

# Axially symmetric processes to model spatial data on large portions of the planet

Laboratorio de Modelación I

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August 10, 2022



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# Motivation

Dataset from *NOAA Physical Sciences Laboratory*.

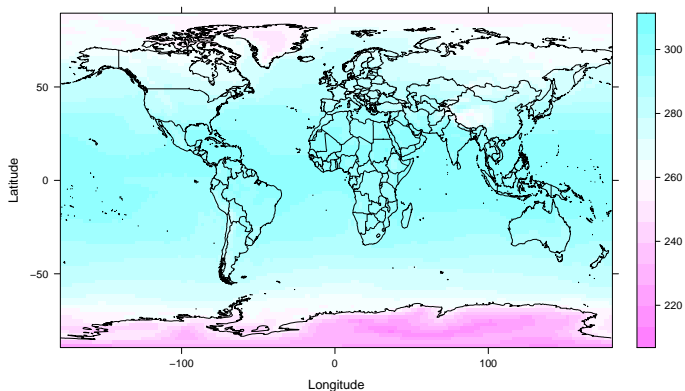


Figure: Air Temperature at 2m Above Ground Level (2021).

# Motivation

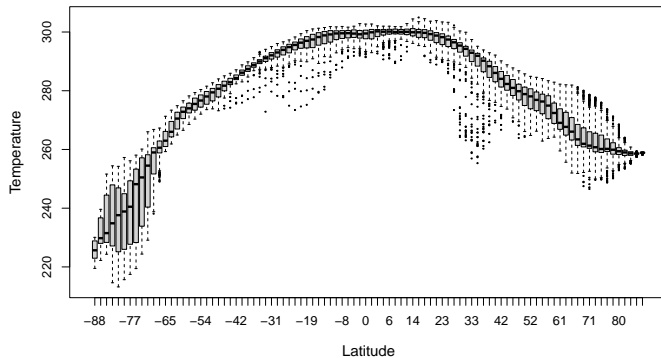


Figure: Air temperature by latitude band.

# Random Fields

**Random Fields.** Let  $\mathcal{D} \subset \mathbb{R}^d$  a spatial domain. A random field is a collection  $\{Z(\mathbf{x}), \mathbf{x} \in \mathcal{D}\}$  of random variables.

In our framework we will work with the following assumptions

1.  $\mathcal{D} \subset \mathbb{S}^2$  and  $\mathbf{x} = (L, \ell)$ , where  $L, \ell$  denote latitude, in a range of  $[0, \pi]$ , and longitude is measured between  $[0, 2\pi)$ , respectively.
2. Second order random fields, i.e.,  $\text{var}[Z(L, \ell)] < \infty$ . Thus, mean and covariance function are well defined as follows

$$\mu(L, \ell) = E[Z(L, \ell)] \quad \text{and} \quad K(L_1, \ell_1, L_2, \ell_2) = \text{cov}[Z(L_1, \ell_1), Z(L_2, \ell_2)].$$

# Axially Symmetric Processes

Random field is referred to as an **axially symmetric process** if

1.  $E[Z(L, \ell)] = m(L)$ , for some function  $m : [0, \pi] \rightarrow \mathbb{R}$ .
2.  $\text{cov}[Z(L_1, \ell_1), Z(L_2, \ell_2)] = C(L_1, L_2, \ell_1 - \ell_2)$ , for some function  $C : \mathbb{S}^2 \rightarrow \mathbb{R}$ .

But, **how do we estimate these functions?**

- $m$  is straightforward given data.
- Covariance function must be positive definite, so we will estimate it using **Matérn Model**

$$C(\mathbf{h}) = \frac{2^{1-\nu}}{\Gamma(\nu)} (\alpha \|\mathbf{h}\|)^\nu K_\nu(\alpha \|\mathbf{h}\|), \quad \mathbf{h} \in \mathbb{S}^2,$$

where  $\Gamma$ ,  $K_\nu$  are gamma and modified Bessel functions of second kind.

# Exponential Matérn Model and empirical covariance

In particular, if  $\nu = 1/2$ , then we obtain an **exponential Matérn model** given by

$$C(\mathbf{h}) = \exp(-\alpha \|\mathbf{h}\|).$$

Now, in order to estimate  $\alpha$ , we will calculate residuals

$$\tilde{Z}(L, \ell) = \frac{Z(L, \ell) - \hat{\mu}(L)}{\hat{\sigma}(L)},$$

and fit a curve for empirical covariance

$$\hat{C}(\mathbf{h}) = \frac{1}{N(\mathbf{h})} \sum_{(i,j): \|\mathbf{x}_i - \mathbf{x}_j\| \approx |\mathbf{h}|} Z(\mathbf{x}_i)Z(\mathbf{x}_j), \quad \mathbf{h} \in \mathbb{S}^2.$$

# Mean and Standard Deviation Functions

Using **generalized additive model (GAM)** in **R** we predicted mean and standard deviation functions

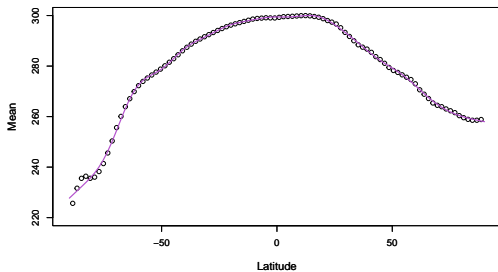


Figure: Mean function.

