

Practical Python - Internet of Things

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Outline

Introduction

Installation

Circuits

Resources

Introducing MicroPython

- ▶ Python for microcontroller boards
- ▶ Started as a Kickstarter
- ▶ All Open Source

Introducing the ESP8266

- ▶ 80MHZ processor
- ▶ lots of GPIO (General Purpose Input/Output) pins
- ▶ Digital interfaces
- ▶ One Analogue
- ▶ Wifi
- ▶ Cheap
- ▶ reasonably well documented (now)

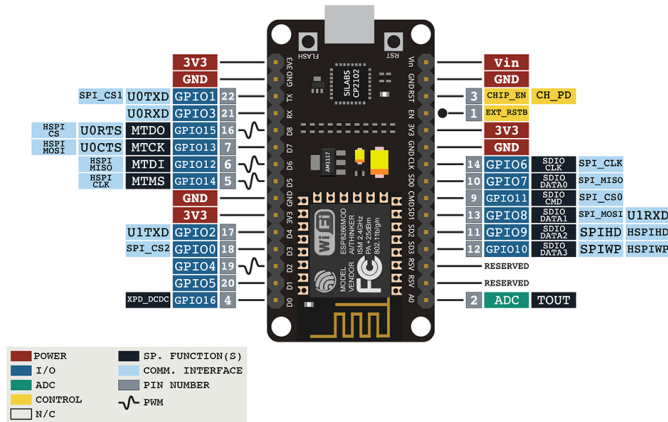
ESP8266 Development Board

Pin Mapping

ESP-12E DEVELOPMENT BOARD PINOUT

NOTES:

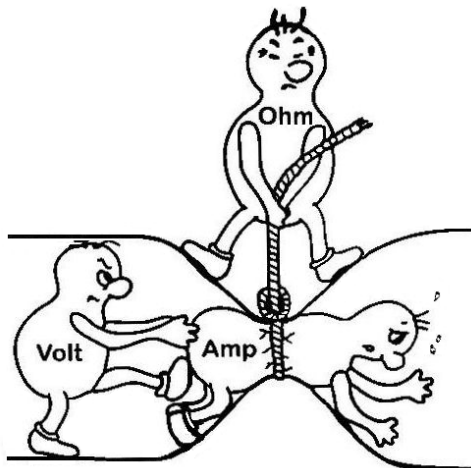
- ▲ Typ. pin current 6mA (Max. 12mA)
- ▲ For sleep mode, connect GPIO16 and EXT_RSTB. On wakeup, GPIO16 will output LOW for system reset.
- ▲ On boot/reset/wakeup, keep GPIO15 LOW and GPIO2 HIGH.



Micropython	Board
0	D3
2	D4 (also Led1 but inverse)*
4	D2
5	D1
9	SD2
10	SD3
12	D6
13	D7
14	D5
15	D8
16	D0 (also Led2 but inverse)*

Introduction to Electricity

- The water analogy



<http://www.electricalonline4u.com/2015/10/ohm-law-explanation-guide.html>

Installation

- Install Python, e.g. <http://anaconda.org>
- Install esptool

```
> pip install esptool
```

- Clear flash memory

```
> esptool.py --port /dev/ttyUSB0 erase_flash
```

- Download MicroPython
<http://github.com/micropython/micropython/releases>
- Flash board

```
> esptool.py --port /dev/ttyUSB0 --baud 460800 write_flash  
--flash_size=detect 0 ~/Downloads/esp8266-$version.bin
```

Setup

- ▶ Connect to the board
- > `screen /dev/ttyUSB0 115200`
 - ▶ Hit enter!
 - ▶ Work out WIFI name
- > `import network`
- > `ap = network.WLAN(network.AP_IF)`
- > `ap.config("ssid")`
 - ▶ Write this down!
 - ▶ Turn on the Web Server
- > `import webrepl_setup`
 - ▶ Follow the prompts. Pick a simple password.
 - ▶ Turn on Web Server
 - ▶ Reboot...
 - ▶ Connect to Board, password is micropython

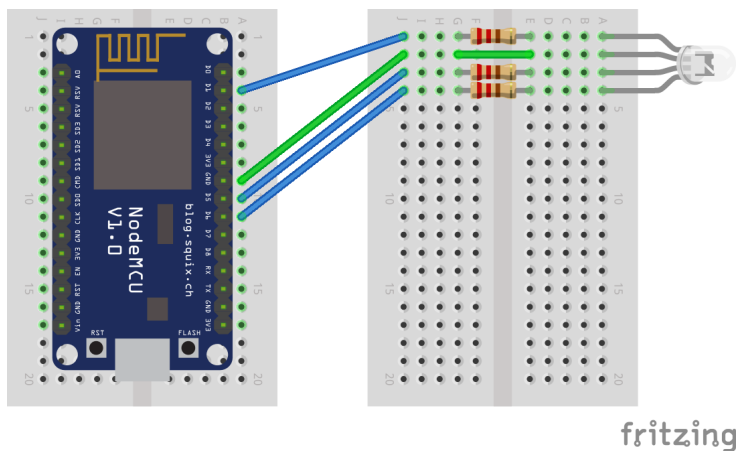
Look Around

- ▶ Micropython implements a filesystem, just like a computer.

```
> import os
> os.listdir()
```

