## PHYS 325: Lecture 25

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We define generalized coordinates

$$\{q_i\} = \{q_1, \dots\} \tag{1}$$

A generalized velocity:

$$\dot{q}_i = \frac{d}{dt}q_i \tag{2}$$

Note,  $\{q_i\}$  is a list of potential paths. We introduce an action as a functional

$$S[\vec{q}(t)] = \int_{t_1}^{t_2} dt L(q_i(t), \dot{q}_i(t), t)$$
(3)