MTH 416: Lecture 10

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Lecture Span

- Rank-nullity Theorem
- Matrix Representation of Linear Transformations

Rank-nullity Theorem

Theorem 0.1. Suppose $T : \to W$, linear, V is finite dimensional, then:

$$\dim R(T) + \dim N(T) = \dim V \tag{1}$$

Example 1

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ and

$$T(x,y) = (y, x+y) \tag{2}$$

Then

$$N(T) = \{(x, y) \in \mathbb{R}^2, (y, x + y = 0)\} \iff \{0\}$$

Thus

$$\dim R(T) + 0 = 2 \iff \dim R(T) = 2 \tag{4}$$

This means that R(T) is surjective, and covers all of \mathbb{R}^2 , thus T is surjective.

Example 2

$$T: P_n(\mathbb{R}) \to P_n(|\mathbb{R}) \tag{5}$$

$$T = f' \tag{6}$$

 $N(T) = \{c\} : c \in \mathbb{R} \iff P_0(\mathbb{R}) \to P_n(\mathbb{R})$

So dim N(T) = 1. By rank nullity, we have that

$$\dim R(T) + \dim N(T) = \dim P_n(\mathbb{R}) \tag{7}$$

Then $R(T) = P_{n-1}(\mathbb{R})$ and has dimension n.

Corollary 0.2. Suppose $T: V \to W$, where dim V = m and dim W = n then

- 1. If T is injective, then $n \geq m$
- 2. If T is surjective, then $m \geq n$
- 3. If n = m, then T is injective iff it's surjective.

Let's prove (3).

Proof. Suppose that $\dim V = \dim W$, then we know that

$$T \text{ injective } \iff N(T) = \{0\}$$
 (8)

But

$$N(T) = \{0\} \iff \dim N(T) = 0 \tag{9}$$

Thus

$$\dim R(T) + \dim N(T) = n \iff \dim R(T) = n \tag{10}$$

$$R(T) = W \tag{11}$$

This is equivalent to saying that R(T) is surjective.

Matrix Representation of Linear Transformations

Suppose V is a vector space, with basis $\beta = \{v_1, \dots, v_n\}$. Then say $v \in V$ can be written uniquely such that

$$v = a_1 v_1 + \dots + a_n v_n \tag{12}$$

Definition 0.3. The <u>coordinate vector</u> of v with respect to the basis β is

$$[v]_{\beta} \iff \langle a_1, a_2, \dots, a_n \rangle \in \mathbb{R}^n \tag{13}$$

Example 1

Suppose $V = P_2(\mathbb{R})$ with basis $\{1, x, x^2\}$ and $v = x^2 + 2x + 3$. Then

$$[v]_{\beta} = <3, 2, 1>$$
 (14)

Note, the order of the basis matters. If $\beta' = \langle x^2, x, 1 \rangle$, then the coordinate vector would be

$$[v]_{\beta} = <1, 2, 3>$$
 (15)

In other words, coordinate vectors depend on an <u>ordered basis</u>.

Example 2

Let $V = \mathbb{R}^n$ with the standard ordered basis, that is

$$\beta = \langle e_1, e_2, \dots, e_n \rangle = \{\{1, 0, \dots, 0\}, \{0, 1, \dots, 0\}, \dots, \}$$

$$\tag{16}$$

Then for any $v = \langle v_1, \dots, v_n \rangle \in \mathbb{R}^n$, we have that

$$[v]_{\beta} = v \tag{17}$$

Theorem 0.4. If V has an ordered basis $\beta = \{v_1, \dots, v_n\}$, then the function

$$T: V \to \mathbb{R}^n \tag{18}$$

and $T(v) = [v]_{\beta}$. This is a bijective linear transformation. That is, each vector is mapped to its coordinate vector. This should be bijective because each vector in V can be expressed uniquely as the sum of its basis vectors.

Let V and W be vector spaces, and suppose we have ordered basis

$$\beta = \{v_1, \dots, v_n\} \in V \tag{19}$$

$$\gamma = \{w_1, \dots, w_m\} \in W \tag{20}$$

Suppose $T \to W$ is linear. Recall T is uniquely determined by $T(v_1), \ldots, T(v_n)$.

Definition 0.5. A matrix of T in the ordered basis β , γ is

$$[T]^{\gamma}_{\beta} = ([T(v_1)]_{\gamma} \dots [T(v_n)]_{\gamma})$$
(21)

This is an $m \times n$ matrix. Explicitly, if the entry in position (i, j) is a_{ij} , then

$$T(v_j) = a_{1j}w_1 + \dots + a_{mj}w_m \tag{22}$$

Example 1

 $T: \mathbb{R}^2 \to \mathbb{R}^2$ such that

$$T(x,y) = (x+y,y) \tag{23}$$

$$\beta = \{e_1, e_2\} \tag{24}$$

$$[T]^{\gamma}_{\beta} = ([T(v_1)]_{\gamma} \dots [T(v_n)]_{\gamma})$$
(25)

or

$$[T]^{\gamma}_{\beta} = \begin{pmatrix} 1 & 1\\ 0 & 1 \end{pmatrix} \tag{26}$$

Because

$$T(\langle 1, 0 \rangle) = \langle x + y, y \rangle \iff \langle 1, 0 \rangle \tag{27}$$

and

$$T(\langle 0, 1 \rangle) = \langle x + y, y \rangle \iff \langle 0 + 1, 1 \rangle \iff \langle 1, 1 \rangle \tag{28}$$

Let

$$\gamma = \left\{ \begin{pmatrix} 1\\0 \end{pmatrix}, \begin{pmatrix} 1\\1 \end{pmatrix} \right\} \tag{29}$$

Fact: Once we choose the ordered basis β for V, and γ for W, then

$$T \iff [T]^{\gamma}_{\beta}$$
 (30)

is a one-to-one correspondence between linear Transformations and $m \times n$ matrices. Suppose

$$A \in M_{m \times n}(\mathbb{R}) \tag{31}$$

and

$$x = \begin{pmatrix} x_1 \\ \dots \\ x_n \end{pmatrix} \in \mathbb{R}^n \tag{32}$$

Recall Ax is the vector $\gamma \in \mathbb{R}^m$ such that

$$y_i = \sum_{j=i}^n A_{ij} x_j \tag{33}$$

Note: if u_1, \ldots, u_n are columns of A, then

$$Ax = x_1 u_1 + x_2 u_2 + \dots + x_n u_n \tag{34}$$

Note: $LS(A, b) \iff Ax = b$ such that x is a vector of variables.

Theorem 0.6. Suppose $T: V \to W$ is linear, and β and γ are ordered basis for V and W respectively. Then for any $v \in V$, we have that

$$[T(v)]_{\gamma} = [T]_{\beta}^{\gamma} [v]_{\beta} \tag{35}$$

That is, every vector in T(v) can be written as a matrix multiplication of $[v]_{\beta}$. Idk why this notation is a thing, since it's basically saying

$$w = Av : \forall v \in V \land w \in W \tag{36}$$