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# Data Structure: Introduction

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# system life cycle

- programming is more than writing code
- development process → system life cycle
  - ▶ sequential, but highly interrelated

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# system life cycle

- **requirements**

- **define the purpose of the project**
- describe information including input and output

- **analysis**

- break the problems into manageable pieces
- bottom-up vs. top-down

- **design**

- view the system as both data objects and operations
  - for example, scheduling system for a university
    - **objects: students, courses, professors...**
    - **operations: inserting, removing, and searching each object...**
- 



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# system life cycle

## ■ coding

- ▶ choose representations for data objects and write algorithms for each operation

## ■ verification

- ▶ correctness proofs
  - ▶ can select algorithms that have been proven correct
- ▶ testing
  - ▶ with working code and sets of test data
  - ▶ include all possible scenarios (more than syntax error)
  - ▶ running time should be considered

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# algorithm

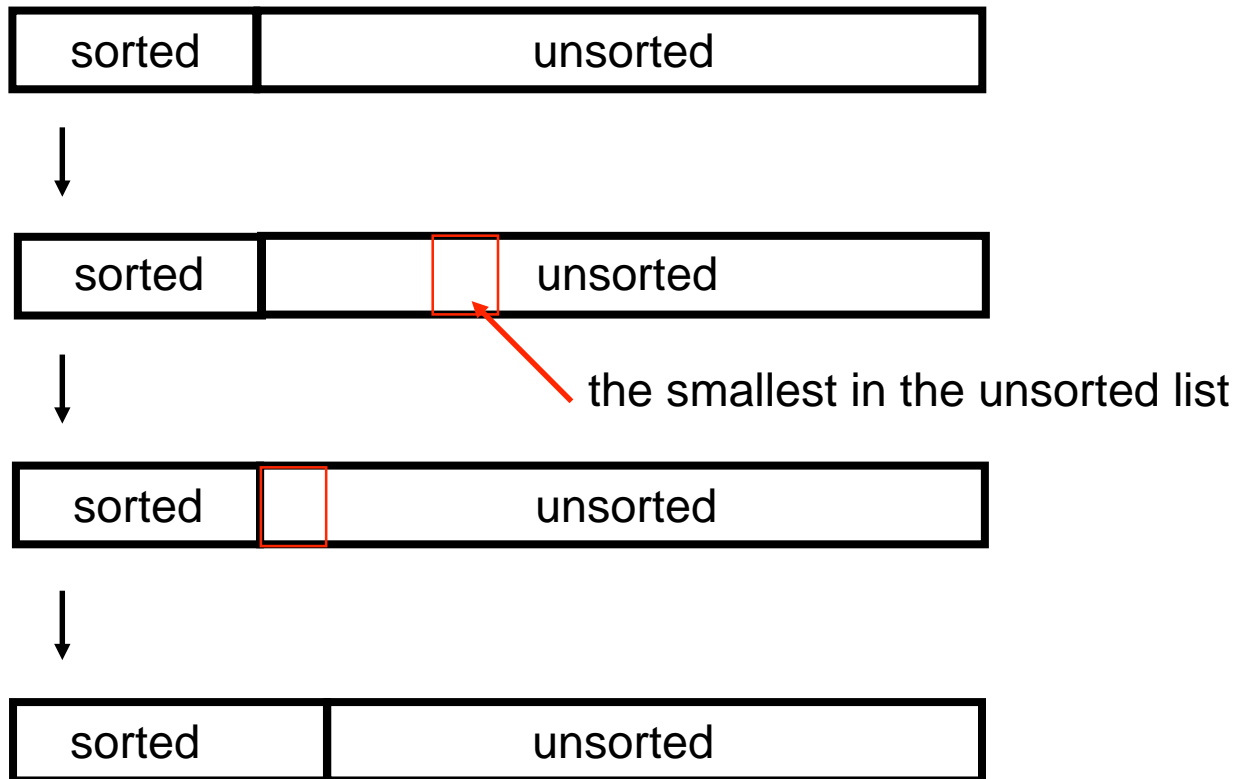
- an algorithm is a finite set of instructions that accomplishes a particular task
- algorithms satisfy the following criteria
  - ▶ zero or more inputs
  - ▶ at least one output
  - ▶ definiteness (clear, unambiguous)
  - ▶ finiteness (terminates after a finite number of steps)
  - ▶ effectiveness

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# algorithm: selection sort

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From the unsorted integers, find the smallest and place it next to the sorted list.



