CLEMENT JAMBOU

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Summary

Technical leader and entrepreneur with 10+ years experience in AI/ML, Robotics & Autonomous Systems, Data Science, Software Engineering, and Space Avionics. Proven track record of building and leading high-performing engineering teams across multiple countries, including founding and working at startups. Expertise in building and delivering products rapidly.

Career Highlights

- Led multiple engineering teams in **Data Science**, **Software Engineering**, **Hardware Engineering** across multiple industries (**Tech**, **Robotics**, **Space**) and countries (**US**, **France**, **Switzerland**, **China**)
- Designed autonomous robots (software and hardware) from drawing board to deployments of up to **30** units in warehouses
- Grew Lyft data science team from 4 to 20+ while delivering critical marketplace algorithms

Selected Experience

CADBuildr Aug 2024 – Present

CEO & Founder – San Francisco, CA

- Founded CADBuildr to create, manage and share 3D designs with open-source and AI technologies
- Built AI-powered CAD platform with natural language and multimodal interactions
- Developed open-source Python CAD library for programmatic 3D modeling
- Created **LLM** microservice to serve models and integrate with **OpenAI** and **Anthropic APIs** Accomplishments:
 - Launched first multimodal AI Agent for CAD (text-to-CAD, image-to-CAD)
 - Wrote 10,000+ lines of Python/TypeScript code
 - Created and released 100s of open-source 3D models on CADBuildr

Exotrail Nov 2023 – Aug 2024

Software & Avionics Engineering Manager – Paris, France

- Managed **Avionics** team developing embedded software for **Spacevan** autonomous satellite delivery vehicle
- Led **5-person** avionics team to release bi-monthly software updates
- Implemented a complete **Telecommand/Telemetry** system facilitating collaboration work on the **Spacevan** vehicle
- Implemented quality guidelines for the avionics team software and validation via a **CI/CD** system Accomplishments:
 - Transformed team structure and processes to establish reliable software delivery practices
 - Upon departure, the company needed **three** new hires to replace my responsibilities

Coactum Oct 2022 – Nov 2023

Software & Avionics Engineering Manager – Bex, Switzerland

- Executive Committee Member leading software/avionics development for early-stage vehicle systems
- Defined early-stage requirements and specifications for onboard software (CCSDS), firmware, and custom avionics
- Proposed and implemented technical interfaces format and process for vehicle engineering teams Accomplishments:
 - Joined as a consultant and was rapidly promoted to Executive Committee Member
 - Created a rigorous hiring process for software engineering team

Mont Blanc Rockets Jan 2021 – Present

Data Science & Software Engineering Consultant – Freelance

• Provided technical leadership and consulting services to companies across Machine Learning, Data Science, Data Engineering and Software Engineering

• Helped companies scale their engineering teams and improve technical processes

Accomplishments:

- Conducted **PostgreSQL** migration on a complex Data pipeline
- Worked with notable companies including AXA, Pfizer
- Became quickly one of the top consultants on **MALT** (French Tech Talent Network) receiving 10s of invitations per month due to positive feedback from companies.

Unsupervised.ai 2016 – 2020

CEO - San Francisco, Shenzhen and Paris

- Co-founded robotics company enabling digital factory transformation
- Led 8-person team across 3 continents
- Built an autonomous robot fleet from ideation to production of a 30-unit batch

Accomplishments:

- Generated \$400k+ of revenue and raised \$800k in funding
- Attempted the selective (10% acceptance rate) HAX accelerator program
- Built a simulation in **Pybullet** to test and validate **RL** algorithms on a quadruped robot

Lyft 2014 – 2016

Senior Data Scientist – San Francisco

- Joined the Marketplace Growth team (ETA prediction, Driver/Passenger matching, pricing) and started the self-driving initiative
- Deployed production-grade machine learning and deep learning algorithms at scale
- Grew data science team from 4 to 20+ members

Accomplishments:

- First joined as an intern and quickly promoted to Senior Data Scientist
- Built a key simulation tool for dispatch optimization that was widely adopted across the **Data Science** team, delivering significant improvements including pricing, driver utilization and **Lyft Line** matching efficiency
- Started the first self-driving program (SLAM, LiDAR) at Lyft

Education

Imperial College London, MSc in Advanced Computing	2013 – 2014
Institut Superieur de l'Aeronautique et de l'Espace, Supaero Graduate Program	2011 - 2014
ESA, Intern, Telerobotics and Haptics Laboratory	2012

Skills

Management & Tools:

- Methodologies: Agile/Scrum, Sprint Planning, Retrospectives
- Project Tools: Jira, Notion

Programming Languages:

- Python (Pandas, NumPy, TensorFlow, PyTorch, Pydantic, FastAPI, Flask)
- C/C++
- JavaScript/TypeScript (React, NextJS)

Data Science & ML:

- Frameworks: Pandas, NumPy, TensorFlow, PyTorch, Scikit-learn
- Algorithms: LLMs(RLHF, RAG, Fine-tuning), Reinforcement Learning, SVM, Random Forest
- Optimization: Operations Research, Back Propagation

Infrastructure & DevOps:

• Containerization: Docker, Kubernetes

- CI/CD: GitHub Actions, GitLab CI, Jenkins
- Cloud: AWS (EC2, S3, Lambda), Google Cloud
- Databases: PostgreSQL, GraphQL

Robotics & Simulation:

- Frameworks: ROS/ROS2Simulation: Gazebo, PyBullet
- Design: CAD (Solidworks, Fusion360), 3D Printing, Electronics(KiCad)
- Algorithms: SLAM, Path Planning, Control

Natural Languages: English (bilingual), French (native), German (intermediate)

Awards, Honors & Publications

These awards and publications demonstrate a strong technical foundation in mathematics, engineering, and	
research, reflecting my consistent record of academic and professional excellence.	
Speaker at PyData Paris	2015
Learning Walking Skills for Modular Robots	2014
Research Project at Imperial College London	
Developed autonomous control gaits for modular robots using reinforcement learning,	
enabling self-assembly and locomotion in simulated physics environments. Implemented	
joystick control interface for human operation.	
Learning Music Representation using RNNs	2014
Master's Thesis at Imperial College London	
Trained recurrent neural networks to learn and generate classical music patterns from	
MIDI files. Leveraged graph theory to add neurons to the networks during training.	
1 st Prize, ASME Student Design Competition	2012
Junior Fermat Prize in Mathematics	2010
1 st Prize, International Tournament of Young Mathematicians	2010
2 nd Prize, Academy of Versailles Mathematics Olympiads	2008

Interests

I love pushing my limits through endurance sports as it keeps me disciplined and resilient but also provides an outlet to come back to a problem with a fresh perspective. I'm also always looking for ways to optimize both physical and mental performance.

- Sports: Running Coach and Competitive Runner (Marathon PR: 2h33, UTMB 105 miles Finisher), Soccer, Mountaineering (Denali summiter)
- Hobbies: Robotics, Electronics, Space
- Music: Cello, Guitar