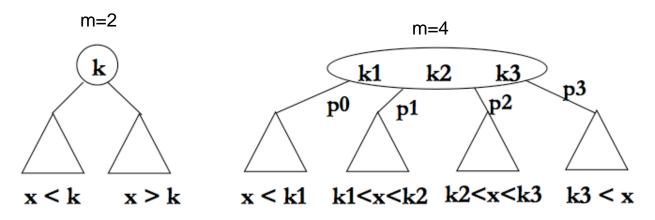
# Data Structure: B-Tree

Yongjun Park
Hanyang University

## m-way search tree

- Binary trees are not quite appropriate for data stored on disks
  - we assumed all data is kept in main memory
  - what if the data is kept in external disk?
    - disk access is much slower than memory access
    - disk is partitioned into blocks (pages) and the access time of a word is the same as that of the entire block containing the word
    - we need to reduce the number of disk access.
      - → make each node of the tree wider (m-way search tree)



## m-way search tree

- In a tree of degree m and height h
  - the maximum number of nodes is (m<sup>h+1</sup> 1) / (m-1)

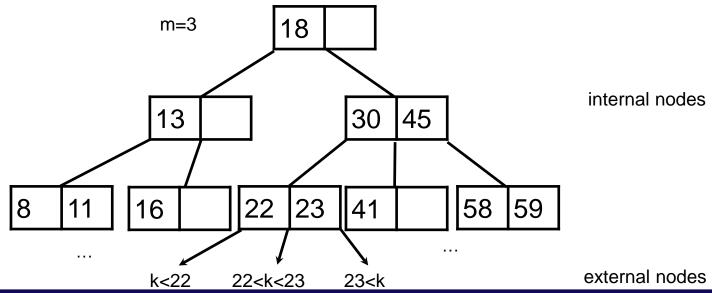
$$(m^0 + m^1 + m^2 + ... m^h)$$

the maximum number of elements in an m-way tree of height h is m<sup>h+1</sup> -1
 ( since each node has at most m-1 elements)

- a binary tree with h=2 has maximum 7 elements in the tree
- a 200-way tree with h=2 has  $200^3 1 = 8 * 10^6 1$  nodes

#### B-Tree

- a B-tree of order m is an m-way search tree with the following properties
  - the root has at least 2 children
  - each node has upto m-1 keys
  - all external nodes are at the same level (perfectly balanced)
  - all internal nodes (except the root) have between m/2 and m children
    - when m=3, all internal nodes of B-tree have a degree of either 2 or 3 (2-3 tree)
    - when m=4, all internal nodes of B-tree have a degree of 2, 3, or 4 (2-3-4 tree)



#### B-Tree

- a B-tree of height h
  - best case: the tree is splitting widely

$$n = m^{h+1} -1$$

$$h = \lceil \log_m(n+1) \rceil$$

$$\log_m n = \frac{\log n}{\log m} = O(\log n)$$

worst case: the tree is splitting m/2 ways

$$\log_{\left\lceil \frac{m}{2} \right\rceil} n = \frac{\log n}{\log \left\lceil \frac{m}{2} \right\rceil} = O(\log n)$$

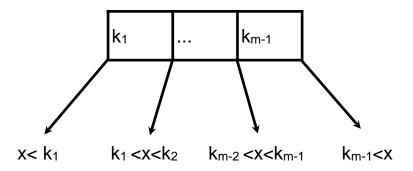
## B-Tree: node structure

```
#define order 3

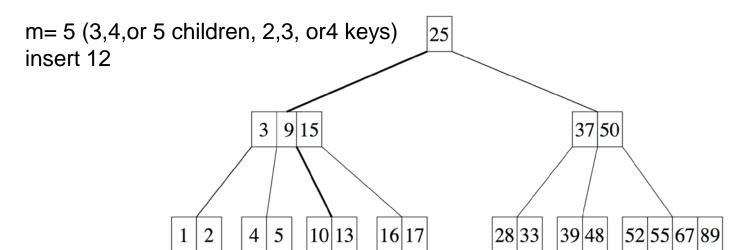
struct B_node {
    int order;    /* number of children */
    B_node *child[order];    /* children pointers */
    int key[order-1];    /* keys    */
}
```

