1. Using direct integration to calculate the following convolutions (Don't use the convolution table):

1).
$$e^{-at}u(t)*e^{-bt}u(t)$$

2).
$$tu(t) * u(t)$$

2. Please use the **convolution table** to calculate following convolutions:

1).
$$e^{-2t}u(t)*(1-e^{-t})u(t)$$

2).
$$[\cos(5t) - e^{-t}]u(t) * \delta(2-t)$$

3).
$$e^{-(t-3)}u(t-3)*[e^{-2(t-1)}-e^{-(t-1)}]u(t-1)$$

3. The unit impulse response of an LTIC system is $h(t) = e^{-t}u(t)$. Please use the **convolution table** to find the zero-state response y(t) if the input is:

1).
$$x(t) = \delta(t-5)$$
;

2).
$$x(t) = (t+4)u(t+4)$$
;

3).
$$x(t) = e^{-2(t-1)}u(t-1) + \sin(3t)u(t)$$