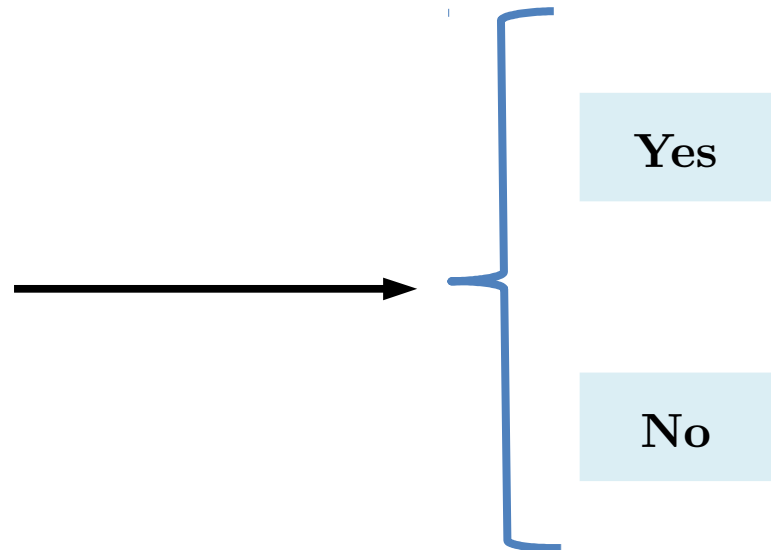


# Stochastic gradient methods

**Pierre Ablin**

**CNRS, Université Paris-Dauphine**

Let's build an algorithm that tells whether there is a cat in a picture:



Let's build an algorithm that tells whether there is a cat in a picture:



Yes

Let's build an algorithm that tells whether there is a cat in a picture:



Yes

Let's build an algorithm that tells whether there is a cat in a picture:



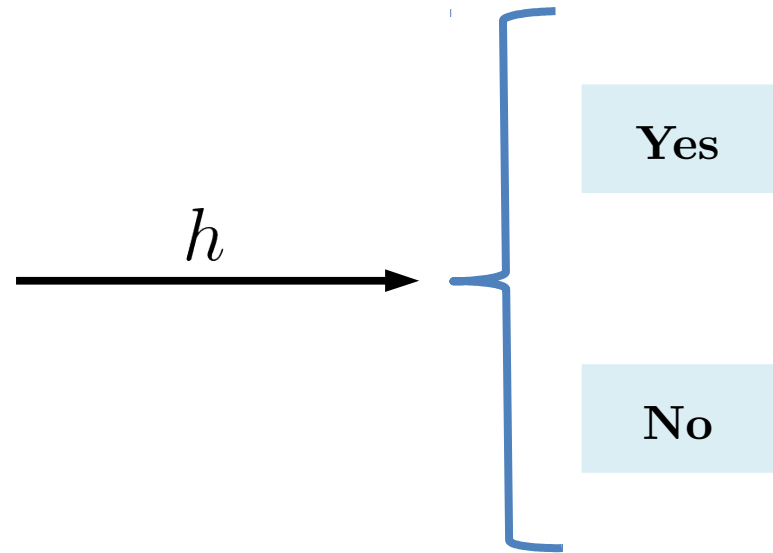
No

Let's build an algorithm that tells whether there is a cat in a picture:



Yes

# Let's build an algorithm that tells whether there is a cat in a picture:



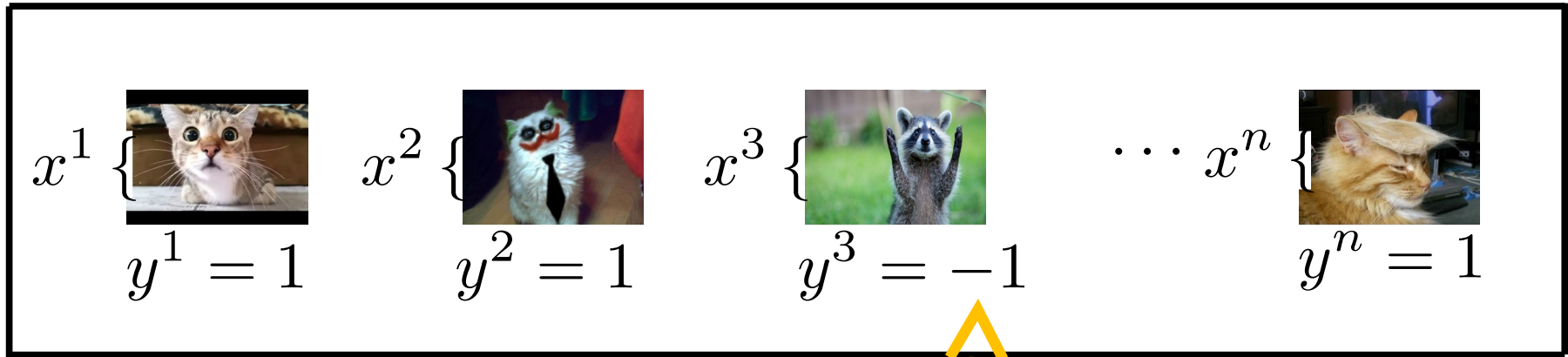
$x$ : Input/Feature

$y$ : Output/Target

Find mapping  $h$  that assigns the “correct” target to each input

$$h : x \in \mathbb{R}^d \longrightarrow y = \pm 1$$

# Labelled Data: The training set



$y = -1$  means no/false

Learning  
Algorithm

$$h : x \in \mathbb{R}^d \rightarrow y \in \pm 1$$

$$h \left( \left( \text{img of a white bulldog sitting on a bench} \right) \right)$$

-1



# A parametrized decision function

$$h : x \in \mathbb{R}^d \rightarrow y$$

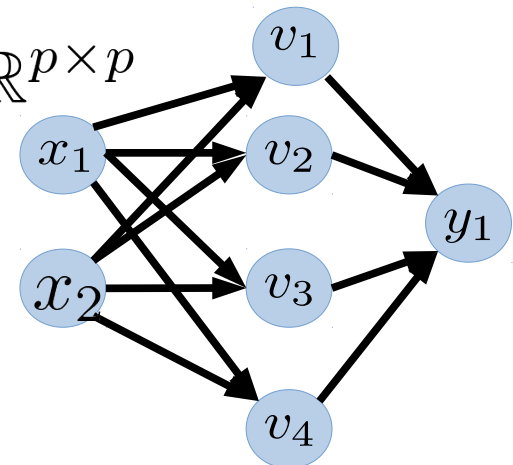
$h$  is a function parametrized by parameters  $\mathbf{w}$

## Examples

Linear:  $h_{\mathbf{w}}(x) = w_1x_1 + \cdots + w_px_p, \quad \mathbf{w} \in \mathbb{R}^p$

Polynomial:  $h_{\mathbf{w}}(x) = \sum_{ij} x_i x_j w_{ij}, \quad \mathbf{w} \in \mathbb{R}^{p \times p}$

Neural network:  $h_{\mathbf{w}}(x) = \mathbf{w}_2 \sigma(\mathbf{w}_1 x)$   
 $\mathbf{w}_2 \in \mathbb{R}^q, \quad \mathbf{w}_1 \in \mathbb{R}^{q \times p}$



# Learning parameters

## Goal :

Find  $\mathbf{w}$  such that for  $(x, y)$  in our dataset :

$$h_{\mathbf{w}}(x) \simeq y$$

## Mathematical reformulation

Find  $\mathbf{w}$  that minimizes a discrepancy:

$$\min F(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(h_{\mathbf{w}}(x_i), y_i)$$

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As many terms as  
images !



# Solving the Finite Sum Training Problem

# Recap

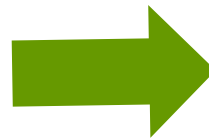
## Training Problem

$$\min_{w \in \mathbf{R}^d} \underbrace{\frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i) + \lambda R(w)}_{L(w)} =: f(w)$$

$L(w)$

General methods

$$\min f(w)$$



- Gradient Descent

# Optimization Sum of Terms

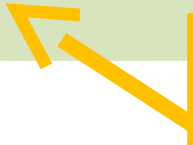
## A Datum Function

$$f_i(w) := \ell(h_w(x^i), y^i) + \lambda R(w)$$

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i) + \lambda R(w) &= \frac{1}{n} \sum_{i=1}^n (\ell(h_w(x^i), y^i) + \lambda R(w)) \\ &= \frac{1}{n} \sum_{i=1}^n f_i(w) \end{aligned}$$

## Finite Sum Training Problem

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) =: f(w)$$



Can we use this  
sum structure?

# The Training Problem

Solving the *training problem*:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

Reference method: Gradient descent

$$\nabla \left( \frac{1}{n} \sum_{i=1}^n f_i(w) \right) = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w)$$

## Gradient Descent Algorithm

Set  $w^0 = 0$ , choose  $\alpha > 0$ .

for  $t = 0, 1, 2, \dots, T - 1$

$$w^{t+1} = w^t - \frac{\alpha}{n} \sum_{i=1}^n \nabla f_i(w^t)$$

Output  $w^T$

# The Training Problem

Solving the *training problem*:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

## Problem with Gradient Descent:

Each iteration requires computing a gradient  $\nabla f_i(w)$  for each data point. One gradient for each cat on the internet!

## Gradient Descent Algorithm

Set  $w^0 = 0$ , choose  $\alpha > 0$ .

for  $t = 0, 1, 2, \dots, T$

$$w^{t+1} = w^t - \frac{\alpha}{n} \sum_{i=1}^n \nabla f_i(w^t)$$

Output  $w^T$





# Stochastic Gradient Descent

Is it possible to design a method that uses only the gradient of a **single** data function  $f_i(w)$  at each iteration?

