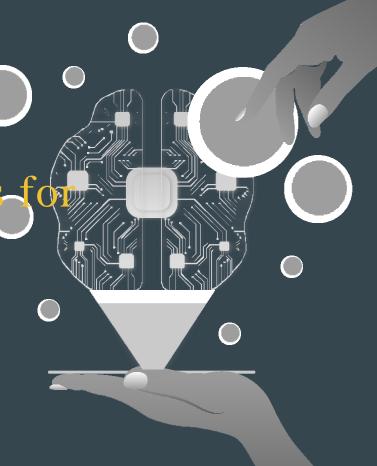
Evaluation of AI Strategies f

Blackjack

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Blackjack is one of the most classic card games in the casino. Since this game has remained popular in casinos for such a long time, it is evident that the dealer usually has a higher winning probability than the player. This observation sparks our curiosity: Are there any strategies that can help players perform better in this game?



The goal is to implement and test various AI agent to observe the winning rate for players under different methods. The strategies we investigate include, Random selection, Basic Strategy, Expectimax, Random Forest Classifier (RFC), and NeuroEvolution of Augmenting Topologies (NEAT). Through these experiments, we aim to answer the following questions: How does the player's win rate vary under different agents? Does the different number of decks affect the win rate? Are the casino's rules inherently designed to favor the dealer?

((DI)

Objectives

Analyze two published ML-based Blackjack strategies

Implement a minimax (Expectimax) based strategy

Implement an AI agent and compare the methods

Identify the most effective AI approach

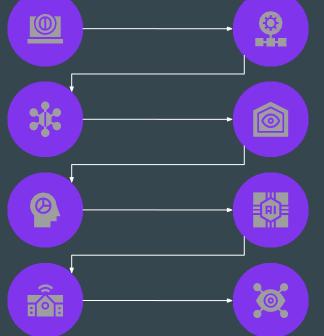
Timeline_

Justin Bodnar's Al Model

Our Contribution

Reflect Agent Classifier (RFC)

Expectimax

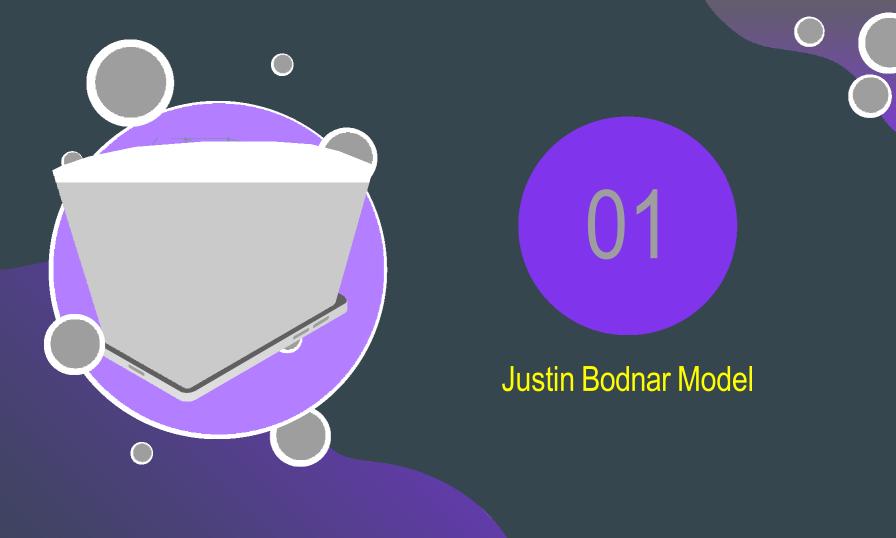


Mason Lee Model

Random and Basic Strategy

Baseline-NeuroEvolution of Augmenting Topologies (NEAT)

Result and Analysis





Goal of the Model

The goal of Bodnar's model is to train network that mimics a basic blackjack strategy that has:

- Input: Information regarding the current game state (e.g., player's hand value)
- Output: Decision to hit or stay.



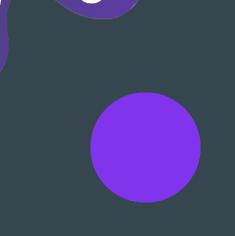
Model Architecture

The model proposed uses Monte Carlo simulations of Blackjack games to create training data.

