)
```

```
self.eye_1 = torch.eye(1, requires_grad=False)
```

```
self.eye_2 = torch.eye(1, requires_grad=False)
```

```
def forward(self, x):
```

```
    x=x.to(device)
```

```
    x,rotation_1 = self.input_transform_1(x)
```

```
    x = x.transpose(2, 1)
```

```
    x = self.fc_1(x)
```

```
    x = self.bn_1(x)
```

```
    x = F.relu(x)
```

```
    x = self.fc_2(x)
```

```
    x = self.bn_2(x)
```

```
    x = F.relu(x)
```

```
    x = self.fc_3(x)
```

```
    x = self.bn_3(x)
```

```
    x = F.relu(x)
```

```
    x = self.fc_4(x)
```

```
    x = self.bn_4(x)
```

```
    x = F.relu(x)
```

```
    x = self.fc_5(x)
```

```
    x = self.bn_5(x)
```

```
    x = F.relu(x)
```

```
    x = self.mp(x)
```

```
    x = torch.flatten(x,start_dim=1)
```

```
    x = self.fc_6(x)
```

```
    x = self.bn_6(x)
```

```
    x = F.relu(x)
```

```
    x = self.fc_7(x)
```

```
    x = self.bn_7(x)
```

```
    x = F.relu(x)
```

```
    x = self.dropout_1(x)
```

```
    x = self.fc_8(x)
```

```
    return x,rotation_1,self.eye_1.repeat(x.size(0), 1, 1).to(device)
```

# Results :

```
In [28]: #PointMLP, no augment
model = PointMLP(NUM_POINTS, NUM_CLASSES)
(loss_train_array_POINTMLP,
 accuracy_train_array_POINTMLP,
 loss_test_array_POINTMLP,
 accuracy_test_array_POINTMLP) = train(
    model,
    dataloader_train,
    dataloader_test,
    epochs=50,
    loss_func=torch.nn.CrossEntropyLoss()
)

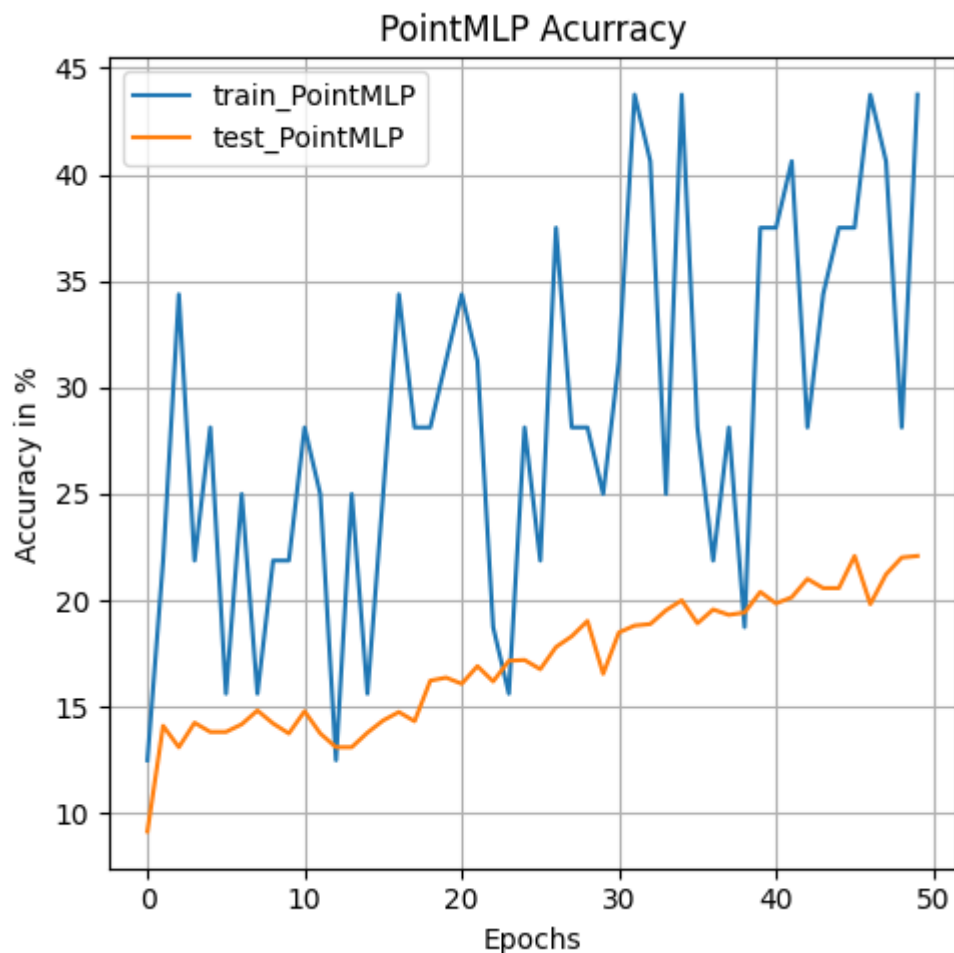
plt.figure(1)
plt.title("PointMLP Accuracy")
plt.xlabel("Epochs")
plt.ylabel("Accuracy in %")

