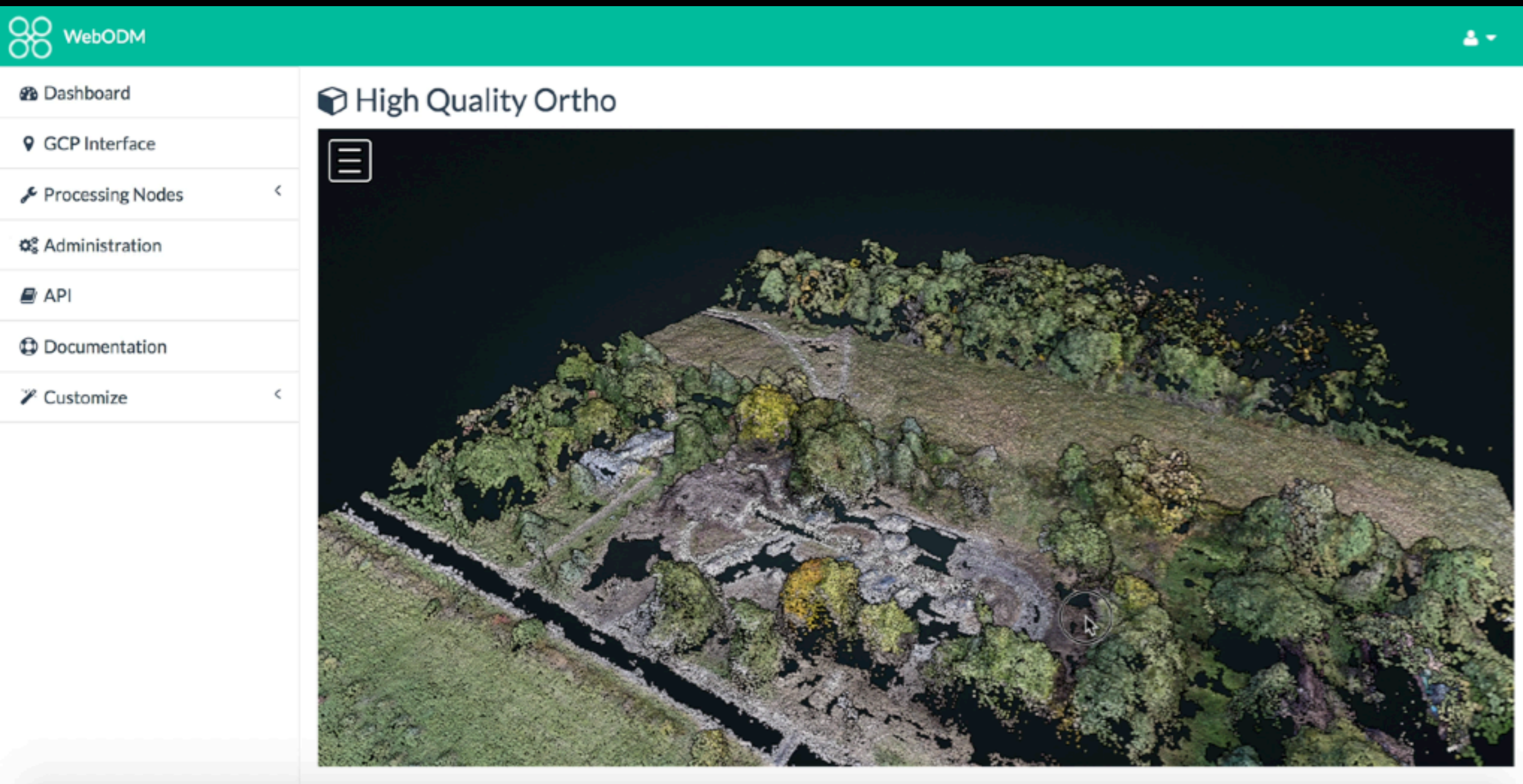




# Dense Point Cloud from finding all matches





# Point Cloud from Matching

