

COMP3048: Lecture 14

Run-Time Organisation I

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This Lecture

One aspect of run-time organisation:
stack-based storage allocation

- Lifetime and storage
- Basic stack allocation:
 - stack frames
 - dynamic links
- Allocation for nested procedures:
 - non-local variable access
 - static links

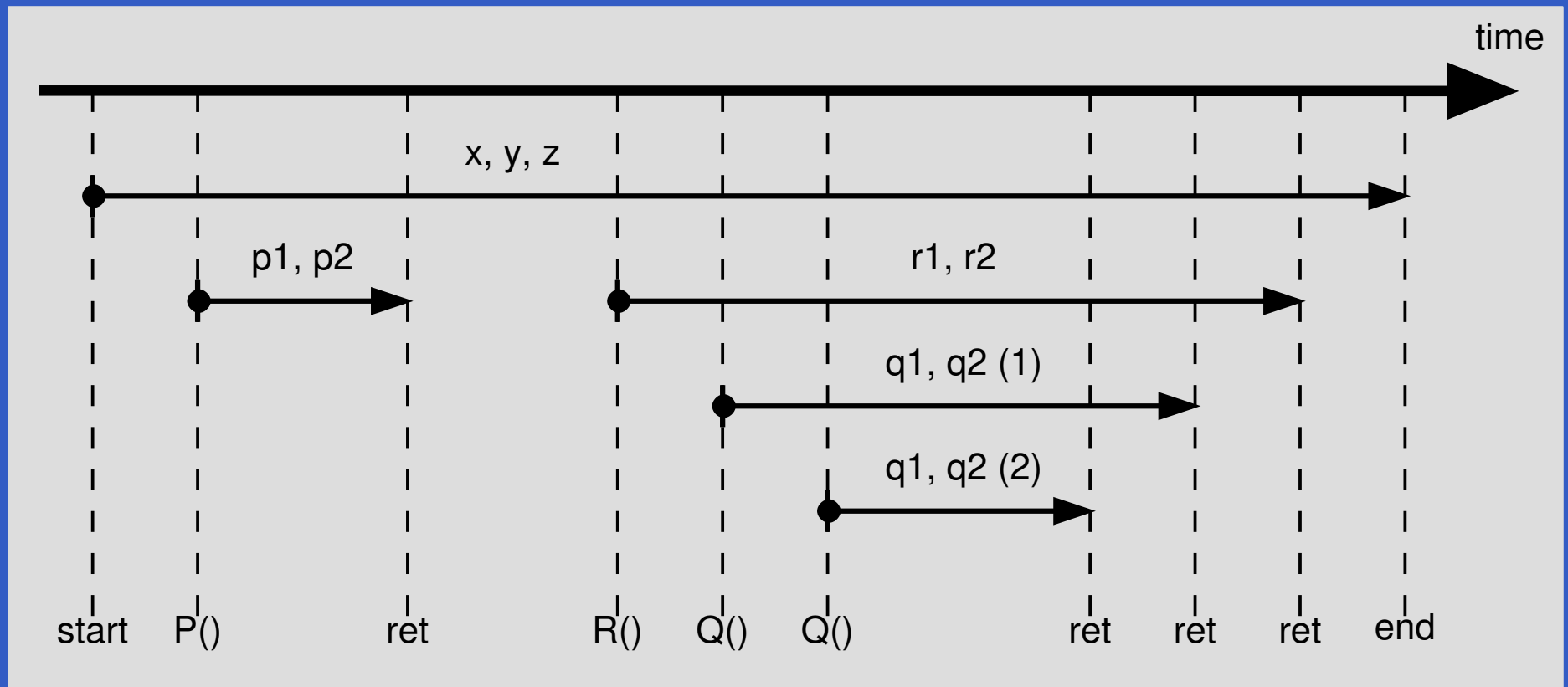
Storage Areas

- **Static storage**: storage for entities that live throughout an execution.
- **Stack storage**: storage allocated dynamically, but deallocation must be carried out in the opposite order to allocation.
- **Heap storage**: region of the memory where entities can be allocated and deallocated dynamically as needed, in any order.