plt.plot(accuracy_train_array_POINTMLP, label="train_PointMLP")
plt.plot(accuracy_test_array_POINTMLP, label="test_PointMLP")
plt.grid()
plt.legend()
```

Epoch: 1, Loss\_train: 2.422, Accuracy\_train: 12.5 %, Loss\_test 2.495, Accuracy\_test: 9.2 %  
Epoch: 2, Loss\_train: 2.261, Accuracy\_train: 21.9 %, Loss\_test 2.359, Accuracy\_test: 14.1 %  
Epoch: 3, Loss\_train: 2.132, Accuracy\_train: 34.4 %, Loss\_test 2.328, Accuracy\_test: 13.1 %  
Epoch: 4, Loss\_train: 2.119, Accuracy\_train: 21.9 %, Loss\_test 2.307, Accuracy\_test: 14.3 %  
Epoch: 5, Loss\_train: 2.143, Accuracy\_train: 28.1 %, Loss\_test 2.303, Accuracy\_test: 13.8 %  
Epoch: 6, Loss\_train: 2.306, Accuracy\_train: 15.6 %, Loss\_test 2.315, Accuracy\_test: 13.8 %  
Epoch: 7, Loss\_train: 2.111, Accuracy\_train: 25.0 %, Loss\_test 2.286, Accuracy\_test: 14.2 %  
Epoch: 8, Loss\_train: 2.206, Accuracy\_train: 15.6 %, Loss\_test 2.302, Accuracy\_test: 14.8 %  
Epoch: 9, Loss\_train: 2.192, Accuracy\_train: 21.9 %, Loss\_test 2.305, Accuracy\_test: 14.2 %  
Epoch: 10, Loss\_train: 2.216, Accuracy\_train: 21.9 %, Loss\_test 2.326, Accuracy\_test: 13.8 %  
Epoch: 11, Loss\_train: 2.069, Accuracy\_train: 28.1 %, Loss\_test 2.298, Accuracy\_test: 14.8 %  
Epoch: 12, Loss\_train: 2.110, Accuracy\_train: 25.0 %, Loss\_test 2.315, Accuracy\_test: 13.8 %  
Epoch: 13, Loss\_train: 2.233, Accuracy\_train: 12.5 %, Loss\_test 2.316, Accuracy\_test: 13.1 %  
Epoch: 14, Loss\_train: 2.141, Accuracy\_train: 25.0 %, Loss\_test 2.322, Accuracy\_test: 13.1 %  
Epoch: 15, Loss\_train: 2.306, Accuracy\_train: 15.6 %, Loss\_test 2.335, Accuracy\_test: 13.8 %  
Epoch: 16, Loss\_train: 2.090, Accuracy\_train: 25.0 %, Loss\_test 2.333, Accuracy\_test: 14.4 %  
Epoch: 17, Loss\_train: 1.942, Accuracy\_train: 34.4 %, Loss\_test 2.313, Accuracy\_test: 14.8 %  
Epoch: 18, Loss\_train: 1.930, Accuracy\_train: 28.1 %, Loss\_test 2.306, Accuracy\_test: 14.3 %  
Epoch: 19, Loss\_train: 2.069, Accuracy\_train: 28.1 %, Loss\_test 2.314, Accuracy\_test: 16.2 %  
Epoch: 20, Loss\_train: 1.989, Accuracy\_train: 31.2 %, Loss\_test 2.286, Accuracy\_test: 16.4 %  
Epoch: 21, Loss\_train: 1.838, Accuracy\_train: 34.4 %, Loss\_test 2.283, Accuracy\_test: 16.1 %  
Epoch: 22, Loss\_train: 2.143, Accuracy\_train: 31.2 %, Loss\_test 2.293, Accuracy\_test: 16.9 %  
Epoch: 23, Loss\_train: 2.208, Accuracy\_train: 18.8 %, Loss\_test 2.286, Accuracy\_test: 16.2 %  
Epoch: 24, Loss\_train: 2.044, Accuracy\_train: 15.6 %, Loss\_test 2.270, Accuracy\_test: 17.2 %  
Epoch: 25, Loss\_train: 2.129, Accuracy\_train: 28.1 %, Loss\_test 2.267, Accuracy\_test: 17.2 %  
Epoch: 26, Loss\_train: 2.203, Accuracy\_train: 21.9 %, Loss\_test 2.279, Accuracy\_test: 16.8 %  
Epoch: 27, Loss\_train: 1.851, Accuracy\_train: 37.5 %, Loss\_test 2.234, Accuracy\_test: 17.8 %  
Epoch: 28, Loss\_train: 1.911, Accuracy\_train: 28.1 %, Loss\_test 2.245, Accuracy\_test: 18.3 %  
Epoch: 29, Loss\_train: 2.165, Accuracy\_train: 28.1 %, Loss\_test 2.241, Accuracy\_test: 19.0 %  
Epoch: 30, Loss\_train: 2.081, Accuracy\_train: 25.0 %, Loss\_test 2.245, Accuracy\_test: 16.6 %  
Epoch: 31, Loss\_train: 1.831, Accuracy\_train: 31.2 %, Loss\_test 2.224, Accuracy\_test: 18.5 %  
Epoch: 32, Loss\_train: 1.817, Accuracy\_train: 43.8 %, Loss\_test 2.225, Accuracy\_test: 18.8 %  
Epoch: 33, Loss\_train: 1.782, Accuracy\_train: 40.6 %, Loss\_test 2.219, Accuracy\_test: 18.9 %

Epoch: 34, Loss\_train: 2.055, Accuracy\_train: 25.0 %, Loss\_test 2.190, Accuracy\_test: 19.5 %  
Epoch: 35, Loss\_train: 1.818, Accuracy\_train: 43.8 %, Loss\_test 2.173, Accuracy\_test: 20.0 %  
Epoch: 36, Loss\_train: 1.991, Accuracy\_train: 28.1 %, Loss\_test 2.170, Accuracy\_test: 18.9 %  
Epoch: 37, Loss\_train: 1.847, Accuracy\_train: 21.9 %, Loss\_test 2.194, Accuracy\_test: 19.6 %  
Epoch: 38, Loss\_train: 1.937, Accuracy\_train: 28.1 %, Loss\_test 2.198, Accuracy\_test: 19.3 %  
Epoch: 39, Loss\_train: 1.943, Accuracy\_train: 18.8 %, Loss\_test 2.152, Accuracy\_test: 19.4 %  
Epoch: 40, Loss\_train: 1.918, Accuracy\_train: 37.5 %, Loss\_test 2.171, Accuracy\_test: 20.4 %  
Epoch: 41, Loss\_train: 1.759, Accuracy\_train: 37.5 %, Loss\_test 2.152, Accuracy\_test: 19.9 %  
Epoch: 42, Loss\_train: 1.621, Accuracy\_train: 40.6 %, Loss\_test 2.153, Accuracy\_test: 20.2 %  
Epoch: 43, Loss\_train: 1.890, Accuracy\_train: 28.1 %, Loss\_test 2.153, Accuracy\_test: 21.0 %  
Epoch: 44, Loss\_train: 1.828, Accuracy\_train: 34.4 %, Loss\_test 2.144, Accuracy\_test: 20.6 %  
Epoch: 45, Loss\_train: 1.751, Accuracy\_train: 37.5 %, Loss\_test 2.143, Accuracy\_test: 20.6 %  
Epoch: 46, Loss\_train: 1.774, Accuracy\_train: 37.5 %, Loss\_test 2.125, Accuracy\_test: 22.1 %  
Epoch: 47, Loss\_train: 1.939, Accuracy\_train: 43.8 %, Loss\_test 2.139, Accuracy\_test: 19.8 %  
Epoch: 48, Loss\_train: 2.001, Accuracy\_train: 40.6 %, Loss\_test 2.107, Accuracy\_test: 21.2 %  
Epoch: 49, Loss\_train: 1.870, Accuracy\_train: 28.1 %, Loss\_test 2.084, Accuracy\_test: 22.0 %  
Epoch: 50, Loss\_train: 1.579, Accuracy\_train: 43.8 %, Loss\_test 2.107, Accuracy\_test: 22.1 %

Out[28]: <matplotlib.legend.Legend at 0x7fd6b420cb50>



```
In [29]: #PointBasic, no augment
model = PointNetBasic(NUM_POINTS, NUM_CLASSES)
(loss_train_array_PointNetBasic,
 accuracy_train_array_PointNetBasic,
 loss_test_array_PointNetBasic,
 accuracy_test_array_PointNetBasic) = train(
    model,
    dataloader_train,
    dataloader_test,
    epochs=50,
    loss_func=torch.nn.CrossEntropyLoss()
)

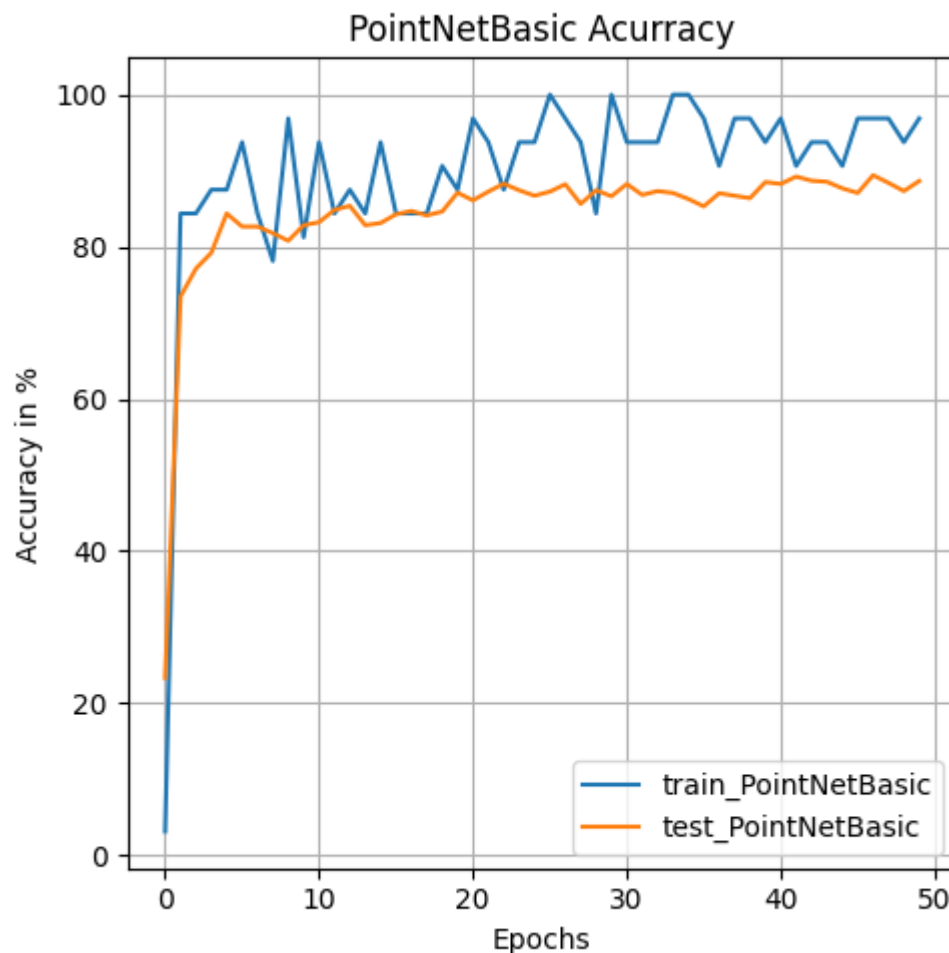
plt.figure(1)
plt.title("PointNetBasic Accuracy")
plt.xlabel("Epochs")
plt.ylabel("Accuracy in %")

