# Clément RØBLØT

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I am passionate about computer science and electronics since I am 12. Now I specialized in backend software (embedded C; C++/QT; python), but front end can also be fun (angular). Constantly picking up new skills by myself, ideas always pop up in my mind. Friendly and reliable I will always prefer to build a script than do twice the same thing by hand.



## Work Experience

#### **Analog Way**

Oct 2014 Sep 2017 (France)

#### Software developer:

- · Developed the evolutions (bug correction in preexisting code base and development of new features) of the livecore video switcher/mixer platform (C on ARM M3) [4K video, custom output formats, areas of interests, automatic image splitting in multi output screens, output mapping in screens,
- · Designed an EDID (256 bytes memory inside displays) editor using QT (available here). This software have since been used and recommended by many industry leaders.
- · Improved an internal control, debug and analysis tool in C# used on all the analog way products (stabilization of existing application and development of new features).
- · Implementation of an internal versioning server now used for all the R&D projects (gitlab on a debian server).

#### **MAV**lab

· Implemented the paparazzi autopilot on an ornithopter (flapping drone).

Mar-Aug 2014

· Improved an ESC for inconsistent load systems like flapping robots.

(Netherlands)

· Built the first ornithopter capable of flying fully autonomously outside.

#### **Emulsar**

Jun-Aug 2012

(France)

· Engineered an application dedicated to measuring the thickness of emulsions (image processing using **opency under QT**).

· Developed a modular control system based on microcontroller elements for scheduling chemicals experiments automatically.

#### **NVT**

May-Aug 2011

· Developed multiple applications dedicated to data processing, motor control and image processing using labview.

(France)

· Did a test campaign in a railway environment needing data acquisition and sensor maintenance.



# Education and Qualifications

The Family 2016	<b>Lion</b> 8 weeks to excel in a startup, from the first day. For employees who want to adapt to this environment.
Rennes 1 2013-2014	<b>Master 2</b> SISEA as a double degree in <b>embedded systems</b> oriented towards research and development.
ENSSAT (France) 2011-2014	3 years student majoring in <b>Electronics and Industrial Computer Science</b> in a selective 3-year postgraduate <b>engineering</b> program in Lannion, France. Equivalent to a US Master's Degree in engineering.

IUT (France) 2009-2011

Completed a two-year degree (DUT) in **Electronics and Industrial Computer Science** in Cachan, France. Equivalent to an HND in the UK.



OS Ubuntu (since 8.04), Debian (since 5.0), Ångström.

Platforms PIC (16f, 18f, 30f), Psoc (1 and 3), NXP LPC17 (ARM cortex M3), ATMEL V71 (ARM cortex M7),

cubieboard (ARM cortex A8), beagleboard (ARM cortex A8).

Protocols UART, I2C, SPI, CAN, CAN-FD, UDP

Techi	nical Projects <del></del>	
2017	Developed a <b>website</b> dedicated to counting the life span of user reminding them to use to use those days well, and in a meaning-full manner.	Django/JQuery
2016	Developed a <b>low power tactile button</b> powered by the pull up it controls.	Electronic board
2015-2016	Developed a <b>website for building random exams</b> in order to limit cheating	(Django/angular)
2015	Developed an <b>application for automatically downloading a feed of videos</b> (full buffering for slow internet connections)	$\begin{array}{c} \texttt{localtube.org} \\ (C{++} \; / \; QT) \end{array}$
2013-2014	Creating a system for <b>redundant self-hosting</b> in order to provide the technical capabilities for everyone not to rely on the web giants	lamamos.org (bash/perl/angular)
2012	Constructed a <b>3D printer</b> , and learning of the basics of mechanics through small improvements of the machine	mechanic + use of soliworks
2010-2011	Developed a <b>robot's image processing system</b> to detect and localize pieces of the game for the 2011 Eurobot cup	Opencv, beagleboard
2010-2011	Implemented a <b>Bluetooth interface</b> for debugging and controlling a robot for the 2011 Eurobot cup	C++ / QT
2009-2010	Designed a line-following robot for a national contest	Electronic board and embedded C



### Languages

French: Native speaker English: spoken and written (CLES B2)



## Interests

Electronics Was member of a robotic association for 3 years. I develop also personal projects, for example a home-made NAS.

Computer Development of personal projects like a modular home page generator, or a home-server easy to use Science by everyone.

Learning Mainly through books and conferences. Lately I spend too much time at The Family in Paris.

Climbing Practiced for 9 years, with the ability to mentor groups.