

C:\Users\uberT\Desktop\cosc364-rip-assignment\Config_file_reader.py

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import sys

def readConfig(filename):
    file = open(filename, "r")
    lines = file.readlines()
    #stripping the newline character from each line
    for i in range(len(lines)-1): lines[i] = lines[i].strip()

    #most of the get functions return -1 when there is an error
    routerId = getRouterId(lines)
    if(routerId == -1):
        raise Exception("Router ID not specified or specified incorrectly")

    inputPorts = getInputPorts(lines)
    if(inputPorts == -1):
        raise Exception("Input ports not specified or specified incorrectly")

    outputPorts = getOutputPorts(lines, inputPorts)
    if(outputPorts == -1):
        raise Exception("Output ports not specified or specified incorrectly")

    #no error checking on timer values as it defaults to 30-180-120
    timerValues = getTimerValues(lines)

    file.close()
    return (routerId, inputPorts, outputPorts, timerValues)

def getRouterId(lines):
    #iterate through all lines for a valid parameter line
    for line in lines:
        try:
            line = line.split()
            #check if line is a valid router id then return the router id
            if(line[0] == "router-id" and 1 <= int(line[1]) <= 64000 and len(line) == 2):
                return int(line[1])
        except:
            #line treated as a comment and ignored
            buffer = 0
    #no properly formatted line found, return -1 as indication of error
    return -1

def getInputPorts(lines):
    #iterate through all lines for a valid parameter line
    for line in lines:
        try:
            line = line.split()
            #check if line is indicated as an input port parameter then check the ports are valid and add them to the input ports list
            if(line[0] == "input-ports"):
                inputPortsEstablished = True
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        inputPorts = []
        for i in line[1:]:
            if(1024 <= int(i) <= 64000 and int(i) not in inputPorts):
                inputPorts.append(int(i))
            else:
                inputPortsEstablished = False
                #if all the input ports are valid, return the input ports list
                if inputPortsEstablished: return inputPorts
        except:
            #line treated as a comment and ignored
            buffer = 0
        #no properly formatted line found, return -1 as indication of error
        return -1

def getOutputPorts(lines, inputPorts):
    #iterate through all lines for a valid parameter line
    for line in lines:
        try:
            line = line.split()
            #check if line is indicated as an output port parameter then check if
            the ports are valid and add them to the output ports list
            if(line[0] == "outputs"):
                outputPortsEstablished = True
                outputPorts = []
                for i in line[1:]:
                    outputPort = []
                    i = i.split("-")
                    if(len(i) == 3 and int(i[0]) not in inputPorts and 1024 <= int(
                    (i[0]) <= 64000 and 1 <= int(i[1]) <= 15 and 1 <= int(i[2]) <= 64000):
                        #have to iterate through outputPorts to check i isn't in it
                        since it is a 2D list
                        for j in outputPorts:
                            if(int(i[0]) == j[0]):
                                outputPortsEstablished = False
                                outputPort.append(int(i[0]))
                                outputPort.append(int(i[1]))
                                outputPort.append(int(i[2]))
                                outputPorts.append(outputPort)
                            else:
                                outputPortsEstablished = False
                        #if all the output ports are valid, return the output ports list
                        if outputPortsEstablished: return outputPorts
        except:
            #line treated as a comment and ignored
            buffer = 0
        #no properly formatted line found, return -1 as indication of error
        return -1

def getTimerValues(lines):
    #iterate through all lines for a valid parameter line
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    for line in lines:
        try:
            line = line.split()
            #check if line is indicated as a timer values parameter then return the
            #the timer values list if the timer values are valid
            if(line[0] == "timer-values"):
                timerValues = line[1].split("-")
                timerValues[0] = int(timerValues[0])
                timerValues[1] = int(timerValues[1])
                timerValues[2] = int(timerValues[2])
                #check timer ratios are correct
                if(timerValues[1] / timerValues[0] == 6 and timerValues[2] /
                timerValues[0] == 4 and len(timerValues) == 3):
                    return timerValues
            except:
                #line treated as a comment and ignored
                buffer = 0
        #no properly formatted line found, return the default values
        print("Timer values not specified or specified incorrectly, setting to default")
        return [30, 180, 120]

def main():

    routerId, inputPorts, outputPorts, timerValues = readConfig(sys.argv[1])
    print("Router ID:", routerId)
    print("Input Ports:", end=" ")
    for i in inputPorts: print(i, end=" ")
    print()
    print("Output Ports:", end=" ")
    for i in outputPorts: print(i, end=" ")
    print()
    print("Timer Values:", timerValues)

    inputSockets = createSockets(inputPorts)
    updateTimer, timeoutTimer, garbageTimer = timerValues
    incomingQueue = []

    while True:
        read, write, special = select.select(inputSockets, [], [])

        for i in read:
            try:
                addr, data = i.recvfrom(BUFFER_SIZE)
                incomingQueue.append((addr, data))
                print(incomingQueue.pop(0))
            except:
                print("Error recieving a packet")

        if need_periodic_update(next_update, updateTimer):
            # send update
```

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print("periodic update time")
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if __name__ == '__main__':  
    main()
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