Yi Zhang

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EDUCATION

2023 -	Doctor of Philosophy(DPhil), Tianjin University, China
	Advisor: Tao Sun (<u>Page</u>) Research Focus: Intelligent Design of Robotic Mechanisms
	Research Focus: Intelligent Design of Robotic Mechanisms
2019 -	Bachelor of Engineering (BEng), Tianjin University, China
2023	Double Major in Intelligent Manufacturing Engineering; and in Computer Science
	Thesis: Design, Control, and Dynamic Identification of Aerial Refueling Robot
	Thesis: Intelligent Content Generation for Social Media Opinion Dissemination

PROJECTS & COURSEWORK

2024 -	Integrated Design of Robot Topology-Scale-Control Independently conducted research on Reinforcement Learning, Graph Neural Networks and Genetic Algorithms
2024 -	Multimodal Model Fine-tuning for Robot Image Interpretation and Topology Analysis Independently conducted research on fine-tuning multimodal large models and designing chain-of-thought reasoning processes.
2023 - 2024	Robot Design Foundation Model Responsible for Graph Neural Networks, Model Evaluation, and Dataset Construction
2022 - 2023	Undergraduate Innovation and Entrepreneurship Project, Provincial Level Reconfigurable Mobile Robot Based on Tensegrity Structures (Team Leader)
2021 - 2022	Undergraduate Innovation and Entrepreneurship Project, Provincial Level Design and Control of a Cable-Driven Multi-Modal Mobile Robot (Team Leader)
2022	Autonomous Mobile Sorting Robot Responsible for Gripper Design, Navigation, and Path Planning
2021	Quadruped Mobile Robot Responsible for Mechanism Design

AWARDS

2024	Second Prize, 21st China Postgraduate Mathematical Contest in Modeling
2024	Third Prize, 6th China Postgraduate Artificial Intelligence Innovation Contest
2023	Outstanding Graduate Award of Tianjin University
2022	First Prize, National College Student Mechanical Innovation Design Competition
2022	3rd Place, ASME Student Design Competition (SMRDC)
2021	National Scholarship
2021	Top 10 Outstanding Youth (Student), School of Mechanical Engineering, Tianjin
_	University
2020	Meritorious Winner, Mathematical Contest in Modeling (MCM)
2020	National Scholarship

PUBLICATIONS

- [1] Yang, Q., Hu, K., Zhang, Y., Lian, B., & Sun, T. (2024). Design and experiment of multi-locomotion tensegrity mobile robot. Mechanism and Machine Theory, 198, 105671.
- [2] Hu, K., Zhang, Y., Bu, Q., Wang, Z., Dong, Y., & Lian, B. (2022). Low-Actuation, Multi-DOF Resettable Gear Transmission Device (Patent Application No. CN202210512755.4). Tianjin University. China: National Intellectual Property Administration. Publicly disclosed under Publication No. CN115111337A on September 27, 2022.
- [3] <u>Zhang, Y.</u> Design and Experiment of a Continuum Robot Based on Tensegrity Structures. Manuscript in Preparation.