# Stochastic Gradient Descent

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## Unbiased Estimate

Let  $j$  be a random index sampled from  $\{1, \dots, n\}$  selected uniformly at random. Then

$$\mathbb{E}_j[\nabla f_j(w)] = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w) = \nabla f(w)$$

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Use  $\nabla f_j(w) \approx \nabla f(w)$



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$$\mathbb{E}_j[\nabla f_j(w)] = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w) = \nabla f(w)$$



Use  $\nabla f_j(w) \approx \nabla f(w)$



**EXE:** Let  $\sum_{i=1}^n p_i = 1$  and  $j \sim p_j$ . Show  $\mathbb{E}[\nabla f_j(w)/(np_j)] = \nabla f(w)$

# Stochastic Gradient Descent

## SGD 0.0 Constant stepsize

Set  $w^0 = 0$ , choose  $\alpha > 0$

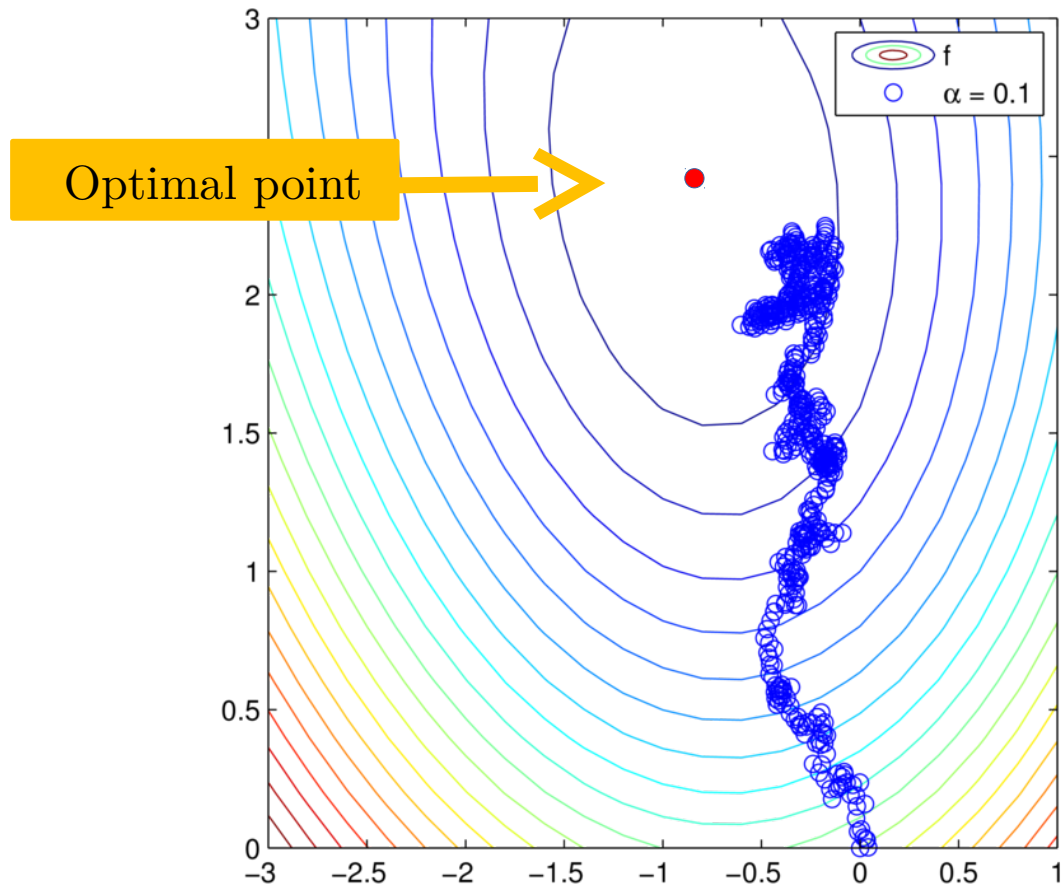
for  $t = 0, 1, 2, \dots, T - 1$

    sample  $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha \nabla f_j(w^t)$$

Output  $w^T$

# Stochastic Gradient Descent



# Convergence Strongly Convex and Bounded Gradient

**Theorem** If  $f$  is  $\mu$  - strongly convex and  $\mathbb{E}[\|\nabla f_i(w)\|^2] \leq B^2$

If  $0 < \alpha \leq \frac{1}{\mu}$  then the iterates of the SGD method satisfy

$$\mathbb{E} [\|w^t - w^*\|_2^2] \leq (1 - \alpha\mu)^t \|w^0 - w^*\|_2^2 + \frac{\alpha}{\mu} B^2$$

Shows that  $\alpha \approx \frac{1}{\mu}$

Shows that  $\alpha \approx 0$

**Proof:**  $w^{t+1} = w^t - \alpha \nabla f_j(w^t), \quad j \sim [1, \dots, n]$

1) Show that

$$\|w^{t+1} - w^*\|_2^2 = \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f_j(w^t), w^t - w^* \rangle + \alpha^2 \|\nabla f_j(w^t)\|_2^2.$$

2) Show that

$$\mathbb{E}_j [\|w^{t+1} - w^*\|_2^2] \leq \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f(w^t), w^t - w^* \rangle + \alpha^2 B^2$$

3) Using strong convexity, demonstrate that

$$\mathbb{E}_j [\|w^{t+1} - w^*\|_2^2] \leq (1 - \alpha\mu) \|w^t - w^*\|_2^2 + \alpha^2 B^2$$

4) Show that

$$\mathbb{E} [\|w^{t+1} - w^*\|_2^2] \leq (1 - \alpha\mu) \mathbb{E} [\|w^t - w^*\|_2^2] + \alpha^2 B^2$$

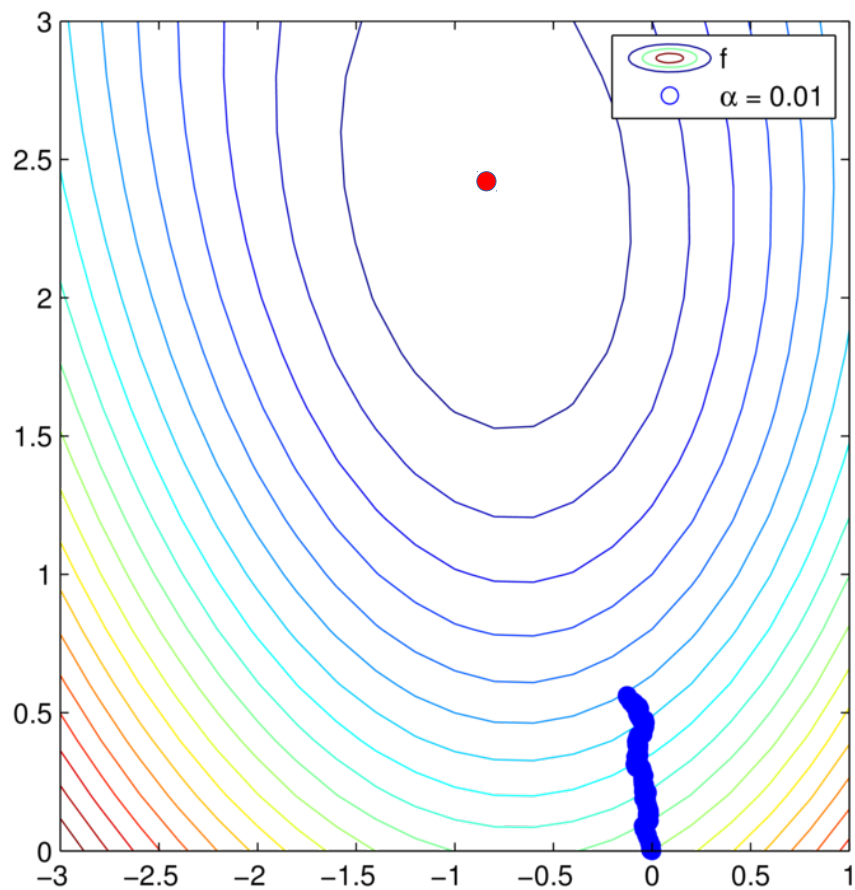
Where the expectation is taken w.r.t. the whole past. Conclude.