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```
for (i = 0; i < n-1; i++) {  
    examine list[i] to list[n-1] to find the smallest integer (i.e. list[min])  
    interchange list[i] and list[min];  
}
```

i	[0]	[1]	[2]	[3]	[4]
	30	10	50	40	20
0	10	30	50	40	20
1	10	20	50	40	30
2	10	20	30	40	50
3	10	20	30	40	50



# algorithm: selection sort

From the unsorted integers, find the smallest and place it next to the sorted list.

```
for (i = 0; i < n; i++) {  
    Examine list[i] to list[n-1] to find the smallest integer (i.e. list[min])  
    interchange list[i] and list[min];  
}
```

```
void sort (int list[], int n){  
    int i, j, min, temp;  
    for (i = 0; i < n - 1; i++){  
        min = i;  
        for (j = i + 1; j < n; j++){  
            if (list[j] < list[min])  
                min = j;  
        }  
        SWAP(list[i], list[min], temp);  
    }  
}
```

# algorithm: selection sort

```
#include <stdio.h>
#include <math.h>
#define MAX_SIZE 101
#define SWAP(x,y,t) ((t) = (x), (x) = (y), (y) = (t))
void sort(int [],int); /*selection sort */
void main(void)
{
    int i,n;
    int list[MAX_SIZE];
    printf("Enter the number of numbers to generate: ");
    scanf("%d",&n);
    if( n < 1 || n > MAX_SIZE) {
        fprintf(stderr, "Improper value of n\n");
        exit(1);
    }
    for (i = 0; i < n; i++) { /*randomly generate numbers*/
        list[i] = rand() % 1000;
        printf("%d ",list[i]);
    }
    sort(list,n);
    printf("\n Sorted array:\n ");
    for (i = 0; i < n; i++) /* print out sorted numbers */
        printf("%d ",list[i]);
    printf("\n");
}

void sort(int list[],int n)
{
    int i, j, min, temp;
    for (i = 0; i < n-1; i++) {
        min = i;
        for (j = i+1; j < n; j++)
            if (list[j] < list[min])
                min = j;
        SWAP(list[i],list[min],temp);
    }
}
```

**Program 1.3:** Selection sort

# algorithm specification: binary search

find query item in the sorted list and return the position

middle = (start + end) / 2;  
compare list[middle] with query

1) query < list[middle]

set end to middle-1

2) query = list[middle]

return middle

3) query > list[middle]

set start to middle+1

[0] [1] [2] [3] [4] [5] [6]

8 14 26 30 43 50 52

start	end	middle	list[middle]	:	searchnum
0	6	3	30	<	43
4	6	5	50	>	43
4	4	4	43	==	43

start	end	middle	list[middle]	:	searchnum
0	6	3	30	>	18
0	2	1	14	<	18
2	2	2	26	>	18
2	1	–			

# algorithm specification: binary search

```
int compare (int x, int y){  
    if (x < y)          return -1;  
    else if (x == y)    return 0  
    else                return 1;  
}
```

```
int binsearch (int list[], int query, int start, int end) {  
  
    int middle;  
    while(start <= end) {  
        middle = (start + end) / 2;  
        switch(compare(list[middle],query)) {  
            case -1: start = middle + 1; break;  
            case 0: return middle;  
            case 1: end = middle - 1;  
        }  
    }  
    return -1;  
}
```

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# recursive algorithms

- recursion
  - direct recursion: call themselves
  - indirect recursion: call other functions that invoke the calling function again
- recursive mechanism
  - extremely powerful
  - allows us to express a complex process in very clear terms



# recursive algorithms: binary search

establish **boundary condition** that terminates the recursive call

1) success

list[middle]=query

2) failure

start & end indices cross

