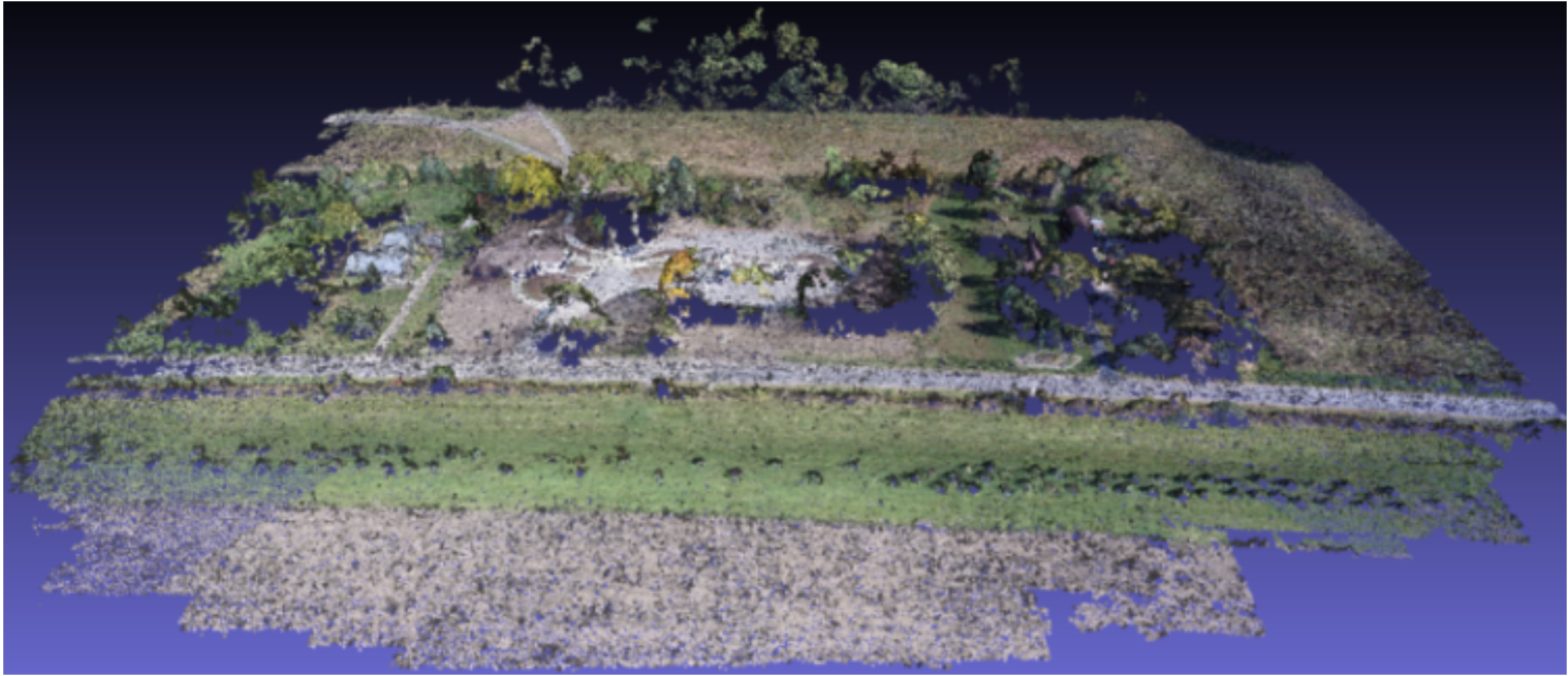
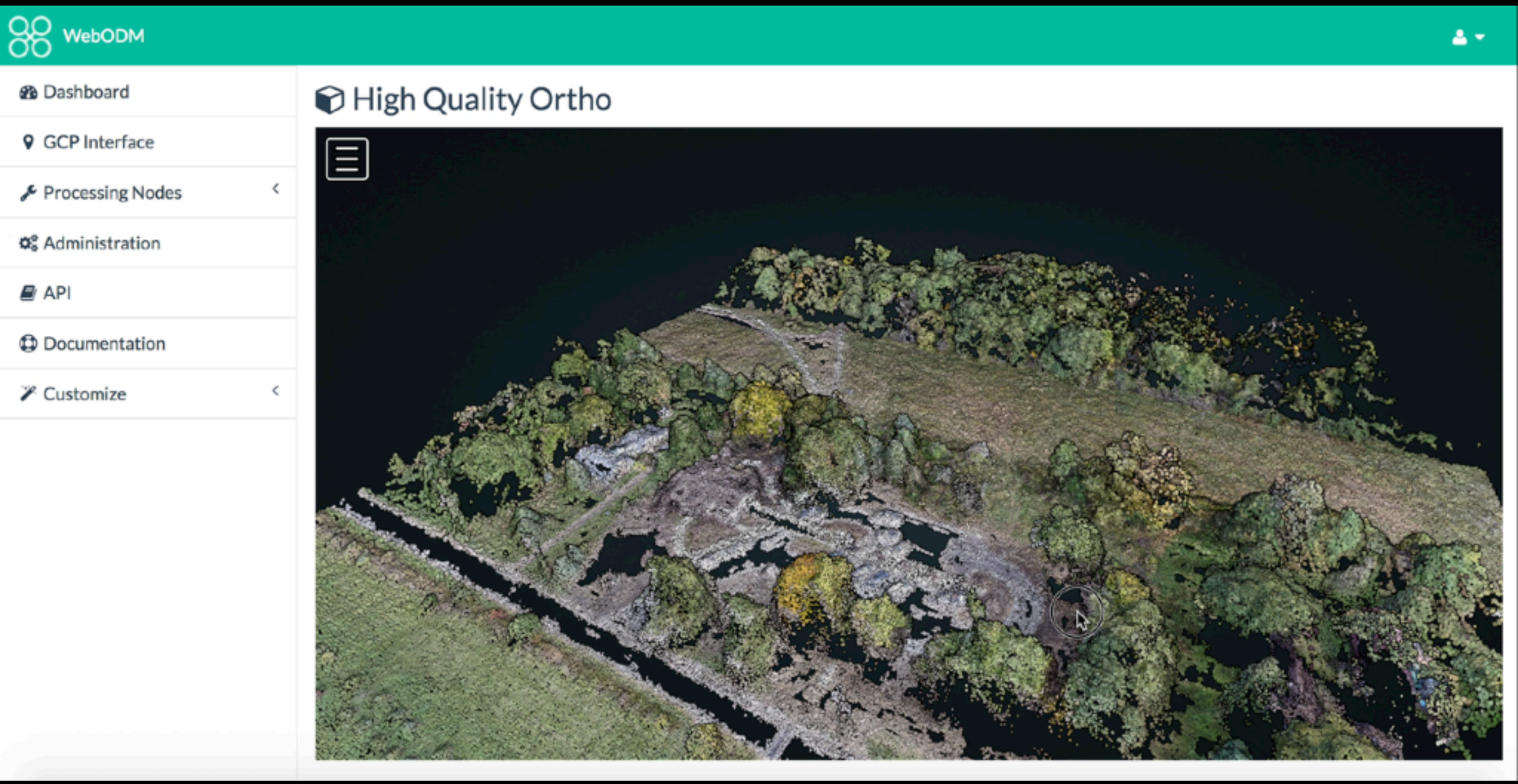