# Stochastic Gradient Descent

$\alpha = 0.01$

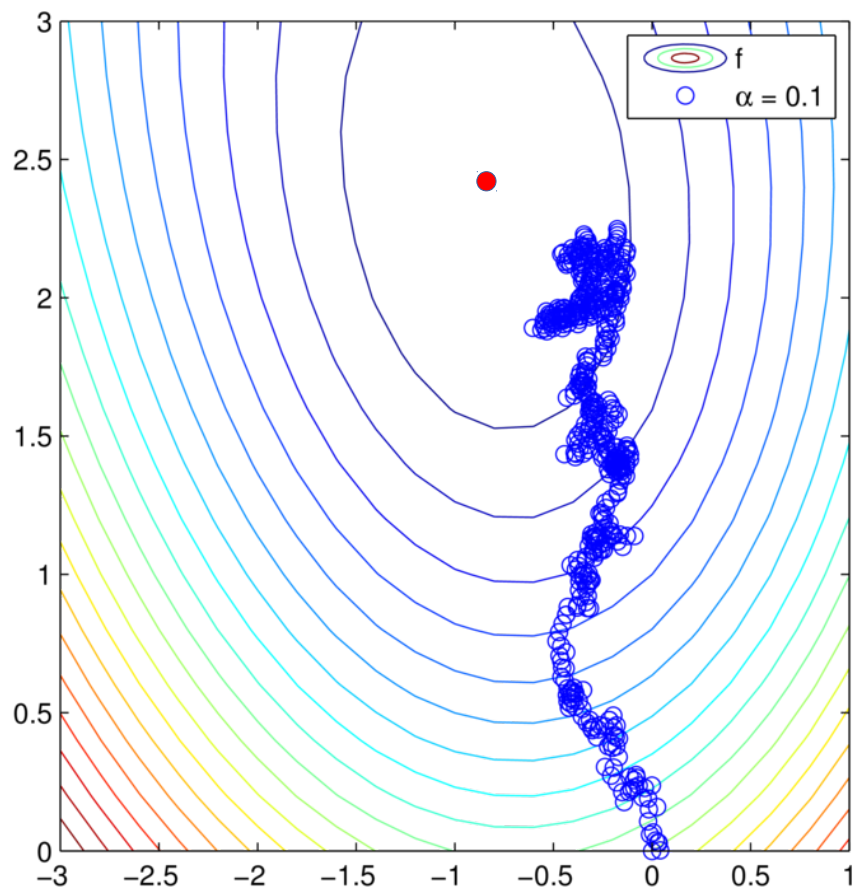
25



# Stochastic Gradient Descent

$\alpha = 0.1$

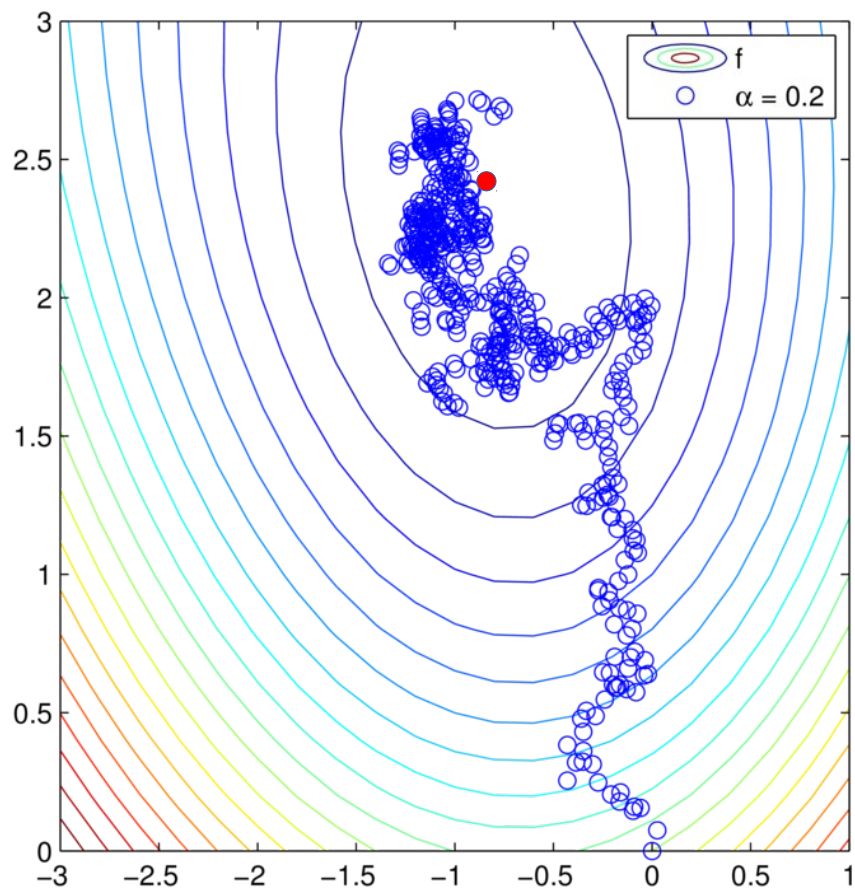
26



# Stochastic Gradient Descent

$\alpha = 0.2$

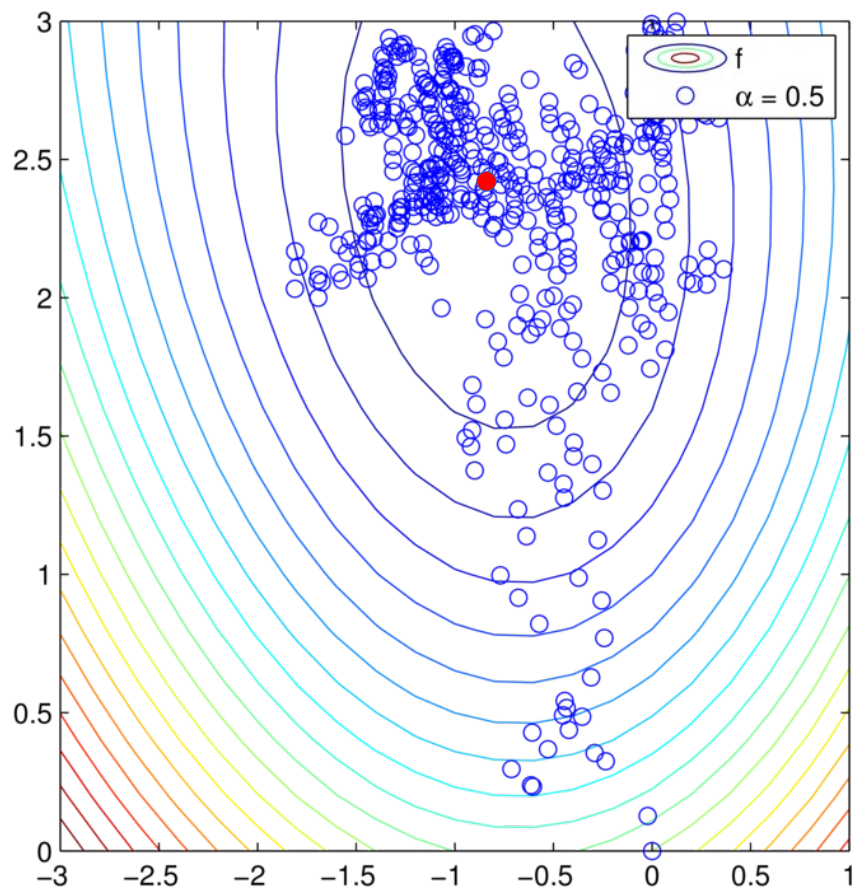
27



# Stochastic Gradient Descent

$\alpha = 0.5$

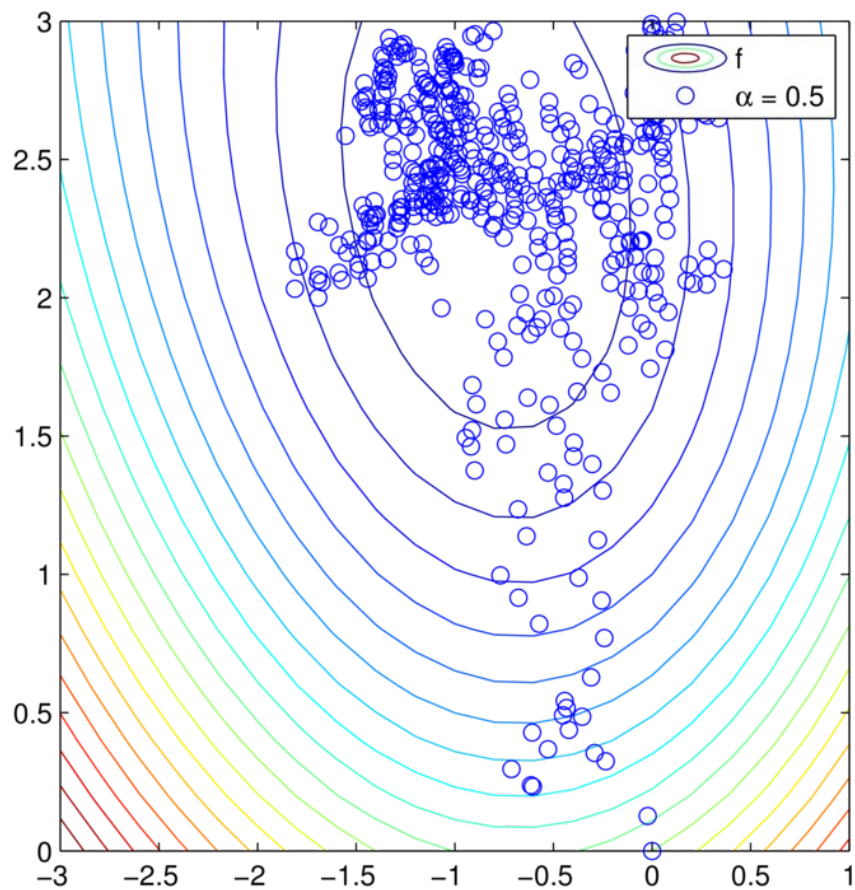
28



# Stochastic Gradient Descent

$\alpha = 0.5$

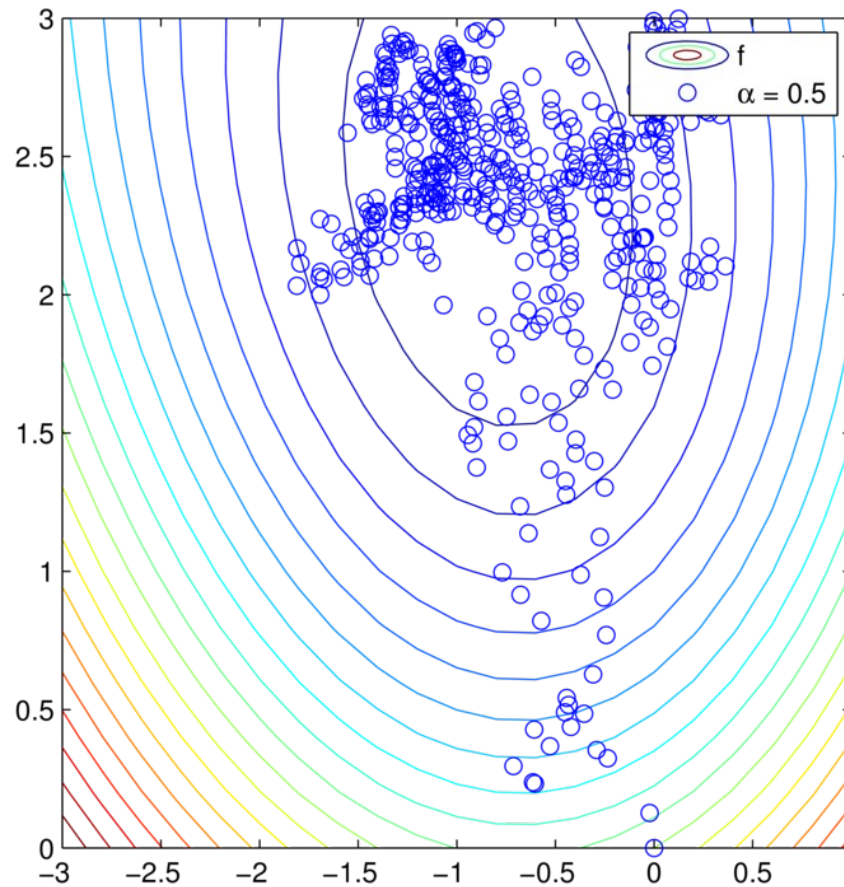
29



# Stochastic Gradient Descent

$\alpha = 0.5$

30

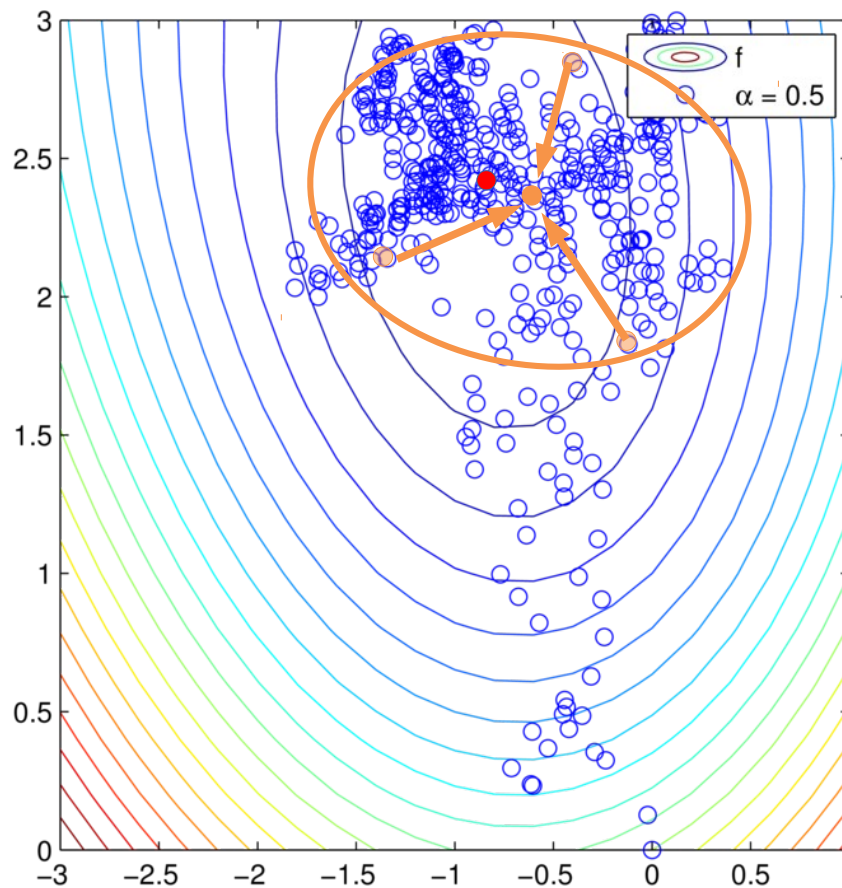


1) Start with big steps and end with smaller steps

# Stochastic Gradient Descent

$\alpha = 0.5$

31



1) Start with big steps and end with smaller steps

2) Try averaging the points

## SGD 1.0: Decreasing stepsize


Set  $w^0 = 0$

Choose  $\alpha_t > 0$ ,  $\alpha_t \rightarrow 0$ ,  $\sum_{t=0}^{\infty} \alpha_t = \infty$   
for  $t = 0, 1, 2, \dots, T - 1$

sample  $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha_t \nabla f_j(w^t)$$

