# Data Structure: Sorting

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#### sorting

sorting is putting the elements into a list in which the elements are in increasing order

# insertion sort

34, 8, 64, 51, 32, 21

0	1	2	3	4	5		
34	8	64	51	32	21		
8	34	64	51	32	21	after p=1	
8	34	64	51	32	21	after p=2	
8	34	51	64	32	21	after p=3	
8	32	34	51	64	21	after p=4	
8	21	32	34	51	64	after p=5	

#### insertion sort

- For each pass P = 1 through n 1, insertion sort ensures that elements in position 0 through P are in sorted order
- In pass *P*, move the element in position *P* left until its correct place is found among the first *P* elements
- $O(n^2)$  comparisons required on average
- any algorithm that sorts by exchanging adjacent elements requires O(n²) time on average
  - average number of swapping in an array of n distinct numbers is n(n-1)/4 since total number of pairs to be compared is n(n-1)/2

34, 8, 64, 51, 32, 21

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34	8	64	51	32	21	
8	34	64	51	32	21	after p=1
8	34	64	51	32	21	after p=2
8	34	51	64	32	21	after p=3
8	32	34	51	64	21	after p=4
8	21	32	34	51	64	after p=5

#### insertion sort

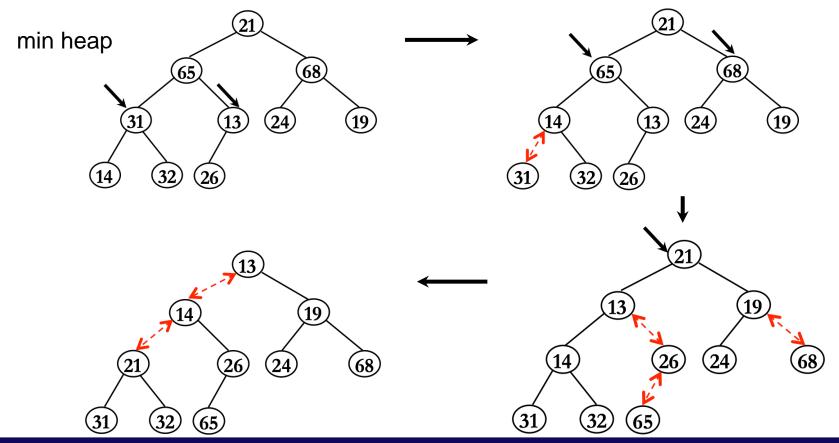
```
void insertionSort (ElementType A[ ], int N)
          int j, P;
          for (P = 1; P < N; P++)
                    Tmp = A [P];
                    for (j = P; j > 0 && A[j-1] > Tmp; j --)
                         A[i] = A[i-1];
                    A[j] = Tmp;
                                  3
                                             4
                                                       5
            8
                       64
                                             32
                                                        21
                                  51
            34
                                             32
                       64
                                  51
                                                        21
                                                                   after p=1
            34
                                             32
                       64
                                  51
                                                        21
                                                                   after p=2
            34
                       51
                                  64
                                             32
                                                       21
                                                                   after p=3
                       34
                                                       21
                                                                   after p=4
                                  51
                                             64
                       32
                                            51
                                  34
                                                       64
                                                                   after p=5
```

# heap sort

- building binary heap of n elements: O(n)
- DeleteMin operation n times: O(n log n)
- use the last cell in the previous heap to save the noted list (in-place algorithm)

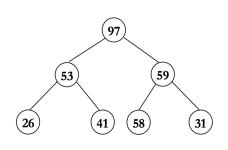
### BuildHeap

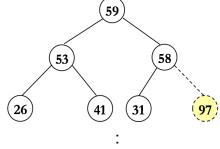
- Build a Heap containing n keys takes  $O(n \log n)$  with consecutive insertions
- But it can take O(n) if they are already in array.
- Starting with the lowest non-leaf node, working back towards root, perform percolatingdown on each node of the tree.

