

Planar Configuration Spaces of Disk Arrangements and Hinged Polygons

Clinton Bowen

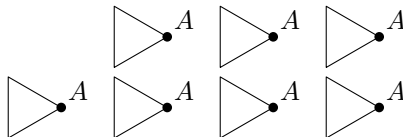
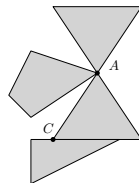
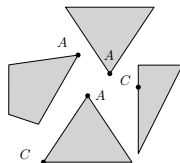
Cal State Northridge

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- * Motivations Slides
- * Related Work
- * Contribution
- * Logic Engine + Problem 1
- * Modified Auxiliary Construction + Problem 3
- * Conclusion

Motivation: Hinged Dissection

- * *Dudeney Problem*: Can a square and an equilateral triangle of the same area have a common dissection into four pieces?
- * Can finite collection of polygons of equal area has a common hinged dissection?



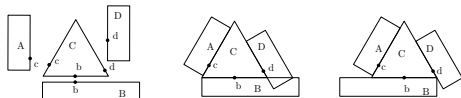
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Motivation: Protein Folding

Protein folding is the process in which a protein chain acquires its 3-dimensional structure.

- * Proteins in an organism fold into a specific geometric pattern (sometimes referred as its *native state*).
- * Geometric patterns can determine a protein's function and behavior.

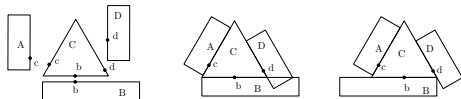


Deciding Realizability of Polygonal Linkages

Problem

What is the complexity of deciding whether a polygonal linkage whose hinge graph is a tree can be realized?

Bhatt and Cosmadakis showed realizability of linkages is NP-Complete.



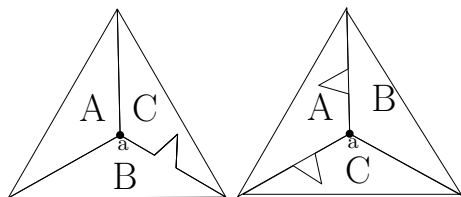
Deciding Realizability of Polygonal Linkages

Problem

What is the complexity of deciding whether a polygonal linkage whose hinge graph is a tree can be realized with fixed orientation?

Bhatt and Cosmadakis showed realizability of linkages is NP-Complete.

Here we have two realizations of a polygonal linkage with two different counter-clockwise order (C,B,A) and (B,C,A) respectively.

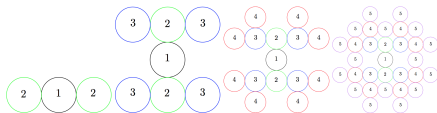


Deciding Realizability of Polygonal Linkages

Problem

What is the complexity of deciding whether a given ordered tree with positive vertex weights is the contact graph of a disk arrangements with specified radii?

Breu and Kirkpatrick proved that it is NP-Hard to decide whether a graph G is the contact graph of unit disks in the plane, i.e., recognizing coin graphs is NP-Hard



Contributions

Theorem

It is strongly NP-Hard to decide whether a polygonal linkage whose hinge graph is a tree can be realized.

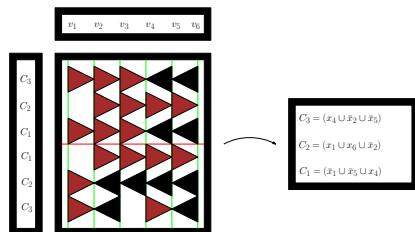
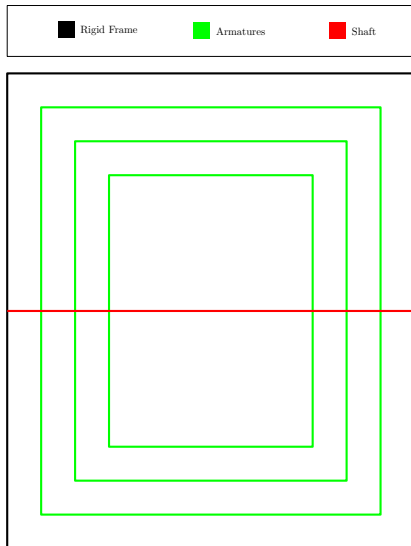
Theorem