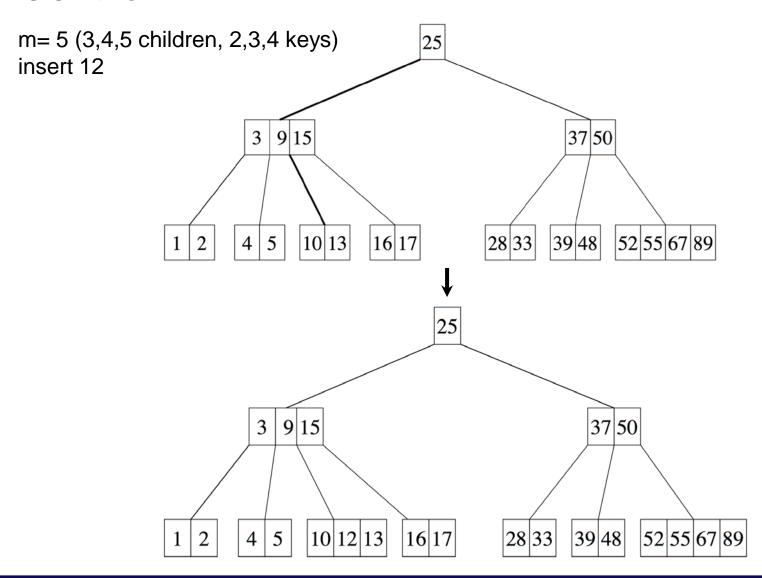
#### search

- When we arrive an internal node with key  $k_1 < k_2 , ... < k_{m-1}$ , search for x in this list (either linearly or by binary search)
  - if you found x, you are done
  - otherwise, find the index i such that  $k_i < x < k_{i+1}$ , and recursively search the subtree pointed by  $p_i$ .
- Complexity =  $\log m \cdot \log_m n = O(\log n)$



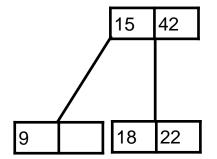
- find the appropriate leaf into which the node can be inserted
  - if the leaf is not full (< m-1 keys), insert it





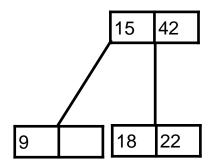
- find the appropriate leaf into which the node can be inserted
  - if the leaf is not full (< m-1 keys), insert it
  - if the node overflows, restore the balance
    - key rotation (if there is a space in the sibling node)
    - node split

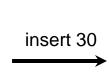
key rotation: check for siblings for rotation into the B-tree of m=3

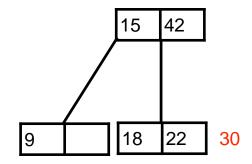




key rotation: check for siblings for rotation into the B-tree of m=3

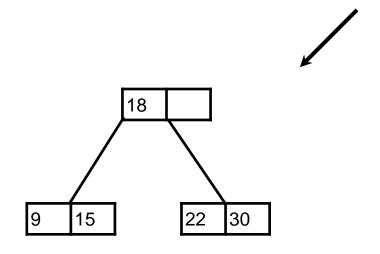


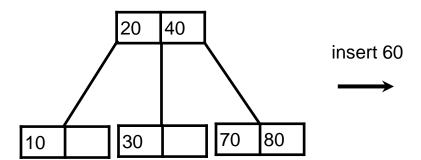


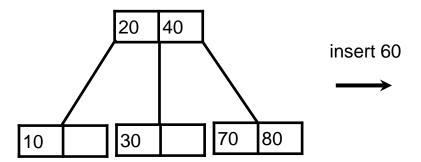


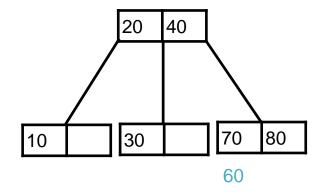
key rotation: check for siblings for rotation into the B-tree of m=3

