## User Guide for SLIP LU, A Sparse Left-Looking Integer Preserving LU Factorization

Version 1.0.0, May 2020

Christopher Lourenco, Jinhao Chen, Erick Moreno-Centeno, Timothy A. Davis Texas A&M University

Contact Information: Contact Chris Lourenco, chrisjlourenco@gmail.com, or Tim Davis, timdavis@aldenmath.com, davis@tamu.edu, DrTimothyAldenDavis@gmail.com

## Contents

1 Overview			
2	Ava	ilability	6
3	Inst	allation	7
4	Mar	naging the SLIP LU environment	7
	4.1	SLIP_LU_VERSION: the software package version	7
	4.2	SLIP_info: status code returned by SLIP LU	7
	4.3	SLIP_initialize: initialize the working environment	8
	4.4	SLIP_initialize_expert: initialize environment (expert version) .	8
	4.5	SLIP_finalize: free the working environment	9
5	Mer	mory Management	9
	5.1	SLIP_calloc: allocate initialized memory	10
	5.2	SLIP_malloc: allocate uninitialized memory	10
	5.3	SLIP_realloc: resize allocated memory	10
	5.4	SLIP_free: free allocated memory	11
6	The	SLIP_options object: parameter settings for SLIP LU	<b>12</b>
	6.1	SLIP_pivot: enum for pivoting schemes	12
	6.2	SLIP_col_order: enum for column ordering schemes	13
	6.3	SLIP_options structure	13
	6.4	SLIP_create_default_options: create default SLIP_options object	14
7	The	SLIP_matrix object	15
	7.1	SLIP_kind: enum for matrix formats	15
	7.2	SLIP_type: enum for data types of matrix entry	15
	7.3	SLIP_matrix structure	16
	7.4	SLIP_matrix_allocate: allocate a m-by-n SLIP_matrix	19
	7.5	SLIP_matrix_free: free a SLIP_matrix	19
	7.6	SLIP_matrix_copy: make a copy of a SLIP_matrix	20
	7.7	SLIP_matrix_nnz: get the number of entries in a SLIP_matrix	20
	7.8	SLIP matrix check: check and print a SLIP matrix	21

Prim	ary Computational Routines	<b>2</b> 1
8.1	SLIP_LU_analysis structure	21
8.2	SLIP_LU_analyze: perform symbolic analysis	22
8.3	SLIP_LU_analysis_free: free SLIP_LU_analysis structure	22
8.4	SLIP_LU_factorize: perform LU factorization	23
8.5	SLIP_LU_solve: solve the linear system $Ax = b$	24
8.6	SLIP_backslash: solve $Ax = b$	25
SLIP	LU wrapper functions for GMP and MPFR	<b>25</b>
Using	g SLIP LU in C	29
10.1	SLIP LU initialization and population of data structures	29
	10.1.1 Initializing the environment	29
		30
	10.1.3 Populating data structures	30
		31
	- · · · · · · · · · · · · · · · · · · ·	31
		32
		32
		32
		32
		33
		33
		34
Using	g SLIP LU in MATLAB	35
		35
		36
	8.1 8.2 8.3 8.4 8.5 8.6 SLIP Usin 10.1 10.2 10.3 10.4 10.5 Usin 11.1	8.2 SLIP_LU_analyze: perform symbolic analysis

## 1 Overview

SLIP LU is a software package designed to exactly solve unsymmetric sparse linear systems, Ax = b, where  $A \in \mathbb{Q}^{n \times n}$ ,  $b \in \mathbb{Q}^{n \times r}$ , and  $x \in \mathbb{Q}^{n \times r}$ . This package performs a left-looking, roundoff-error-free (REF) LU factorization PAQ = LDU, where L and U are integer, D is diagonal, and P and Q are row and column permutations, respectively. Note that the matrix D is never explicitly computed nor needed; thus this package uses only the matrices L and U. The theory associated with this code is the Sparse Left-looking Integer-Preserving (SLIP) LU factorization [8]. Aside from solving sparse linear systems exactly, one of the key goals of this package is to provide a framework for other solvers to benchmark the reliability and stability of their linear solvers, as our final solution vector x is guaranteed to be exact. In addition, SLIP LU provides a wrapper class for the GNU Multiple Precision Arithmetic (GMP) [7] and GNU Multiple Precision Floating Point Reliable (MPFR) [6] libraries in order to prevent memory leaks and improve the overall stability of these external libraries. SLIP LU is written in ANSI C and is accompanied by a MATLAB interface.