plt.plot(accuracy_train_array_PointNetBasic, label="train_PointNetBasic")
plt.plot(accuracy_test_array_PointNetBasic, label="test_PointNetBasic")
plt.grid()
plt.legend()
```

Epoch: 1, Loss\_train: 2.460, Accuracy\_train: 3.1 %, Loss\_test 2.155, Accuracy\_test: 3.3 %  
Epoch: 2, Loss\_train: 0.481, Accuracy\_train: 84.4 %, Loss\_test 0.806, Accuracy\_test: 73.5 %  
Epoch: 3, Loss\_train: 0.413, Accuracy\_train: 84.4 %, Loss\_test 0.660, Accuracy\_test: 77.1 %  
Epoch: 4, Loss\_train: 0.316, Accuracy\_train: 87.5 %, Loss\_test 0.630, Accuracy\_test: 79.2 %  
Epoch: 5, Loss\_train: 0.420, Accuracy\_train: 87.5 %, Loss\_test 0.493, Accuracy\_test: 84.4 %  
Epoch: 6, Loss\_train: 0.244, Accuracy\_train: 93.8 %, Loss\_test 0.522, Accuracy\_test: 82.7 %  
Epoch: 7, Loss\_train: 0.334, Accuracy\_train: 84.4 %, Loss\_test 0.501, Accuracy\_test: 82.7 %  
Epoch: 8, Loss\_train: 0.494, Accuracy\_train: 78.1 %, Loss\_test 0.565, Accuracy\_test: 81.8 %  
Epoch: 9, Loss\_train: 0.111, Accuracy\_train: 96.9 %, Loss\_test 0.600, Accuracy\_test: 80.8 %  
Epoch: 10, Loss\_train: 0.733, Accuracy\_train: 81.2 %, Loss\_test 0.553, Accuracy\_test: 82.8 %  
Epoch: 11, Loss\_train: 0.139, Accuracy\_train: 93.8 %, Loss\_test 0.498, Accuracy\_test: 83.2 %  
Epoch: 12, Loss\_train: 0.485, Accuracy\_train: 84.4 %, Loss\_test 0.468, Accuracy\_test: 84.8 %  
Epoch: 13, Loss\_train: 0.457, Accuracy\_train: 87.5 %, Loss\_test 0.427, Accuracy\_test: 85.4 %  
Epoch: 14, Loss\_train: 0.387, Accuracy\_train: 84.4 %, Loss\_test 0.570, Accuracy\_test: 82.8 %  
Epoch: 15, Loss\_train: 0.136, Accuracy\_train: 93.8 %, Loss\_test 0.523, Accuracy\_test: 83.1 %  
Epoch: 16, Loss\_train: 0.275, Accuracy\_train: 84.4 %, Loss\_test 0.514, Accuracy\_test: 84.3 %  
Epoch: 17, Loss\_train: 0.275, Accuracy\_train: 84.4 %, Loss\_test 0.468, Accuracy\_test: 84.7 %  
Epoch: 18, Loss\_train: 0.355, Accuracy\_train: 84.4 %, Loss\_test 0.484, Accuracy\_test: 84.1 %  
Epoch: 19, Loss\_train: 0.282, Accuracy\_train: 90.6 %, Loss\_test 0.491, Accuracy\_test: 84.6 %  
Epoch: 20, Loss\_train: 0.315, Accuracy\_train: 87.5 %, Loss\_test 0.439, Accuracy\_test: 87.1 %  
Epoch: 21, Loss\_train: 0.146, Accuracy\_train: 96.9 %, Loss\_test 0.439, Accuracy\_test: 86.1 %  
Epoch: 22, Loss\_train: 0.140, Accuracy\_train: 93.8 %, Loss\_test 0.425, Accuracy\_test: 87.2 %  
Epoch: 23, Loss\_train: 0.312, Accuracy\_train: 87.5 %, Loss\_test 0.409, Accuracy\_test: 88.3 %  
Epoch: 24, Loss\_train: 0.225, Accuracy\_train: 93.8 %, Loss\_test 0.425, Accuracy\_test: 87.4 %  
Epoch: 25, Loss\_train: 0.139, Accuracy\_train: 93.8 %, Loss\_test 0.408, Accuracy\_test: 86.7 %  
Epoch: 26, Loss\_train: 0.065, Accuracy\_train: 100.0 %, Loss\_test 0.410, Accuracy\_test: 87.2 %  
Epoch: 27, Loss\_train: 0.091, Accuracy\_train: 96.9 %, Loss\_test 0.438, Accuracy\_test: 88.2 %  
Epoch: 28, Loss\_train: 0.210, Accuracy\_train: 93.8 %, Loss\_test 0.477, Accuracy\_test: 85.6 %  
Epoch: 29, Loss\_train: 0.413, Accuracy\_train: 84.4 %, Loss\_test 0.422, Accuracy\_test: 87.4 %  
Epoch: 30, Loss\_train: 0.042, Accuracy\_train: 100.0 %, Loss\_test 0.437, Accuracy\_test: 86.6 %  
Epoch: 31, Loss\_train: 0.142, Accuracy\_train: 93.8 %, Loss\_test 0.425, Accuracy\_test: 88.3 %  
Epoch: 32, Loss\_train: 0.089, Accuracy\_train: 93.8 %, Loss\_test 0.392, Accuracy\_test: 86.8 %  
Epoch: 33, Loss\_train: 0.113, Accuracy\_train: 93.8 %, Loss\_test 0.451, Accuracy\_test: 87.3 %

Epoch: 34, Loss\_train: 0.042, Accuracy\_train: 100.0 %, Loss\_test 0.445, Accuracy\_test: 87.1 %  
Epoch: 35, Loss\_train: 0.042, Accuracy\_train: 100.0 %, Loss\_test 0.446, Accuracy\_test: 86.3 %  
Epoch: 36, Loss\_train: 0.058, Accuracy\_train: 96.9 %, Loss\_test 0.546, Accuracy\_test: 85.3 %  
Epoch: 37, Loss\_train: 0.147, Accuracy\_train: 90.6 %, Loss\_test 0.431, Accuracy\_test: 87.0 %  
Epoch: 38, Loss\_train: 0.085, Accuracy\_train: 96.9 %, Loss\_test 0.469, Accuracy\_test: 86.7 %  
Epoch: 39, Loss\_train: 0.102, Accuracy\_train: 96.9 %, Loss\_test 0.466, Accuracy\_test: 86.4 %  
Epoch: 40, Loss\_train: 0.203, Accuracy\_train: 93.8 %, Loss\_test 0.401, Accuracy\_test: 88.5 %  
Epoch: 41, Loss\_train: 0.094, Accuracy\_train: 96.9 %, Loss\_test 0.435, Accuracy\_test: 88.3 %  
Epoch: 42, Loss\_train: 0.282, Accuracy\_train: 90.6 %, Loss\_test 0.388, Accuracy\_test: 89.2 %  
Epoch: 43, Loss\_train: 0.261, Accuracy\_train: 93.8 %, Loss\_test 0.408, Accuracy\_test: 88.7 %  
Epoch: 44, Loss\_train: 0.106, Accuracy\_train: 93.8 %, Loss\_test 0.398, Accuracy\_test: 88.5 %  
Epoch: 45, Loss\_train: 0.208, Accuracy\_train: 90.6 %, Loss\_test 0.432, Accuracy\_test: 87.7 %  
Epoch: 46, Loss\_train: 0.053, Accuracy\_train: 96.9 %, Loss\_test 0.443, Accuracy\_test: 87.1 %  
Epoch: 47, Loss\_train: 0.055, Accuracy\_train: 96.9 %, Loss\_test 0.426, Accuracy\_test: 89.4 %  
Epoch: 48, Loss\_train: 0.134, Accuracy\_train: 96.9 %, Loss\_test 0.402, Accuracy\_test: 88.4 %  
Epoch: 49, Loss\_train: 0.082, Accuracy\_train: 93.8 %, Loss\_test 0.475, Accuracy\_test: 87.3 %  
Epoch: 50, Loss\_train: 0.088, Accuracy\_train: 96.9 %, Loss\_test 0.423, Accuracy\_test: 88.6 %

Out[29]: <matplotlib.legend.Legend at 0x7fd6b41a1670>



```
In [30]: #PointFull, no augment
model = PointNetFull(NUM_POINTS, NUM_CLASSES)
(loss_train_array_POINTNetFull,
 accuracy_train_array_POINTNetFull,
 loss_test_array_POINTNetFull,
 accuracy_test_array_POINTNetFull) = train(
    model,
    dataloader_train,
    dataloader_test,
    epochs=50,
    loss_func=torch.nn.CrossEntropyLoss()
)

plt.figure(1)
plt.title("PointNetFull Accuracy")
plt.xlabel("Epochs")
plt.ylabel("Accuracy in %")

