## Excercise 13

$$U_i = U_0 + i\Delta U$$

$$V_i = V_0 + i\Delta V$$

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$$\frac{U_0^{n+1} - U_0^n}{\Delta t} = A_V \left( \frac{U_{0-1}^n - 2u_0^n + U_{0+1}^n}{(\Delta z)^2} \right) +$$

$$U_0^{\Lambda t_1} = U_1^{\Lambda} + \Delta t \left[ A_V \left( \frac{u_{0,1}^2 - 2u_0 + u_{0,1}^2}{(\Delta z)^2} \right) + f v_E \right]$$

$$\frac{C}{(Dz)^2} \left( \frac{u_0^n - 2u_0^n + U_{on}^n}{(0z)^2} \right)$$

$$C = \frac{A_V \Delta t}{(\Delta 2)^2}$$

$$\Delta t = 200s$$

$$\therefore C = \frac{\left(10^{-4} \frac{n^2}{8}\right) \left(2008\right)}{2008}$$

$$-: C = 5 \times 10^{-3}$$

efficiency). .. at these values, system is stability (not

...

F. 1. 1.

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