For all primary computational routines in Section 8, the input argument A must be stored in a compressed sparse column (CSC) matrix with entries in mpz\_t type (referred to as CSC mpz\_t matrix henceforth), while b must be stored as a dense mpz\_t matrix (i.e., a dense matrix with entries in mpz\_t type). However, the original data type of entries in the input matrix A and right hand side (RHS) vectors b can be any one of: double, int64\_t, mpq\_t, mpz\_t, or mpfr\_t, and their format(s) are allowed to be CSC, sparse triplet or dense. A discussion of how to use these matrix formats and data types in the SLIP\_matrix, and to perform conversions between matrix types and formats in Section 10.1.3.

The matrices L and U are computed using integer-preserving routines with the big integer (mpz\_t) data types from the GMP Library [7]. The matrices L and U are computed one column at a time, where each column is computed via the sparse REF triangular solve detailed in [8]. All divisions performed in the algorithm are guaranteed to be exact (i.e., integer); therefore, no greatest common divisor algorithms are needed to reduce the size of entries.

The permutation matrices P and Q define the pivot ordering; Q is the fill-reducing column ordering, and P is determined dynamically during the factorization. For the matrix P, the default option is to use a partial pivoting scheme in which the diagonal entry in column k is selected if it is the same magnitude as the smallest entry of k-th column, otherwise the smallest entry is selected as the k-th pivot. In addition to this approach, the code allows diagonal pivoting, partial pivoting which selects the largest pivot, or various tolerance based diagonal pivoting schemes. For the matrix

Q, the default ordering is the Column Approximate Minimum Degree (COLAMD) algorithm [4, 5]. Other approaches include using the Approximate Minimum Degree (AMD) ordering [1, 2], or no ordering (Q = I). A discussion of how to select these permutations prior to factorization is given in Section 8.

Once the factorization LDU = PAQ is computed, the solution vector x is computed via sparse REF forward and backward substitution. The forward substitution is a variant of the sparse REF triangular solve discussed above. The backward substitution is a typical column oriented sparse backward substitution. Both of these routines require b stored as a dense  $mpz_t$  matrix. At the conclusion of the forward and backward substitution routines, the final solution vector(s) x are guaranteed to be exact. The solution x is returned as a dense  $mpq_t$  matrix.

Using the SLIP matrix copy function, any matrix in any of the 15 combinations of the set (CSC, triplet, dense) × (mpz\_t, mpq\_t, mpfr\_t, int64\_t, or double), can be copied and converted into any one of the 15 combinations.

One key advantage of utilizing SLIP LU with floating-point output is that the solution is guaranteed to be exact until this final conversion; meaning that roundoff errors are only introduced in the final conversion from rational numbers. Thus, the solution x output in double precision are accurate to machine roundoff (approximately  $10^{-16}$ ) and SLIP LU utilizes higher precision for the MPFR output; thus it is also accurate to user-specified precision.

Most routines expect the input sparse matrix A to be stored in CSC format. This data structure stores the matrix A as a sequence of three arrays:

- A->p: Column pointers; an array of size n+1. The row indices of column j are located in positions A->p[j] to A->p[j+1]-1 of the array A->i. Data type: int64\_t.
- A->i: Row indices; an array of size equal to the number of entries in the matrix. The entry A->i[k] is the row index of the kth nonzero in the matrix. Data type: int64\_t.
- A->x: Numeric entries. The entry A->x[k] is the numeric value of the kth nonzero in the matrix. The array A->x has a union type, and must be accessed via a suffix according to the type of A. For details, see Section 7.