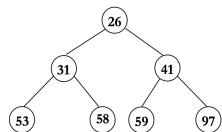


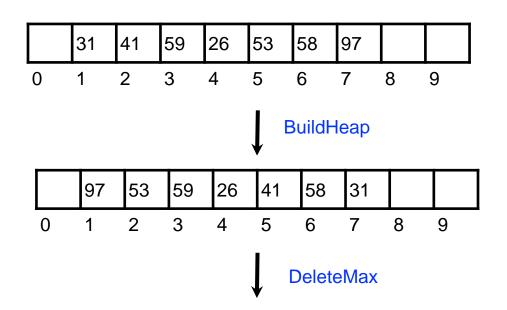
# heap sort

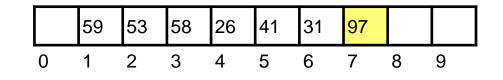
Increasing order using Max heap







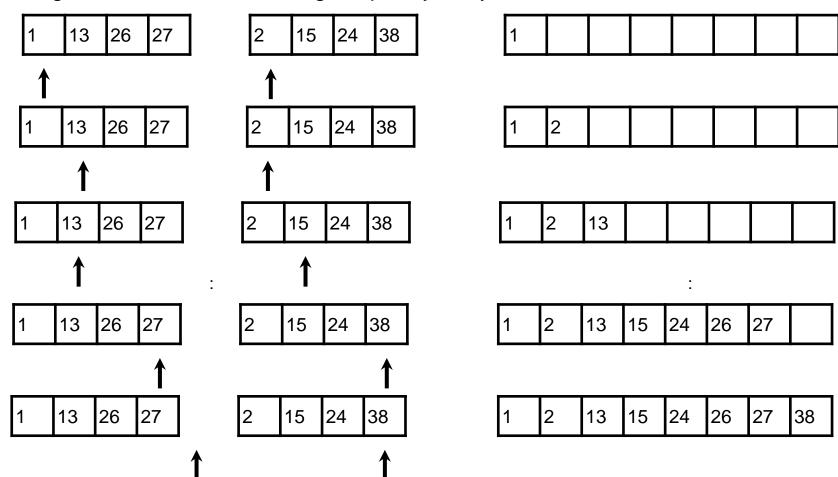




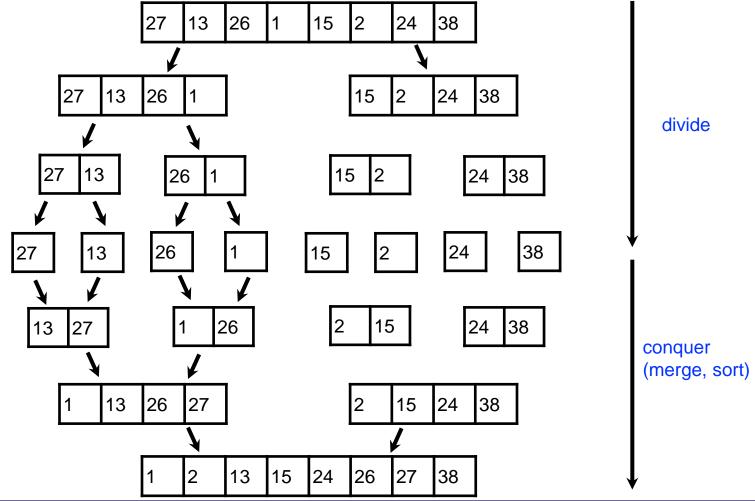
:

	26	31	41	53	58	59	97		
0	1	2	3	4	5	6	7	8	9

merge two sorted sublists using temporary array

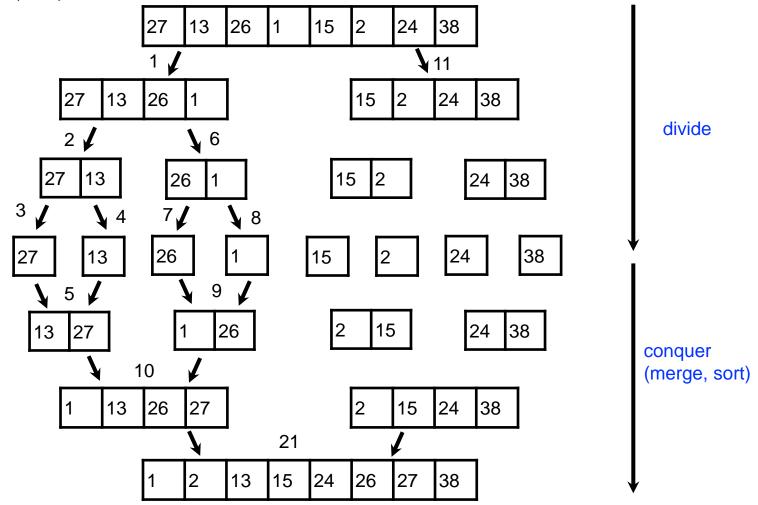


- divide a list into two sublists
- conquer (sort) the sorted sublist into the list



```
void MSort (ElementType A[], ElementType TmpArray[], int Left, int Right)
{
    int Center;
    if (Left < Right){
        Center = (Left + Right) / 2;
        MSort (A, TmpArray, Left, Center);
        MSort (A, TmpArray, Center+1, Right);
        Merge (A, TmpArray, Left, Center+1, Right);
}</pre>
```

- divide a list into two sublists
- conquer (sort) the sorted sublist into the list



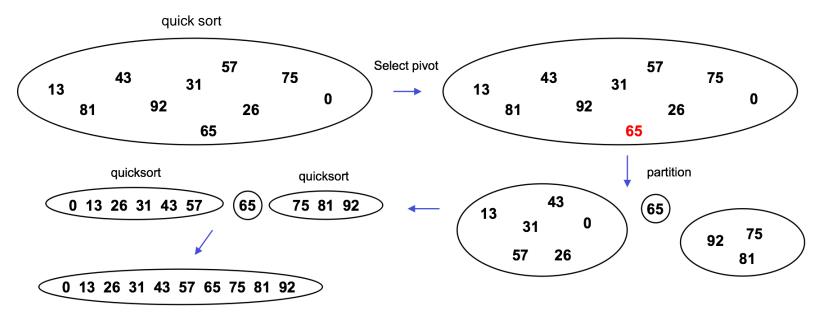
```
void Merge (ElementType A[], ElementType TmpArray[], int Lpos, int Rpos, int RightEnd)
          int i, LeftEnd, NumElements, TmpPos;
          LeftEnd = Rpos - 1;
          TmpPos = Lpos;
          NumElements = RightEnd - Lpos + 1;
          while (Lpos <= LeftEnd && Rpos <= RightEnd)
                    if (A[Lpos] \le A[Rpos])
                              TmpArray[TmpPos++] = A[Lpos++];
                    else
                              TmpArray[TmpPos++] = A[Rpos++];
          while (Lpos <= LeftEnd)
                    TmpArray[TmpPos++] = A[Lpos++]:
          while (Rpos <= RightEnd)
                    TmpArray[TmpPos++] = A[Rpos++]:
          for(i=0; i<NumElements; i++, RightEnd--)
                    A[RightEnd] = TmpArray[RightEnd];
```