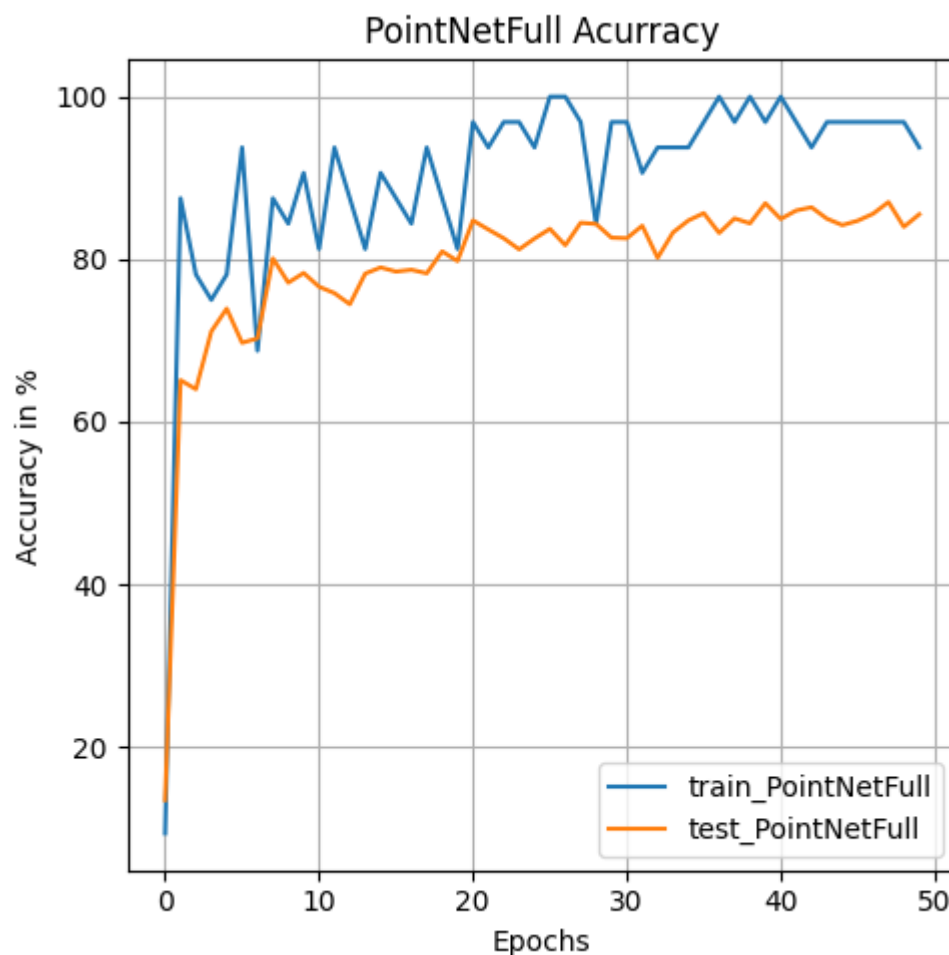
plt.plot(accuracy_train_array_POINTNetFull, label="train_PointNetFull")
plt.plot(accuracy_test_array_POINTNetFull, label="test_PointNetFull")
plt.grid()
plt.legend()
```



Epoch: 1, Loss\_train: 2.399, Accuracy\_train: 9.4 %, Loss\_test 2.378, Accuracy\_test: 13.5 %  
Epoch: 2, Loss\_train: 0.525, Accuracy\_train: 87.5 %, Loss\_test 1.142, Accuracy\_test: 65.1 %  
Epoch: 3, Loss\_train: 0.637, Accuracy\_train: 78.1 %, Loss\_test 1.090, Accuracy\_test: 64.0 %  
Epoch: 4, Loss\_train: 0.682, Accuracy\_train: 75.0 %, Loss\_test 0.842, Accuracy\_test: 71.1 %  
Epoch: 5, Loss\_train: 0.576, Accuracy\_train: 78.1 %, Loss\_test 0.817, Accuracy\_test: 73.9 %  
Epoch: 6, Loss\_train: 0.356, Accuracy\_train: 93.8 %, Loss\_test 0.966, Accuracy\_test: 69.7 %  
Epoch: 7, Loss\_train: 0.864, Accuracy\_train: 68.8 %, Loss\_test 0.889, Accuracy\_test: 70.3 %  
Epoch: 8, Loss\_train: 0.438, Accuracy\_train: 87.5 %, Loss\_test 0.688, Accuracy\_test: 80.1 %  
Epoch: 9, Loss\_train: 0.411, Accuracy\_train: 84.4 %, Loss\_test 0.767, Accuracy\_test: 77.1 %  
Epoch: 10, Loss\_train: 0.174, Accuracy\_train: 90.6 %, Loss\_test 0.722, Accuracy\_test: 78.3 %  
Epoch: 11, Loss\_train: 0.666, Accuracy\_train: 81.2 %, Loss\_test 0.784, Accuracy\_test: 76.6 %  
Epoch: 12, Loss\_train: 0.153, Accuracy\_train: 93.8 %, Loss\_test 0.783, Accuracy\_test: 75.8 %  
Epoch: 13, Loss\_train: 0.411, Accuracy\_train: 87.5 %, Loss\_test 0.846, Accuracy\_test: 74.5 %  
Epoch: 14, Loss\_train: 0.402, Accuracy\_train: 81.2 %, Loss\_test 0.736, Accuracy\_test: 78.2 %  
Epoch: 15, Loss\_train: 0.312, Accuracy\_train: 90.6 %, Loss\_test 0.663, Accuracy\_test: 79.0 %  
Epoch: 16, Loss\_train: 0.297, Accuracy\_train: 87.5 %, Loss\_test 0.673, Accuracy\_test: 78.5 %  
Epoch: 17, Loss\_train: 0.432, Accuracy\_train: 84.4 %, Loss\_test 0.730, Accuracy\_test: 78.7 %  
Epoch: 18, Loss\_train: 0.146, Accuracy\_train: 93.8 %, Loss\_test 0.718, Accuracy\_test: 78.3 %  
Epoch: 19, Loss\_train: 0.365, Accuracy\_train: 87.5 %, Loss\_test 0.567, Accuracy\_test: 81.0 %  
Epoch: 20, Loss\_train: 0.639, Accuracy\_train: 81.2 %, Loss\_test 0.657, Accuracy\_test: 79.8 %  
Epoch: 21, Loss\_train: 0.071, Accuracy\_train: 96.9 %, Loss\_test 0.540, Accuracy\_test: 84.8 %  
Epoch: 22, Loss\_train: 0.208, Accuracy\_train: 93.8 %, Loss\_test 0.561, Accuracy\_test: 83.7 %  
Epoch: 23, Loss\_train: 0.098, Accuracy\_train: 96.9 %, Loss\_test 0.540, Accuracy\_test: 82.6 %  
Epoch: 24, Loss\_train: 0.111, Accuracy\_train: 96.9 %, Loss\_test 0.604, Accuracy\_test: 81.2 %  
Epoch: 25, Loss\_train: 0.144, Accuracy\_train: 93.8 %, Loss\_test 0.577, Accuracy\_test: 82.5 %  
Epoch: 26, Loss\_train: 0.040, Accuracy\_train: 100.0 %, Loss\_test 0.546, Accuracy\_test: 83.7 %  
Epoch: 27, Loss\_train: 0.067, Accuracy\_train: 100.0 %, Loss\_test 0.598, Accuracy\_test: 81.7 %  
Epoch: 28, Loss\_train: 0.321, Accuracy\_train: 96.9 %, Loss\_test 0.489, Accuracy\_test: 84.5 %  
Epoch: 29, Loss\_train: 0.381, Accuracy\_train: 84.4 %, Loss\_test 0.519, Accuracy\_test: 84.3 %  
Epoch: 30, Loss\_train: 0.193, Accuracy\_train: 96.9 %, Loss\_test 0.539, Accuracy\_test: 82.7 %  
Epoch: 31, Loss\_train: 0.150, Accuracy\_train: 96.9 %, Loss\_test 0.581, Accuracy\_test: 82.6 %  
Epoch: 32, Loss\_train: 0.191, Accuracy\_train: 90.6 %, Loss\_test 0.551, Accuracy\_test: 84.1 %  
Epoch: 33, Loss\_train: 0.198, Accuracy\_train: 93.8 %, Loss\_test 0.613, Accuracy\_test: 80.2 %

Epoch: 34, Loss\_train: 0.326, Accuracy\_train: 93.8 %, Loss\_test 0.534, Accuracy\_test: 83.3 %  
Epoch: 35, Loss\_train: 0.132, Accuracy\_train: 93.8 %, Loss\_test 0.489, Accuracy\_test: 84.8 %  
Epoch: 36, Loss\_train: 0.143, Accuracy\_train: 96.9 %, Loss\_test 0.471, Accuracy\_test: 85.7 %  
Epoch: 37, Loss\_train: 0.076, Accuracy\_train: 100.0 %, Loss\_test 0.572, Accuracy\_test: 83.2 %  
Epoch: 38, Loss\_train: 0.118, Accuracy\_train: 96.9 %, Loss\_test 0.549, Accuracy\_test: 85.0 %  
Epoch: 39, Loss\_train: 0.044, Accuracy\_train: 100.0 %, Loss\_test 0.574, Accuracy\_test: 84.4 %  
Epoch: 40, Loss\_train: 0.090, Accuracy\_train: 96.9 %, Loss\_test 0.456, Accuracy\_test: 86.9 %  
Epoch: 41, Loss\_train: 0.031, Accuracy\_train: 100.0 %, Loss\_test 0.515, Accuracy\_test: 84.9 %  
Epoch: 42, Loss\_train: 0.109, Accuracy\_train: 96.9 %, Loss\_test 0.467, Accuracy\_test: 86.0 %  
Epoch: 43, Loss\_train: 0.194, Accuracy\_train: 93.8 %, Loss\_test 0.468, Accuracy\_test: 86.4 %  
Epoch: 44, Loss\_train: 0.083, Accuracy\_train: 96.9 %, Loss\_test 0.484, Accuracy\_test: 85.0 %  
Epoch: 45, Loss\_train: 0.097, Accuracy\_train: 96.9 %, Loss\_test 0.550, Accuracy\_test: 84.2 %  
Epoch: 46, Loss\_train: 0.044, Accuracy\_train: 96.9 %, Loss\_test 0.568, Accuracy\_test: 84.7 %  
Epoch: 47, Loss\_train: 0.049, Accuracy\_train: 96.9 %, Loss\_test 0.514, Accuracy\_test: 85.6 %  
Epoch: 48, Loss\_train: 0.103, Accuracy\_train: 96.9 %, Loss\_test 0.439, Accuracy\_test: 87.0 %  
Epoch: 49, Loss\_train: 0.072, Accuracy\_train: 96.9 %, Loss\_test 0.547, Accuracy\_test: 84.0 %  
Epoch: 50, Loss\_train: 0.091, Accuracy\_train: 93.8 %, Loss\_test 0.514, Accuracy\_test: 85.5 %

Out[30]: <matplotlib.legend.Legend at 0x7fd6b411e5e0>

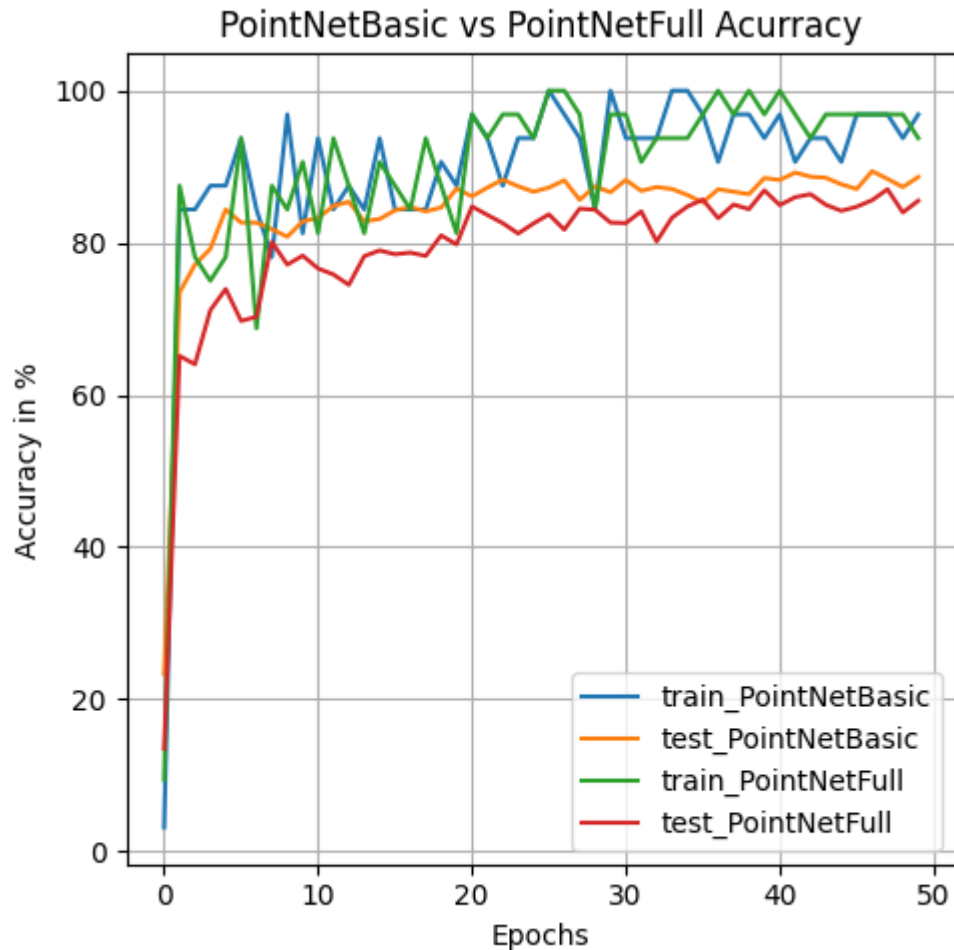