```
int binsearch (int list[], int query, int start, int end) {  
    int middle;  
    if(start <= end) {  
        middle=(start+end) / 2;  
        switch(compare(list[middle], query)) {  
            case -1 : return binsearch(list, query, middle+1, end);  
            case 0 : return middle;  
            case 1 : return binsearch(list, query, start, middle-1);  
        }  
    }  
    return -1;  
}
```

# recursive algorithms: permutations

given a set of  $n(\geq 1)$  elements, print out all possible permutations of this set

if set  $\{a,b,c\}$  is given, then set of permutations is

(a, b, c) (a, c, b)

(b, a, c) (b, c, a)

(c, b, a) (c, a, b)

# recursive algorithms: permutations

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(a, b, c) (a, c, b)

(b, a, c) (b, c, a)

(c, b, a) (c, a, b)

for the set  $\{a,b,c\}$ , the set of permutations are

1) a followed by all permutations of (b,c) (a, (b, c))

2) b followed by all permutations of (a,c) (b, (a, c))

3) c followed by all permutations of (b,a) (c, (b, a))



# recursive algorithms: permutations

given a set of  $n(\geq 1)$  elements, print out all possible permutations of this set

if set  $\{a,b,c,d\}$  is given, then set of permutations is

(a, b, c, d) (a, b, d, c) (a, c, b, d) (a, c, d, b) (a, d, c, b) (a, d, b, c)  
(b, a, c, d) :

for the set  $\{a,b,c,d\}$ , the set of permutations are

- |  |                |
|--|----------------|
| 1) a followed by all permutations of (b,c,d) | (a, (b, c, d)) |
| 2) b followed by all permutations of (a,c,d) | (b, (a, c, d)) |
| 3) c followed by all permutations of (b,a,d) | (c, (b, a, d)) |
| 4) d followed by all permutations of (b,c,a) | (d, (b, c, a)) |

# recursive algorithms: permutation

```
void perm(char *list, int i, int n) {  
  
    int j, temp;  
    if (i==n)  
        for(j=0; j<=n; j++)  
            printf("%c ", list[j]);  
        printf("\n");  
    else {  
        for(j=i; j<=n; j++) {  
            swap(list[i], list[j]);  
            perm(list, i+1, n);  
            swap(list[i], list[j]);  
        }  
    }  
}
```

```
void main(){  
    :  
    perm(list, 0, n-1);  
}
```

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# data abstraction

- a **data type** is a collection of objects and a set of operations that act on those objects
  - ▶ the data type **int** consists of the objects {0, +1, -1, +2, -2, ..., INT\_MAX, INT\_MIN} and the operations {+, -, \*, /, and %}
- different data types
  - ▶ basic data type: char, int, float, double
  - ▶ composite data type: array, structure
  - ▶ user-defined data type
  - ▶ pointer data type

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# data abstraction

- an **abstract data type (ADT)** is a data type that is organized in such a way that the specification of the objects and their operations is separated from the implementation of the objects and operations
- specification of operations consists of
  - ▶ function name
  - ▶ types of arguments
  - ▶ types of its results
  - ▶ description of what the function does



# data abstraction: an example

**ADT** Natural\_Number(Nat\_No) is

**objects:** an ordered subrange of the integers starting at zero and ending at the max. integer on the computer

**functions:** for all  $x, y \in \text{Natural\_Number}$ ;  $\text{TRUE}, \text{FALSE} \in \text{Boolean}$  and  $+, -, <$ , and  $==$  are the usual integer operations

Nat\_No Zero() ::= 0

Nat\_No Add(x,y) ::= if  $((x+y) \leq \text{INT\_MAX})$  return  $x+y$   
                                  else return INT\_MAX

Nat\_No Subtract(x,y) ::= if  $(x < y)$  return 0  
                                  else return  $x-y$

Boolean Equal(x,y) ::= if  $(x == y)$  return TRUE  
                                  else return FALSE

Nat\_No Successor(x) ::= if  $(x == \text{INT\_MAX})$  return  $x$   
                                  else return  $x+1$

Boolean Is\_Zero(x) ::= if  $(x)$  return FALSE  
                                  else return TRUE

end Natural\_Number

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# performance evaluation

- performance analysis (machine independent, complexity theory)
  - ▶ **space complexity**: the amount of memory that it needs to run to completion
  - ▶ **time complexity**: the amount of computer time that it needs to run to completion
- performance measurement (machine dependent)



# space complexity

- fixed space requirements:  $C$

not depend on the number and size of the program's inputs and outputs  
eg) instruction space, simple variable, fixed-size structure variables,  
constant

- variable space requirement:  $S_p(I)$

the space needed by structured variable whose size depends on the  
particular instance of the problem being solved

**total space requirement  $S(P)$**

$$S(P) = C + S_p(I)$$

$C$  : fixed space requirements

$S_p(I)$  : function of some characteristics of the instance  $I$



## Example: a simple arithmetic function