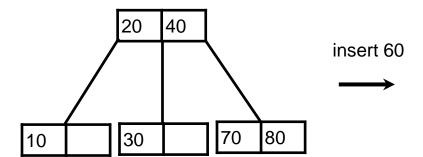


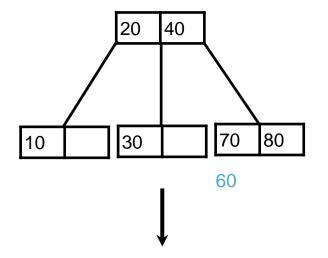


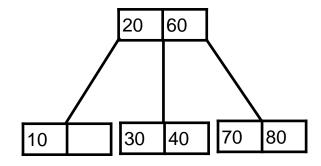










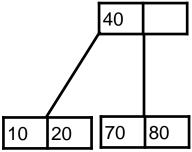


#### node split

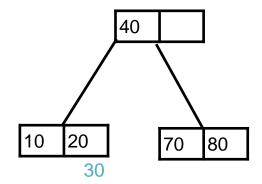
- if we have a node with m keys after insertion (overflow), split the node into three groups
  - (a) a node with the keys smaller than the middle key
  - (b) a node with the middle key
  - (c) a node with the keys greater than the middle key
- make (a) and (c) as new nodes and push (b) to the parent
- if the parent overflows, repeat the process
- if the root overflows, create a new node with 2 children

m= 3 (2,3 children, 1,2 keys)

insert 30

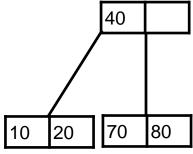




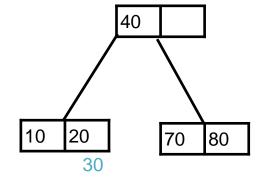


m= 3 (2,3 children, 1,2 keys)

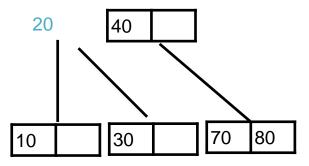
insert 30





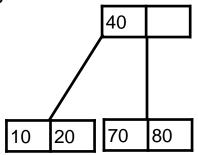


find the middle one and push it to the parent node

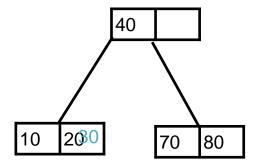


m= 3 (2,3 children, 1,2 keys)