```

In [31]: plt.figure(1)
plt.title("PointNetBasic vs PointNetFull Accuracy")
plt.xlabel("Epochs")
plt.ylabel("Accuracy in %")
plt.plot(accuracy_train_array_POINTNetBasic,label="train_PointNetBasic")
plt.plot(accuracy_test_array_POINTNetBasic,label="test_PointNetBasic")
plt.plot(accuracy_train_array_POINTNetFull,label="train_PointNetFull")
plt.plot(accuracy_test_array_POINTNetFull,label="test_PointNetFull")
plt.grid()
plt.legend()

```

Out[31]: <matplotlib.legend.Legend at 0x7fd6b40e2280>



```

In [32]: #PointFull, augment, AxisReducing
model = PointNetBasic(NUM_POINTS,NUM_CLASSES)
(loss_train_array_POINTNetBasic_augment,
accuracy_train_array_POINTNetBasic_augment,
loss_test_array_POINTNetBasic_augment,
accuracy_test_array_POINTNetBasic_augment) = train(
    model,
    dataloader_train_augment,
    dataloader_test_augment,
    epochs=50,
    loss_func=torch.nn.CrossEntropyLoss()
)

plt.figure(1)
plt.title("PointNetBasic_augment Accuracy")
plt.xlabel("Epochs")
plt.ylabel("Accuracy in %")

plt.plot(accuracy_train_array_POINTNetBasic,label="train_PointNetBasic")
plt.plot(accuracy_test_array_POINTNetBasic,label="test_PointNetBasic")

plt.plot(accuracy_train_array_POINTNetBasic_augment,label="train_PointNetBasic_augmen")
plt.plot(accuracy_test_array_POINTNetBasic_augment,label="test_PointNetBasic_augment")

