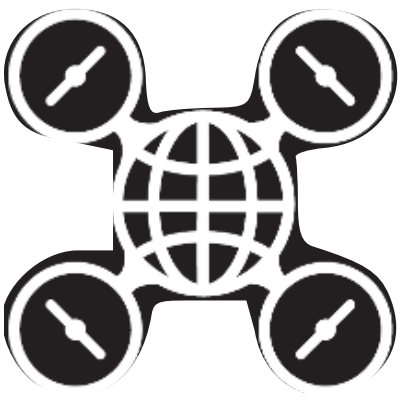
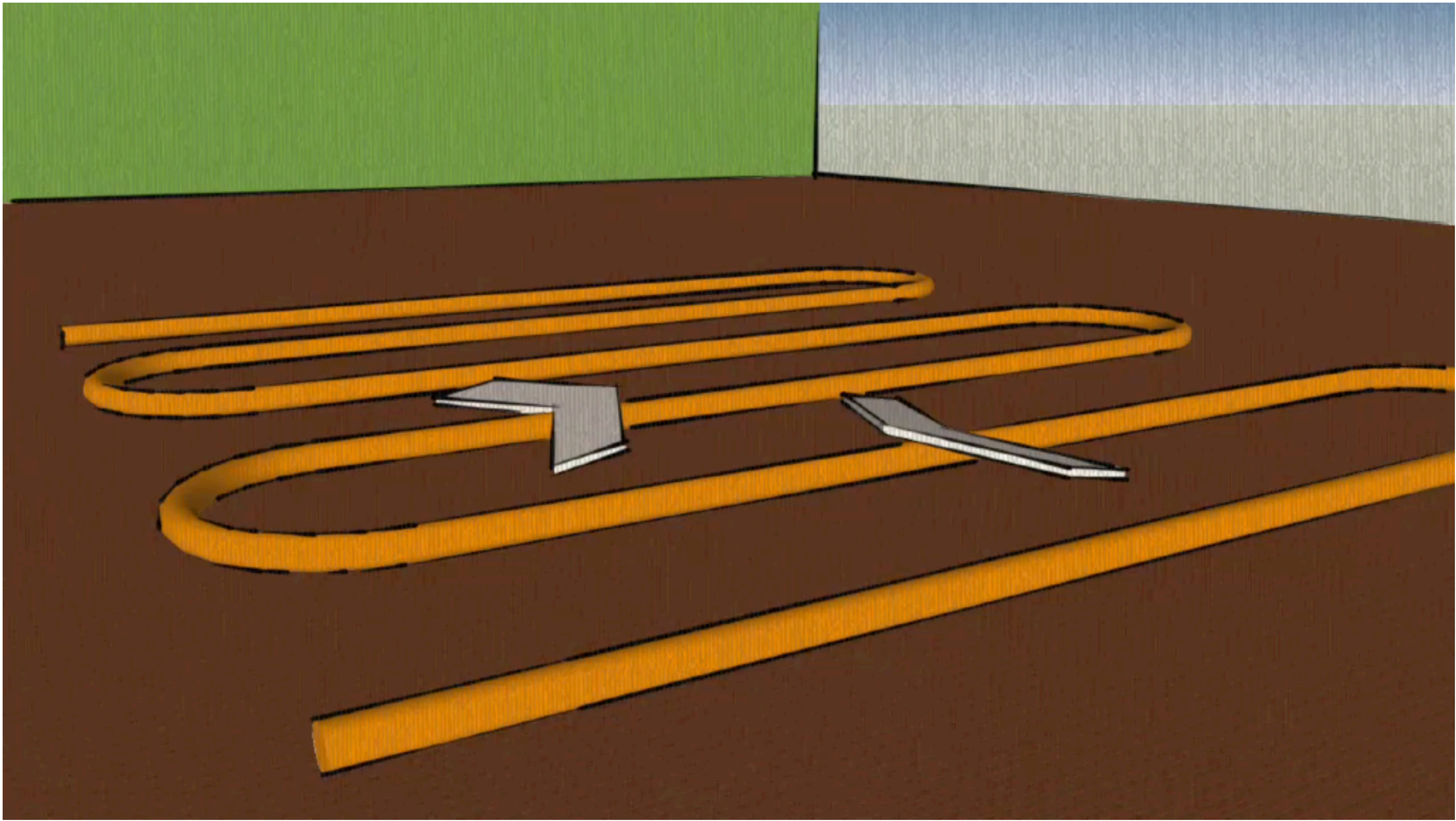
