# MTH 416: Lecture 5

### Cliff Sun

#### September 10, 2024

## Lecture Span

- Reduced row echelon form (RREF)
- Linear independence

## Recap:

#### Elementary row operations

- 1. Switch 2 rows
- 2. Scalar a row by a const  $\neq 0$
- 3. Add multiple of one row to another row

#### RREF

- 1. All rows of 0's are at the bottom
- 2. First non-zero entry per row is a 1
- 3. Each leading 1 is the only non-zero entry in its column
- 4. Leading 1's go Northwest to Southeast.

Goal: Put any matrix in RREF using elementary row operations. The algorithm that establishes this is Gaussian Elimination.

#### Notation

- 1. M is a  $m \times n$  matrix (m rows & n columns)
- 2.  $R_i = i$ -th row
- 3.  $C_j = \text{j-th column}$

## Algorithm

- 1. Set r = 0 and j = 0
- 2. If  $j \geq n$ , then stop and return current matrix, otherwise increment j.
- 3. If  $C_j$  has all 0's, below the r-th row, then go to step 1.
- 4. Find a non-zero among rows r+1 of  $C_j$ , by switching rows put it on r+1, then set r=r+1.
- 5. Scale row r by a constant to make its j-th entry = 1.
- 6. Subtract multiples of  $R_r$  from every other row to zero out all of column j except for  $R_r$ .
- 7. Go to step 1.

#### **Proof of Gaussian Elimination**

*Proof.* First, the algorithm must stop eventually because when we reach step 1 n times, then j = n which stops the algorithm.

To prove that this algorithm returns a matrix in RREF, we claim that everytime we get to step 1, the matrix has the form

 $\begin{pmatrix} RREF & ? \\ 0 & ? \end{pmatrix}$ 

That is the RREF form is j columns wide and r rows long. We will prove this by induction on j, or the column index. This means that once j = n, we will have the above matrix be in completely RREF form, which proves our claim.

#### **Base Case**

The first time we reach step 1, j = 0. But this means that any  $m \times n$  matrix has the form of the above matrix when j = 0.

### **Induction Step**

Suppose that the matrix is currently in the form of the above matrix, then we must prove that the next time we go to step 1 that the matrix remains in the form of the above matrix, but with the known RREF section expanded. There are 2 cases:

- 1. If we leave step 1, and proceed to step 2 and immediately go back to step 1, then j has been incremented and the matrix has been unchanged. In this case, the known RREF section has increased a column, but this section is still in RREF form.
- 2. We return to step 1 from step 6. In this case, r and j have incremented, and the matrix has changed. In particular, the RREF section has increased by 1 in both its rows and columns. But we claim that this matrix is still in RREF. In step 3, we found some non-zero number and brought it to r + 1 (note the RREF matrix has not been changed) Then in step 4, we scale the column by a constant such that the value at  $M_{r,j} = 1$ , then we take this row and subtract multiples of this row from other rows to "zero-out" all other entires in  $C_j$ . Note that the entire left side of the matrix has been left untouched. To prove that M is still in the form

$$\begin{pmatrix} RREF & ? \\ 0 & ? \end{pmatrix}$$

Note that the top left corner by adding a pivot plus a row of 0's (0's in front of pivot) and a column of 0's. Therefore, by induction, we have shown that the final matrix will be in RREF.

# Linear Independence

Recall: one powerful method to construct subspaces W of vector space V is through spans.

$$span(u_1, \dots, u_k) = \{a_1u_1 + \dots + a_ku_k\} \tag{1}$$

- 1. If  $W = span(u_1, \dots, u_k)$ , are all these vectors necessary?
- 2. Or can W be written as

$$span(u_1, \cdots, u_k)$$
 (2)

And how many vectors do I need?

3. Given  $W \subseteq V$ , then how "big" is W. e.g Subspaces of  $\mathbb{R}^3$  include  $\{0\}$ , a line through 0, a plane through 0, or  $\mathbb{R}^3$ . Can we mathematically measure its "dimensionality"?

**Definition 0.1.** Let V be a vector space and  $u_1, \dots, u_k \in V$ , then

1. The vectors are linearly dependent if there exist scalars  $a_1, \dots, a_k$  not zero such that

$$a_1 u_1 + \dots + a_k u_k = 0 \tag{3}$$

All scalars equaling zero is the "trivial solution".

2. Otherwise, the vectors are a linearly independent set.