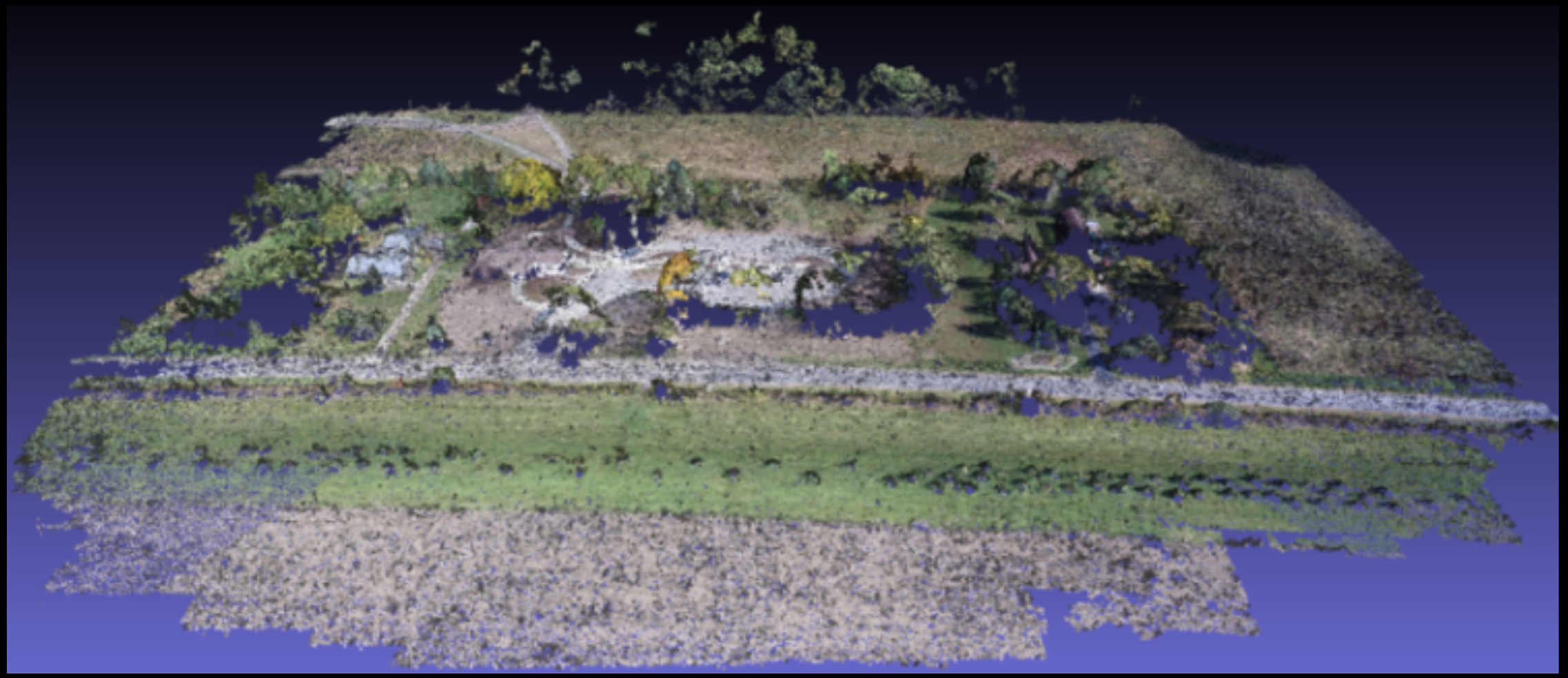


Dense Point Cloud from finding all matches



Point Cloud from Matching