

# Laplace Equation

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The Laplace Equation is defined as followed:

$$\nabla^2 u(x_1, x_2, \dots) = 0 \iff \nabla \cdot \nabla u(x_1, x_2, \dots) = 0 \quad (1)$$

Solutions to the Laplace Equation are called harmonic functions. As long as we assign values at the end points of the domain  $D$ , we have that the solution exists and is unique. We will solve for this solution using Fourier Series. Given some domain  $D$ , we can define the boundary of  $D$ , denoted as  $\partial D$ , to be zero horizontally. In other words,  $u(0, y) = u(a, y) = 0$ . Using this, we can use the Fourier Sine Series to fit a solution to this equation. Then the Fourier expansion is as follows:

$$u(x, y) = \sum_{n=1}^{\infty} A_n(y) \sin\left(\frac{n\pi x}{a}\right) \quad (2)$$

Inserting this equation into the Laplacian, we have that

$$\Delta u = \sum_{n=1}^{\infty} (A_n''(y) - \left(\frac{n\pi}{a}\right)^2 \cdot A_n(y)) \sin\left(\frac{n\pi x}{a}\right) \quad (3)$$

This implies that

$$A_n''(y) - \left(\frac{n\pi}{a}\right)^2 \cdot A_n(y) = 0 \quad (4)$$

The solution to this equation is

$$A_n(y) = \alpha_n e^{\frac{n\pi}{a}y} + \beta_n e^{-\frac{n\pi}{a}y} \quad (5)$$

In general, if the boundary conditions aren't satisfied. You can always decompose it so that one domain has a zero boundary condition horizontally and another vertically. This is due to the nature of linearity within the Laplacian. Just make sure to correctly define the length to be the respective width and length of the rectangle.

## Properties of the solutions

1. Maximum principle
2. Invariance of Laplacian

**Definition 0.1.** Let  $D \in \mathbb{R}^2$ , (that is  $D$  is a open and connected domain), let  $\partial D$  be the boundary of  $D$  and  $\bar{D} : D \cup \partial D$ . You can think of  $D$  as the open brackets, not including the boundary.

Then we state the maximum principle:

**Definition 0.2.** Let  $D \in \mathbb{R}^2$  be a bounded domain, let  $U$  be a harmonic function on  $D$  (that is  $\nabla^2 U = 0$ ), then we have the following equality:

$$\max_{\bar{D}} U = \max_{\partial D} U \quad (6)$$

That is to say the maximum of a harmonic function must exist on its boundaries. Intuitively, because the divergence of the function is 0 everywhere, if there was a maximum in the middle, then its divergence would be non-zero. Thus, there cannot be a maximum inside  $D$ , only at  $\partial D$ . Thus, one can also explore the minimum principle.

**Corollary 0.3.** Let  $D \in \mathbb{R}^2$ , and let  $U$  be harmonic function. Then we have that

$$\min_{\bar{D}} U = \min_{\partial D} U \quad (7)$$

**Corollary 0.4.** This is for uniqueness. Then let  $D \in \mathbb{R}^2$  be a bounded domain, let  $u_1$  and  $u_2$  be harmonic functions. Suppose that

$$u_1 = u_2 \text{ for } (x, y) \in \partial D \quad (8)$$

Then

$$u_1 = u_2 \text{ for } (x, y) \in D \quad (9)$$

Next is the invariance of the Laplacian. The Laplacian holds under rigid motion (like rotations). This is due to the invariance of the gradient and divergence, which I proved in a special relativity p-set.

**Definition 0.5.** Firstly, we define what rigid motion is. Rigid motion is the following:

1. translation  $(x, y) \rightarrow (x + a, y + b)$
2. rotation  $R\vec{v} = \vec{v}'$  such that  $R$  is a rotation matrix.
3. Reflection across an axis

More precisely, Rigid motion is a map from  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$  that is created through combinations of rotations and translations.

**Theorem 0.6.** Let  $u$  be a harmonic function, and  $R$  is a rigid motion transformation that we apply to a function, then we define the invariance of the harmonic function such that:

$$\nabla^2 u = (\nabla^2 (Ru)) \iff \nabla^2(\tilde{u}) = 0 \quad (10)$$

**Theorem 0.7.** Let  $u(x, y)$  be a 2 variable function, and let  $T(x, y)$  be an orientation preserving rigid motion. Such that

$$T(x, y) = (\cos \alpha x + \sin \alpha y - a, -\sin \alpha x + \cos \alpha y - b) \iff (\bar{x}, \bar{y}) \quad (11)$$

Then we define  $\bar{u}(\bar{x}, \bar{y}) = u \circ T^{-1}(\bar{x}, \bar{y})$ . Then we see that

$$\nabla^2 \bar{u}(\bar{x}, \bar{y}) = (\nabla^2 u) \circ (T^{-1}(\bar{x}, \bar{y})) \quad (12)$$

That is, we are describing this function in terms of the new coordinate system  $(\bar{x}, \bar{y})$

## Laplacian under Polar Coordinates

That is  $(x, y) \iff (r, \theta)$  such that  $x = r \cos \theta$  and  $y = r \sin \theta$ . Where  $r = \sqrt{x^2 + y^2}$  and  $\theta = \arctan(\frac{y}{x})$ . Then the Laplacian under this new coordinate system is

$$\nabla^2 u = u_{rr} + \frac{1}{r} u_r + \frac{1}{r^2} u_{\theta\theta} \quad (13)$$

**Theorem 0.8.** Let  $h(\theta)$  be a function with period  $2\pi$ . Let define the domain  $D$  to be a circle with radius  $a$ . Then  $\nabla^2 u = 0$  on  $D$  and  $u = h$  on  $\partial D$  has a unique solution. The solution is the following:

$$u(r, \theta) = \frac{A_0}{2} + \sum_{n=1}^{\infty} (A_n r^n \cos(n\theta) + B_n r^n \sin(n\theta)) \quad (14)$$

Where

$$A_n = \frac{1}{\pi a^n} \int_{-\pi}^{\pi} h(\theta) \cos(n\theta) d\theta \quad (15)$$

The same equation can be used for  $B_n$ . Where  $a$  is the radius of the circle.