An example matrix A with mpz\_t type is stored as follows (notice that via C

convention, the indexing is zero based).

$$A = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 2 & 0 & 4 & 12 \\ 7 & 1 & 1 & 1 \\ 0 & 2 & 3 & 0 \end{bmatrix}$$

```
A \rightarrow p = [0, 3, 5, 8, 11]

A \rightarrow i = [0, 1, 2, 2, 3, 1, 2, 3, 0, 1, 2]

A \rightarrow x.mpz = [1, 2, 7, 1, 2, 4, 1, 3, 1, 12, 1]
```

For example, the last column appears in positions 8 to 10 of A->i and A->x.mpz, with row indices 0, 1, and 2, and values  $a_{03} = 1$ ,  $a_{13} = 12$ , and  $a_{23} = 1$ .

## 2 Availability

**Copyright:** This software is copyright by Christopher Lourenco, Jinhao Chen, Erick Moreno-Centeno, and Timothy Davis.

Contact Info: Contact Chris Lourenco, chrisjlourenco@gmail.com, or Tim Davis, timdavis@aldenmath.com, davis@tamu.edu, or DrTimothyAldenDavis@gmail.com

**License:** This software package is dual licensed under the GNU General Public License version 2 or the GNU Lesser General Public License version 3. Details of this license are in SLIP\_LU/License/license.txt. For alternative licenses, please contact the authors.

Location: https://github.com/clouren/SLIP\_LU and www.suitesparse.com
Required Packages: SLIP LU requires the installation of AMD [1, 2], COLAMD [5, 4], SuiteSparse\_config [3], the GNU GMP [7] and GNU MPFR [6] libraries. AMD and COLAMD are available under a BSD 3-clause license, and no license restrictions apply to SuiteSparse\_config. Notice that AMD, COLAMD, and SuiteSparse\_config are included in this distribution for convenience. The GNU GMP and GNU MPFR library can be acquired and installed from https://gmplib.org/ and http://www.mpfr.org/ respectively.

With a Debian/Ubuntu based Linux system, a compatible version of GMP and MPFR can be installed with the following terminal commands:

```
sudo apt-get install libmpfr-dev libmpfr-doc libmpfr4 libmpfr4-dbg
```

## 3 Installation

Installation of SLIP LU requires the make utility in Linux/MacOS, or Cygwin make in Windows. With the proper compiler, typing make under the main directory will compile AMD, COLAMD and SLIP LU to the respective SLIP\_LU/Lib folder. To further install the libraries onto your computer, simply type make install. Thereafter, to use the code inside of your program, precede your code with #include "SLIP\_LU.h".

To run the statement coverage tests, go to the Tcov folder and type make. The last line of output should read:

#### statments not yet tested: 0

If you want to use SLIP LU within MATLAB, from your installation of MATLAB, cd to the folder SLIP\_LU/SLIP\_LU/MATLAB then type SLIP\_install. This should compile the necessary code so that you can use the SLIP\_backslash function from within MATLAB. Note that SLIP\_install does not add the correct directory to your path; therefore, if you want to use SLIP\_backslash in future sessions, type pathtool and save your path for future MATLAB sessions. If you cannot save your path because of file permissions, edit your startup.m by adding addpath commands (type doc startup and doc addpath for more information).

## 4 Managing the SLIP LU environment

## 4.1 SLIP\_LU\_VERSION: the software package version

SLIP LU defines the following strings with #define. Refer to the SLIP\_LU.h file for details.