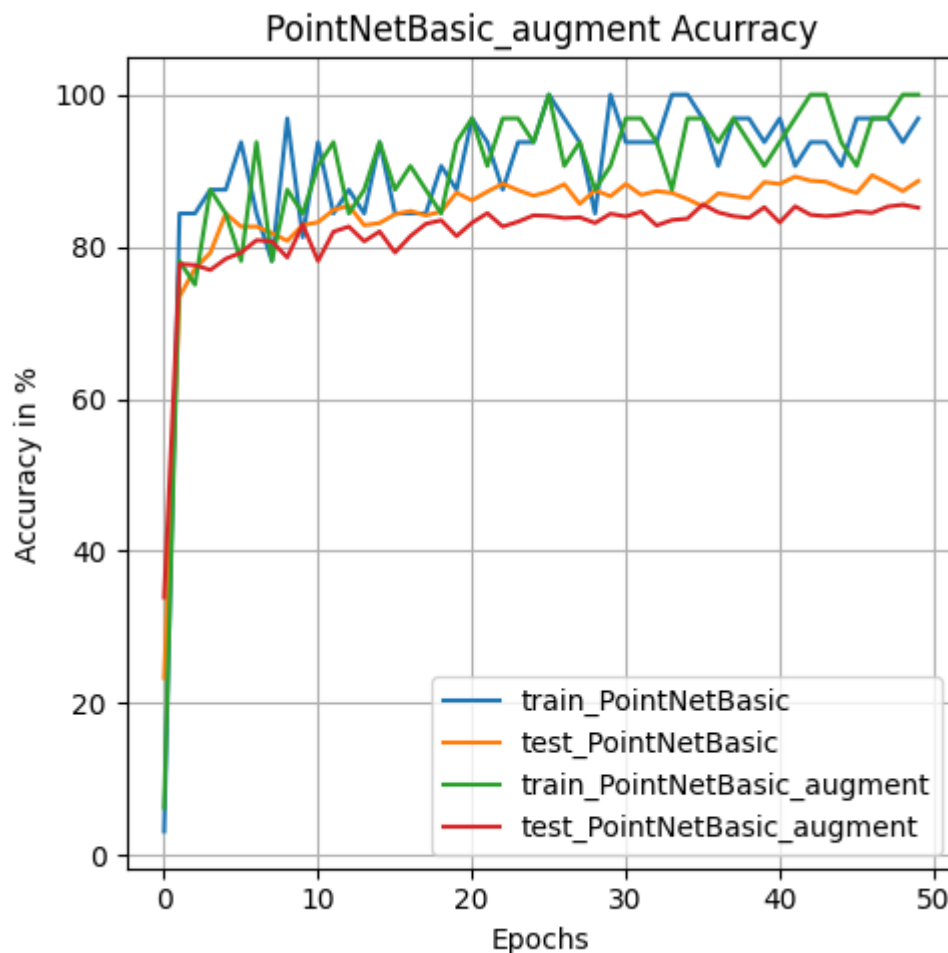
```

```
plt.grid()  
plt.legend()
```

Epoch: 1, Loss\_train: 2.510, Accuracy\_train: 6.2 %, Loss\_test 1.984, Accuracy\_test: 3.9 %  
Epoch: 2, Loss\_train: 0.629, Accuracy\_train: 78.1 %, Loss\_test 0.696, Accuracy\_test: 77.7 %  
Epoch: 3, Loss\_train: 0.518, Accuracy\_train: 75.0 %, Loss\_test 0.685, Accuracy\_test: 77.6 %  
Epoch: 4, Loss\_train: 0.373, Accuracy\_train: 87.5 %, Loss\_test 0.677, Accuracy\_test: 76.9 %  
Epoch: 5, Loss\_train: 0.504, Accuracy\_train: 84.4 %, Loss\_test 0.639, Accuracy\_test: 78.4 %  
Epoch: 6, Loss\_train: 0.538, Accuracy\_train: 78.1 %, Loss\_test 0.611, Accuracy\_test: 79.2 %  
Epoch: 7, Loss\_train: 0.114, Accuracy\_train: 93.8 %, Loss\_test 0.619, Accuracy\_test: 80.9 %  
Epoch: 8, Loss\_train: 0.413, Accuracy\_train: 78.1 %, Loss\_test 0.640, Accuracy\_test: 80.7 %  
Epoch: 9, Loss\_train: 0.284, Accuracy\_train: 87.5 %, Loss\_test 0.672, Accuracy\_test: 78.6 %  
Epoch: 10, Loss\_train: 0.450, Accuracy\_train: 84.4 %, Loss\_test 0.557, Accuracy\_test: 82.9 %  
Epoch: 11, Loss\_train: 0.208, Accuracy\_train: 90.6 %, Loss\_test 0.659, Accuracy\_test: 78.1 %  
Epoch: 12, Loss\_train: 0.237, Accuracy\_train: 93.8 %, Loss\_test 0.612, Accuracy\_test: 82.0 %  
Epoch: 13, Loss\_train: 0.283, Accuracy\_train: 84.4 %, Loss\_test 0.511, Accuracy\_test: 82.7 %  
Epoch: 14, Loss\_train: 0.210, Accuracy\_train: 87.5 %, Loss\_test 0.613, Accuracy\_test: 80.7 %  
Epoch: 15, Loss\_train: 0.128, Accuracy\_train: 93.8 %, Loss\_test 0.626, Accuracy\_test: 82.0 %  
Epoch: 16, Loss\_train: 0.253, Accuracy\_train: 87.5 %, Loss\_test 0.649, Accuracy\_test: 79.2 %  
Epoch: 17, Loss\_train: 0.364, Accuracy\_train: 90.6 %, Loss\_test 0.640, Accuracy\_test: 81.4 %  
Epoch: 18, Loss\_train: 0.249, Accuracy\_train: 87.5 %, Loss\_test 0.553, Accuracy\_test: 83.0 %  
Epoch: 19, Loss\_train: 0.322, Accuracy\_train: 84.4 %, Loss\_test 0.571, Accuracy\_test: 83.5 %  
Epoch: 20, Loss\_train: 0.132, Accuracy\_train: 93.8 %, Loss\_test 0.647, Accuracy\_test: 81.4 %  
Epoch: 21, Loss\_train: 0.141, Accuracy\_train: 96.9 %, Loss\_test 0.565, Accuracy\_test: 83.2 %  
Epoch: 22, Loss\_train: 0.206, Accuracy\_train: 90.6 %, Loss\_test 0.528, Accuracy\_test: 84.4 %  
Epoch: 23, Loss\_train: 0.074, Accuracy\_train: 96.9 %, Loss\_test 0.611, Accuracy\_test: 82.7 %  
Epoch: 24, Loss\_train: 0.044, Accuracy\_train: 96.9 %, Loss\_test 0.579, Accuracy\_test: 83.3 %  
Epoch: 25, Loss\_train: 0.190, Accuracy\_train: 93.8 %, Loss\_test 0.574, Accuracy\_test: 84.1 %  
Epoch: 26, Loss\_train: 0.040, Accuracy\_train: 100.0 %, Loss\_test 0.565, Accuracy\_test: 84.1 %  
Epoch: 27, Loss\_train: 0.166, Accuracy\_train: 90.6 %, Loss\_test 0.590, Accuracy\_test: 83.8 %  
Epoch: 28, Loss\_train: 0.110, Accuracy\_train: 93.8 %, Loss\_test 0.615, Accuracy\_test: 83.9 %  
Epoch: 29, Loss\_train: 0.234, Accuracy\_train: 87.5 %, Loss\_test 0.602, Accuracy\_test: 83.1 %  
Epoch: 30, Loss\_train: 0.167, Accuracy\_train: 90.6 %, Loss\_test 0.593, Accuracy\_test: 84.3 %  
Epoch: 31, Loss\_train: 0.103, Accuracy\_train: 96.9 %, Loss\_test 0.617, Accuracy\_test: 84.0 %  
Epoch: 32, Loss\_train: 0.061, Accuracy\_train: 96.9 %, Loss\_test 0.571, Accuracy\_test: 84.6 %  
Epoch: 33, Loss\_train: 0.113, Accuracy\_train: 93.8 %, Loss\_test 0.655, Accuracy\_test: 82.8 %

Epoch: 34, Loss\_train: 0.179, Accuracy\_train: 87.5 %, Loss\_test 0.610, Accuracy\_test: 83.5 %  
Epoch: 35, Loss\_train: 0.064, Accuracy\_train: 96.9 %, Loss\_test 0.619, Accuracy\_test: 83.7 %  
Epoch: 36, Loss\_train: 0.083, Accuracy\_train: 96.9 %, Loss\_test 0.538, Accuracy\_test: 85.6 %  
Epoch: 37, Loss\_train: 0.102, Accuracy\_train: 93.8 %, Loss\_test 0.590, Accuracy\_test: 84.5 %  
Epoch: 38, Loss\_train: 0.054, Accuracy\_train: 96.9 %, Loss\_test 0.589, Accuracy\_test: 84.0 %  
Epoch: 39, Loss\_train: 0.164, Accuracy\_train: 93.8 %, Loss\_test 0.655, Accuracy\_test: 83.8 %  
Epoch: 40, Loss\_train: 0.107, Accuracy\_train: 90.6 %, Loss\_test 0.582, Accuracy\_test: 85.2 %  
Epoch: 41, Loss\_train: 0.139, Accuracy\_train: 93.8 %, Loss\_test 0.651, Accuracy\_test: 83.2 %  
Epoch: 42, Loss\_train: 0.074, Accuracy\_train: 96.9 %, Loss\_test 0.576, Accuracy\_test: 85.3 %  
Epoch: 43, Loss\_train: 0.029, Accuracy\_train: 100.0 %, Loss\_test 0.670, Accuracy\_test: 84.2 %  
Epoch: 44, Loss\_train: 0.039, Accuracy\_train: 100.0 %, Loss\_test 0.650, Accuracy\_test: 84.0 %  
Epoch: 45, Loss\_train: 0.119, Accuracy\_train: 93.8 %, Loss\_test 0.645, Accuracy\_test: 84.2 %  
Epoch: 46, Loss\_train: 0.175, Accuracy\_train: 90.6 %, Loss\_test 0.613, Accuracy\_test: 84.6 %  
Epoch: 47, Loss\_train: 0.080, Accuracy\_train: 96.9 %, Loss\_test 0.618, Accuracy\_test: 84.4 %  
Epoch: 48, Loss\_train: 0.077, Accuracy\_train: 96.9 %, Loss\_test 0.646, Accuracy\_test: 85.3 %  
Epoch: 49, Loss\_train: 0.006, Accuracy\_train: 100.0 %, Loss\_test 0.618, Accuracy\_test: 85.5 %  
Epoch: 50, Loss\_train: 0.024, Accuracy\_train: 100.0 %, Loss\_test 0.692, Accuracy\_test: 85.1 %

Out[32]: <matplotlib.legend.Legend at 0x7fd6b077fee0>