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Theorem

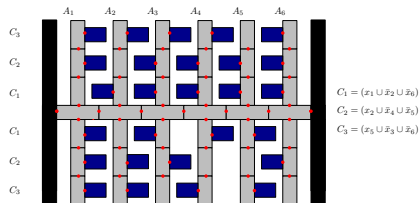
It is NP-Hard to decide whether a given ordered tree with positive vertex weights is the contact graph of a disk arrangement with specified radii.

The Logic Engine



Logic Engine Realized as Hinged Polygons

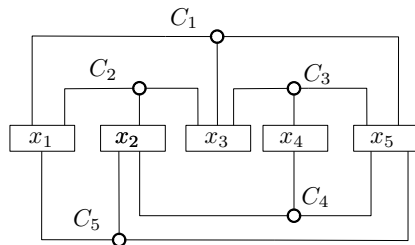
- * Suppose we are given an Boolean formula with m clauses and n variables in 3-CNF form, Φ , we construct the polygonal linkage similarly to the logic engine.



- * Breu and Kirkpatrick [?] proved that it is NP-hard to decide whether a graph G is the contact graph of unit disks in the plane, i.e., recognizing *coin graphs* is NP-hard; see also [?].

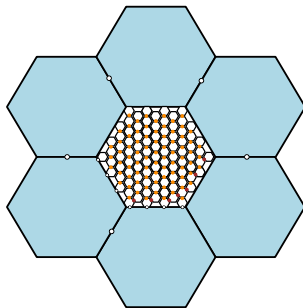
Planar 3SAT

- * Given a Boolean formula Φ in 3-CNF such that its associated graph is $A(\Phi)$, decide whether it is satisfiable is a *3-SAT problem*.



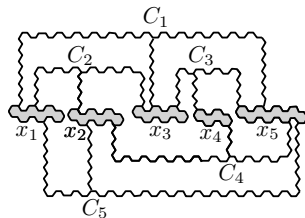
Modified Auxiliary Construction

- * Define the *associated graph* $A(\Phi)$ as follows: the vertices correspond to the variables and clauses in Φ . We place an edge in the graph if variable x_i appears in clause C_j .
- * Given a Boolean formula Φ in 3-CNF such that its associated graph is planar, decide whether it is satisfiable is a *3-SAT problem*.



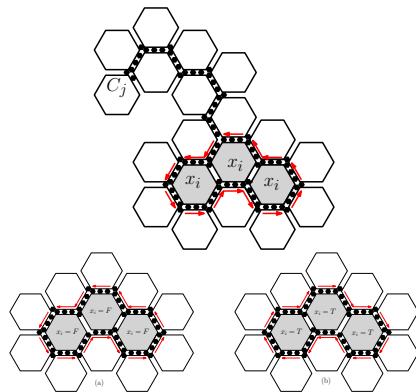
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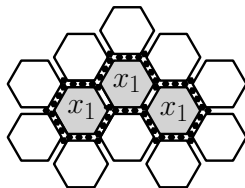
Transmitter Gadget

- * A *transmitter gadget* is constructed for each edge $\{x_i, C_j\}$ of the graph $A(\Phi)$; it consists of a sequence of junctions and corridors from a variable gadget's junction to a clause gadget.



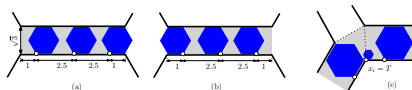
Variable Gadget

- * Variable x_i corresponds to a cycle in the associated graph $\tilde{A}(\Phi)$.