Macro	purpose
SLIP_LU_VERSION	current version of the code (as a string)
SLIP_LU_VERSION_MAJOR	major version of the code
SLIP_LU_VERSION_MINOR	minor version of the code
SLIP_LU_VERSION_SUB	sub version of the code

## 4.2 SLIP\_info: status code returned by SLIP LU

Most SLIP LU functions return their status to the caller as their return value, an enumerated type called SLIP\_info. All current possible values for SLIP\_info are listed as follows:

0	SLIP_OK	The function was successfully executed.
-1	SLIP_OUT_OF_MEMORY	out of memory
-2	SLIP_SINGULAR	The input matrix $A$ is exactly singular.
-3	SLIP_INCORRECT_INPUT	One or more input arguments are incorrect.
-4	SLIP_INCORRECT	The solution is incorrect.
-5	SLIP_PANIC	SLIP LU environment error

Either SLIP\_initialize or SLIP\_initialize\_expert (but not both) must be called prior to using any other SLIP LU function. SLIP\_finalize must be called as the last SLIP LU function.

Subsequent SLIP LU sessions can be restarted after a call to SLIP\_finalize, by calling either SLIP\_initialize or SLIP\_initialize\_expert (but not both), followed by a final call to SLIP\_finalize when finished.

### 4.3 SLIP\_initialize: initialize the working environment

```
SLIP_info SLIP_initialize
(
     void
);
```

SLIP\_initialize initializes the working environment for SLIP LU functions. SLIP LU utilizes a specialized memory management scheme in order to prevent potential memory failures caused by GMP and MPFR libraries. Either this function or SLIP\_initialize\_expert must be called prior to using any other function in the library. Returns SLIP\_PANIC if SLIP LU has already been initialized, or SLIP\_OK if successful.

## 4.4 SLIP\_initialize\_expert: initialize environment (expert version)

SLIP\_initialize\_expert is the same as SLIP\_initialize except that it allows for a redefinition of custom memory functions that are used for SLIP LU and GM-P/MPFR. The four inputs to this function are pointers to four functions with the same signatures as the ANSI C malloc, calloc, realloc, and free functions. That is:

```
#include <stdlib.h>
void *malloc (size_t size) ;
void *calloc (size_t nmemb, size_t size) ;
void *realloc (void *ptr, size_t size) ;
void free (void *ptr) ;
```

Returns SLIP\_PANIC if SLIP LU has already been initialized, or SLIP\_OK if successful.

## 4.5 SLIP\_finalize: free the working environment

```
SLIP_info SLIP_finalize
(
void
);
```

SLIP\_finalize finalizes the working environment for SLIP LU library, and frees any internal workspace created by SLIP LU. It must be called as the last SLIP\_\* function called, except that a subsequent call to SLIP\_initialize\* may be used to start another SLIP LU session. Returns SLIP\_PANIC if SLIP LU has not been initialized, or SLIP\_OK if successful.

## 5 Memory Management

The routines in this section are used to allocate and free memory for the data structures used in SLIP LU. By default, SLIP LU relies on the SuiteSparse memory management functions, SuiteSparse\_malloc, SuiteSparse\_calloc, SuiteSparse\_realloc, and SuiteSparse\_free. By default, those functions rely on the ANSI C malloc, calloc, realloc, and free, but this may be changed by initializing the SLIP LU environment with SLIP\_initialize\_expert.

#### 5.1 SLIP\_calloc: allocate initialized memory

SLIP\_calloc allocates a block of memory for an array of nitems elements, each of them size bytes long, and initializes all its bits to zero. If any input is less than 1, it is treated as if equal to 1. If the function failed to allocate the requested block of memory, then a NULL pointer is returned. Returns NULL if SLIP LU has not been initialized.

#### 5.2 SLIP\_malloc: allocate uninitialized memory

```
void *SLIP_malloc
(
    size_t size  // size of memory space to allocate
);
```

SLIP\_malloc allocates a block of size bytes of memory, returning a pointer to the beginning of the block. The content of the newly allocated block of memory is not initialized, remaining with indeterminate values. If size is less than 1, it is treated as if equal to 1. If the function fails to allocate the requested block of memory, then a NULL pointer is returned. Returns NULL if SLIP LU has not been initialized.