```
In [33]: #PointNetBasic, augment, voxel
model = PointNetBasic(NUM_POINTS, NUM_CLASSES)
(loss_train_array_POINTNetBasic_augment_voxel,
 accuracy_train_array_POINTNetBasic_augment_voxel,
 loss_test_array_POINTNetBasic_augment_voxel,
 accuracy_test_array_POINTNetBasic_augment_voxel) = train(
    model,
    dataloader_train_augment_voxel,
    dataloader_test_augment_voxel,
    epochs=50,
    loss_func=torch.nn.CrossEntropyLoss()
)

plt.figure(1)
plt.title("PointNetBasic_augment_voxel Accuracy")
plt.xlabel("Epochs")
plt.ylabel("Accuracy in %")

plt.plot(accuracy_train_array_POINTNetBasic, label="train_PointNetBasic")
plt.plot(accuracy_test_array_POINTNetBasic, label="test_PointNetBasic")

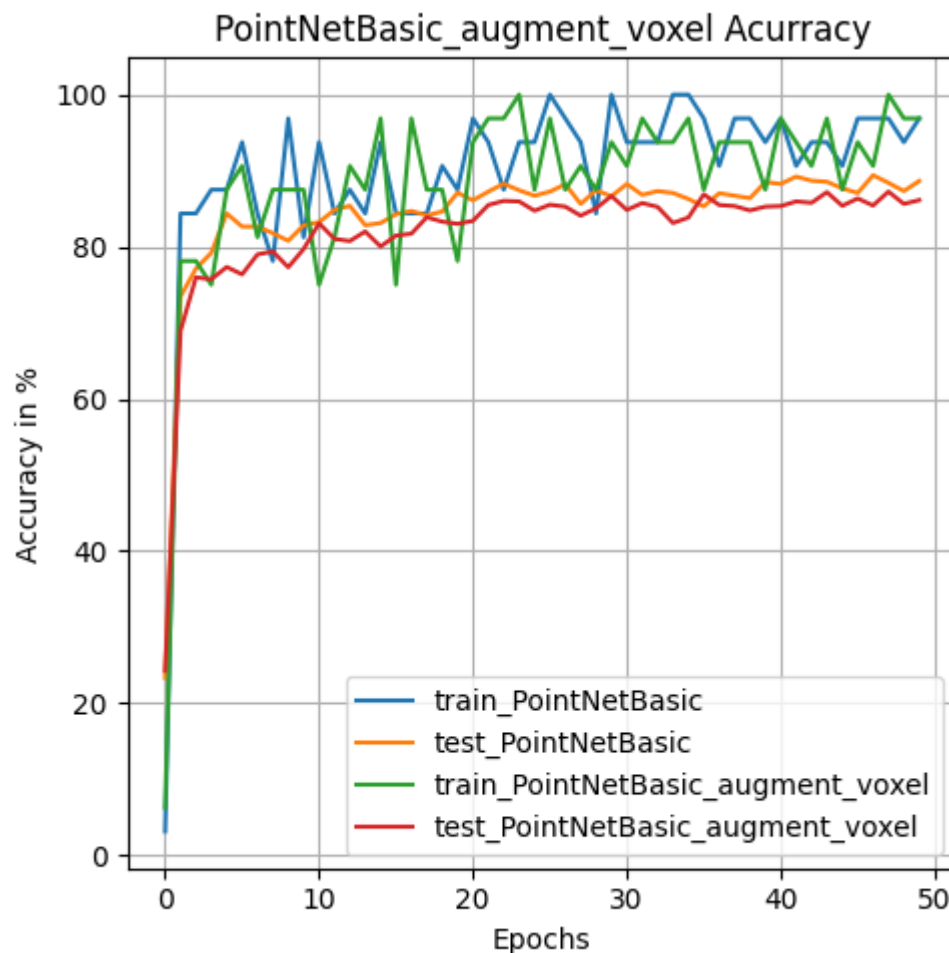
plt.plot(accuracy_train_array_POINTNetBasic_augment_voxel, label="train_PointNetBasic_")
plt.plot(accuracy_test_array_POINTNetBasic_augment_voxel, label="test_PointNetBasic_au")
plt.grid()
plt.legend()
```

Epoch: 1, Loss\_train: 2.418, Accuracy\_train: 6.2 %, Loss\_test 2.123, Accuracy\_test: 24.2 %  
Epoch: 2, Loss\_train: 0.680, Accuracy\_train: 78.1 %, Loss\_test 0.892, Accuracy\_test: 68.9 %  
Epoch: 3, Loss\_train: 0.577, Accuracy\_train: 78.1 %, Loss\_test 0.784, Accuracy\_test: 76.0 %  
Epoch: 4, Loss\_train: 0.629, Accuracy\_train: 75.0 %, Loss\_test 0.709, Accuracy\_test: 75.7 %  
Epoch: 5, Loss\_train: 0.425, Accuracy\_train: 87.5 %, Loss\_test 0.650, Accuracy\_test: 77.3 %  
Epoch: 6, Loss\_train: 0.405, Accuracy\_train: 90.6 %, Loss\_test 0.695, Accuracy\_test: 76.4 %  
Epoch: 7, Loss\_train: 0.434, Accuracy\_train: 81.2 %, Loss\_test 0.634, Accuracy\_test: 79.0 %  
Epoch: 8, Loss\_train: 0.333, Accuracy\_train: 87.5 %, Loss\_test 0.588, Accuracy\_test: 79.4 %  
Epoch: 9, Loss\_train: 0.372, Accuracy\_train: 87.5 %, Loss\_test 0.677, Accuracy\_test: 77.3 %  
Epoch: 10, Loss\_train: 0.400, Accuracy\_train: 87.5 %, Loss\_test 0.630, Accuracy\_test: 79.7 %  
Epoch: 11, Loss\_train: 0.722, Accuracy\_train: 75.0 %, Loss\_test 0.541, Accuracy\_test: 83.1 %  
Epoch: 12, Loss\_train: 0.493, Accuracy\_train: 81.2 %, Loss\_test 0.568, Accuracy\_test: 81.0 %  
Epoch: 13, Loss\_train: 0.373, Accuracy\_train: 90.6 %, Loss\_test 0.598, Accuracy\_test: 80.7 %  
Epoch: 14, Loss\_train: 0.491, Accuracy\_train: 87.5 %, Loss\_test 0.540, Accuracy\_test: 82.0 %  
Epoch: 15, Loss\_train: 0.146, Accuracy\_train: 96.9 %, Loss\_test 0.617, Accuracy\_test: 80.0 %  
Epoch: 16, Loss\_train: 0.673, Accuracy\_train: 75.0 %, Loss\_test 0.573, Accuracy\_test: 81.5 %  
Epoch: 17, Loss\_train: 0.140, Accuracy\_train: 96.9 %, Loss\_test 0.592, Accuracy\_test: 81.7 %  
Epoch: 18, Loss\_train: 0.337, Accuracy\_train: 87.5 %, Loss\_test 0.527, Accuracy\_test: 83.9 %  
Epoch: 19, Loss\_train: 0.480, Accuracy\_train: 87.5 %, Loss\_test 0.584, Accuracy\_test: 83.3 %  
Epoch: 20, Loss\_train: 0.389, Accuracy\_train: 78.1 %, Loss\_test 0.544, Accuracy\_test: 83.0 %  
Epoch: 21, Loss\_train: 0.221, Accuracy\_train: 93.8 %, Loss\_test 0.521, Accuracy\_test: 83.4 %  
Epoch: 22, Loss\_train: 0.161, Accuracy\_train: 96.9 %, Loss\_test 0.485, Accuracy\_test: 85.5 %  
Epoch: 23, Loss\_train: 0.149, Accuracy\_train: 96.9 %, Loss\_test 0.463, Accuracy\_test: 86.0 %  
Epoch: 24, Loss\_train: 0.070, Accuracy\_train: 100.0 %, Loss\_test 0.489, Accuracy\_test: 86.0 %  
Epoch: 25, Loss\_train: 0.200, Accuracy\_train: 87.5 %, Loss\_test 0.472, Accuracy\_test: 84.7 %  
Epoch: 26, Loss\_train: 0.232, Accuracy\_train: 96.9 %, Loss\_test 0.467, Accuracy\_test: 85.5 %  
Epoch: 27, Loss\_train: 0.292, Accuracy\_train: 87.5 %, Loss\_test 0.494, Accuracy\_test: 85.3 %  
Epoch: 28, Loss\_train: 0.172, Accuracy\_train: 90.6 %, Loss\_test 0.497, Accuracy\_test: 84.1 %  
Epoch: 29, Loss\_train: 0.258, Accuracy\_train: 87.5 %, Loss\_test 0.503, Accuracy\_test: 85.1 %  
Epoch: 30, Loss\_train: 0.107, Accuracy\_train: 93.8 %, Loss\_test 0.434, Accuracy\_test: 86.7 %  
Epoch: 31, Loss\_train: 0.299, Accuracy\_train: 90.6 %, Loss\_test 0.484, Accuracy\_test: 84.8 %  
Epoch: 32, Loss\_train: 0.073, Accuracy\_train: 96.9 %, Loss\_test 0.467, Accuracy\_test: 85.7 %  
Epoch: 33, Loss\_train: 0.321, Accuracy\_train: 93.8 %, Loss\_test 0.497, Accuracy\_test: 85.2 %



Epoch: 34, Loss\_train: 0.167, Accuracy\_train: 93.8 %, Loss\_test 0.528, Accuracy\_test: 83.1 %  
Epoch: 35, Loss\_train: 0.071, Accuracy\_train: 96.9 %, Loss\_test 0.541, Accuracy\_test: 83.8 %  
Epoch: 36, Loss\_train: 0.257, Accuracy\_train: 87.5 %, Loss\_test 0.478, Accuracy\_test: 86.9 %  
Epoch: 37, Loss\_train: 0.208, Accuracy\_train: 93.8 %, Loss\_test 0.528, Accuracy\_test: 85.5 %  
Epoch: 38, Loss\_train: 0.184, Accuracy\_train: 93.8 %, Loss\_test 0.496, Accuracy\_test: 85.3 %  
Epoch: 39, Loss\_train: 0.268, Accuracy\_train: 93.8 %, Loss\_test 0.454, Accuracy\_test: 84.8 %  
Epoch: 40, Loss\_train: 0.244, Accuracy\_train: 87.5 %, Loss\_test 0.445, Accuracy\_test: 85.3 %  
Epoch: 41, Loss\_train: 0.086, Accuracy\_train: 96.9 %, Loss\_test 0.465, Accuracy\_test: 85.3 %  
Epoch: 42, Loss\_train: 0.116, Accuracy\_train: 93.8 %, Loss\_test 0.442, Accuracy\_test: 86.0 %  
Epoch: 43, Loss\_train: 0.243, Accuracy\_train: 90.6 %, Loss\_test 0.471, Accuracy\_test: 85.8 %  
Epoch: 44, Loss\_train: 0.133, Accuracy\_train: 96.9 %, Loss\_test 0.473, Accuracy\_test: 87.2 %  
Epoch: 45, Loss\_train: 0.304, Accuracy\_train: 87.5 %, Loss\_test 0.475, Accuracy\_test: 85.4 %  
Epoch: 46, Loss\_train: 0.150, Accuracy\_train: 93.8 %, Loss\_test 0.467, Accuracy\_test: 86.4 %  
Epoch: 47, Loss\_train: 0.173, Accuracy\_train: 90.6 %, Loss\_test 0.509, Accuracy\_test: 85.4 %  
Epoch: 48, Loss\_train: 0.062, Accuracy\_train: 100.0 %, Loss\_test 0.406, Accuracy\_test: 87.2 %  
Epoch: 49, Loss\_train: 0.313, Accuracy\_train: 96.9 %, Loss\_test 0.444, Accuracy\_test: 85.6 %  
Epoch: 50, Loss\_train: 0.183, Accuracy\_train: 96.9 %, Loss\_test 0.474, Accuracy\_test: 86.1 %

Out[33]: <matplotlib.legend.Legend at 0x7fd6b45a70a0>



# The model :

