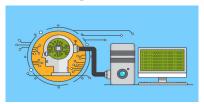
Reza Jafari, Ph.D

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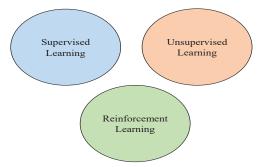


- 1. Machine Learning & Applications
- 2. Machine Learning Algorithms
- 3. Multilayer Perceptron MLP
- 4. Perceptron Learning rule
- 5. Practical Example
- 6. Demo

- A discipline within the field of Artificial Intelligence, by means
 of algorithms, provides computers with the ability to identify
 patterns from mass data in order to make predictions.
- Learning is the process of gaining knowledge or skills through experience.
- The input to this learning process is training data and the output is some expertise that can perform some task.



- Aerospace
 - Autopilot
- Intelligent vehicles
 - Driverless cars.
- Social networks
 - Spam detection.
- Medicine
 - Early breast cancer detection.
- Computer vision
 - Object detection.
- Speech
 - Translation from one language to another



Learning rules

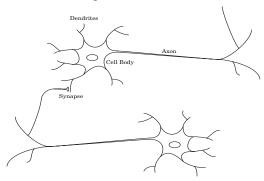
• Supervised learning: Network is provided with a set of examples of proper network behavior inputs and targets. $\{p_1, t_1\}, \{p_2, t_2\}, ..., \{p_O, t_O\}$

• Reinforcement learning: Network is only provided with a grade, or score, which indicates network performance.

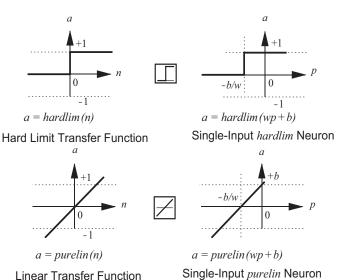
• Unsupervised learning: Only network inputs are available to the learning algorithm. Network learns to categorize (cluster) the inputs.

Brain Function

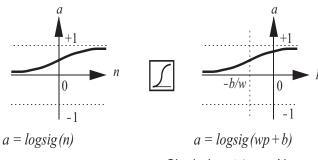
- Neurons Respond Slowly
 - 10^{-3} s compared to to 10^{-9} s for electrical circuits.
- The brain uses massively parallel comptation
 - $\approx 10^{11}$ neurons in the brain.
 - $\sim 10^4$ connections per neurons.



Transfer function



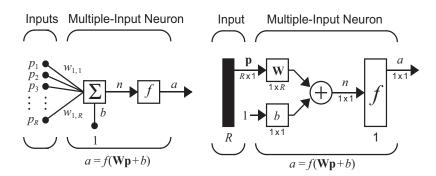
Transfer function



Log-Sigmoid Transfer Function

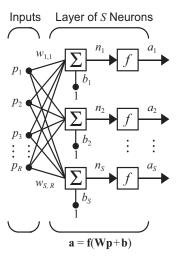
Single-Input *logsig* Neuron

Multiple input neuron

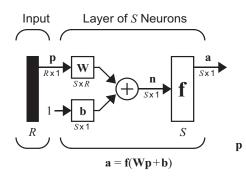


Abreviated Notation

Layer of neurons



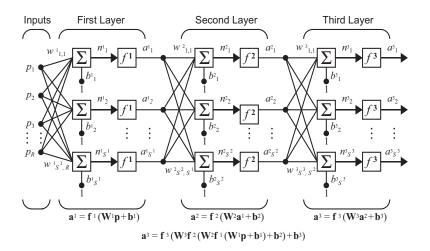
Abbreviated notation



$$\mathbf{W} = \begin{bmatrix} w_{1,1} & w_{1,2} & \cdots & w_{1,R} \\ w_{2,1} & w_{2,2} & \cdots & w_{2,R} \\ \vdots & \vdots & & \vdots \\ w_{S,1} & w_{S,2} & \cdots & w_{S,R} \end{bmatrix}$$

$$\mathbf{p} = \begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_R \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_S \end{bmatrix} \quad \mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_S \end{bmatrix}$$

Multilayer network



Abbreviated notation

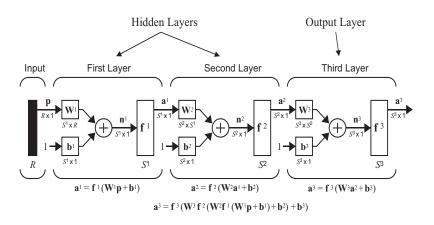
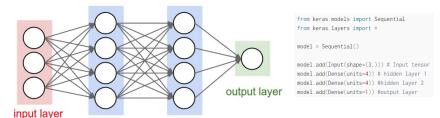