# merge sort: analysis of time complexity

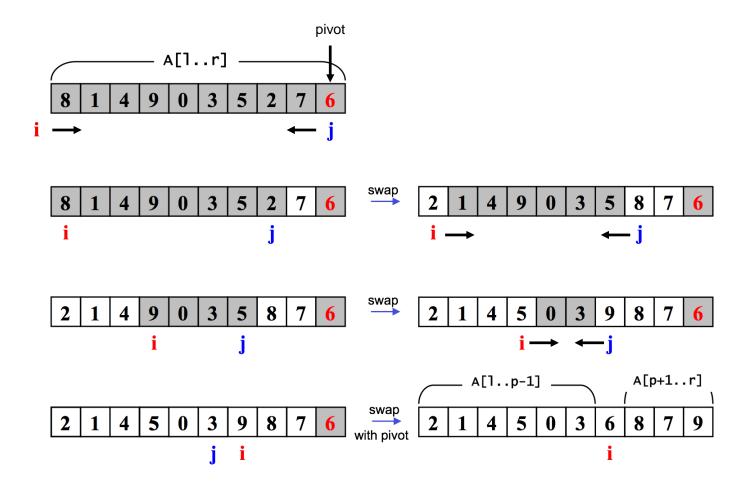
$$T(1) = 1$$
  
 $T(N) = 2T(N/2) + N$   
 $T(N)/N = T(N/2) / (N/2) + 1$   
 $T(N/2) / (N/2) = T(N/4) / (N/4) + 1$   
 $T(N/4) / (N/4) = T(N/8) / (N/8) + 1$   
:  
 $T(2) / (2) = T(1) / (1) + 1$   
 $T(N)/N = T(1)/1 + log N$   
 $T(N) = N log N + N = O(N log N)$ 

# quick sort

- divide: partition the array A[I..r] into two subarrays A[I..p-1] and A[p+1..r]
  - all elements in A[l..p-1] are less than or equal to a pivot element A[p]
  - all elements in A[p+1..r] are greater than pivot element A[p].
- conquer: sort the two subarrays A[I..p-1] and A[p+1..r] by recursive calls to quicksort.
  - -> since the subarrays are sorted in place, no work is needed.



# quick sort



### quick sort

```
void Quicksort(A, I, r)
       if (l >= r)
                   return;
       p = Partition(A, I, r);
       Quicksort(A, I, p-1);
       Quicksort(A, p+1, r);
}
int Partition(A, I, r)
       pivot = select_pivot(A, I, r);
       i = 1 - 1;
       j = r;
       for(;;) {
           while (A[--i] > pivot);
           while (A[++i] \le pivot);
           if (i < j) swap(&A[i], &A[j]);
           else {
                 swap(&A[i], &A[r]);
                 return i;
```

# quick sort: picking the pivot

- use the first element or the last element
  - worst if the input is presorted or in reverse order
- choose the pivot randomly
  - safe, but does not reduce the average running time
  - median-of-three choose the median of the leftmost, rightmost, and center elements

# quick sort: picking the pivot

$$T(0) = T(1) = 0$$
  
 $T(n) = T(i) + T(n-i-1) + n$ 

- performance depends on the selection of pivot
  - worst-case partitioning: divide n 1 and pivot

$$T(n) = T(n-1) + n$$

$$= T(n-2) + n - 1 + n$$

$$= :$$

$$= T(1) + 2 + 3 + ... + n$$

$$= O(n^2)$$

best-case partitioning: divide n/2 and n/2 elements

$$T(n) = 2T(n/2) + n$$
  
=  $4T(n/4) + 2n$   
=  $8T(n/8) + 3n$   $\leftarrow 2(2T(n/4) + n/2) + n$   
= :  
=  $nT(1) + logn * n$   
=  $O(n log n)$ 

# quick sort: picking the pivot

$$T(n) = T(i) + T(n-i-1) + n$$

#### average-case partitioning

assume that the size of a partition is equally likely (that is, probability is 1/n) the average value of T(i) or T(n-i-1) is  $\frac{1}{n}\sum_{j=0}^{n-1}T(j)$ 

$$T(n) = \frac{2}{n} \left[ \sum_{j=0}^{n-1} T(j) \right] + n$$

$$nT(n) = 2 \left[ \sum_{j=0}^{n-1} T(j) \right] + n^{2}$$

$$(n-1)T(n-1) = 2 \left[ \sum_{j=0}^{n-2} T(j) \right] + (n-1)^{2}$$

$$nT(n) - (n-1)T(n-1) = 2T(n-1) + 2n - 1$$

$$nT(n) = (n+1)T(n-1) + 2n$$

$$\frac{T(n)}{n+1} = \frac{T(n-1)}{n} + \frac{2}{n+1}$$

$$\frac{T(n)}{n+1} = \frac{T(1)}{2} + 2 \sum_{i=3}^{n+1} \frac{1}{i}$$

$$\frac{T(n)}{n+1} = O(\log n), \quad T(n) = O(n \log n)$$