The model runs on a neural network:

- Level $1 \rightarrow Player$ and hand value
- Level 2 →Player hand + dealer's face-up card
- Level 3 →All card seen







Goal of the Model

The goal of this project is to train an AI agent to play Blackjack by evolving its decision-making strategy using NEAT (NeuroEvolution of Augmenting Topologies).

input: Current game state (player's hand, dealer's visible card, usable ace info, etc.)
Output: AI decides action: hit, stand, double

Model Architecture

Evolve neural networks based on fitness (win rate, performance)

- 1 →Initialize game
- 2 → Player decision making
- 3 → Dealer logic
- 4 → Determine result



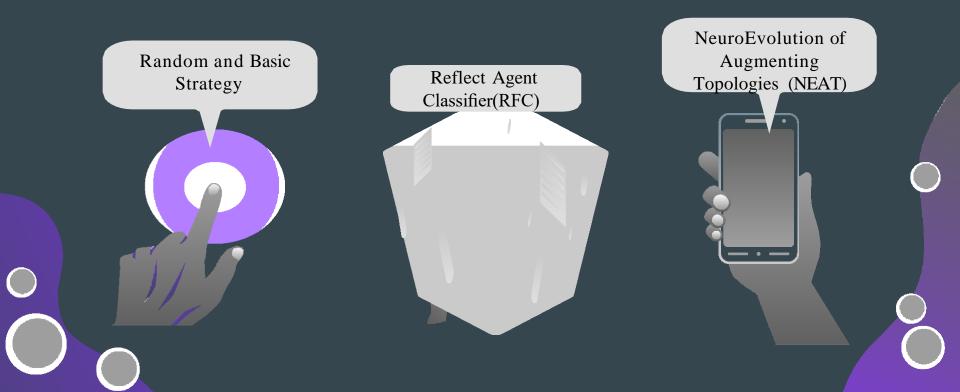


- Implement Agent/ Training /Compare Win Rate of multiple AI strategies

(Random, Basic, RFC, NEAT)

- Implement these AI agents into an application about Blackjack

AI Strategies;



Baseline-Random and Basic Strategy

The Random Agent makes decisions purely based on randomness. At each decision point, the agent randomly chooses between two actions: Hit/Stand

The Basic Strategy Agent strictly follows the static Blackjack decision table from the

B.2. One Up-Card. The following table give the basic strategy for the one up-card variation played using one deck.

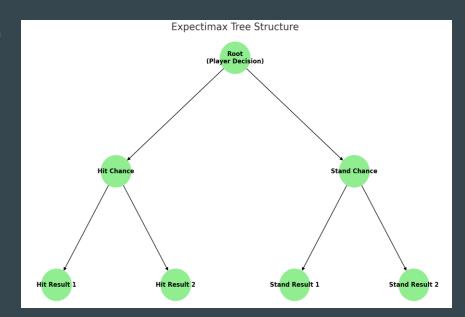
| Dealer Player | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |
|------------------|----|----|----|---|----|---|---|----|----|----|
| Hard 4 - 12 | Н | Н | Н | Н | Н | Н | Н | Н | Н | Н |
| Hard 13 | Н | Н | Н | Н | H* | Н | Н | Н | Н | Н |
| Hard 14 | S* | H* | H* | S | S | Н | Н | Н | Н | Н |
| Hard 15 | S | S | S | S | S | Н | Η | Н | Н | Н |
| Hard 16 | S | S | S | S | S | Η | Н | H* | H* | S |
| Hard 17 - 20 | S | S | S | S | S | S | S | S | S | S |
| Soft 12 - 16 | Н | Н | Н | Н | Н | Н | Н | Н | Н | Н |
| Soft 17 | S | S | S | Н | Н | Η | Н | Н | Н | Н |
| Soft 18 | S | S | S | S | S | S | S | Н | S | S |
| Soft 18 - 20 | S | S | S | S | S | S | S | S | S | S |

Table 7. Basic strategy for the one up-card variation (single deck). The * signifies that the optimal decision depends on the specific layout given this hand total.