Diagram representation

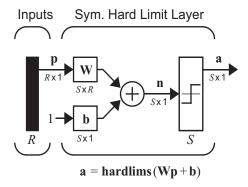
- input layer = 3 units (feature space dimension)
- hidden layer 1 = 4 units
- hidden layer 2 = 4 units

hidden layer 1

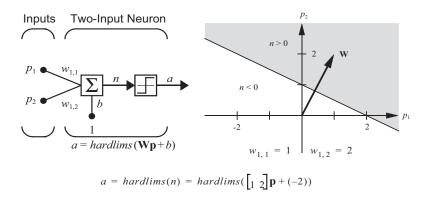
• output layer = 2 units



hidden layer 2



Two input case



$$\mathbf{W}\mathbf{p} + b = 0 \qquad \begin{bmatrix} 1 & 2 \end{bmatrix} \mathbf{p} + (-2) = 0$$

$$\mathbf{p} = \begin{bmatrix} \text{shape} \\ \text{texture} \\ \text{weight} \end{bmatrix}$$

Shape: {1 : round ; -1 : eliptical} Texture: {1 : smooth ; -1 : rough} Weight: {1 :> 1 lb.; -1 :< 1 lb.} Prototype Banana Prototype Apple

$$\mathbf{p}_1 = \begin{bmatrix} -1\\1\\-1 \end{bmatrix} \qquad \qquad \mathbf{p}_2 = \begin{bmatrix} 1\\1\\-1 \end{bmatrix}$$

Apple banana example

$$a = hardlims \left[w_{1,1} \ w_{1,2} \ w_{1,3} \right] \begin{bmatrix} p_1 \\ p_2 \\ p_3 \end{bmatrix} + b$$

$$p_1$$

$$p_2 \text{ (apple)} \qquad p_1 \text{ (banana)}$$

- The decision boundary should separate the prototype vectors
- $p_1 = 0$
- The weight vector should be orthogonal to the decision boundary, and should point in the direction of the vector which should produce an output of 1. The bias determines the position of the boundary.

Testing the network

Banana:

$$a = hardlims \left[\begin{bmatrix} -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + 0 \right] = 1(banana)$$

Apple:

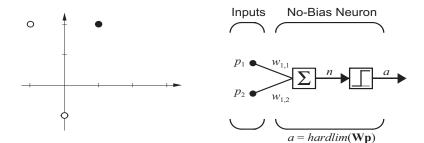
$$a = hardlims \left[\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} + 0 \right] = -1 \text{ (apple)}$$

"Rough" Banana:

$$a = hardlims \left[\begin{bmatrix} -1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix} + 0 \right] = 1 \text{(banana)}$$

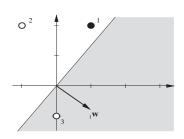
Learning rule test problem

$$\begin{aligned} & \{\mathbf{p}_1, \mathbf{t}_1\}, \{\mathbf{p}_2, \mathbf{t}_2\}, \dots, \{\mathbf{p}_{Q}, \mathbf{t}_{Q}\} \\ \\ & \left\{\mathbf{p}_1 = \begin{bmatrix} 1\\2 \end{bmatrix}, t_1 = 1 \right\} \qquad \left\{\mathbf{p}_2 = \begin{bmatrix} -1\\2 \end{bmatrix}, t_2 = 0 \right\} \qquad \left\{\mathbf{p}_3 = \begin{bmatrix} 0\\-1 \end{bmatrix}, t_3 = 0 \right\} \end{aligned}$$



Random initial weight:

$$_{1}\mathbf{w} = \begin{bmatrix} 1.0 \\ -0.8 \end{bmatrix}$$



Present \mathbf{p}_1 to the network:

$$a = hardlim({}_{1}\mathbf{w}^{T}\mathbf{p}_{1}) = hardlim\left[\begin{bmatrix} 1 & 0 & -0.8 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}\right]$$
$$a = hardlim(-0.6) = 0$$

Incorrect Classification.

Tentative learning rule

$$\begin{array}{ccc}
\operatorname{Set}_{1}\mathbf{w} \text{ to } \mathbf{p}_{1} \\
-\operatorname{Not stable}
\end{array} \times$$

$$\begin{array}{c}
\bullet \\
\bullet \\
\bullet \\
\bullet \\
\bullet
\end{array}$$

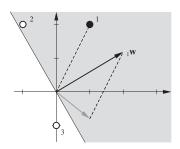
$$\begin{array}{c}
\bullet \\
\bullet \\
\bullet \\
\bullet \\
\bullet
\end{array}$$

$$\begin{array}{c}
\bullet \\
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\end{array}$$

$$\begin{array}{c}
\bullet \\
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\bullet \\
\bullet \\
\bullet \\
\bullet
\end{array}$$

If t = 1 and a = 0, then $\mathbf{w}^{new} = \mathbf{w}^{old} + \mathbf{p}$ Tentative Rule:

$$_{1}\mathbf{w}^{new} = _{1}\mathbf{w}^{old} + \mathbf{p}_{1} = \begin{bmatrix} 1.0 \\ -0.8 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 2.0 \\ 1.2 \end{bmatrix}$$



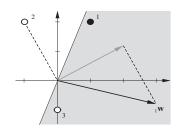
Second input vector

$$a = hardlim({}_{1}\mathbf{w}^{T}\mathbf{p}_{2}) = hardlim\left[\begin{bmatrix} 2.0 & 1.2 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix}\right]$$