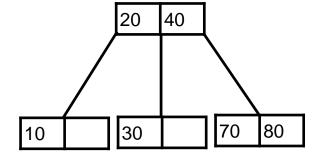
insert 30

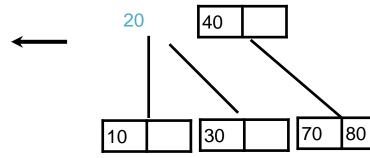


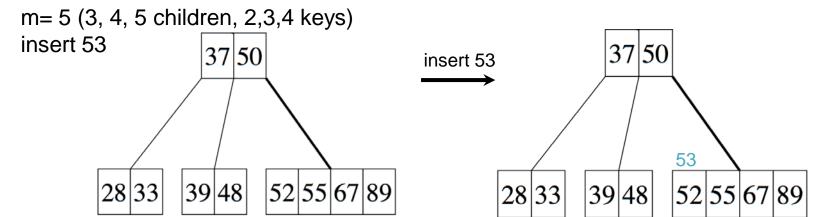


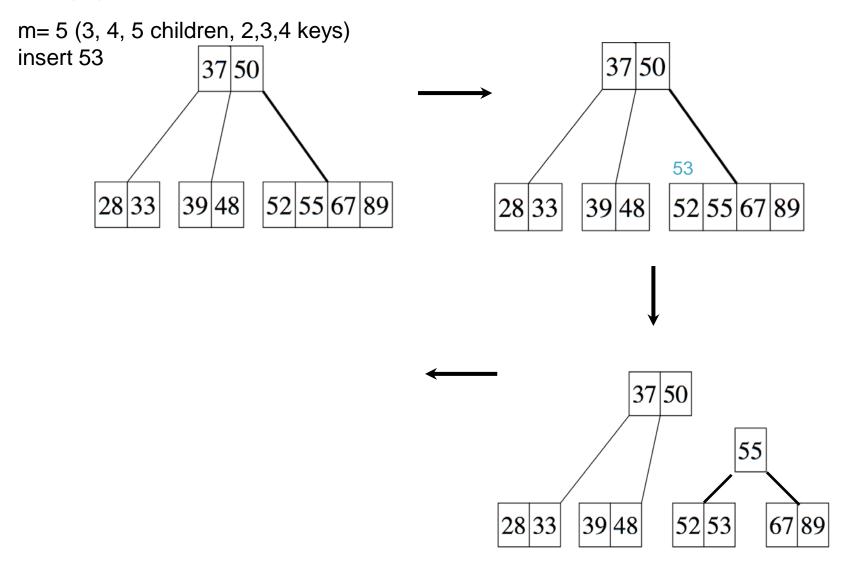


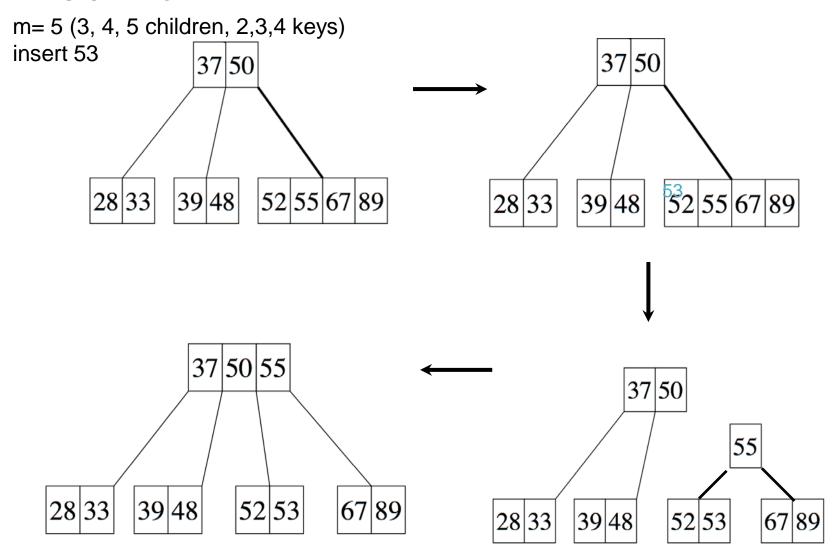
find the middle one and push it to the parent node