```
float abc (float a, float b, float c) {  
    return a+b+b*c+(a+b-c)/(a+b)+4.00;  
}
```

- ▶ input - three simple variables
- ▶ output - a simple value
- ▶ variable space requirements  $S_{abc}(l) = 0$
- ▶ need only fixed space requirements



## Example: iterative function for summing a list of numbers

```
float sum (float list[], int n) {  
  
    float temp_sum = 0;  
    int i;  
    for(i = 0; i < n; i++)  
        temp_sum += list[i];  
    return temp_sum;  
}
```

- ▶ input - an array variable
- ▶ output - a simple value
- ▶ **C passes arrays by pointer**  
passing the address of the first element of the array (not copying the array)  
variable space requirements  $S_{\text{sum}}(n) = 0$

## Example: recursive function for summing a list of numbers

```
float rsum (float list[], int n) {  
    if(n)    return rsum(list,n-1) + list[n-1];  
    return 0;  
}
```

- ▶ compiler must save parameters, local variables, return address for each recursive call

type	name	number of bytes
parameter: array pointer	list[]	4
parameter: integer	n	4
return address		4
total per recursive call		12

- ▶ assume that array has  $n = \text{MAX\_SIZE}$  numbers,
- ▶ total variable space  $S_{\text{rsum}}(\text{MAX\_SIZE}) = 12 * \text{MAX\_SIZE}$

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# time complexity

- time  $T(P)$ , taken by a program  $P$ , is the sum of its compile time and its run (or execution) time
  - ▶ compile time is similar to the fixed space component
- We are really concerned only about the **program's execution time**,  $T_p$ 
  - ▶ count **the number of operations** that the program performs
  - ▶ give a machine-independent estimation
- A *program step* is a syntactically or semantically meaningful program segment whose execution time is independent of the instance characteristics

## Example: iterative summing of a list of numbers

statement	steps/exec ution	total steps