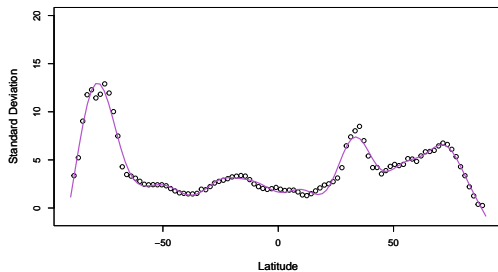


Figure: Standard deviation function.



# Residues and normalization

Normalizing errors we obtain **residuals** of our data.

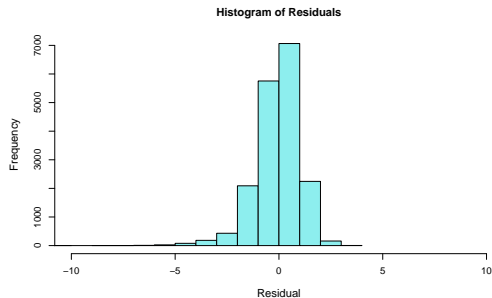


Figure: Histogram of residuals.

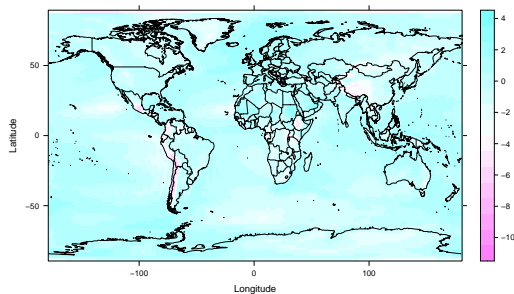


Figure: Residual worldwide map.

# Residual Representation in Spherical Coordinates

Using spherical coordinates

$$\begin{cases} x = R \cos(L\omega) \cos(\ell\omega) \\ y = R \cos(L\omega) \sin(\ell\omega) \\ z = R \sin(L\omega) \end{cases}$$

where  $R = 6378$  [km] and  $\omega = \pi/180$ .

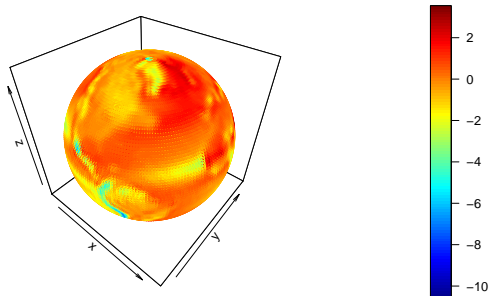


Figure: Residual projection over sphere.

# Variogram and Empirical Covariance

Plotting empirical covariance and fitting a curve we obtain our model.

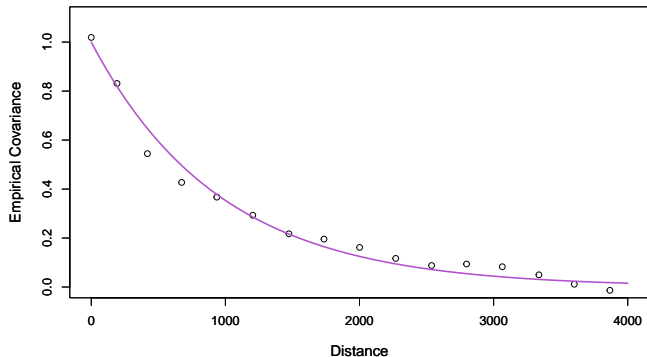


Figure: Empirical covariance.

# Model applications: Kriging

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- Method of interpolation based on Gaussian process governed by prior covariances.
- **Kriging** predicts the value of a function at a given point by computing a weighted average of the known values of the function in the neighborhood of the point.
- **Simple kriging**:

$$\mu(\mathbf{x}) = 0 \quad \text{and} \quad C(\mathbf{x}_1, \mathbf{x}_2) = \text{cov}(Z(\mathbf{x}_1), Z(\mathbf{x}_2)),$$

for all  $\mathbf{x} \in \mathbb{S}^2$ .

Since residuals are normalized,  $\mu \sim 0$ , **simple kriging** can be applied because of we have a known covariance function.

# Downscaling projections

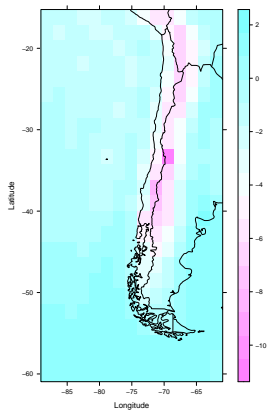


Figure: Original data.

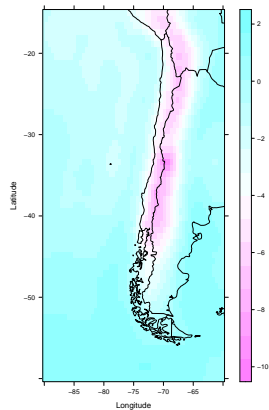



Figure: Kriging downscaling.

# Conclusions and future work

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Some remarkable facts about the project:

- Axially symmetric covariance functions technique was developed on  $\mathbb{S}^2$ .
- All the calculations were done using the euclidean distance on the sphere.
- Kriging method allowed us to build accurate temperature maps around Chile.

For future analysis, project files were uploaded to a public repository  MAT282. Commendable future work would be to compare the predictions obtained with a different covariance model.

# Bibliography

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Thank you.  
Questions?