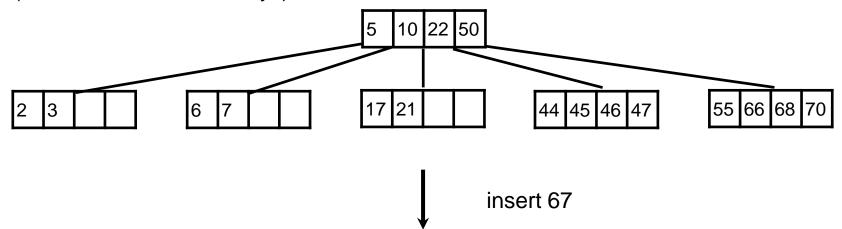


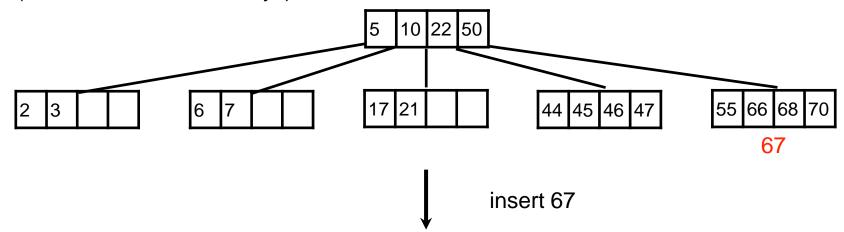


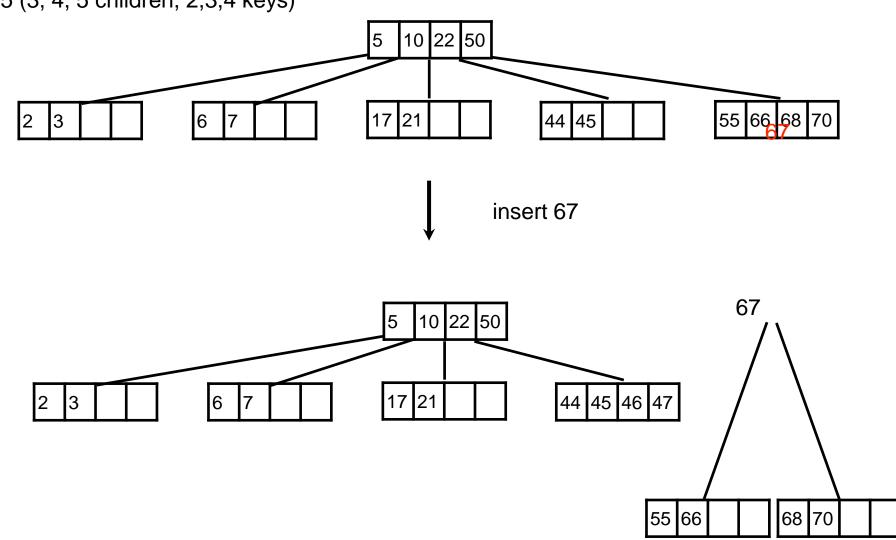


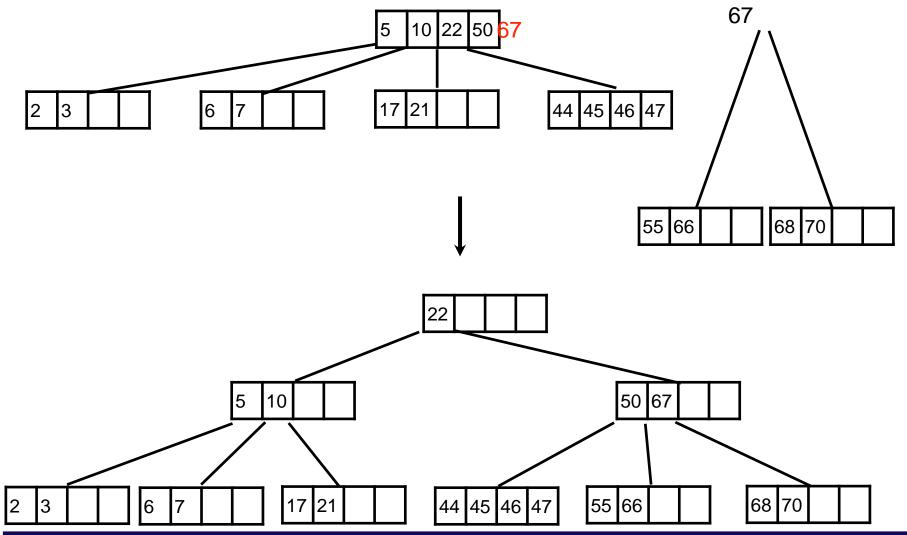








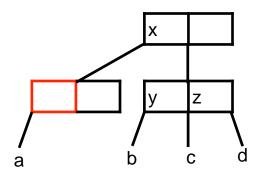


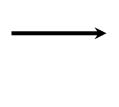


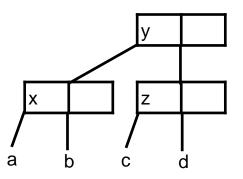
- find a suitable replacement which is the largest key in the left child (or the smallest in the right) and move it to fill the hole
  - key rotation
  - node merging

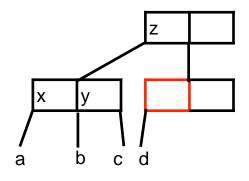
key rotation: check for siblings for rotation

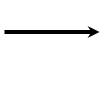
m= 3 (2,3 children, 1,2 keys)