```
In [121... model = PointMLP(NUM_POINTS, NUM_CLASSES)
print(model)

PointMLP(
  (fc_1): Linear(in_features=3072, out_features=512, bias=True)
  (bn_1): BatchNorm1d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_2): Linear(in_features=512, out_features=256, bias=True)
  (dropout_1): Dropout(p=0.3, inplace=False)
  (bn_2): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_3): Linear(in_features=256, out_features=1024, bias=True)
  (bn_3): BatchNorm1d(1024, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
)
```

```
In [122... model = PointNetBasic(NUM_POINTS, NUM_CLASSES)
print(model)

PointNetBasic(
  (fc_1): Conv1d(3, 32, kernel_size=(1,), stride=(1,))
  (bn_1): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_2): Conv1d(32, 32, kernel_size=(1,), stride=(1,))
  (bn_2): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_3): Conv1d(32, 32, kernel_size=(1,), stride=(1,))
  (bn_3): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_4): Conv1d(32, 128, kernel_size=(1,), stride=(1,))
  (bn_4): BatchNorm1d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_5): Conv1d(128, 512, kernel_size=(1,), stride=(1,))
  (bn_5): BatchNorm1d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (mp): MaxPool1d(kernel_size=512, stride=512, padding=0, dilation=1, ceil_mode=False)
  (fc_6): Linear(in_features=1024, out_features=256, bias=True)
  (bn_6): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_7): Linear(in_features=256, out_features=128, bias=True)
  (dropout_1): Dropout(p=0.3, inplace=False)
  (bn_7): BatchNorm1d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
  (fc_8): Linear(in_features=128, out_features=10, bias=True)
)
```

```
In [123... model = PointNetFull(NUM_POINTS, NUM_CLASSES)
print(model)
```

```

PointNetFull
(input_transform_1): InputTransform(
  (t_net): Tnet(
    (fc_1): Conv1d(3, 32, kernel_size=(1,), stride=(1,))
    (bn_1): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (fc_2): Conv1d(32, 64, kernel_size=(1,), stride=(1,))
    (bn_2): BatchNorm1d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (fc_3): Conv1d(64, 256, kernel_size=(1,), stride=(1,))
    (bn_3): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (mp): MaxPool1d(kernel_size=256, stride=256, padding=0, dilation=1, ceil_mode=False)
    (fc_4): Linear(in_features=1024, out_features=128, bias=True)
    (bn_4): BatchNorm1d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (fc_5): Linear(in_features=128, out_features=64, bias=True)
    (bn_5): BatchNorm1d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (fc_6): Linear(in_features=64, out_features=9, bias=True)
  )
)
(fc_1): Conv1d(3, 32, kernel_size=(1,), stride=(1,))
(bn_1): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(fc_2): Conv1d(32, 32, kernel_size=(1,), stride=(1,))
(bn_2): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(fc_3): Conv1d(32, 32, kernel_size=(1,), stride=(1,))
(bn_3): BatchNorm1d(32, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(fc_4): Conv1d(32, 128, kernel_size=(1,), stride=(1,))
(bn_4): BatchNorm1d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(fc_5): Conv1d(128, 512, kernel_size=(1,), stride=(1,))
(bn_5): BatchNorm1d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(mp): MaxPool1d(kernel_size=512, stride=512, padding=0, dilation=1, ceil_mode=False)
(fc_6): Linear(in_features=1024, out_features=256, bias=True)
(bn_6): BatchNorm1d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(fc_7): Linear(in_features=256, out_features=128, bias=True)
(dropout_1): Dropout(p=0.3, inplace=False)
(bn_7): BatchNorm1d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
(fc_8): Linear(in_features=128, out_features=10, bias=True)
)

```