Output  $w^T$



Shrinking  
Stepsize



## SGD 1.0: Decreasing stepsize


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Shrinking  
Stepsize

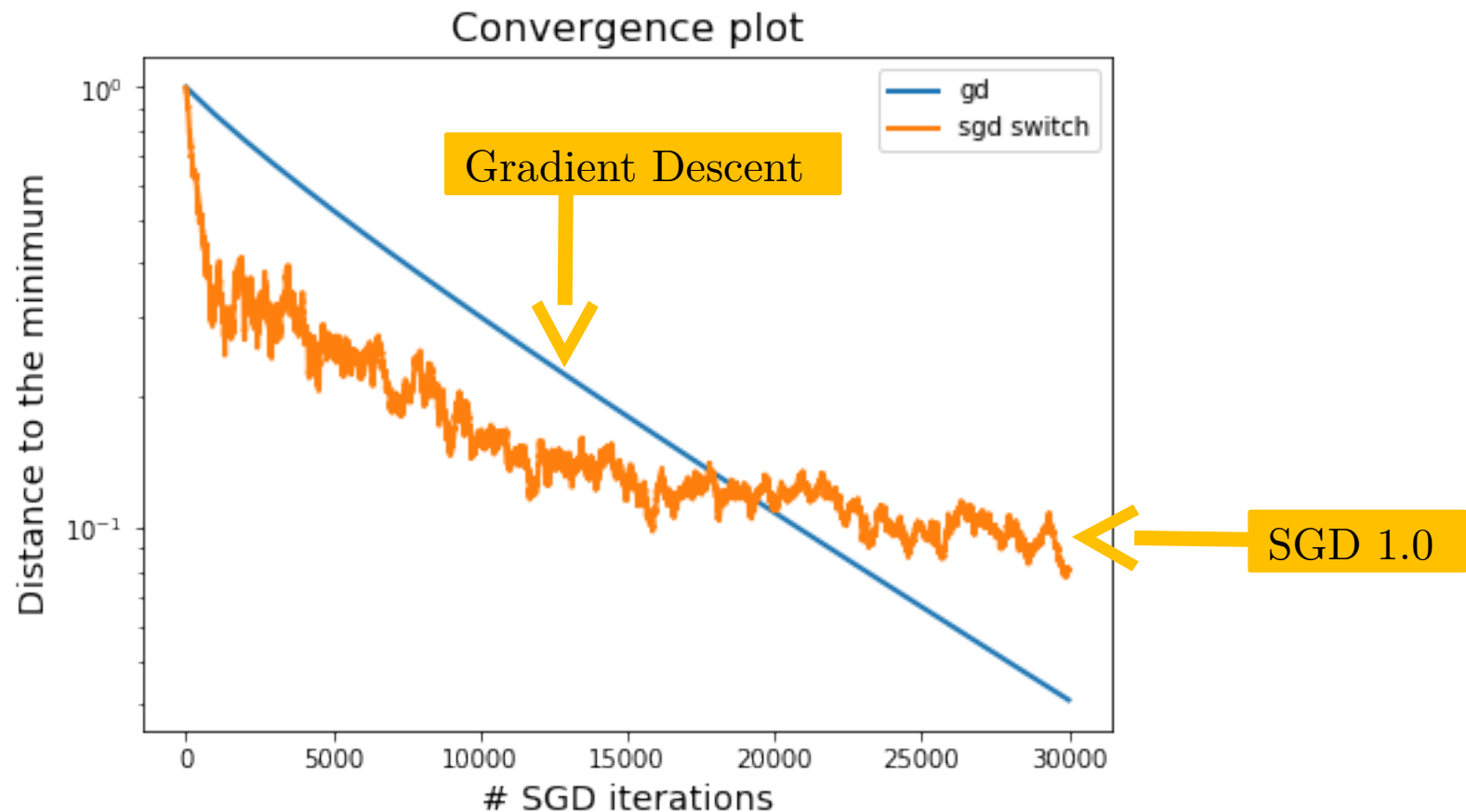
How should we  
sample  $j$  ?

How fast  $\alpha_t \rightarrow 0$ ?

Does this converge?

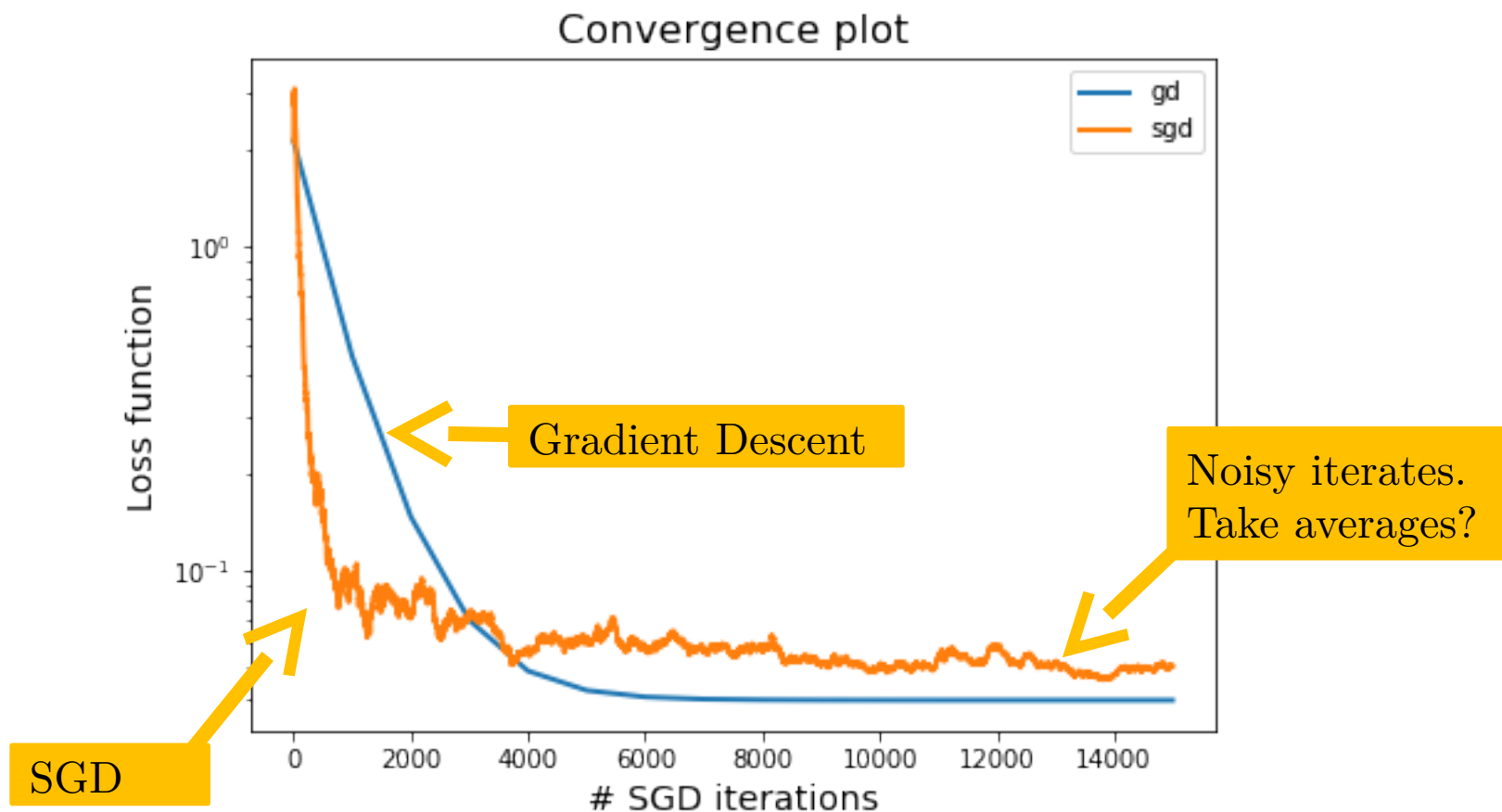
# SGD with shrinking stepsize

## Compared with Gradient Descent



# SGD with shrinking stepsize

## Compared with Gradient Descent



**Proof:**  $w^{t+1} = w^t - \alpha_t \nabla f_j(w^t), \quad j \sim [1, \dots, n]$

1) Recall that  $\mathbb{E} [\|w^{t+1} - w^*\|_2^2] \leq (1 - \alpha_t \mu) \mathbb{E} [\|w^t - w^*\|_2^2] + \alpha_t^2 B^2$   
 Let  $\delta_t = \mathbb{E} [\|w_t - w^*\|^2]$  and  $\pi_t^i = (1 - \alpha_{t-1} \mu) \times \dots \times (1 - \alpha_i \mu)$

$$\delta_t \leq \pi_t^0 + \sum_{i=0}^{t-1} \pi_t^i \alpha_i^2 B^2$$

2) Show that if  $\sum_{t=0}^{+\infty} \alpha_t = +\infty$  then  $\lim_{t \rightarrow +\infty} \pi_t^0 = 0$

3) Using  $\pi_t^i \leq \pi_t^0$ , show that if  $\sum_{t=0}^{+\infty} \alpha_i^2 < +\infty$ , then  $\lim_{t \rightarrow +\infty} \sum_{i=0}^{t-1} \pi_t^i \alpha_i^2 = 0$

Convergence when  $\sum_{t=0}^{+\infty} \alpha_i = +\infty$  and  $\sum_{t=0}^{+\infty} \alpha_i^2 < +\infty$

# SGD with (late start) averaging

## SGDA 1.1

Set  $w^0 = 0$

Choose  $\alpha_t > 0$ ,  $\alpha_t \rightarrow 0$ ,  $\sum_{t=0}^{\infty} \alpha_t = \infty$

Choose averaging start  $s_0 \in \mathbb{N}$

for  $t = 0, 1, 2, \dots, T - 1$

    sample  $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha_t \nabla f_j(w^t)$$

    if  $t > s_0$

$$\bar{w} = \frac{1}{t - s_0} \sum_{i=s_0}^t w^i$$

    else:  $\bar{w} = w$

Output  $\bar{w}$



B. T. Polyak and A. B. Juditsky, SIAM Journal on Control and Optimization (1992)

**Acceleration of stochastic approximation by averaging**

# SGD with (late start) averaging

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else:  $\bar{w} = w$

Output  $\bar{w}$

This is not efficient. How to make this efficient?