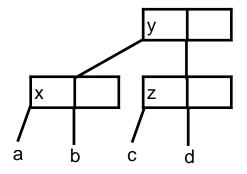


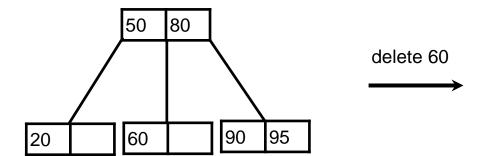


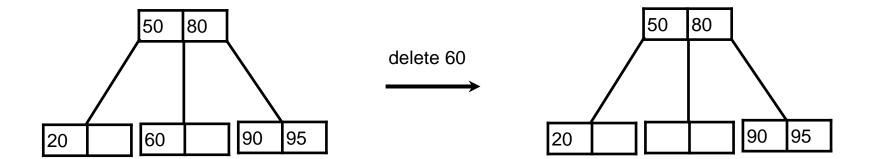


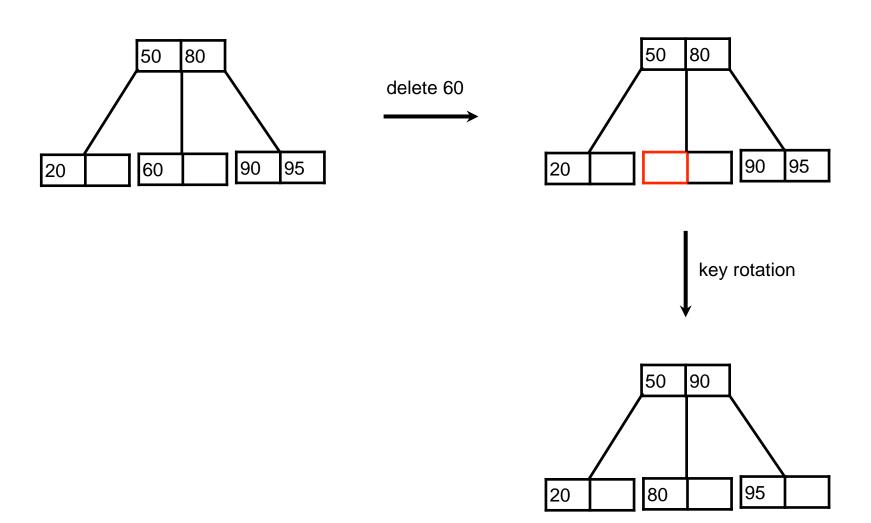






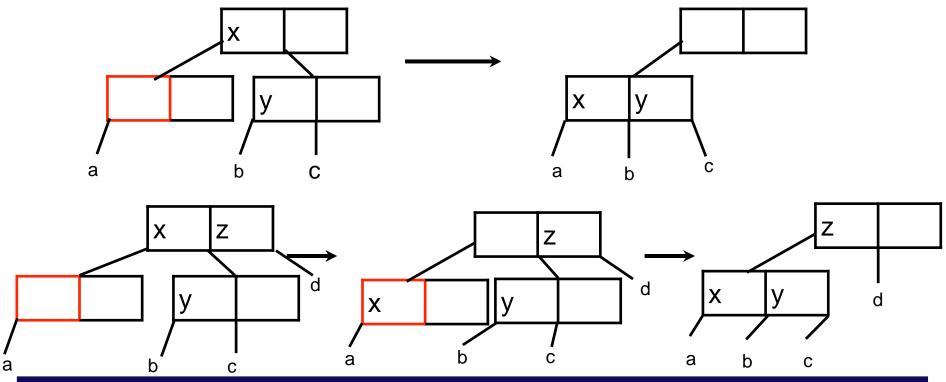


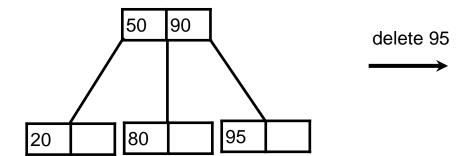


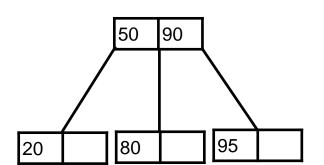


#### node merging

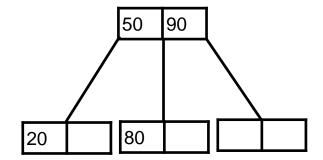
- no sibling that can be rotated
- move down the intermediate node from the parent and put it in the new node
- if this might cause underflow in the parent node, repeat the process



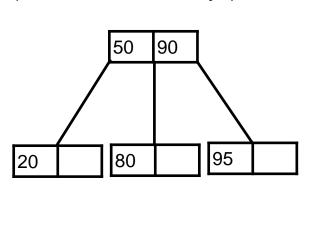




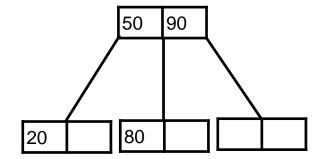


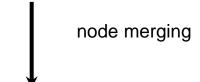


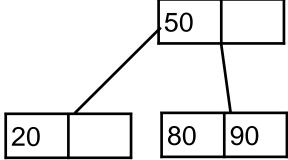
m= 3 (2,3 children, 1,2 keys)