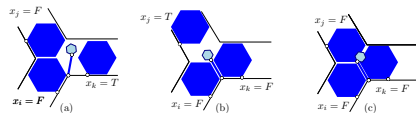
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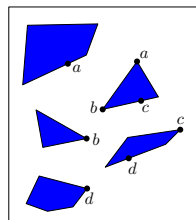
Clause Junction Gadget

- * The *clause gadget* lies at a junction adjacent to three transmitter gadgets.x

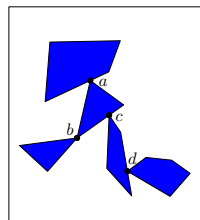


Motivation: Weighted Trees and Disk Arrangements

- * Is it strongly NP-hard to decide whether a polygonal linkage whose hinge graph is a *tree* can be realized?
- * Is it NP-Hard to decide whether a given ordered tree with positive vertex weights is the contact graph of a disk arrangements with specified radii?



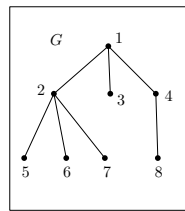
(a)



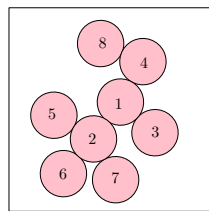
(b)

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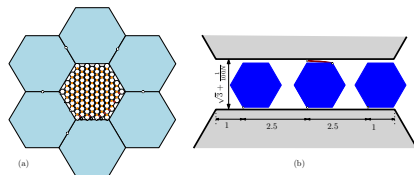
(a)



(b)

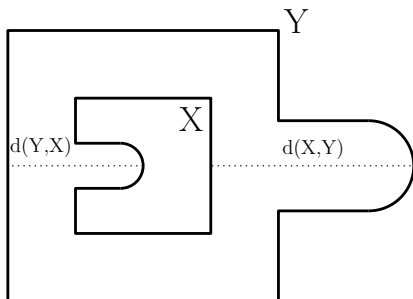
Modified Auxiliary Gadget

- * The modified auxiliary gadget channels and junctions in a hexagonal grid enclosed by six frame hexagons.
- * A comment about NAE3SAT....



Approximation of Hexagon with a Disk Arrangement: Hausdorff Distance

- * An illustrative example of $d(X, Y)$ and $d(Y, X)$ where X is the inner curve, and Y is the outer curve.



Approximation of Hexagon with a Disk Arrangement

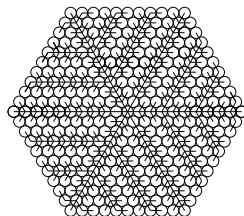
Lemma

For every $\epsilon > 0$ and $x > 0$, there exists an ordered weighted tree T and regular hexagon h of side length x such that:

- * Every realization σ_i of T as an ordered disk contact graph where the radii of the disks equal the vertex weights, approximates the hexagon in the sense that:*

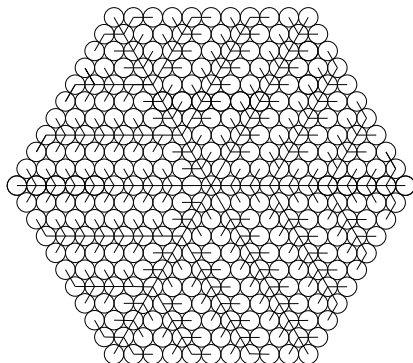
$$H(h, \sigma) \leq \epsilon$$

- * The number of nodes in T and the weights are polynomial in ϵ and x , the weights $\frac{\epsilon}{10}$ and $\frac{\epsilon}{10} + \zeta$ are polynomial.*



Approximation of Hexagon with a Disk Arrangement

- * A drawing of a tree T overlaid with a corresponding disk arrangement, each disk with unit radius.
- * The nodes of the tree are the centers of the disks.



Conclusion

Thank You!