Example: Lifetime (1)

```
var x, y, z: ...
proc P()
    var p1, p2: ...
    begin ... end
proc Q()
    var q1, q2: ...
    begin ... if ... Q(); ... end
proc R()
    var r1, r2: ...
    begin ... Q() ... end
begin ... P() ... R() ... end
```

Example: Lifetime (2)



Example: Lifetime (3)

```
private static Integer foo(int i) {  
    Integer n = new Integer(i);  
    return n;  
}
```

- The lifetimes of `i` and `n` coincides with the invocation of `foo`.
- The lifetime of the integer **object** created by `new` starts when `new` is executed and ends when there are no more references to it.
- The integer object thus **survives** the invocation of `foo`.

Storage Allocation (1)

- **Global variables** exist throughout the program's run-time.
- Where to store such variables can thus be decided **statically**, at compile (or link) time, once and for all.

Example:

```
private static String [] tokenTable = ...
```

Storage Allocation (2)

- **Arguments** and **local variables** exist only during a function (or procedure or method) invocation:
 - Function calls are properly nested.
 - In case of **recursion**, a function may be **re-entered** any number of times.
 - Each function activation needs a private set of arguments and local variables.
- These observations suggest that storage for arguments and local variables should be allocated on a **stack**.

Storage Allocation (3)

- When the lifetime does not coincide with procedure/function invocations, **heap allocation** is needed. E.g. for:
 - objects in object-oriented languages
 - function closures in languages supporting functions as first class entities
 - storage allocated by procedures like `malloc` in C.
- Such storage either **explicitly deallocated** when no longer needed, or **automatically reclaimed** by a garbage collector.

Stack Frames

One **stack frame** or **activation record** for each currently active function/procedure/method.

Contents:

- Arguments
- Bookkeeping information; e.g.
 - Return address
 - Dynamic link
 - Static link
- Local variables
- Temporary workspace

Defining the Stack

The stack is usually defined by a handful of registers, dictated by the CPU architecture and/or convention. For example:

- ***SB***: Stack Base
- ***ST***: Stack Top
- ***LB***: Local Base

The names vary. Stack Pointer (SP) and Frame Pointer (FP) are often used instead of ST and LB, respectively.

Typical Stack Frame Layout

address	contents
LB - <i>argOffset</i>	arguments
...	...
LB	static link
LB + 1	dynamic link
LB + 2	return address
LB + 3	local variables
...	...
LB + <i>tempOffset</i>	temporary storage

where

$$\text{argOffset} = \text{size}(\text{arguments})$$

$$\text{tempOffset} = 3 + \text{size}(\text{local variables})$$

TAM uses this convention. (Word (e.g. 4 bytes) addressing assumed, offsets in **words**.)

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•
•

Example: A function f

(Not quite current MiniTriangle, but language could easily be extended in this way.)

```
var n: Integer;  
...  
fun f(x, y: Integer): Integer =  
  let  
    z: Integer  
  in begin  
    z := x * x + y * y;  
    return n * z  
  end
```

Example: Calling f

Call sequence for $f(3, 7) * 8$:

2015	LOADL	3	; 1st arg. (x)
2016	LOADL	7	; 2nd arg. (y)
2017	CALL	f	
2018	LOADL	8	
2019	MUL		

Address of each instruction explicitly indicated to the left. Address of f here given symbolically by a label. Corresponds to the address where the code for f starts, say 2082.

Example: Stack layout on entry to f

On entry to f ; caller's $ST = f$'s LB :

address	contents
...	...
$SB + 42$	$n: n$
...	...
$LB - 2$	$x: 3$
$LB - 1$	$y: 7$
LB	static link
$LB + 1$	dynamic link
$LB + 2$	return address = 2018

Ret. addr. = old program counter (PC) = addr. of instruction immediately after the call instruction.

New PC = address of first instruction of $f = 2082$.

Example: TAM Code for \mathfrak{f}

TAM-code for the function \mathfrak{f} (at address 2082):

LOADL 0	ADD
LOAD [LB - 2]; x	STORE [LB + 3]; z
LOAD [LB - 2]; x	LOAD [SB + 42]; n
MUL	LOAD [LB + 3]; z
LOAD [LB - 1]; y	MUL
LOAD [LB - 1]; y	POP 1 1
MUL	RETURN 1 2

RETURN replaces activation record (frame) of \mathfrak{f} by result, restores LB, and jumps to ret. addr. (2018).