 $a = hardlim(0.4) = 1$ (Incorrect Classification)

Modification to Rule: If t = 0 and a = 1, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} - \mathbf{p}$

$$_{1}\mathbf{w}^{new} = _{1}\mathbf{w}^{old} - \mathbf{p}_{2} = \begin{bmatrix} 2.0 \\ 1.2 \end{bmatrix} - \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 3.0 \\ -0.8 \end{bmatrix}$$

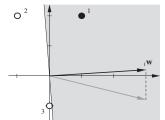


Third input vector

$$a = hardlim({}_{1}\mathbf{w}^{T}\mathbf{p}_{3}) = hardlim\left[\begin{bmatrix} 3.0 & -0.8 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \end{bmatrix}\right]$$

$$a = hardlim(0.8) = 1 \qquad \text{(Incorrect Classification)}$$

$$_{1}\mathbf{w}^{new} = _{1}\mathbf{w}^{old} - \mathbf{p}_{3} = \begin{bmatrix} 3.0 \\ -0.8 \end{bmatrix} - \begin{bmatrix} 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 3.0 \\ 0.2 \end{bmatrix}$$



Patterns are now correctly classified.

If
$$t = a$$
, then $\mathbf{w}^{new} = \mathbf{w}^{old}$.

,

Unified learning rule

If
$$t = 1$$
 and $a = 0$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} + \mathbf{p}$
If $t = 0$ and $a = 1$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} - \mathbf{p}$
If $t = a$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old}$
 $e = t - a$
If $e = 1$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} + \mathbf{p}$
If $e = -1$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old} - \mathbf{p}$
If $e = 0$, then ${}_{1}\mathbf{w}^{new} = {}_{1}\mathbf{w}^{old}$

$$_{1}\mathbf{w}^{new} = {_{1}}\mathbf{w}^{old} + e\mathbf{p} = {_{1}}\mathbf{w}^{old} + (t-a)\mathbf{p}$$

$$b^{new} = b^{old} + e$$

A bias is a weight with an input of 1.

$$_{i}\mathbf{w}^{new} = _{i}\mathbf{w}^{old} + e_{i}\mathbf{p}$$

$$b_i^{\ new} = b_i^{\ old} + e_i$$

Matrix form:

$$\mathbf{W}^{new} = \mathbf{W}^{old} + \mathbf{ep}^T$$

$$\mathbf{b}^{new} = \mathbf{b}^{old} + \mathbf{e}$$

Apple banana example

$$\left\{\mathbf{p}_1 = \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}, t_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right\} \qquad \left\{\mathbf{p}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, t_2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}\right\}$$

Initial Weights

$$\mathbf{W} = \begin{bmatrix} 0.5 & -1 & -0.5 \end{bmatrix} \qquad b = 0.5$$

First Iteration

$$a = hardlim(\mathbf{W}\mathbf{p}_1 + b) = hardlim \begin{bmatrix} 0.5 - 1 & -0.5 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + 0.5$$

$$a = hardlim(-0.5) = 0 \qquad e = t_1 - a = 1 - 0 = 1$$

$$\mathbf{W}^{new} = \mathbf{W}^{old} + e\mathbf{p}^T = \begin{bmatrix} 0.5 & -1 & -0.5 \end{bmatrix} + (1) \begin{bmatrix} -1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} -0.5 & 0 & -1.5 \end{bmatrix}$$

$$b^{new} = b^{old} + e = 0.5 + (1) = 1.5$$

$$e = t_2 - a = 0 - 1 = -1$$

a = hardlim(2.5) = 1

$$\mathbf{W}^{new} = \mathbf{W}^{old} + e\mathbf{p}^{T} = \begin{bmatrix} -0.5 & 0 & -1.5 \end{bmatrix} + (-1)\begin{bmatrix} 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} -1.5 & -1 & -0.5 \end{bmatrix}$$

$$b^{new} = b^{old} + e = 1.5 + (-1) = 0.5$$

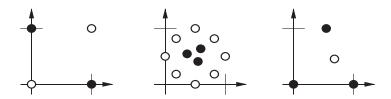
$$a = hardlim (\mathbf{W}\mathbf{p}_1 + b) = hardlim (\begin{bmatrix} -1.5 & -1 & -0.5 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix} + 0.5)$$
$$a = hardlim (1.5) = 1 = t_1$$

$$a = hardlim (\mathbf{W}\mathbf{p}_2 + b) = hardlim \left(\begin{bmatrix} -1.5 & -1 & -0.5 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} + 0.5 \right)$$
$$a = hardlim (-1.5) = 0 = t_2$$

Linear Decision Boundary

$$_{1}\mathbf{w}^{T}\mathbf{p}+b=0$$

Linearly Inseparable Problems



- Label the dataset with target value of 0 and 1.
- Implement the perceptron rule that classifies the dataset and draw the decision boundary.