<pre>float sum (float list[], int n) {     float temp_sum=0;     int i;     for(i = 0; i &lt; n; i++)         temp_sum += list[i];     return temp_sum; }</pre>	<pre>1 0 1 1 1</pre>	<pre>1 0 n+1 n 1</pre>
total		$2n+3$

## Example: recursive summing of a list of numbers

Statement	s/e	total steps
<pre>float rsum(float list[], int n) {     if(n)         return rsum(list,n-1)+list[n-1];     return list[0]; }</pre>	<pre>1 1 1</pre>	<pre>n+1 n 1</pre>
total		$2n+2$

## Example: matrix addition

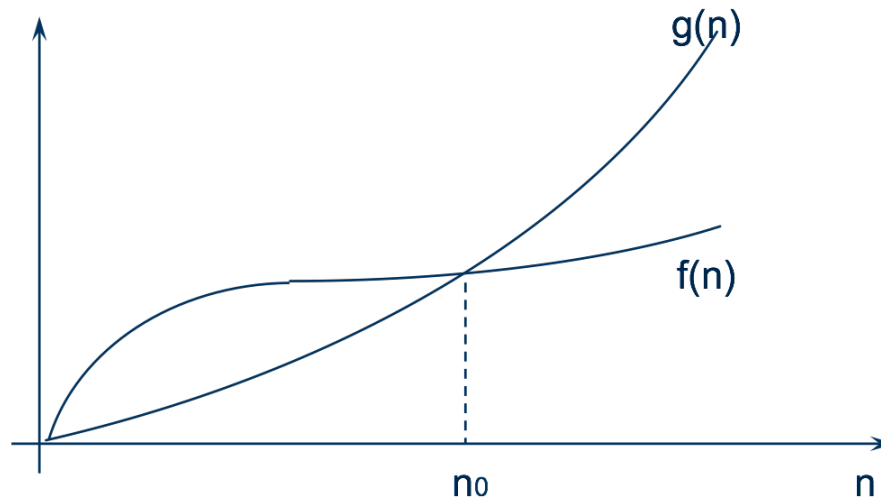
statement	s/e	total steps
<pre>void add(int a[][M_SIZE], ...) {     int i, j;     for(i = 0; i &lt; rows; i++)         for(j = 0; j &lt; cols; j++)             c[i][j] = a[i][j] + b[i][j]; }</pre>	<pre>0 1 1 1</pre>	<pre>0 rows+1 rows*(cols+1) rows*cols</pre>
total		$2rows*cols+2rows+1$

# Asymptotic notation: big-O notation

## Definition [big-O]

$f(n) = O(g(n))$  iff there exist positive constants  $c$  and  $n_0$  such that  
 $f(n) \leq c \cdot g(n)$  for all  $n, n \geq n_0$

- ▶  $g(n)$  is an **upper bound** on the value of  $f(n)$  for all  $n \geq n_0$
  - ▶ but, doesn't say anything about how good this bound is
- $n = O(n^2), n = O(n^{2.5}), n = O(n^3), n = O(2^n)$

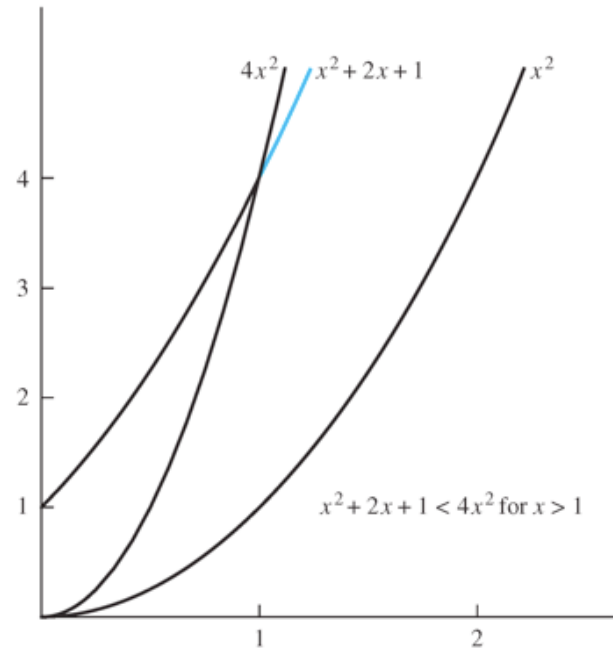


# big-O notation

- show that  $T(x) = x^2 + 2x + 1$  is  $O(x^2)$

$$|T(x)| \leq C |g(x)| \quad \text{whenever } x > k$$

- ▶ when  $x > 1$ ,  $x < x^2$  and  $1 < x^2$
- ▶  $x^2 + 2x + 1 < x^2 + 2x^2 + x^2 = 4x^2$
- ▶  $|T(x)| \leq 4 |x^2|$  whenever  $x > 1$
- ▶  $T(x)$  is  $O(x^2)$  when  $C = 4$ ,  $k = 1$





# big-O notation

- show that  $T(x) = x^2 + 2x + 1$  is  $O(x^3)$

$$|T(x)| \leq C |g(x)| \quad \text{whenever } x > k$$

- ▶ when  $x > 1$ ,  $x^2 < x^3$ ,  $x < x^3$ , and  $1 < x^3$
- ▶  $x^2 + 2x + 1 < x^3 + 2x^3 + x^3 = 4x^3$
- ▶  $|T(x)| \leq 4 |x^3|$  whenever  $x > 1$
- ▶  $T(x)$  is  $O(x^3)$  when  $C = 4$ ,  $k = 1$



# $\Omega$ notation

## Definition [Omega]

$f(n) = \Omega(g(n))$  iff there exist positive constants  $c$  and  $n_0$  such that