Note: all variable offsets are *static*.

Dynamic and Static Links

- **Dynamic Link**: Value to which LB (Local Base) is restored by `RETURN` when exiting procedure; i.e. addr. of **caller's frame** = old LB :
 - “Dynamic” because depends on where function was called from.
- **Static Link**: Base of underlying frame of function that **immediately lexically encloses** this one.
 - “Static” because depends on the program's structure and not on its execution.
 - Used to determine addresses of variables of lexically enclosing functions.

Example: Stack Allocation (1)

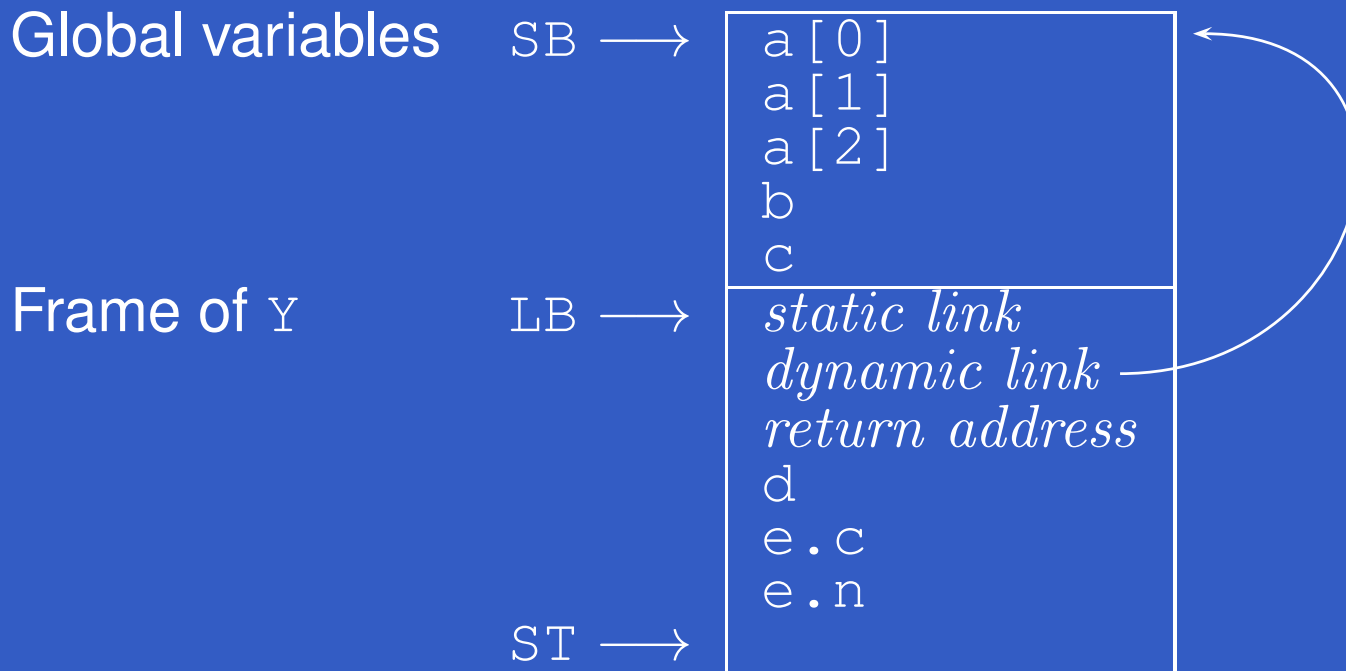
```
let
  var a: Integer[3];
  var b: Boolean;
  var c: Character;

  proc Y ()
    let
      var d: Integer;
      var e: record c: Character, n: Integer end
    in
      ...;
  proc Z ()
    let
      var f: Integer
    in
      begin ...; Y(); ... end
  in
    begin ...; Y(); ...; Z(); ... end
```

Example: Stack Allocation (2)