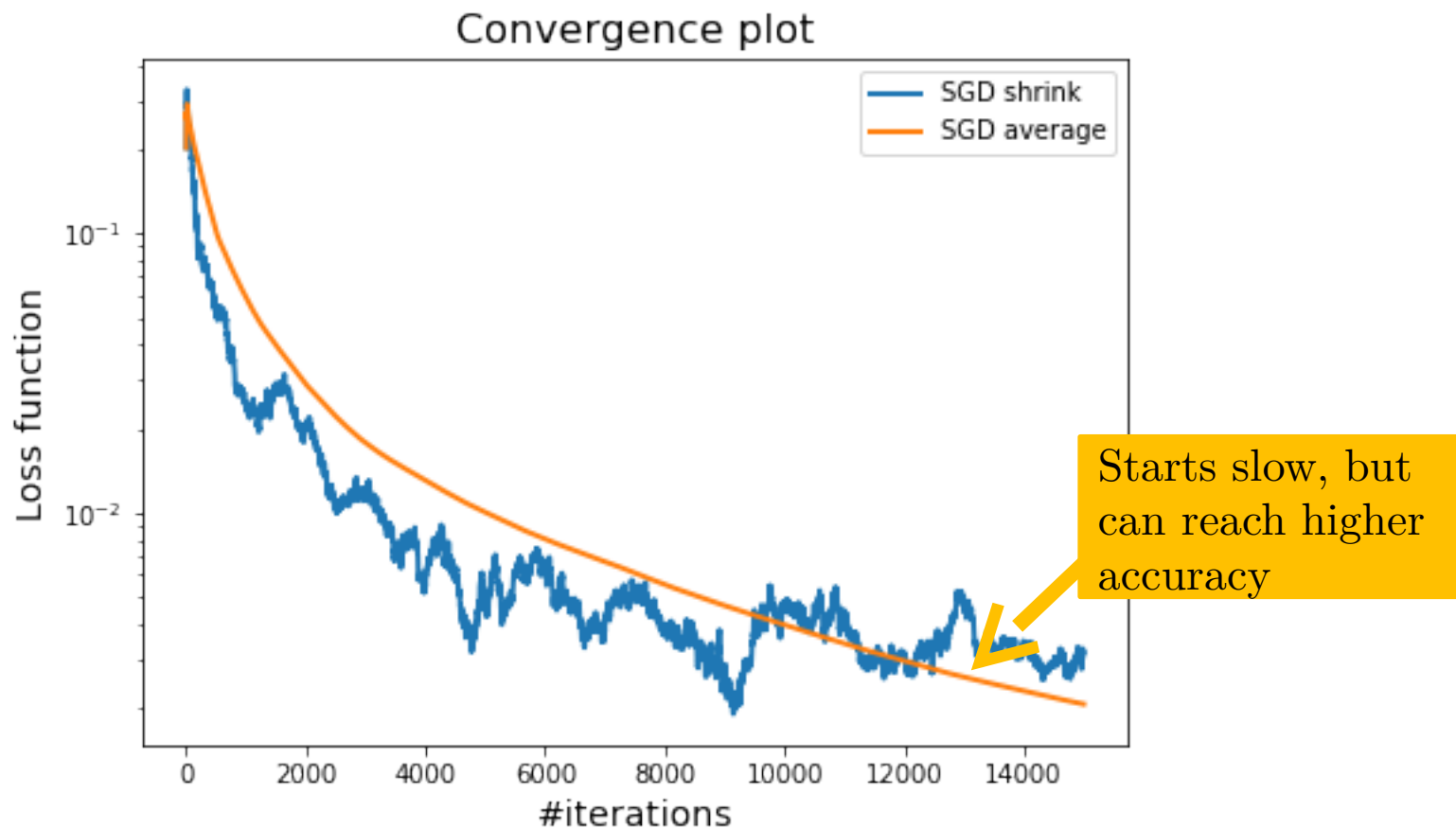


B. T. Polyak and A. B. Juditsky, SIAM Journal on Control and Optimization (1992)

**Acceleration of stochastic approximation by averaging**

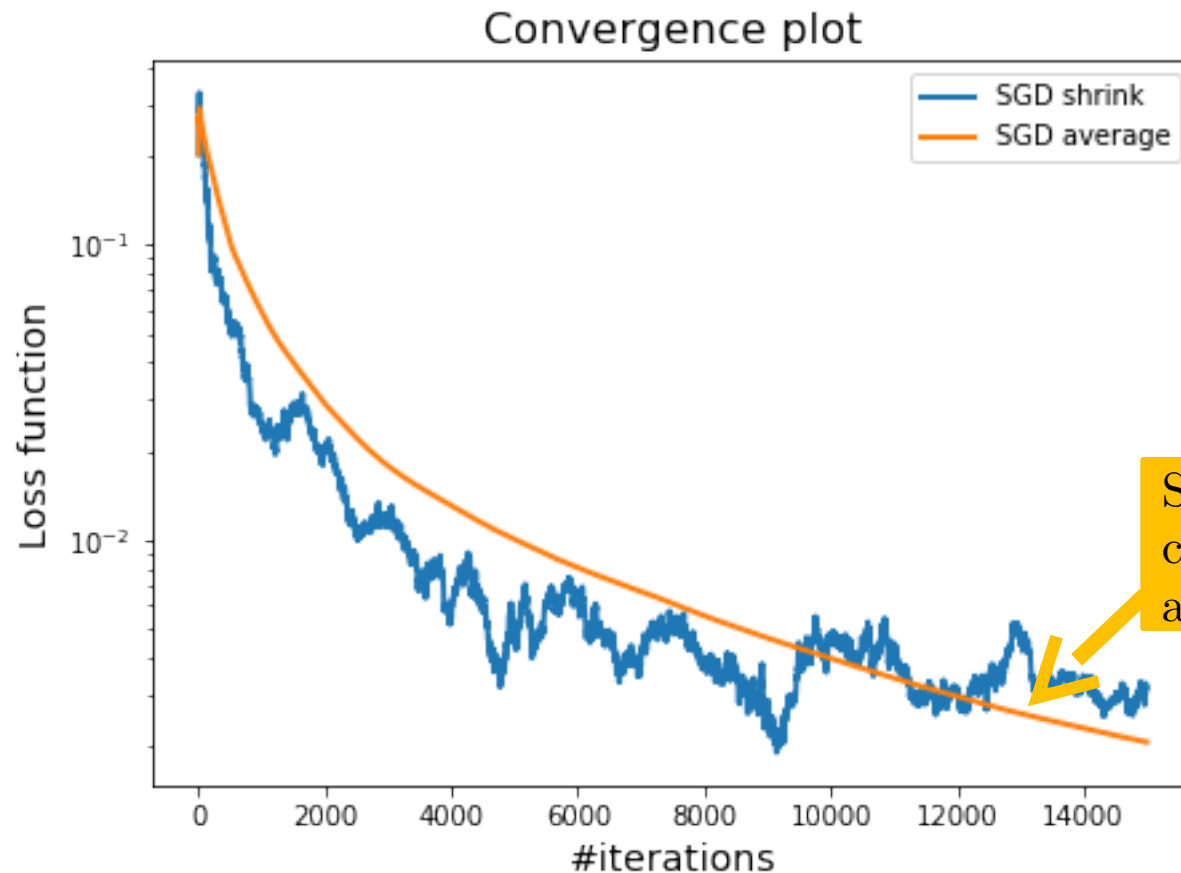
# Stochastic Gradient Descent

## With and without averaging



# Stochastic Gradient Descent

## With and without averaging



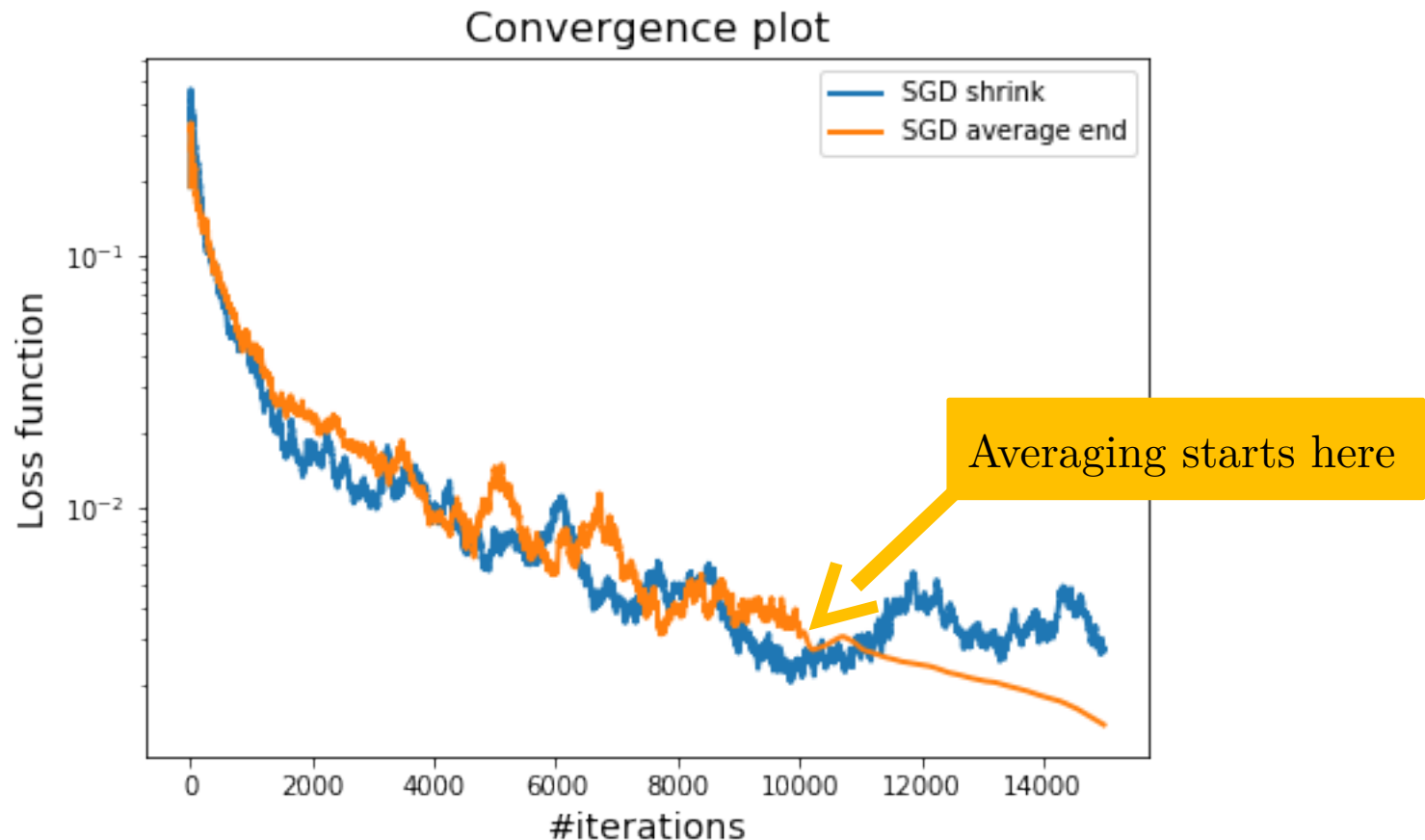
Starts slow, but  
can reach higher  
accuracy

Only use  
averaging  
towards the end?