## 5.3 SLIP\_realloc: resize allocated memory

SLIP\_realloc is a wrapper for realloc. If p is non-NULL on input, it points to a previously allocated object of size nitems\_old × size\_of\_item. The object is reallocated to be of size nitems\_new × size\_of\_item. If p is NULL on input, then

a new object of that size is allocated. On success, a pointer to the new object is returned. Returns ok as false if SLIP LU has not been initialized.

If the reallocation fails, p is not modified, and ok is returned as false to indicate that the reallocation failed. If the size decreases or remains the same, then the method always succeeds (ok is returned as true), unless SLIP LU has not been initialized..

Typical usage: the following code fragment allocates an array of 10 int's, and then increases the size of the array to 20 int's. If the SLIP\_malloc succeeds but the SLIP\_realloc fails, then the array remains unmodified, of size 10.

```
int *p;
p = SLIP_malloc (10 * sizeof (int));
if (p == NULL) { error here ... }
printf ("p points to an array of size 10 * sizeof (int)\n");
bool ok;
p = SLIP_realloc (20, 10, sizeof (int), p, &ok);
if (ok) printf ("p has size 20 * sizeof (int)\n");
else printf ("realloc failed; p still has size 10 * sizeof (int)\n");
SLIP_free (p);
```

## 5.4 SLIP\_free: free allocated memory

```
void SLIP_free
(
    void *p  // Pointer to memory space to free
);
```

SLIP\_free deallocates the memory previously allocated by a call to SLIP\_calloc, SLIP\_malloc, or SLIP\_realloc. If p is NULL on input, then no action is taken (this is not an error condition). To guard against freeing the same memory space twice, the following macro SLIP\_FREE is provided, which calls SLIP\_free and then sets the freed pointer to NULL.

Returns silently, with no action taken, if SLIP LU has not been initialized.

# 6 The SLIP\_options object: parameter settings for SLIP LU

The SLIP\_options object contains numerous parameters that may be modified to change the behavior of the SLIP LU functions. Default values of these parameters will lead to good performance in most cases. Modifying this struct provides control of column orderings, pivoting schemes, and other components of the factorization.

## 6.1 SLIP\_pivot: enum for pivoting schemes

There are six available pivoting schemes provided in SLIP LU that can be selected with the SLIP\_options structure. If the matrix is non-singular (in an exact sense), then the pivot is always nonzero, and is chosen as the *smallest* nonzero entry, with the smallest magnitude. This may seem counter-intuitive, but selecting a small nonzero pivot leads to smaller growth in the number of digits in the entries of L and U. This choice does not lead to any kind of numerical inaccuracy, since SLIP LU is guaranteed to find an exact roundoff-error free factorization of a non-singular matrix (unless it runs out of memory), for any nonzero pivot choice.

The pivot tolerance for two of the pivoting schemes is specified by the tol component in SLIP\_options. The pivoting schemes are as follows:

0	SLIP_SMALLEST	The $k$ -th pivot is selected as the smallest entry in the $k$ -th
		column.
1	SLIP_DIAGONAL	The $k$ -th pivot is selected as the diagonal entry. If the di-
		agonal entry is zero, this method instead selects the smallest
		pivot in the column.
2	SLIP_FIRST_NONZERO	The $k$ -th pivot is selected as the first eligible nonzero in the
		column.
3	SLIP_TOL_SMALLEST	The $k$ -th pivot is selected as the diagonal entry if the diagonal
		is within a specified tolerance of the smallest entry in the
		column. Otherwise, the smallest entry in the $k$ -th column is
		selected. This is the default pivot selection strategy.
4	SLIP_TOL_LARGEST	The $k$ -th pivot is selected as the diagonal entry if the diago-
		nal is within a specified tolerance of the largest entry in the
		column. Otherwise, the largest entry in the $k$ -th column is
		selected.
5	SLIP_LARGEST	The $k$ -th pivot is selected as the largest entry in the $k$ -th
		column.