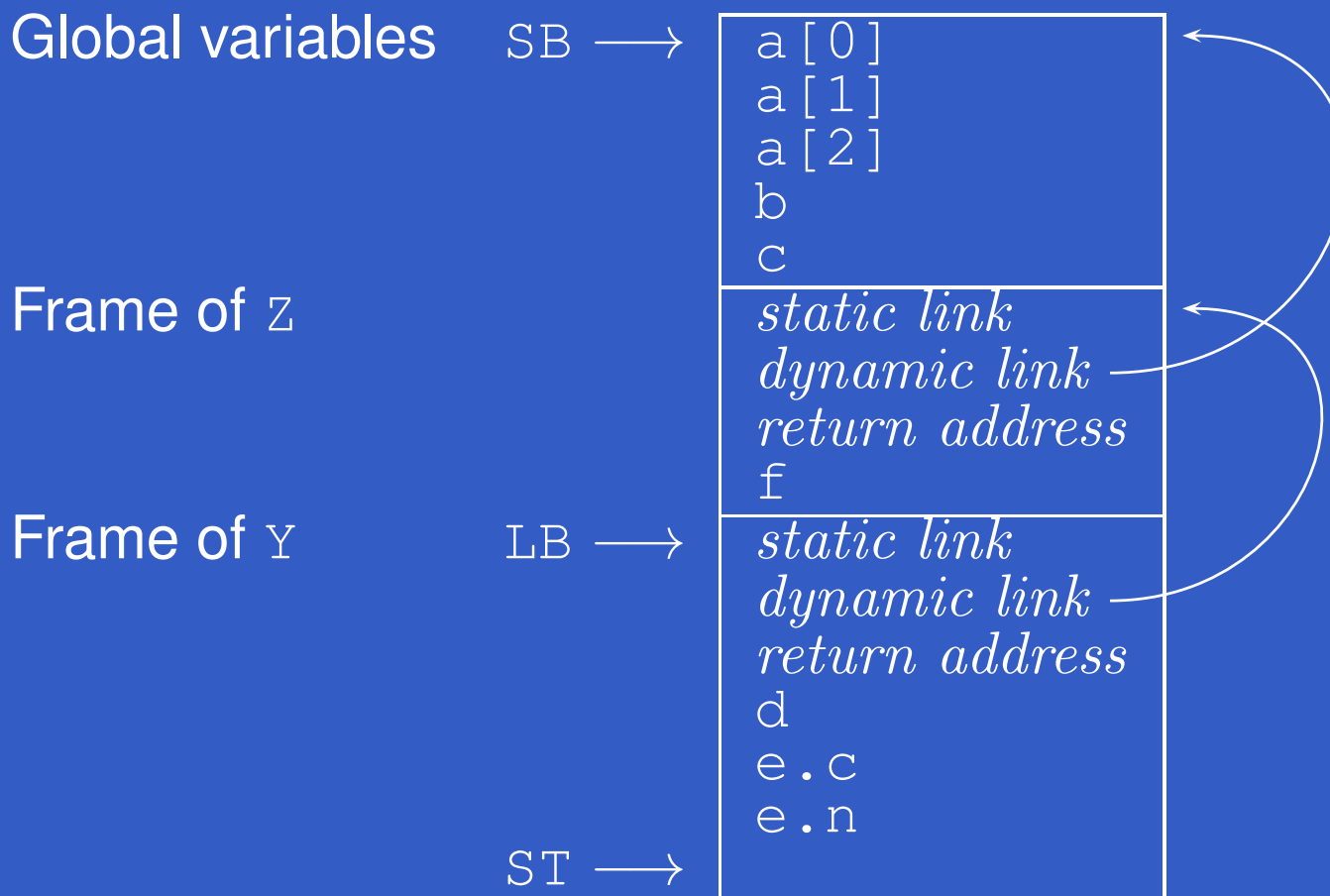
Initially $LB = SB$; i.e., the global variables constitute the frame of the main program.

Call sequence: $\text{main} \rightarrow Y$ (i.e. after main calling Y):

