

PHYS 325: Lecture 15

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Lecture Span

- Damped harmonic oscillator

The EOM for damped harmonic oscillators is

$$m\ddot{y} + c\dot{y} + ky = 0 \quad (1)$$

The "normal" form:

$$\ddot{y} + 2\zeta\omega_n\dot{y} + \omega_n^2 y = 0 \quad (2)$$

Then the eigen frequency, or the normal frequency is

$$\omega_n = \sqrt{\frac{k_{eff}}{m_{eff}}} \quad (3)$$

and

$$\zeta = \frac{c}{2m\omega_n} \quad (4)$$

Guess

$$y \sim e^{\lambda t} \quad (5)$$

insert in EOM

$$\lambda^2 + 2\zeta\omega_n\lambda + \omega_n^2 = 0 \quad (6)$$

Then

$$\lambda_{\pm} = -\omega_n(\zeta \pm \sqrt{\zeta^2 - 1}) \quad (7)$$

Undamped

Let $\zeta = 0$, then

$$\lambda_{\pm} = \pm i\omega_n \quad (8)$$

Overdamped

Let $\zeta > 1$

$$\lambda_{\pm} = -\omega_n(\zeta \pm \sqrt{\zeta^2 - 1}) \quad (9)$$

Note that

$$\lambda_{\pm} < 0 \quad (10)$$

Critical damping

Let $\zeta = 1$, then

$$\lambda_{\pm} = -\omega_n \quad (11)$$

Then

$$y(t) = A_1 e^{\omega_n t} + A_2 t e^{-\omega_n t} \quad (12)$$

Underdamping

Let $0 < \zeta < 1$, then

$$\lambda_p m = -\omega_n (\zeta \pm \sqrt{\zeta^2 - 1}) \quad (13)$$

Then

$$\lambda_p m = \omega_n \zeta \pm i \sqrt{1 - \zeta^2} \quad (14)$$

Versions we can work with:

$$y(t) = e^{-\zeta \omega_n t} (A \cos(\omega_n t) + B \sin(\omega_n t)) \quad (15)$$

What happens if $\zeta < 0$? Then double yo work dumbass.

Forced oscillator

Oscillator with external driving force. Note, energy is not conserved. Then

$$\frac{dE}{dt} + P_{\text{diss}} = \frac{dW}{dt}_{\text{ext}} \iff F_{\text{ext}} \cdot v \quad (16)$$

$$m_{\text{eff}} \frac{d^2 \vec{x}}{dt^2} + c_{\text{eff}} \frac{d\vec{x}}{dt} + k_{\text{eff}} \vec{x} = \vec{F}_{\text{ext}}(t) \quad (17)$$

No damping means that

$$P_{\text{diss}} = 0 \quad (18)$$

We also have

$$T = \frac{1}{2} m v^2 \iff \frac{1}{2} m L^2 \dot{\theta}^2 \quad (19)$$

$$U = mgh \iff mgL(1 - \cos \theta) \quad (20)$$

Note we have that

$$F \cdot v \iff L \dot{\theta} F \cdot e_{\theta} \iff L \dot{\theta} F \cos \theta \quad (21)$$

Thus we have that

$$\frac{1}{2} m L^2 2 \dot{\theta} \ddot{\theta} + mgL \dot{\theta} \sin \theta = L \dot{\theta} F \cos \theta \quad (22)$$

$$mL \ddot{\theta} + mg \sin \theta = F \cos \theta \quad (23)$$

For small angles:

$$mL \ddot{\theta} + mg \theta = F(t) \quad (24)$$

Cart on a cart

- Big cart as acceleration \ddot{y}
- Displacement of big truck = y , displacement of everything is $y + x$
- also another force $-kx$

Then

$$m(\ddot{x} + \ddot{y}) = -kx \quad (25)$$

then

$$m\ddot{x} + kx = -m\ddot{y} \quad (26)$$