RGB LED Layout

Red/Green/Blue Light Emitting Diode



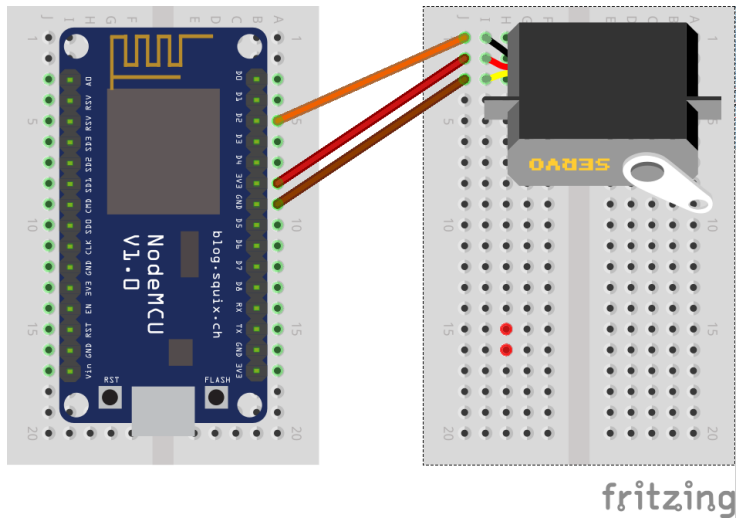
RGB LED Code

Pulse Width Modulation

```
> from machine import Pin, PWM
> r = PWM(Pin(4), freq=500, duty=0)
> g = PWM(Pin(12), freq=500, duty=0)
> b = PWM(Pin(14), freq=500, duty=0)
>
```

Servo Layout

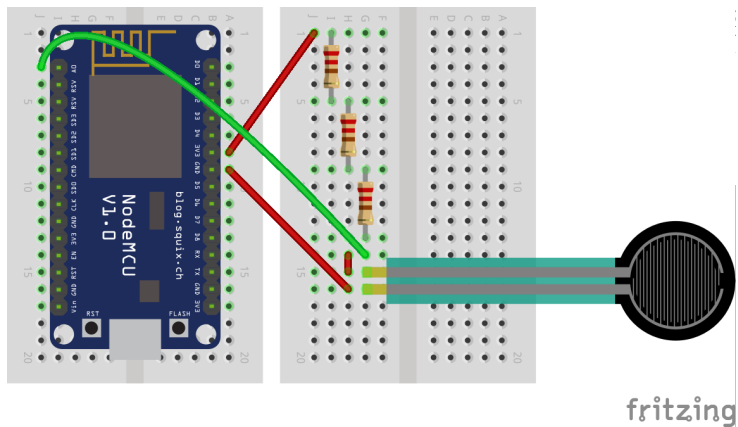
- ▶ Orange - PWM
- ▶ Red - +V
- ▶ Brown - Ground



Servo Code

```
> from machine import Pin, PWM  
> s = PWM(Pin(14), freq=50, duty=0)
```

Force Sensor Layout

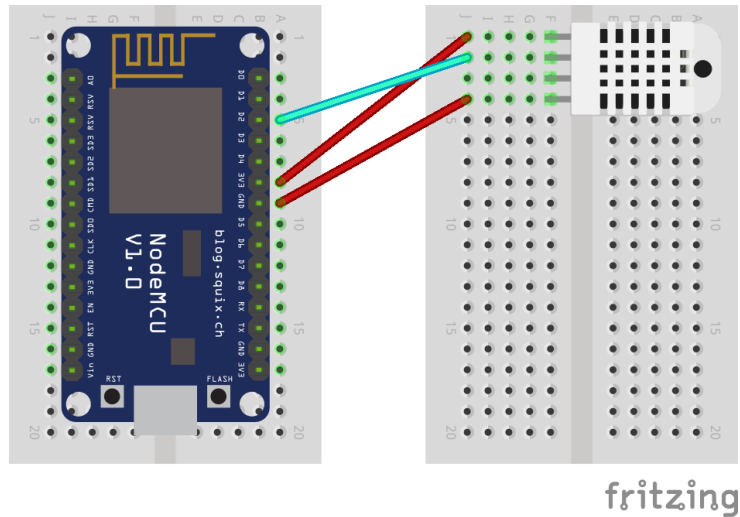


Force Sensor Code

- ▶ Analogue to Digital Converter

```
> from machine import ADC  
> adc = ADC(0)  
> adc.read()
```

Temperature Sensor Layout



Temperature Sensor Code

```
> import dht
> import machine
> d = dht.DHT11(machine.Pin(4))
>
> # Only once a second.
> d.measure()
> d.temperature()
> d.humidity()
```

Stand Alone Mode

- ▶ Special files:
 - ▶ boot.py, main.py
- ▶ Wifi

```
> import network
> n = network.WLAN(network.STA_IF)
> n.active(True)
> n.connect("slqwireless")
> n.isconnected()
> n.ifconfig()
```

Resources

- ▶ These notes: Copyright © 2017 Clinton Roy
 - ▶ <https://github.com/clintonroy/slq2017python> © ⓘ
- ▶ <https://docs.micropython.org/en/latest/esp8266/esp8266/tutorial/>
- ▶ <http://fritzing.org/>