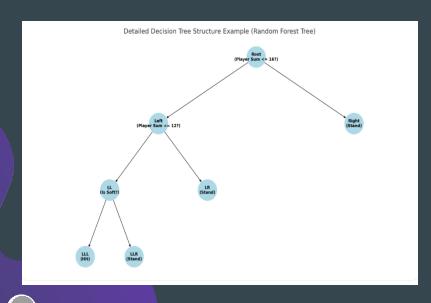
Baseline-Expectimax

- Build the Game Tree
 Max nodes for player's choices (Hit/Stand)
 Chance nodes for random events (card draws)
- Evaluate Leaf Nodes
 Calculate terminal state values (win, lose, draw scores).
- Backpropagate Values
 Max nodes: Choose the maximum value.
 Chance nodes: Compute the expected value (weighted average of outcomes).
- Choose Optimal Action

 At the root, pick the action with the highest expected value.



Baseline-Random Forest Classifier (RFC)



- 1. Bootstrap Sampling: Randomly sample the training data with replacement to create a new dataset for each tree.
- 2. Feature Subset Selection: At each node split, randomly select a subset of features.
- 3. Tree Construction: Grow each decision tree to the maximum depth or until a stopping condition is met
- 4. Ensemble Prediction: For a new input, get predictions from all trees and use majority voting for classification.
- 5. Final Output: Return the majority class (classification) or average prediction (regression).

Baseline-NeuroEvolution of Augmenting Topologies (NEA

| Step | Action | | | |
|-----------------|--|--|--|--|
| Initialize | Create random, simple networks | | | |
| Fitness Eval | Run network → get fitness score | | | |
| Speciation | Group by genetic distance (innovation #) | | | |
| Fitness Sharing | Divide fitness within species | | | |
| Select Parents | Based on adjusted fitness | | | |
| Crossover | Align by innovation #, combine genes | | | |
| Mutation | Adjust weights, add nodes/connections | | | |
| New Generation | Offspring + elite genomes | | | |

Main Approach-AI Agent and Training Process

- Random Agent
 At each decision step, randomly selects Hit or Stand.

 No learning, no logic.
- Basic Strategy Agent
 Follows Blackjack basic strategy table, derived from the reference paper.
 Rules include:

| Dealer Player | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 |
|------------------|----|----|----|---|----|---|---|----|----|----|
| Hard 4 - 12 | Н | Н | Н | Н | Н | Н | Н | Н | Н | Н |
| Hard 13 | Н | Н | Н | Н | H* | Н | Η | Н | Н | Н |
| Hard 14 | S* | H* | H* | S | S | Н | Н | Н | Н | Н |
| Hard 15 | S | S | S | S | S | Н | Η | Н | Н | Н |
| Hard 16 | S | S | S | S | S | Н | Н | H* | H* | S |
| Hard 17 - 20 | S | S | S | S | S | S | S | S | S | S |
| Soft 12 - 16 | Н | Н | Н | Н | Н | Н | Н | Н | Н | Н |
| Soft 17 | S | S | S | Н | Н | Н | Н | Н | Н | Н |
| Soft 18 | S | S | S | S | S | S | S | Н | S | S |
| Soft 18 - 20 | S | S | S | S | S | S | S | S | S | S |

```
def act(self, player sum, dealer card, is soft, num cards):
    if is_soft:
        if 12 <= player sum <= 16:
        elif player sum == 17:
        elif player_sum == 18:
           if dealer in [2, 7, 8]:
        elif player_sum >= 19:
        if 4 <= player_sum <= 8:</pre>
        elif player_sum == 9:
            if dealer in [3,4,5,6]:
        elif player sum == 10:
```

Purely rule-based, no learning.

Main Approach - Environment Code

- Deck Generation and Shuffling (reset_deck)
 Generates multiple decks of standard 52-card playing cards (1=A, 11=J, 12=Q, 13=K) and shuffles them randomly.
- Game Initialization (reset)

 At the start of each round, deals two cards to the player and one upcard to the

dealer, and resets the game state.