# Stochastic Gradient Descent

## Averaging the last few iterates



# Comparison GD and SGD for strongly convex

42

	SGD	GD
Iteration complexity	$O\left(\frac{1}{\epsilon}\right)$	$O\left(\log\left(\frac{1}{\epsilon}\right)\right)$

# Comparison GD and SGD for strongly convex

	SGD	GD
Iteration complexity	$O\left(\frac{1}{\epsilon}\right)$	$O\left(\log\left(\frac{1}{\epsilon}\right)\right)$
Cost of an iteration	$O(1)$	$O(n)$

# Comparison GD and SGD for strongly convex

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Iteration complexity	$O\left(\frac{1}{\epsilon}\right)$	$O\left(\log\left(\frac{1}{\epsilon}\right)\right)$
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Total complexity*	$O\left(\frac{1}{\epsilon}\right)$	$O\left(n \log\left(\frac{1}{\epsilon}\right)\right)$

# Comparison GD and SGD for strongly convex

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# Comparison GD and SGD for strongly convex

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Cost of an iteration	$O(1)$	$O(n)$
Total complexity*	$O\left(\frac{1}{\epsilon}\right)$	$O\left(n \log\left(\frac{1}{\epsilon}\right)\right)$

What happens if  $\epsilon$  is small?

What happens if  $n$  is big?

\*Total complexity = (Iteration complexity)  $\times$  (Cost of an iteration)

# Why Machine Learners Like SGD

# Why Machine Learners like SGD

Though we solve:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i) + \lambda R(w)$$

We want to solve:

**The statistical learning problem:**

Minimize the expected loss over an *unknown* expectation

$$\min_{w \in \mathbf{R}^d} \mathbb{E}_{(x,y) \sim \mathcal{D}} [\ell(h_w(x), y)]$$

SGD can solve the  
statistical learning problem!



# Why Machine Learners like SGD

**The statistical learning problem:**

Minimize the expected loss over an *unknown* expectation

$$\min_{w \in \mathbf{R}^d} \mathbb{E}_{(x,y) \sim \mathcal{D}} [\ell(h_w(x), y)]$$