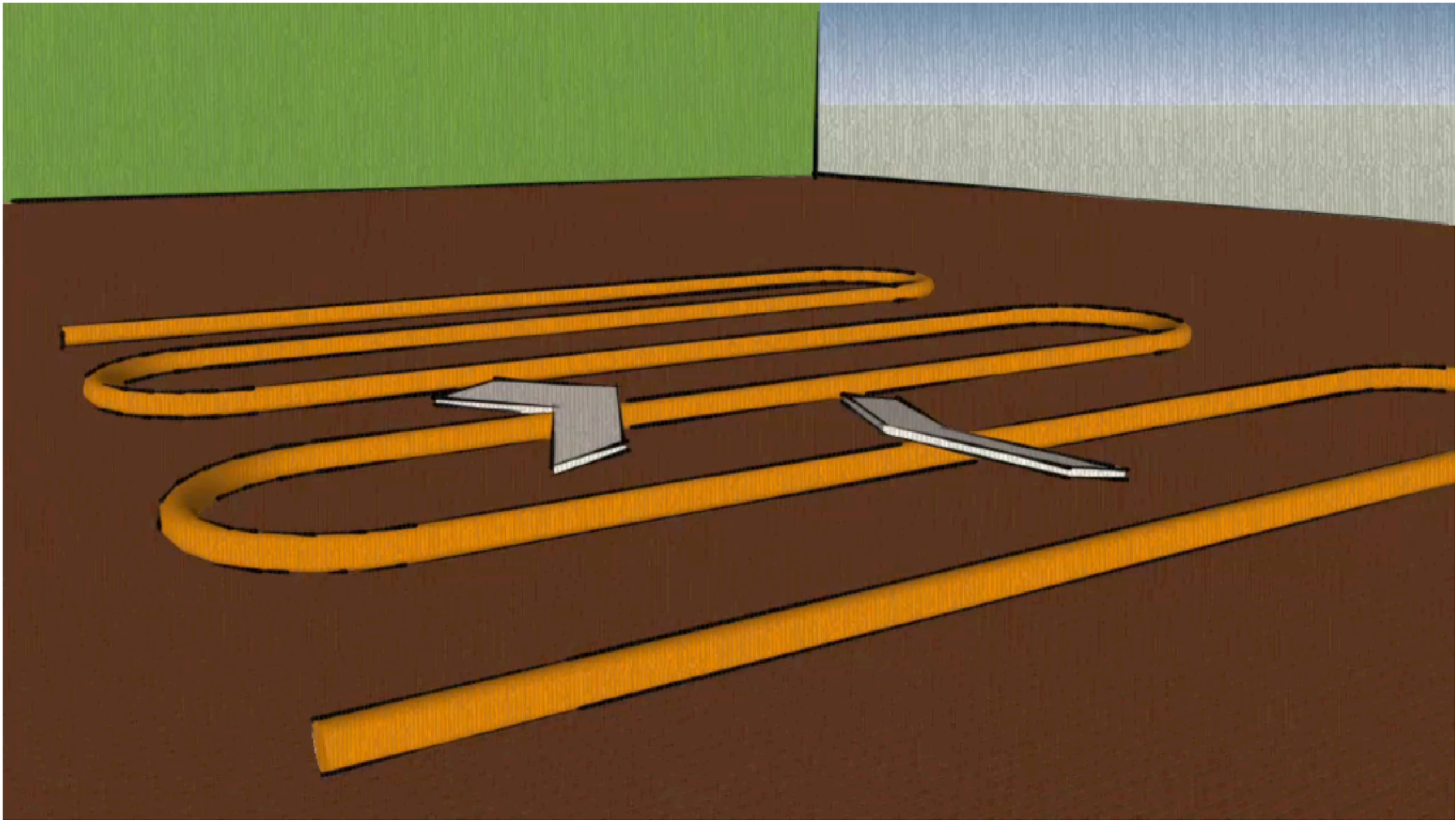
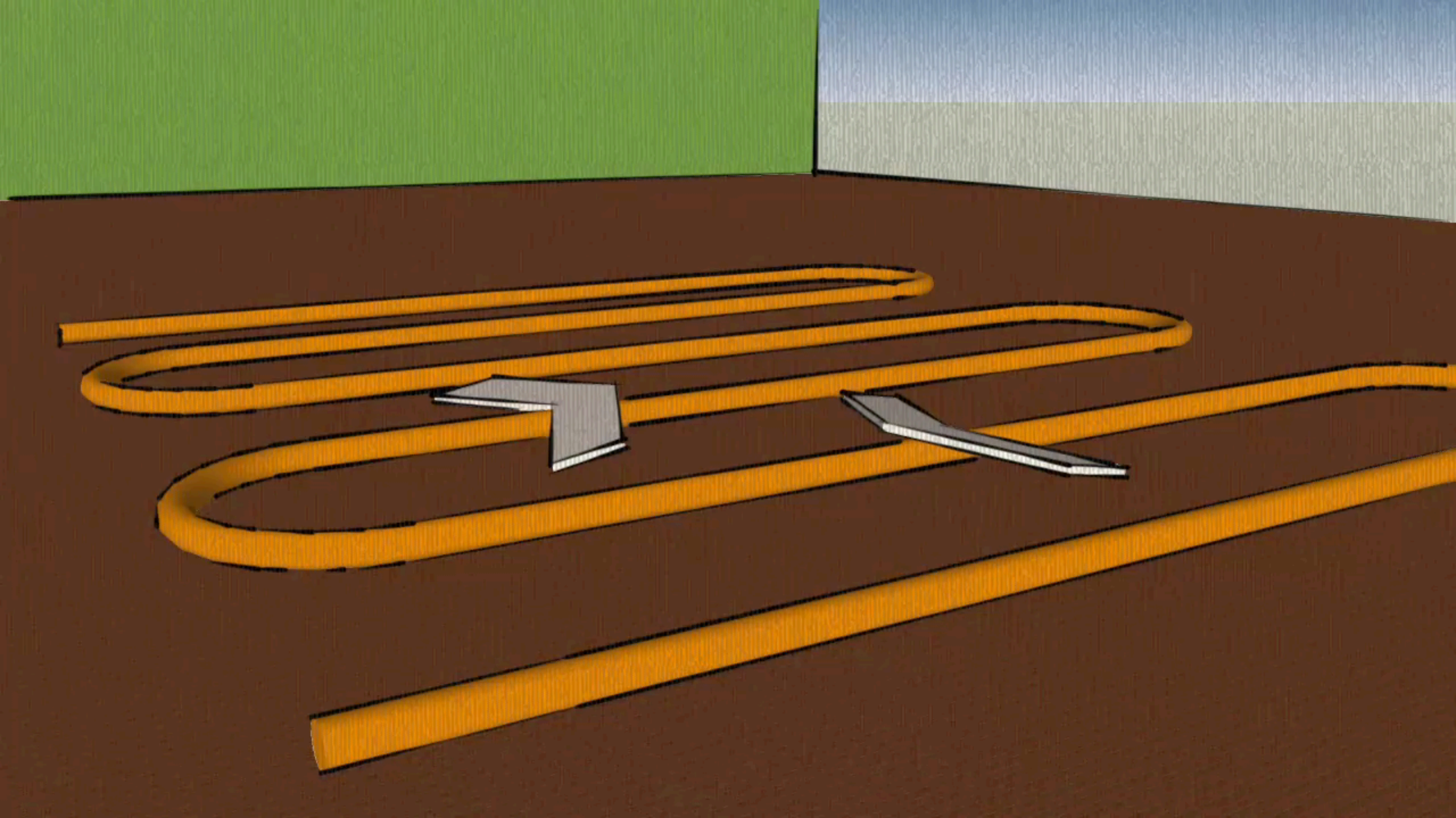