Main Approach - Environment Code

Game State Representation (get_obs)

Outputs player state features at each step, including:

Player total sum (player_sum)

Soft hand status (is_soft)

Dealer upcard (dealer_card)

Number of player cards (num_cards)

• Player Action Handling

```
def get_obs(self):
    player_sum, is_soft = self.hand_value(self.player_hand)
    dealer_card = min(self.dealer_hand[0][0], 10)
    num_cards = len(self.player_hand)
    return {
        "player_sum": player_sum,
        "dealer_card": dealer_card,
        "is_soft": int(is_soft),
        "num_cards": num_cards
}
```

```
def player hit(self):
    if self.done:
        return self.get_obs(), "game_over", True
    self.player_hand.append(self.draw_card())
    player_sum, _ = self.hand_value(self.player_hand)
    if player sum > 21:
        self.done = True
        return self.get_obs(), "lose", True
    return self.get obs(), None, False
def player stand(self):
    return self.get_obs(), None, False
def dealer_draw_one(self):
    if self.done:
    self.dealer_hand.append(self.draw_card())
    return self.dealer_is_done()
def dealer is done(self):
    dealer sum, dealer soft = self.hand value(self.dealer hand)
    if dealer sum >= 17 and not (dealer sum == 17 and dealer soft):
        self.done = True
```

Players can choose "hit" or "stand"; the system updates the game state accordingly:

If "hit", draw a card and update the state.

If "stand", the dealer plays automatically following standard rules (stop at 17 or higher unless it's a soft 17).

Game Result Evaluation (get_game_result)

Compares player and dealer final hands to determine the outcome: win / lose / draw.

Main Approach-Expectimax Agent

Objective:

Compare expected outcomes of 'Hit' and 'Stand' to decide optimal move.

Approach:

- 1st Loop (Stand):
 - Loop through all dealer possible values (2–11).
 - If dealer < 17, assume dealer draws to 17.
 - Compute difference: Agent Value - Dealer Value
 - Accumulate differences to get Stand EV.

• 2nd Loop (Hit):

- Agent draws all possible cards (excluding dealer's card).
- Add drawn card to agent's hand.
- Re-run 1st loop logic for each new agent value.
- Accumulate differences to get Hit EV.

• Final Decision:

- Compare averages:
 Hit EV vs Stand EV
- Choose the action with the higher expected value.

Main Approach – Random Forest Classifier (RFC)

- Training Process (train_rfc_agent.py):
- Data Source: blackjack_simulator.csv
- Features: player_sum, dealer_card, is_soft, num_cards
- Label: 0=Hit, 1=Stand

```
df = pd.read_csv("blackjack_simulator.csv", nrows=500000)
X, y = [], []
for idx, row in tqdm(df.iterrows(), total=len(df), desc="Processing Data"):
        hand = ast.literal eval(row['initial hand'])
        actions = ast.literal eval(row['actions taken'])[0]
        for action in actions:
            player_sum = sum(hand)
            is_soft = int(11 in hand and player_sum <= 21)</pre>
            features = [player_sum, int(row['dealer_up']), is_soft, len(hand)]
            label = 0 if action == 'H' else 1
            X.append(features)
            y.append(label)
            if action == 'H':
                hand.append(random.choice([2,3,4,5,6,7,8,9,10,11]))
    except:
```

Main Approach – Random Forest Classifier (RFC)

Training Process (train_rfc_agent.py):
Random Forest Training Logic

- Train multiple decision trees (default: 5 trees, max depth 5) using Bagging for diversity.
- Each tree is trained on a bootstrap sample (random subset with replacement). Decision trees are built recursively:
 - 1. Use Gini impurity to find the best split.
 - 2. Create left/right branches until max depth or pure leaf.

```
def _build_tree(self, X, y, depth):
    if depth >= self.max_depth or len(set(y)) == 1:
        return int(Counter(y).most_common(1)[0][0])
    feature, threshold = self._best_split(X, y)
    if feature is None:
        return int(Counter(y).most_common(1)[0][0])
    left_mask = X[:, feature] <= threshold</pre>
    right mask = ~left mask
         'feature': int(feature).
        'threshold': float(threshold),
        'left': self._build_tree(X[left_mask], y[left_mask], depth+1),
        'right': self. build tree(X[right mask], y[right mask], depth+1)
def predict_one(self, x, node=None):
        node = self.tree
    if not isinstance(node, dict):
        return node
    if x[node['feature']] <= node['threshold']:</pre>
        return self.predict one(x, node['left'])
        return self.predict_one(x, node['right'])
def predict(self, X):
    return np.array([self.predict one(x) for x in X])
    self.n_trees = n_trees
    self.max depth = max depth
    self.trees = []
def fit(self, X, y):
    self.trees = []
    for _ in tqdm(range(self.n_trees), desc="Training Trees"):
        indices = np.random.choice(len(X), len(X), replace=True)
        tree = DecisionTree(self.max depth)
        tree.fit(X[indices], y[indices])
        self.trees.append(tree)
def predict(self, X):
    all preds = np.array([tree.predict(X) for tree in self.trees])
    final preds = []
    for i in range(X.shape[0]):
        votes = all_preds[:, i]
```