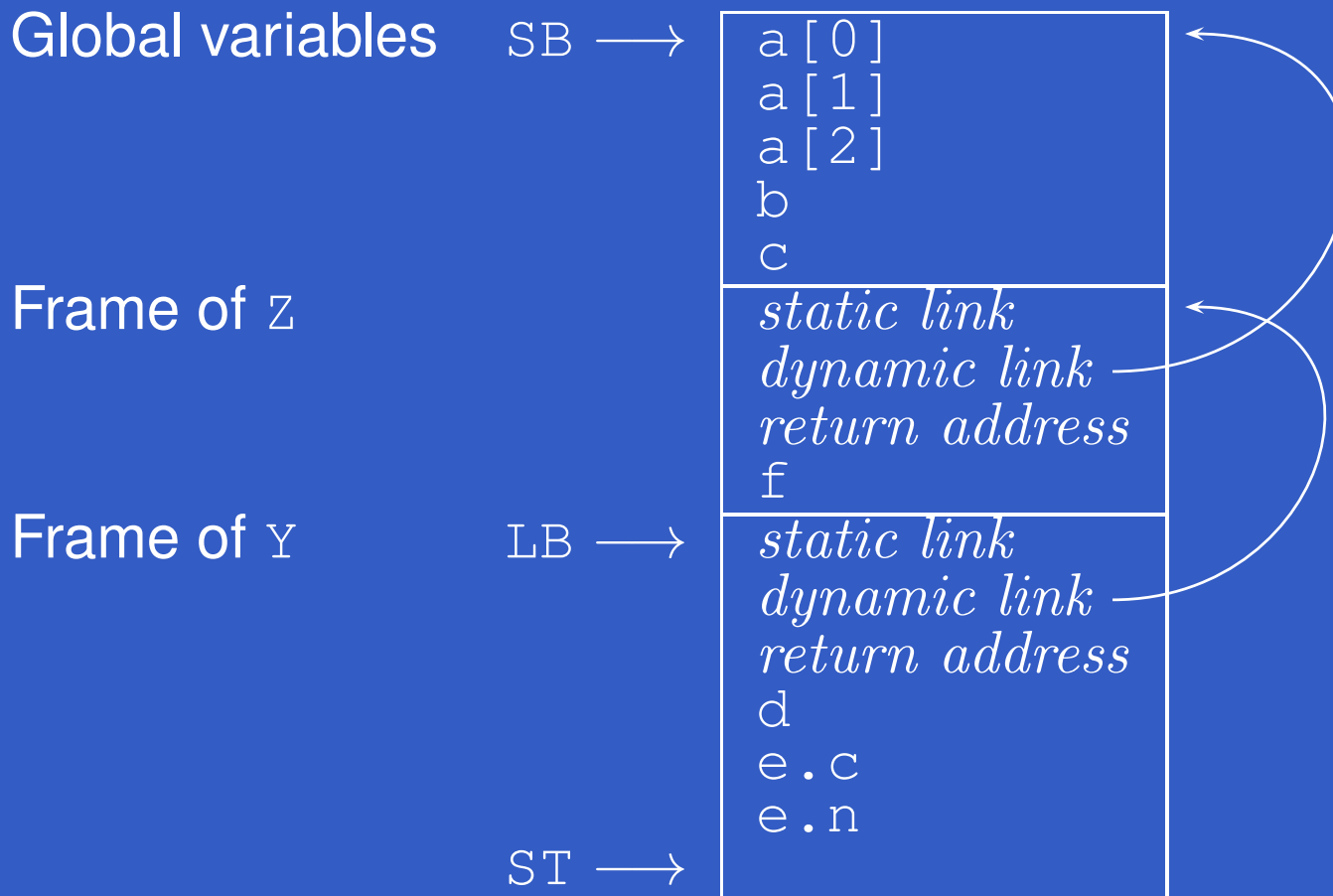


Example: Stack Allocation (3)

Call sequence: $\text{main} \rightarrow \text{Z} \rightarrow \text{Y}$:



Exercise: Stack Allocation



In Y, what is the address of: b? e.c? f?

Non-Local Variable Access (1)

Consider *nested* procedures:

```
proc P()  
  var x, y, z: Integer  
  proc Q()  
    ...  
    begin ... if ... Q() ... end  
  proc R()  
    ...  
    begin ... Q() ... end  
  begin ... Q() ... R() ... end
```

P's variables are in scope also in Q and R.

But how to access them from Q or R?

Neither global, nor local!

Belong to the *lexically enclosing procedure*.

Non-Local Variable Access (2)

In particular:

- We cannot access x , y , z relative to the stack base (SB) since we cannot (in general) statically know if P was called directly from the main program or indirectly via one or more other procedures.
- I.e., there could be arbitrarily many stack frames **below** P 's frame.