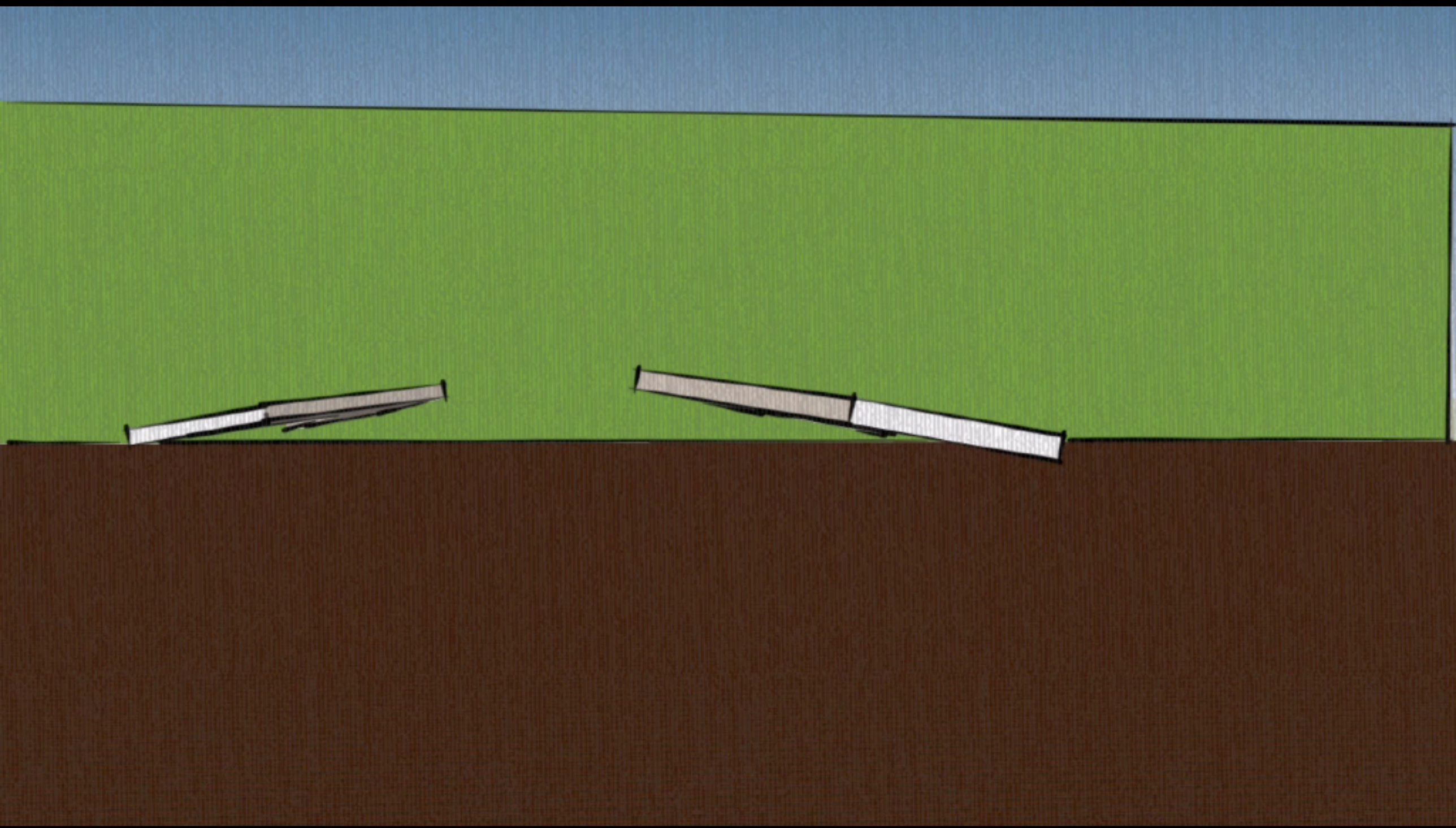
OpenDroneMap