$f(n) \geq c \cdot g(n)$  for all  $n$ ,  $n \geq n_0$

- ▶  $g(n)$  is a **lower bound** on the value of  $f(n)$  for all  $n$ ,  $n \geq n_0$
- ▶ if  $f(n) = a_m n^m + \dots + a_1 n + a_0$  and  $a_m > 0$ , then  $f(n) = \Omega(n^m)$



# $\Theta$ notation

## Definition [Theta]

$f(n) = \Theta(g(n))$  iff there exist positive constants  $c_1$ ,  $c_2$ , and  $n_0$  such that

$$c_1 \cdot g(n) \leq f(n) \leq c_2 \cdot g(n) \text{ for all } n, n \geq n_0$$

- ▶ more precise than both the “big oh” and “big omega” notations
- ▶  $g(n)$  is both an upper and lower bound on  $f(n)$



# $\Theta$ notation

statement	total steps
<pre>void add(int a[][M_SIZE], ...) {     int i, j;      for(i = 0; i &lt; rows; i++)         for(j = 0; j &lt; cols; j++)             c[i][j] = a[i][j] + b[i][j]; }</pre>	<p>0</p> <p><math>\Theta(\text{rows})</math></p> <p><math>\Theta(\text{rows} * \text{cols})</math></p> <p><math>\Theta(\text{rows} * \text{cols})</math></p>
total	$\Theta(\text{rows} * \text{cols})$

# asymptotic notation

		Instance characteristic $n$					
Time	Name	1	2	4	8	16	32
1	Constant	1	1	1	1	1	1
$\log n$	Logarithmic	0	1	2	3	4	5
$n$	Linear	1	2	4	8	16	32
$n \log n$	Log linear	0	2	8	24	64	160
$n^2$	Quadratic	1	4	16	64	256	1024
$n^3$	Cubic	1	8	64	512	4096	32768
$2^n$	Exponential	2	4	16	256	65536	4294967296
$n!$	Factorial	1	2	24	40326	20922789888000	$26313 \times 10^{33}$

# time complexity of algorithms

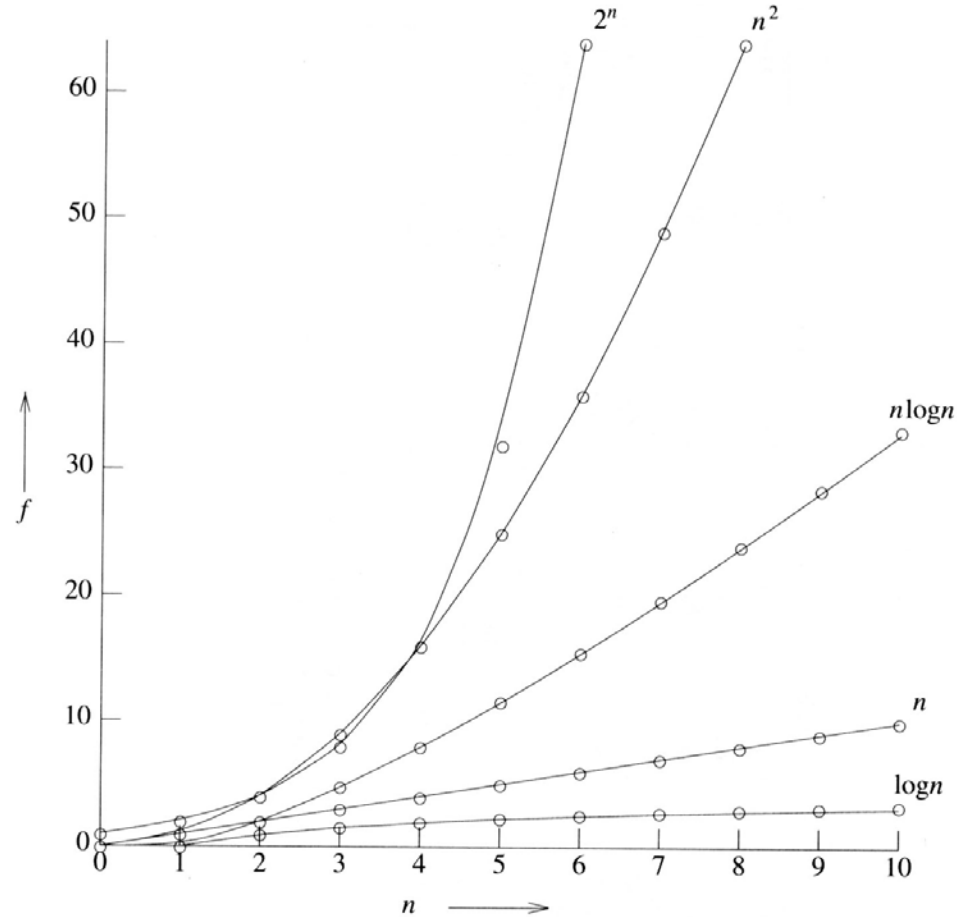


Figure 1.8 Plot of function values

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# asymptotic notation

If a program needs  $2^n$  steps for execution

$n=40$  --- number of steps =  $1.1 \times 10^{12}$

in computer systems 1 billion ( $10^9$ ) steps/sec --- 18.3 min

$n=50$  --- 13 days

$n=60$  --- 310.56 years

$n=100$  ---  $4 \times 10^{13}$  years

If a program needs  $n^{10}$  steps for execution

$n=10$  --- 10 sec

$n=100$  --- 3171 years