Non-Local Variable Access (3)

- We cannot access x , y , z relative to the local base (LB) since we cannot (in general) statically know if e.g. Q was called directly from P , or indirectly via R and/or recursively via itself.
- I.e., there could be arbitrarily many stack frames *between* Q 's and P 's frames.

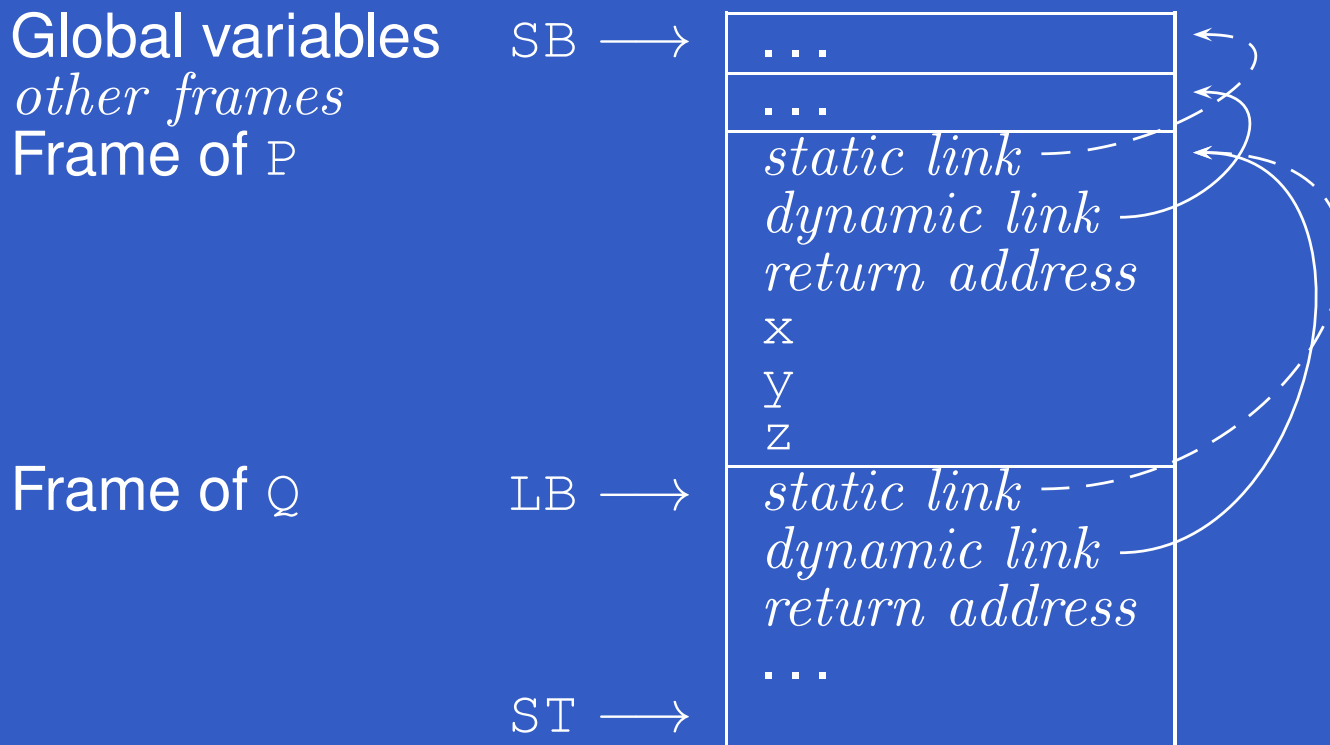
Non-Local Variable Access (4)

Answer:

- The **Static Links** in Q's and R's frames are set to point to P's frame on each activation.
- The static link in P's frame is set to point to the frame of **its** closest lexically enclosing procedure, and so on.
- Thus, by following the chain of static links, one can access variables at any level of a nested scope.

