

# Linghao Chen

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## Education

- 2015–2019 **Bachelor in Computer Science and English (dual-degree)**, Zhejiang University.  
GPA: 89.0/100
- 2019–Now **Ph.D. in Computer Science**, Zhejiang University, Advised by Prof. Xiaowei Zhou.  
GPA: 89.9/100

## Award Experiences

- 2017 First-class Scholarship of ZJU
- 2019 Postgraduate Scholarship of ZJU
- 2021 The Most Academic Value Award of Zhejiang University Doctoral Conference Forum
- 2020 Excellent and Miyoshi Postgraduate
- 2019 Excellent graduation thesis
- 2018 Full marks in PAT Level-A
- 2016,2018 Second-class Scholarship of Zhejiang University
- 2016 The Third Prize of the National College Student Mathematics Competition
- 2016 Mathematics Modeling S Prize

## Selected Publications

- CVPR 2020, TPAMI 2021 **Disp R-CNN: Stereo 3D Object Detection via Shape Prior Guided Instance Disparity Estimation.**  
Proposed a 3D object detection pipeline that estimates instance-level disparity maps on individual objects. This design guides the network to learn the category-level object shape prior for better disparity estimation and 3D object detection. Even when LiDAR ground-truth is not available at training time, Disp R-CNN outperforms previous state-of-the-art methods by 20% in terms of average precision.
- CVPR 2021 **NeuralRecon: Real-time Coherent 3D Reconstruction with Monocular Video.**  
(Oral) Proposed the first learning-based pipeline that reconstructs 3D scene geometry from a monocular video in real-time. Unlike previous methods that estimate single-view depth maps and perform TSDF fusion later, NeuralRecon jointly reconstructs and fuses local surfaces directly in the sparse volumetric TSDF representation. This design allows the network to capture local smoothness prior and global shape prior of 3D surfaces, resulting in accurate and coherent surface reconstruction. NeuralRecon generalizes well to new data domains and is able to reconstruct large-scale 3D scenes on a laptop GPU in 33 keyframes per second.

ICCV 2021 **You Don't Only Look Once: Constructing Spatial-Temporal Memory for Integrated 3D Object Detection and Tracking.**

Proposed a novel system named UDOLLO that simultaneously detects and tracks 3D objects, which uses a dynamic object occupancy map and previous object states as spatial-temporal memory to assist object detection in future frames. This memory, together with the ego-motion from back-end odometry, guides the detector to achieve more efficient object proposal generation and more accurate object state estimation.

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## Engineering Projects

2018.12 **Real-time 3D object pose estimation for 3D-printed objects**, *SenseTime*.

Designed a training pipeline for real-time 3D object pose estimation for 3D-printed objects based on PVNet. Proposed to first perform object detection before applying PVNet, which reached real-time running speed using an GTX 1060 GPU.

2019.2 – 2019.8 **Monocular vehicle orientation estimation and key-point detection**, *SenseTime*.

Working on improving the accuracy of vehicle orientation estimation. Implementing MultiBin algorithm which improved the accuracy to 95.81%. Designed a cross-training scheme for training a unified model for orientation estimation and key-point detection using different training sets.

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## Work Experiences

2018.9–2019.6 **Monitor of Class 1507**, *ZJU*.

2018.12–Now **Technical Secretary**, *GAMES (Graphics And Mixed Environment Seminar)*.

Managing live-streaming of GAMES Webinar and GAMES Courses. Maintainer of official website and Bilibili account of GAMES.

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## Skills

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|-------------|---|
| Programming | Python, C/C++, JavaScript/HTML/CSS, $\text{\LaTeX}$ |
| Library     | PyTorch, TensorFlow                                 |
| English     | TEM-4 (Good), TOFEL (103), CET-6 (606)              |
| Designing   | Blender, Unity                                      |

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## Service

- Conference reviewer: PRCV, CVM, IEEE RA-L

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## Publication List

\* denotes equal contribution.

### Journal Papers

- [1] **Linghao Chen\***, Jiaming Sun\*, Yiming Xie, Siyu Zhang, Qing Shuai, Qinhong Jiang, Guofeng Zhang, Hujun Bao, and Xiaowei Zhou. Shape Prior Guided Instance Disparity Estimation for 3D Object Detection. *IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)*, 2021.

### Conference Papers (Peer-reviewed)

- [2] Jiaming Sun\*, **Linghao Chen\***, Yiming Xie, Siyu Zhang, Qinhong Jiang, Xiaowei Zhou, and Hujun Bao. Disp R-CNN: Stereo 3D Object Detection via Shape Prior Guided

Instance Disparity Estimation. *IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, 2020.

- [3] Jiaming Sun\*, Yiming Xie\*, **Linghao Chen**, Xiaowei Zhou, and Hujun Bao. NeuralRecon: Real-Time Coherent 3D Reconstruction from Monocular Video. *IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, 2021. **Oral presentation** and **Best paper candidate**.
- [4] Jiaming Sun\*, Yiming Xie\*, Siyu Zhang, **Linghao Chen**, Guofeng Zhang, Hujun Bao, and Xiaowei Zhou. You Don't Only Look Once: Constructing-Spatial-Temporal-Memory-for Integrated 3D Object Detection. *International Conference on Computer Vision (ICCV)*, 2021.