final_preds.append(int(Counter(votes).most_common(1)[0][0]))

return np.array(final_preds)

```
def __init__(self, max_depth=5):
    self.max_depth = max_depth
    self.tree = None
    self.tree = self. build tree(X, y, depth=0)
def gini(self, y):
    counts = Counter(y)
    impurity = 1.0
    for label in counts:
        prob = counts[label] / len(y)
        impurity -= prob ** 2
    return impurity
def best split(self, X, y):
    best_gain = -1
    best feature, best threshold = None, None
    current gini = self. gini(v)
    for feature in range(X.shape[1]):
        thresholds = np.unique(X[:, feature])
        for threshold in thresholds:
            left_mask = X[:, feature] <= threshold</pre>
            right mask = ~left mask
            if sum(left mask) == 0 or sum(right mask) == 0:
            left_y, right_y = y[left_mask], y[right_mask]
            gain = current gini - (
                len(left_y) / len(y) * self._gini(left_y) +
                len(right_y) / len(y) * self._gini(right_y)
            if gain > best gain:
                best gain = gain
                best_feature = feature
                best threshold = threshold
    return best_feature, best_threshold
```

Main Approach – Random Forest Classifier (RFC)

Training Process (train_rfc_agent.py)

• Output: Model saved as JSON (rfc_model.json) with feature, threshold, left, right structure

Inference Logic (rfc_agent.py)

- Loads rfc_model.json
- For each state, traverse trees and collect votes
- Final action by majority voting: Hit/Stand

```
X = np.array(X)
y = np.array(y)

model = RandomForest(n_trees=5, max_depth=5)
model.fit(X, y)

forest_structure = [tree.tree for tree in model.trees]
forest_structure = convert_to_builtin(forest_structure)

with open('rfc_model.json', 'w') as f:
    json.dump(forest_structure, f)

print("RFC model trained and saved as rfc_model.json")
```

```
import json
class RFCAgent:
   def __init__(self, model_file):
       with open(model file, 'r') as f:
           self.forest = json.load(f)
   def act(self, player sum, dealer card, is soft, num cards):
       features = [player sum, dealer card, int(is soft), num cards]
       votes = []
       for tree in self.forest:
           votes.append(self.predict tree(features, tree))
       decision = max(set(votes), key=votes.count)
       return "hit" if decision == 0 else "stand"
   def predict tree(self, x, node):
       if not isinstance(node, dict):
            return node
       if x[node['feature']] <= node['threshold']:</pre>
           return self.predict_tree(x, node['left'])
           return self.predict tree(x, node['right'])
```

Main Approach – NEAT Agent

- NEAT (NeuroEvolution of Augmenting Topologies) evolves both network topology and weights for the Blackjack AI.
- Each genome = a neural network:
 Node genes (key, bias, layer: input/output/hidden)
 Connection genes (src, dst, weight, enabled, innovation)
- Mutation operations: Change weights, change biases, add connections, add nodes
- Crossover: Combine two parents based on innovation numbers
- Speciation: Group genomes by similarity to preserve diversity
- Fitness: Total reward from 1000 Blackjack games (input features: player sum, dealer card, is soft, num cards)
- Output: 1 node → "hit" (if >0.5) or "stand"
- Final model: Saved as JSON (node biases, layers, connection weights) for inference.