**SGD**  $\infty.0$  for learning

Set  $w^0 = 0$ ,  $\alpha > 0$

for  $t = 0, 1, 2, \dots, T - 1$

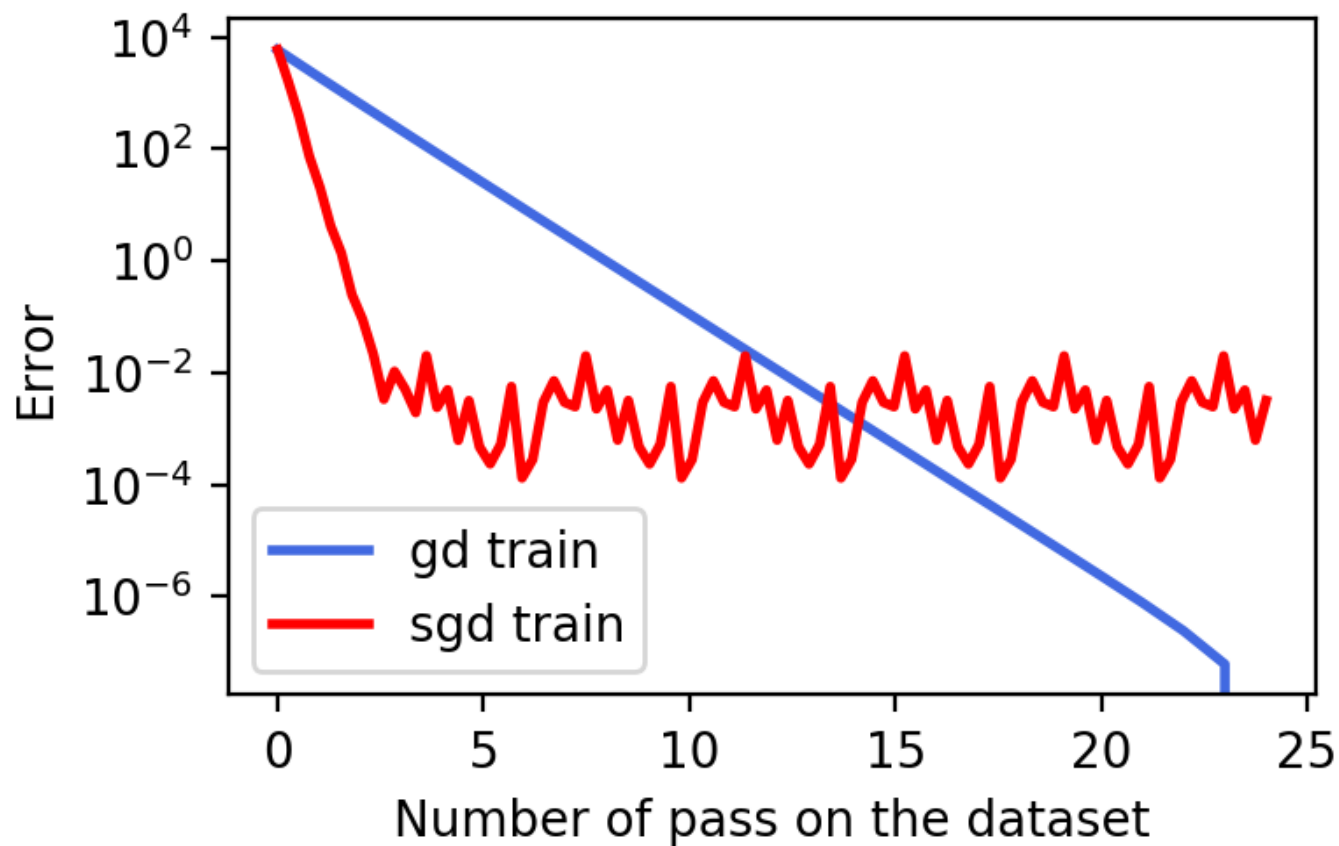
sample  $(x, y) \sim \mathcal{D}$

calculate  $v_t \in \partial \ell(h_{w^t}(x), y)$

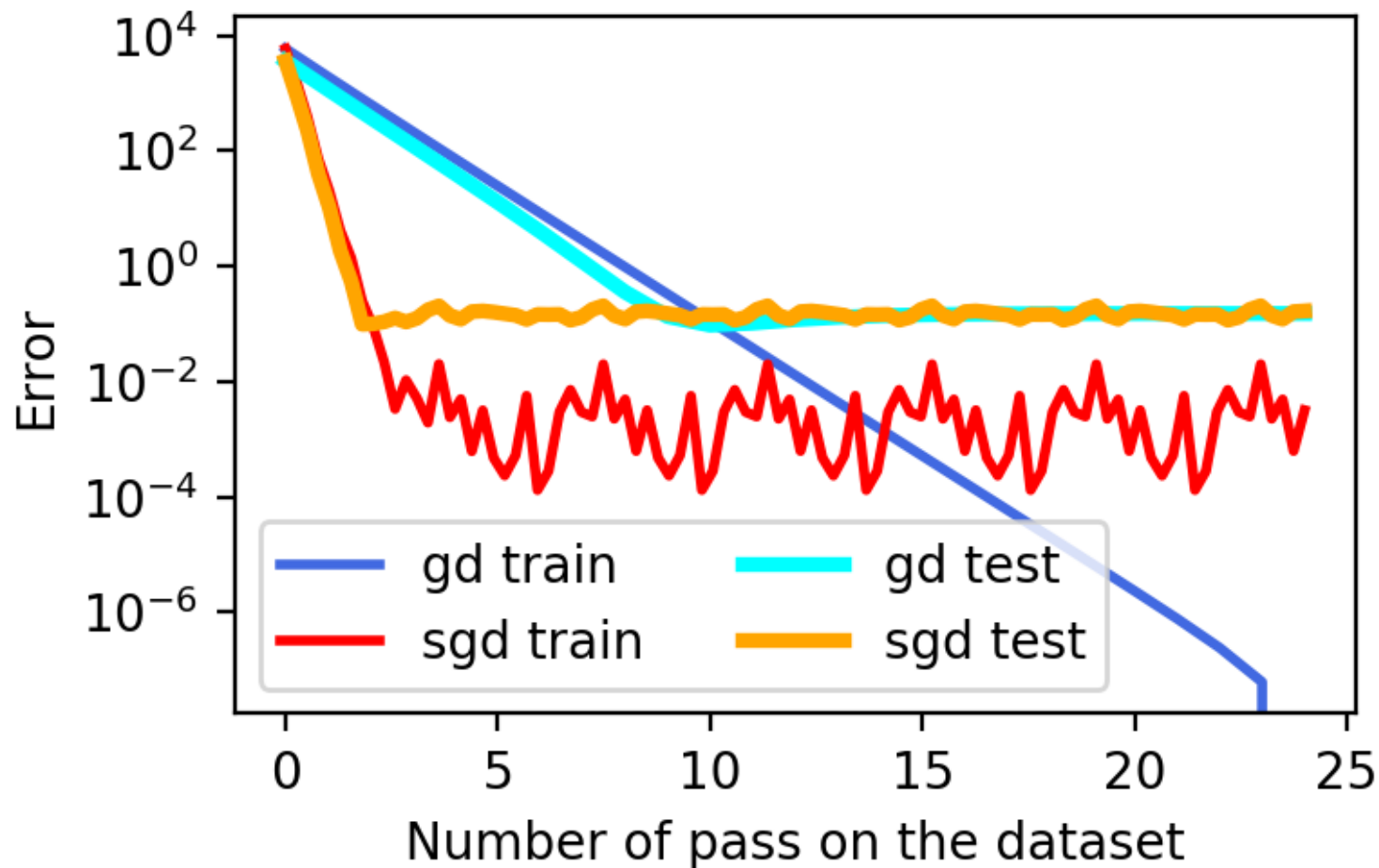
$w^{t+1} = w^t - \alpha v_t$

Output  $\bar{w}^T = \frac{1}{T} \sum_{t=1}^T w^t$

# Train error

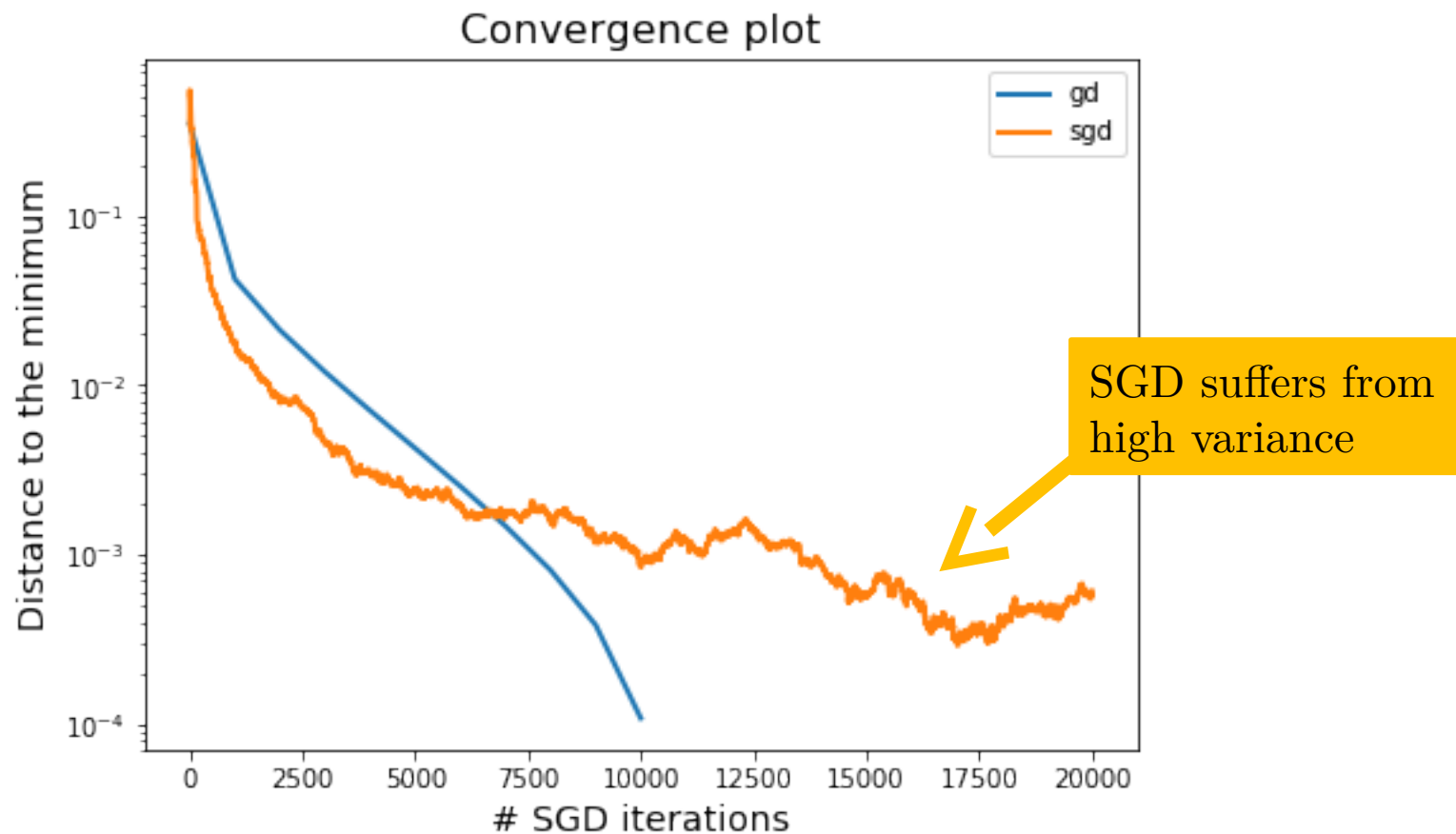


# Train error and test error

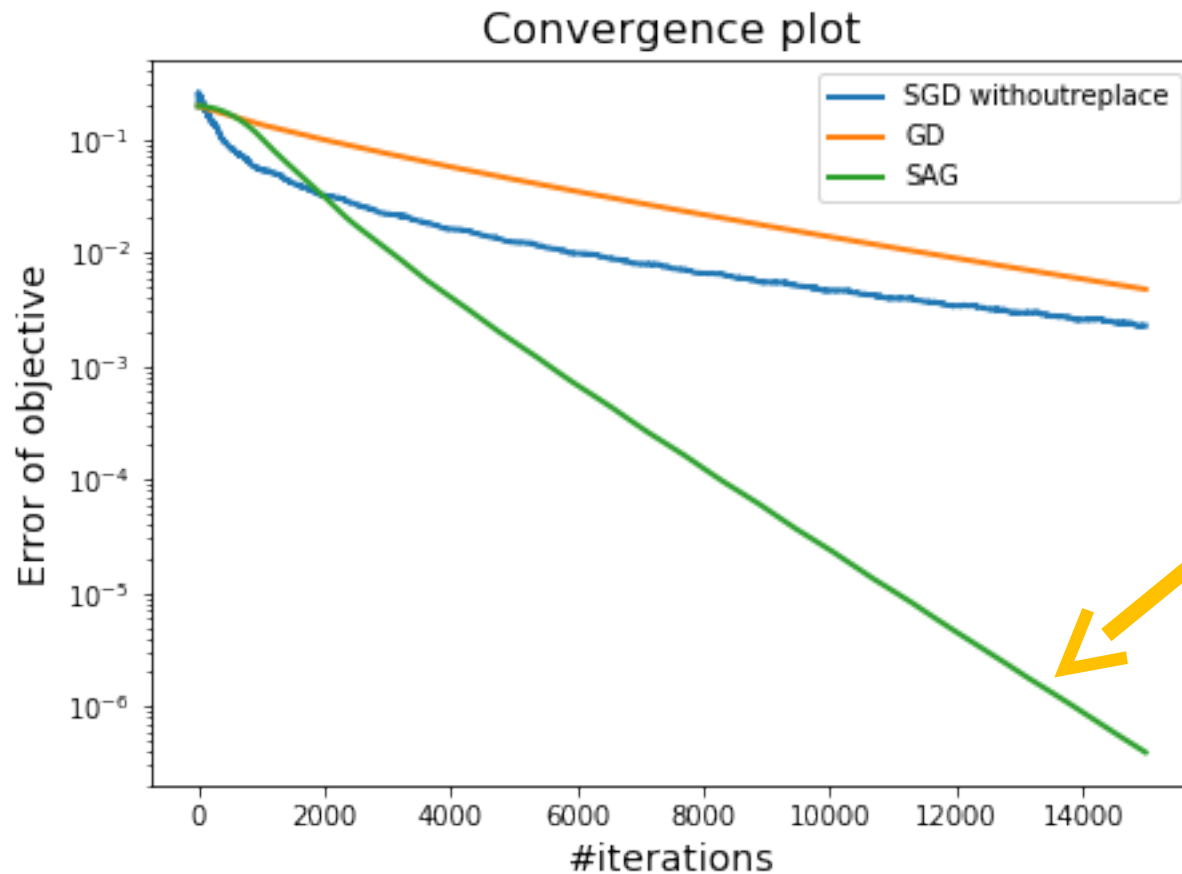


# Variance reduction methods

# SGD initially fast, slow later



# Can we get best of both?



Let's learn about methods like this one

# Build an Estimate of the Gradient



Instead of using directly  $\nabla f_j(w^t) \approx \nabla f(w^t)$   
 Use  $\nabla f_j(w^t)$  to update estimate  $g_t \approx \nabla f(w^t)$



$$w^{t+1} = w^t - \gamma g^t$$

We would like gradient estimate such that:

Typically unbiased  
 $\mathbf{E}[g^t] = \nabla f(w^t)$

Similar

$$g^t \approx \nabla f(w^t)$$

Converges  
 in  $L^2$

$$\mathbb{E}||g^t||_2^2 \xrightarrow{w^t \rightarrow w^*} 0$$

Solves problem of  
 $\alpha_t \xrightarrow{t \rightarrow \infty} 0$

# Controlled Stochastic Reformulation

Covariate functions:

$$z_i : w \mapsto z_i(w) \in \mathbb{R}, \quad \text{for } i = 1, \dots, n$$

$$\frac{1}{n} \sum_{i=1}^n f_i(w) = \mathbb{E}[f_{\color{red}{i}}(w)] = \mathbb{E}[f_{\color{red}{i}}(w)] - \mathbb{E}[z_{\color{red}{i}}(w)] + \mathbb{E}[z_{\color{red}{i}}(w)]$$

$\uparrow$   $i \sim \frac{1}{n}$

$$= \mathbb{E}[f_{\color{red}{i}}(w) - z_{\color{red}{i}}(w) + \mathbb{E}[z_{\color{red}{i}}(w)]]$$

Cancel out
  
 $\swarrow \quad \searrow$

**Original finite  
sum problem**

$$\min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w)$$



**Controlled Stochastic Reformulation**

$$\min_{w \in \mathbb{R}^d} \mathbb{E}[f_{\color{red}{i}}(w) - z_{\color{red}{i}}(w) + \mathbb{E}[z_{\color{red}{i}}(w)]]$$

Use covariates to **control the variance**



# Variance reduction as SGD on another<sup>57</sup> function

$$\min_{w \in \mathbb{R}^d} \mathbb{E} [f_{\mathbf{i}}(w) - z_{\mathbf{i}}(w) + \mathbb{E}[z_{\mathbf{i}}(w)]]$$



By design we have that  
 $\mathbb{E}[g_{\mathbf{i}}(w^t)] = \nabla f(w^t)$

Sample  $\mathbf{i} \sim \frac{1}{n}$

$$w^{t+1} = w^t - \gamma g_{\mathbf{i}}(w^t)$$

$$g_{\mathbf{i}}(w) := \nabla f_{\mathbf{i}}(w) - \nabla z_{\mathbf{i}}(w) + \mathbb{E}[\nabla z_{\mathbf{i}}(w)]$$

How to choose  $z_{\mathbf{i}}(w)$ ?

# Covariates

$$\text{cov}(x, z) := \mathbb{E}[(x - \mathbb{E}[x])(z - \mathbb{E}[z])]$$

Let  $x$  and  $z$  be random variables. We say that  $x$  and  $z$  are covariates if:

$$\text{cov}(x, z) \geq 0$$

Variance Reduced Estimate:

$$x_z = x - z + \mathbb{E}[z]$$

- EXE:**
1. Show that  $\mathbb{E}[x_z] = \mathbb{E}[x]$
  2.  $\text{VAR}[x_z] = \mathbb{E}[(x_z - \mathbb{E}[x_z])^2] = ?$
  3. When is  $\text{VAR}[x_z] \leq \text{VAR}[x]$

$$\begin{aligned}\mathbb{E}[(x_z - \mathbb{E}[x_z])^2] &= \mathbb{E}[(x - \mathbb{E}[x] - (z - \mathbb{E}[z]))^2] \\ &= \mathbb{E}[(x - \mathbb{E}[x])^2] - 2\mathbb{E}[(x - \mathbb{E}[x])(z - \mathbb{E}[z])] \\ &\quad + \mathbb{E}[(z - \mathbb{E}[z])^2] \\ &= \text{VAR}[x] - 2\text{cov}(x, z) + \text{VAR}[z]\end{aligned}$$

Larger covariance between  $x$  and  $z$  is good

# Covariates

Let  $x$  and  $z$  be random variables. We say that  $x$  and  $z$  are covariates if:

