Raspberry Pi Lab 1.2
Autonomous Servo motion
ECE/BME 296

Program the servo to sweep back and forth. In future labs we will mount an ultrasonic sensor to the servo. The servo should move 45° per step (i.e. 0°, 45°, 90° 135°, 180°, 135°, 90°, 45°, 0°...) and repeat until the program is terminated.