Main Approach – NEAT Agent

Node / Connection Structures

```
class Node:
    def __init__(self, key, bias=None, layer=None):
        self.key = key
        self.bias = random.uniform(-1, 1) if bias is None else bias
        self.layer = layer

class Conn:
    def __init__(self, src, dst, weight=None, enabled=True, tag=None):
        self.src = src
        self.dst = dst
        self.weight = random.uniform(-1, 1) if weight is None else weight
        self.enabled = enabled
        self.tag = tag
```

Mutation Logic

```
def mutate(self):
    if random.random() < 0.8: self.mutate_weights()
    if random.random() < 0.8: self.mutate_biases()
    if random.random() < 0.03: self.add_conn()
    if random.random() < 0.05: self.add_node()</pre>
```

Inference Logic

```
class NEATAgent:
    def __init__(self, model_path="neat_model.json"):
        with open(model_path, encoding="utf-8") as f: data = json.load(f)
        self.net = Network(data)
    def act(self, player_sum, dealer_card, is_soft, num_cards):
        x = [player_sum/21, dealer_card/10, int(is_soft), num_cards/5]
        return "hit" if self.net.activate(x) > 0.5 else "stand"
```

Crossover

```
@staticmethod
def crossover(p1, p2, cfg):
    if p2.fitness > p1.fitness: p1, p2 = p2, p1
    child = Genome(None, cfg)
    child.nodes = {k: Node(k, n.bias, n.layer) for k, n in p1.nodes.items()}
    child.conns = {}
    for k, c in p1.conns.items():
        other = p2.conns.get(k, c)
        chosen = other if random.random() < 0.5 else c
        child.conns[k] = Conn(chosen.src, chosen.dst, chosen.weight, chosen.enabled, chosen.tag)
    return child</pre>
```

Evaluate

Main Approach-Graphical User Interface (GUI) (blackjack_gui.py)

GUI Features

| Component | Description |
|------------------------|--|
| Mode Selection | Dropdown menu: Manual, Random, Basic, RFC, NEAT |
| Manual Play Buttons | Hit, Stand |
| Al Simulation Control | Auto-run games in batch, update results without dialog boxes |
| Card Display | Visual display of cards using Vector Playing Cards images |
| Game Status Display | Shows player/dealer hands, scores, wins, losses, draws |
| Result Dialog (Manual) | After each manual game, popup shows result and allows new game |

Integration Logic:

GUI interacts with BlackjackEnv to get game state and render visuals.

When AI mode is selected, the GUI runs simulations automatically.

The GUI updating statistics and history in real-time.

Manual mode supports full gameplay with user decisions.

Each agent is tested over 100 trials, each trial simulating 1000 games. Metrics collected: Win rate. Results visualized as line plots in compare.png

Main Approach-Graphical User Interface (GUI) (blackjack_gui.py)



Expectimax Agent

Win Rate:

• Approximately 40% win rate

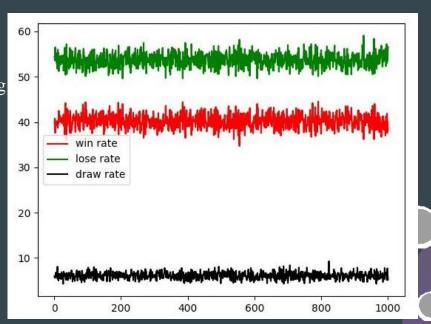
Notable, considering Blackjack's high uncertainty and the agent's lack of advanced features (e.g., card counting

Stability:

- Variance < 1.5% across multiple runs
- Indicates a consistently performing agent,
 not overly affected by random fluctuations

Interpretation:

- Expectimax performs well despite the game's probabilistic nature
- Suggests strong decision-making logic in terms of evaluating Hit vs Stand



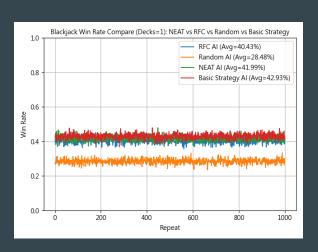
Result and Analysis

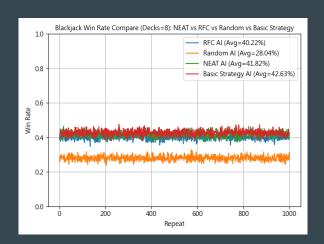
Al Agent

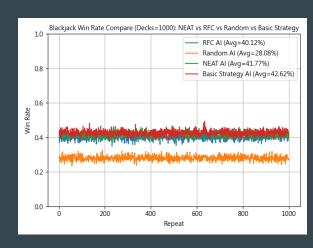
Deck=1

Deck=8

Deck=1000







The Better Model?

After testing, the result is:

When comparing winning rate:

Basic strategy > NEAT > Expectimax > RFC > Random

Thank You!