fly in a cross pattern



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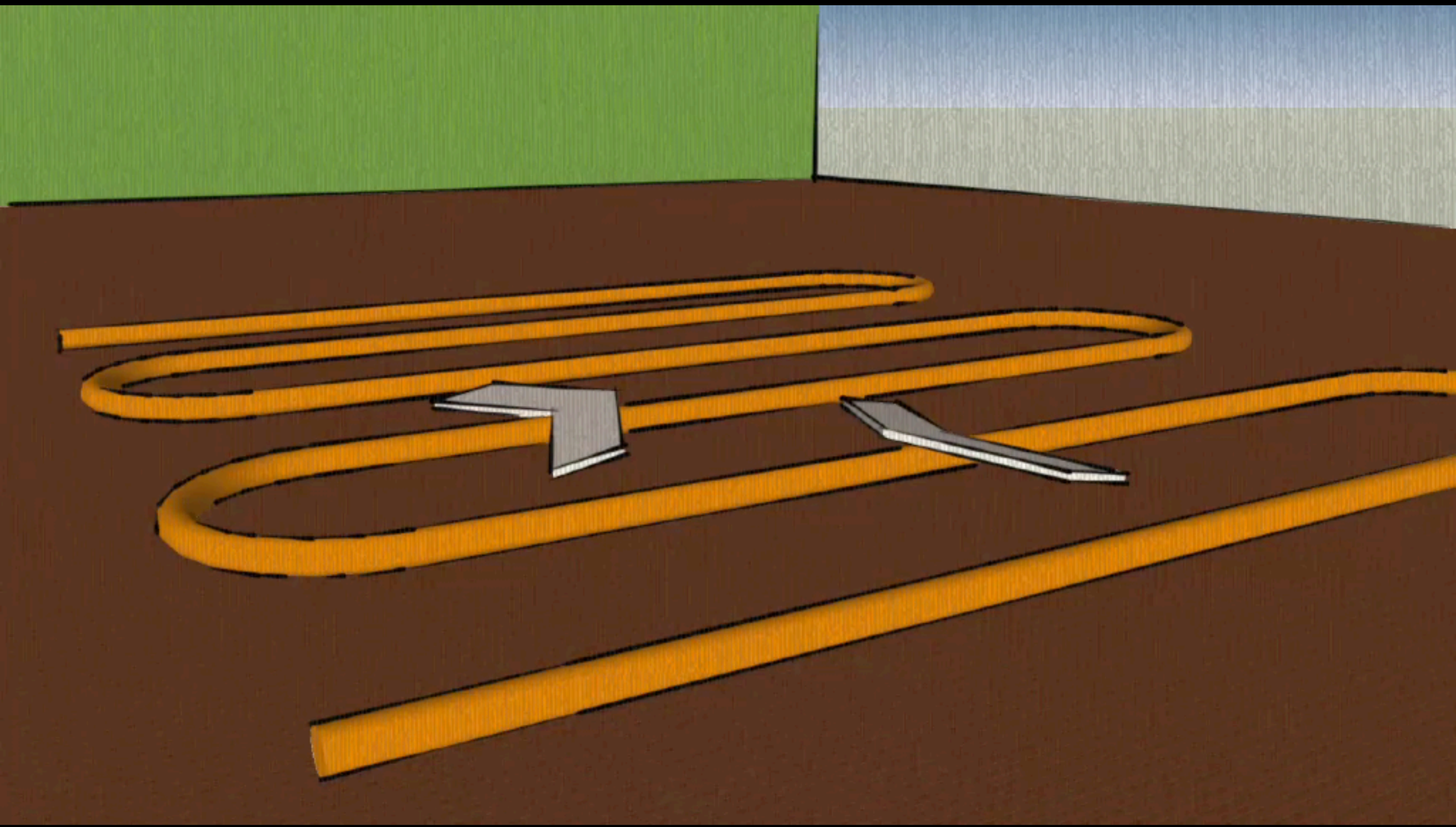
with 10° up-tilt