Variance Reduced Estimate:

$$\text{cov}(x, z) := \mathbb{E}[(x - \mathbb{E}[x])(z - \mathbb{E}[z])]$$

$$\text{cov}(x, z) \geq 0$$

$$x_z = x - z + \mathbb{E}[z]$$

$$g_i(w) := \nabla f_{\textcolor{red}{i}}(w) - \nabla z_{\textcolor{red}{i}}(w) + \mathbb{E}[\nabla z_{\textcolor{red}{i}}(w)]$$

$$x$$

$$z$$

$$\mathbb{E}[z]$$

$$\nabla z_{\textcolor{red}{i}}(w) \approx \nabla f_{\textcolor{red}{i}}(w)$$



$$\text{cov}(\nabla z_{\textcolor{red}{i}}(w), \nabla f_{\textcolor{red}{i}}(w))$$

# Choosing the covariate as a linear approximation

Sample  $i \sim \frac{1}{n}$

$$w^{t+1} = w^t - \gamma g_i(w^t) \quad := \nabla f_i(w) - \nabla z_i(w) + \mathbb{E}[\nabla z_i(w)]$$

We would like:

$$\nabla z_i(w) \approx \nabla f_i(w)$$

**Linear approximation around  $w$**

$$z_i(w) = f_i(\tilde{w}) + \langle \nabla f_i(\tilde{w}), w - \tilde{w} \rangle$$

A reference point/ snap shot

# SVRG: Stochastic Variance reduced method gradient



Johnson & Zhang, 2013 NIPS

$$w^{t+1} = w^t - \gamma g_{\mathbf{i}}(w^t)$$

Reference point

$$\tilde{w} \in \mathbb{R}^d$$

Sample

$$\nabla f_{\mathbf{i}}(w^t), \quad \text{i.i.d sample with prob } \frac{1}{n}$$

Grad. estimate

$$g_{\mathbf{i}}(w^t) = \nabla f_{\mathbf{i}}(w^t) - \nabla f_{\mathbf{i}}(\tilde{w}) + \nabla f(\tilde{w})$$

It's unbiased  
because:

$$\begin{aligned} \mathbb{E}[g_{\mathbf{i}}(w)] &= \mathbb{E}[\nabla f_{\mathbf{i}}(w)] - \mathbb{E}[\nabla f_{\mathbf{i}}(\tilde{w})] + \nabla f(\tilde{w}) \\ &= \nabla f(w) - \cancel{\nabla f(\tilde{w})} + \cancel{\nabla f(\tilde{w})} \end{aligned}$$

# free-SVRG: Stochastic Variance Reduced Gradients

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Jonhson & Zhang  
NIPS 2013Sebbouh, et. al 2019  
Neurips 2019

Set  $\tilde{w}^0 = 0 = x_0^m$ , choose  $\gamma > 0, m \in \mathbb{N}$ ,

$\alpha_t > 0$  with  $\sum_{t=0}^{m-1} \alpha_t = 1$

for  $s = 1, 2, \dots, T$

$x_s^0 = x_{s-1}^m$

for  $t = 0, 1, 2, \dots, m - 1$

i.i.d sample  $i \sim \frac{1}{n}$

$g^t = \nabla f_i(x_s^t) - \nabla f_i(\tilde{w}^{s-1}) + \nabla f(\tilde{w}^{s-1})$

$x_s^{t+1} = x_s^t - \gamma g^t$

$\tilde{w}^{s+1} = \sum_{t=0}^{m-1} \alpha_t x_s^t$

Output  $\tilde{w}^{T+1}$

Adding  
indices in  
 $t$  and  $s$

Reference point is an  
average of inner iterates



Most iterates cost  $O(1)$



Tune inner loop size  $m$

# SAGA: Stochastic Average Gradient



Defazio, Bach, & Lacoste-Julien, 2014 NIPs

$$w^{t+1} = w^t - \gamma g_i(w^t)$$

Sample

$\nabla f_i(w^t)$ , i.i.d sample with prob  $\frac{1}{n}$

Grad. estimate

$$g_i(w^t) = \nabla f_i(w^t) - \nabla f_i(w^{t_i}) + \frac{1}{n} \sum_{j=1}^n \nabla f_j(w^{t_j})$$

$$z_i(w) = f_i(w^{t_i}) + \langle \nabla f_i(w^{t_i}), w - w^{t_i} \rangle$$



$$\nabla z_i(w^t) = \nabla f_i(w^{t_i})$$

$$\mathbb{E}[\nabla z_i(w^t)]$$

Store grad.

$$\nabla f_i(w^{t_i}) = \nabla f_i(w^t)$$

# SAGA: Stochastic Average Gradient

Set  $w^0 = 0, g_i = \nabla f_i(w^0)$ , for  $i = 1 \dots, n$

Choose  $\gamma > 0$

for  $t = 0, 1, 2, \dots, T - 1$

sample  $i \in \{1, \dots, n\}$

$$g^t = \nabla f_i(w^t) - g_i + \frac{1}{n} \sum_{j=1}^n g_j$$

$$w^{t+1} = w^t - \gamma g^t$$

$$g_i = \nabla f_i(w^t)$$

Output  $w^T$



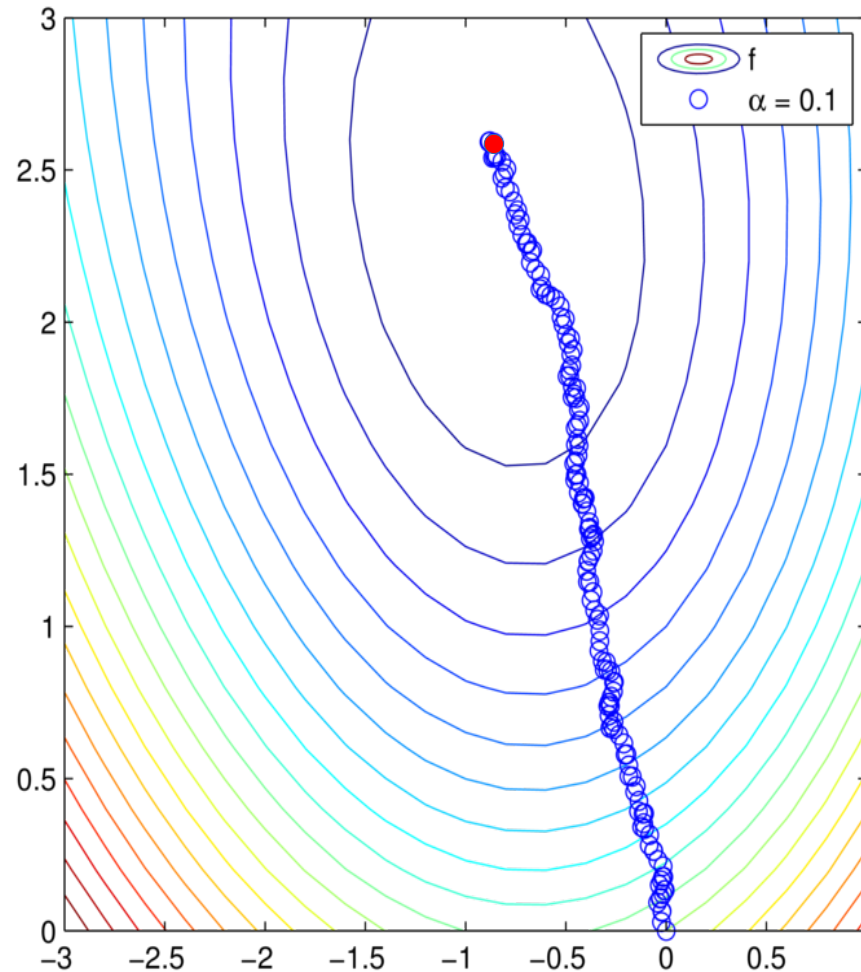
No inner loop, rolling update



Stores a  $d \times n$  matrix



# The Stochastic Average Gradient



How to prove this converges? Is this the only option?

# Convergence Theorems

# Assumptions for Convergence

## Strong Convexity

$$f(w) \geq f(y) + \langle \nabla f(y), w - y \rangle + \frac{\mu}{2} \|w - y\|_2^2$$

## Smoothness + convexity

$$f_i(w) \leq f_i(y) + \langle \nabla f_i(y), w - y \rangle + \frac{L_i}{2} \|w - y\|_2^2$$

$$f_i(w) \geq f_i(y) + \langle \nabla f_i(y), w - y \rangle \quad \text{for } i = 1, \dots, n$$

$$L_{\max} := \max_{i=1, \dots, n} L_i$$

# Convergence SAGA

## Theorem SAGA

If  $f(w)$  is  $\mu$ -strongly convex,  $f_i(w)$  is  $L_{\max}$ -smooth and  $\alpha = 1/(3L_{\max})$  then

$$\mathbb{E} [\|w^t - w^*\|_2^2] \leq \left(1 - \min \left\{ \frac{1}{4n}, \frac{\mu}{3L_{\max}} \right\}\right)^t C_0$$

where  $C_0 = \frac{2n}{3L_{\max}}(f(w^0) - f(w^*)) + \|w^0 - w^*\|_2^2 \geq 0$

An even more practical convergence result!

Difficult proof technique



A. Defazio, F. Bach and J. Lacoste-Julien (2014)  
NIPS, **SAGA: A Fast Incremental Gradient Method With Support for Non-Strongly Convex Composite Objectives.**

# Comparisons in total complexity for strongly convex

**Approximate solution**

$$\mathbb{E}[f(w^T)] - f(w^*) \leq \epsilon \quad \text{or} \quad \mathbb{E}\|w^t - w^*\|^2 \leq \epsilon$$

**SGD**

$$O\left(\frac{1}{\epsilon}\right)$$

**Gradient descent**

$$O\left(\frac{nL}{\mu} \log\left(\frac{1}{\epsilon}\right)\right)$$

**SVRG/SAGA/SAG**

$$O\left(\left(n + \frac{L_{\max}}{\mu}\right) \log\left(\frac{1}{\epsilon}\right)\right)$$

Variance reduction faster than GD when

$$L \geq \mu + L_{\max}/n$$

# Practicals implementation of SAG for Linear Classifiers

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**Finite Sum Training Problem**

L2 regularizer +  
linear hypothesis

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n \ell(\langle w, x^i \rangle, y^i) + \frac{\lambda}{2} \|w\|_2^2$$

$$\nabla f_i(w) = \underbrace{\ell'(\langle w, x^i \rangle, y^i) x^i}_{\text{Nonlinear in } w} + \underbrace{\lambda w}_{\text{Linear in } w}$$

Reduce  
Storage  
to  $O(n)$

Only store real number

Stoch. gradient estimate

Full gradient estimate

$$\beta_i = \ell'(\langle w^{t_i}, x^i \rangle, y^i)$$

$$\nabla f_i(w^{t_i}) = \beta_i x^i + \lambda w^t$$

$$g^t = \frac{1}{n} \sum_{j=1}^n \beta_j x_j + \lambda w^t$$

# Take for home Variance Reduction

- Variance reduced methods use only **one stochastic gradient per iteration** and converge linearly on strongly convex functions
- Choice of **fixed stepsize** possible
- **SAGA** only needs to know the smoothness parameter to work, but requires storing  $n$  past stochastic gradients
- **SVRG** only has  $O(d)$  storage, but requires full gradient computations every so often. Has an extra “number of inner iterations” parameter to tune