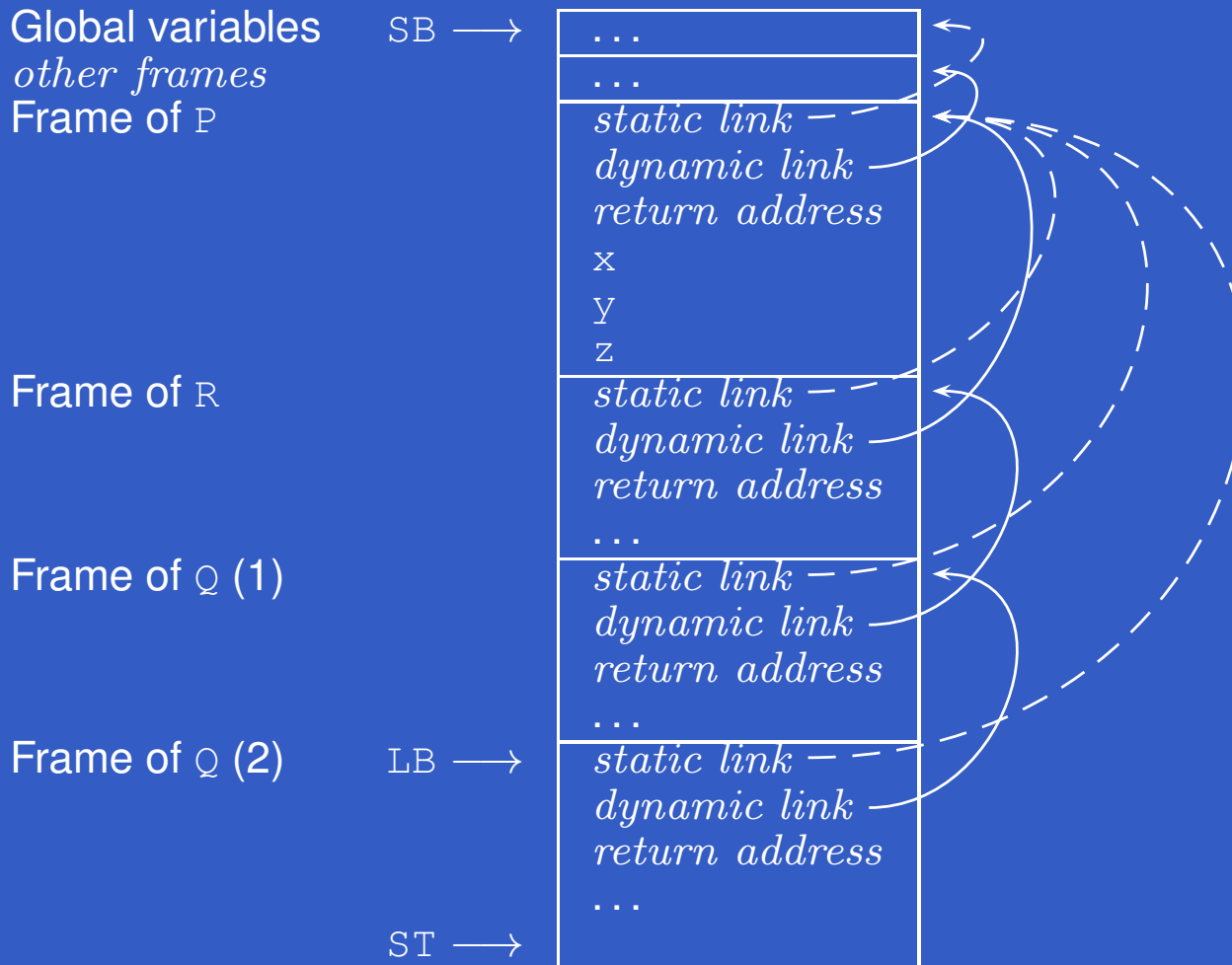
Non-Local Variable Access (5)

Call sequence: $\text{main} \rightarrow \dots \rightarrow P \rightarrow Q$:



Non-Local Variable Access (6)

Call sequence: $\text{main} \rightarrow \dots \rightarrow \text{P} \rightarrow \text{R} \rightarrow \text{Q} \rightarrow \text{Q}$:



Non-Local Variable Access (7)

Consider further levels of nesting:

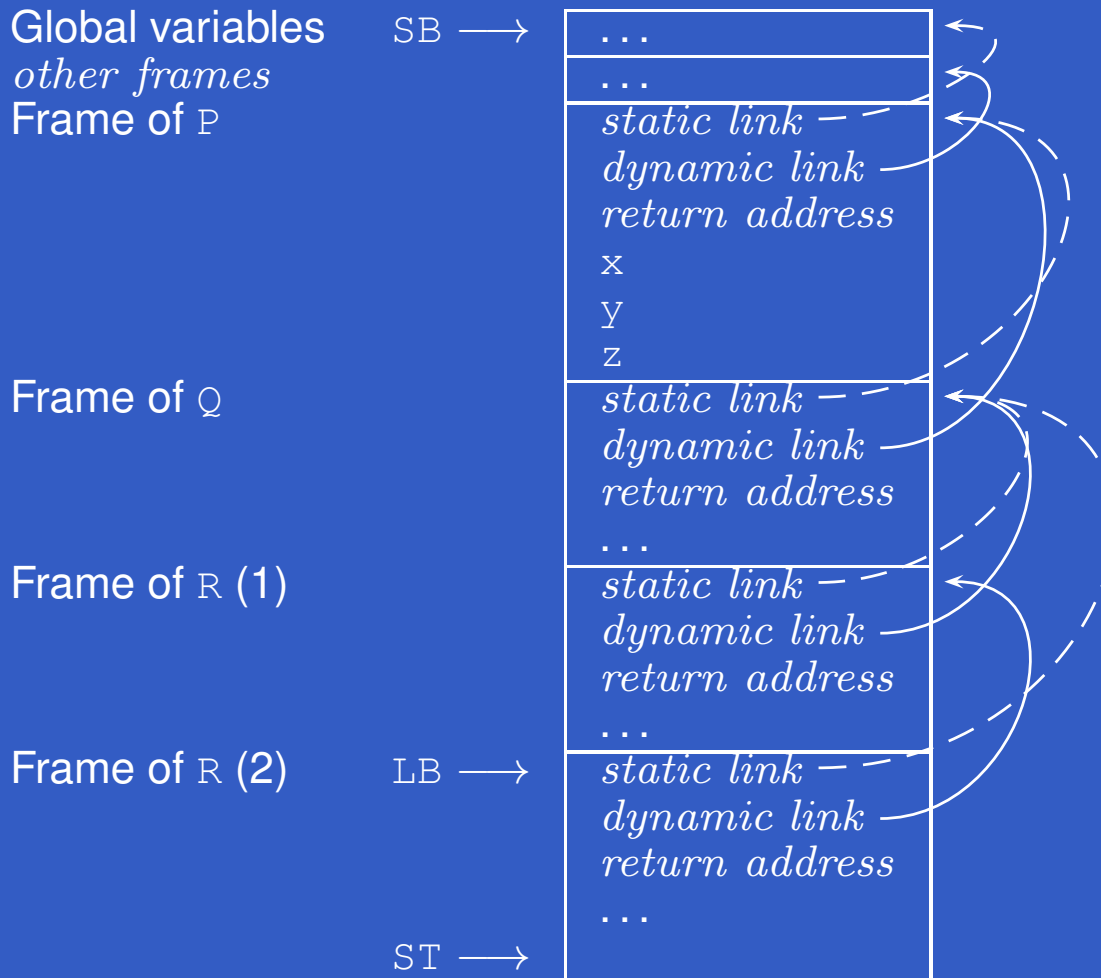
```
proc P()  
  var x, y, z: Integer  
  proc Q()  
    proc R()  
      ...  
      begin ...if ... R() ... end  
      ...  
    begin ... R() ... end  
  begin ... Q() ... end
```

Note: Q's variables now in scope in R.

To access, compute the **difference between scope levels** of the accessing procedure/function and the accessed variable (**note: static information**), and follow that many static links.

Non-Local Variable Access (8)

Call sequence: $\text{main} \rightarrow \dots \rightarrow P \rightarrow Q \rightarrow R \rightarrow R:$



Non-Local Variable Access (9)

TAM code, P calling Q: Q's static link = P's local base, pushed onto stack prior to call:

```
LOADA    [LB + 0]    ; Q's static link
LOADCA   #1_Q         ; Address of Q
CALLI
```

TAM code, R calling itself recursively: copy of R's static link (as calle's and caller's scope levels are the same) pushed onto stack prior to call:

```
LOAD     [LB + 0]    ; R's static link
LOADCA   #2_R        ; Address of R
CALLI
```

Non-Local Variable Access (10)

Accessing y in P from within R ; scope level difference is 2:

```
LOAD    [LB + 0]    ; R's static link
LOADI   0           ; Q's static link
LOADI   4           ; y at offset 4 in P's frame
```