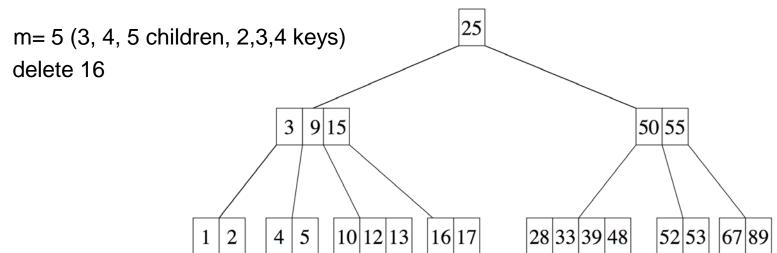


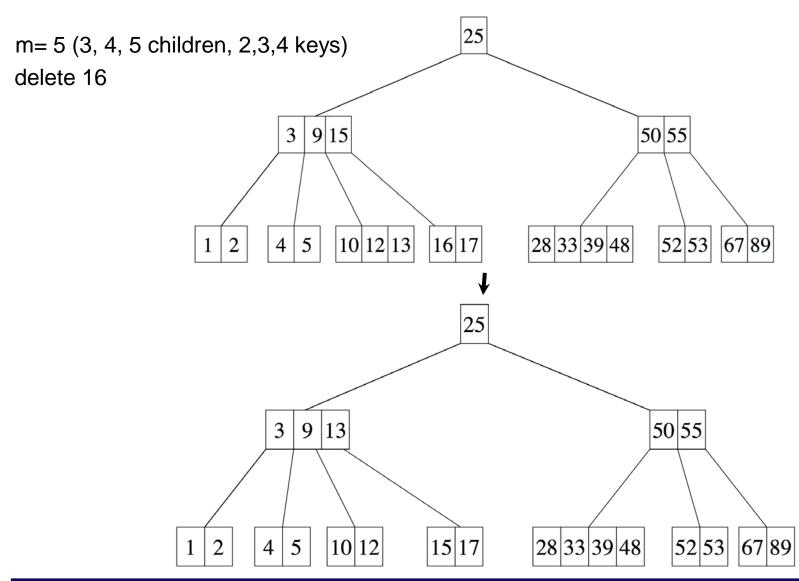


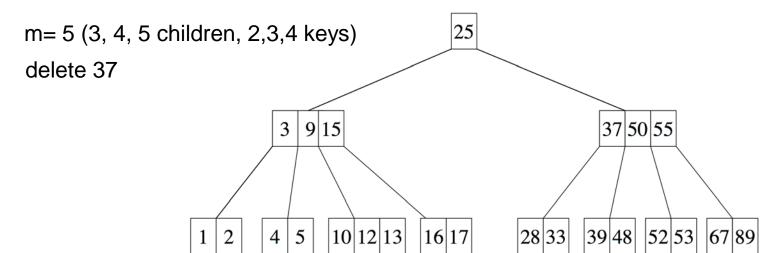


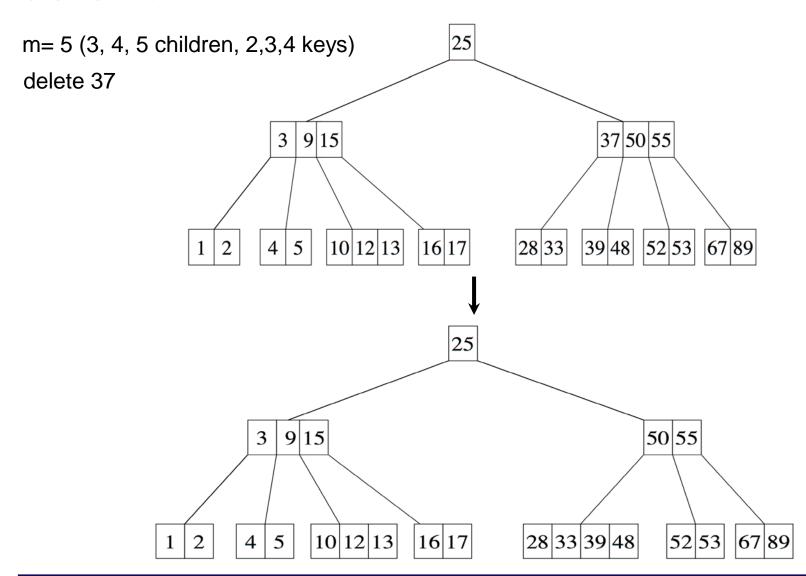












## Use of B-tree in database system

- $\blacksquare$  number of disk access is  $O(\log_m n)$
- each disk access requires  $O(\log m)$  overhead to determine the direction to branch, but this is done in main memory without a hard disk access, thus negligible.
- m can be determined as large as possible, but it must still be small enough so that an internal node can fit into one disk block.
- $\blacksquare$  *m* is typically between 32 and 256.
- often one or two levels of internal nodes reside in main memory.