### 6.2 SLIP\_col\_order: enum for column ordering schemes

The SLIP LU library provides three column ordering schemes: no pre-ordering, CO-LAMD, and AMD, selected via the order component in the SLIP\_options structure described in Section 6.3.

0	SLIP_NO_ORDERING	No pre-ordering is performed on the matrix $A$ , that is $Q = I$ .
1	SLIP_COLAMD	The columns of $A$ are permuted prior to factorization using
		the COLAMD [4] ordering. This is the default ordering.
2	SLIP_AMD	The nonzero pattern of $A + A^T$ is analyzed and the columns
		of $A$ are permuted prior to factorization based on the AMD
		[2] ordering of $A + A^T$ . This works well if A has a mostly
		symmetric pattern, but tends to be worse than COLAMD on
		matrices with unsymmetric pattern. [5].

## 6.3 SLIP\_options structure

The SLIP\_options struct stores key command parameters for various functions used in the SLIP LU package. The SLIP\_options\* option struct contains the following components:

- option->pivot: An enum SLIP\_pivot type (discussed in Section 6.1) which controls the type of pivoting used. Default value: SLIP\_TOL\_SMALLEST (3).
- option->order: An enum SLIP\_col\_order type (discussed in Section 6.2) which controls what column ordering is used. Default value: SLIP\_COLAMD (1).
- option->tol: A double tolerance for the tolerance-based pivoting scheme, i.e., SLIP\_TOL\_SMALLEST or SLIP\_TOL\_LARGEST. option->tol must be in the range of (0, 1]. Default value: 1 meaning that the diagonal entry will be selected if it has the same magnitude as the smallest entry in the k the column.
- option->print\_level: An int which controls the amount of output: 0: print nothing, 1: just errors, 2: terse, with basic stats from COLAMD/AMD and SLIP, 3: all, with matrices and results. Default value: 0.
- option->prec: An int32\_t which specifies the precision used for multiple precision floating point numbers, (i.e., MPFR). This can be any integer larger than MPFR\_PREC\_MIN (value of 1 in MPFR 4.0.2 and 2 in some legacy versions) and smaller than MPFR\_PREC\_MAX (usually the largest possible integer available in your system). Default value: 128 (quad precision).

- option->round: A mpfr\_rnd\_t which determines the type of MPFR rounding to be used by SLIP LU. This is a parameter of the MPFR library. The options for this parameter are:
  - MPFR\_RNDN: round to nearest (roundTiesToEven in IEEE 754-2008)
  - MPFR\_RNDZ: round toward zero (roundTowardZero in IEEE 754-2008)
  - MPFR\_RNDU: round toward plus infinity (roundTowardPositive in IEEE 754-2008)
  - MPFR\_RNDD: round toward minus infinity (roundTowardNegative in IEEE 754-2008)
  - MPFR\_RNDA: round away from zero
  - MPFR\_RNDF: faithful rounding. This is not stable.

Refer to the MPFR User Guide available at <a href="https://www.mpfr.org/mpfr-current/mpfr.pdf">https://www.mpfr.org/mpfr-current/mpfr.pdf</a> for details on the MPFR rounding style and any other utilized MPFR convention. Default value: MPFR\_RNDN.

• option->check: A bool which indicates whether the solution to the system should be checked. Intended for debugging only; the SLIP LU library is guaranteed to return the exact solution. Default value: false.

All SLIP LU routines except basic memory management routines in Sections 5.1-4.5 and SLIP\_options allocation routine in 6.4 require option as an input argument. The construction of the option struct can be avoided by passing NULL for the default settings. Otherwise, the following functions create and destroy a SLIP\_options object:

function/macro name	description	section
SLIP_create_default_options	create and return SLIP_options pointer with default parameters upon successful allocation	6.4
SLIP_FREE	destroy SLIP_options object	5.4

## 6.4 SLIP\_create\_default\_options: create default SLIP\_options object

```
SLIP_options* SLIP_create_default_options
(
         void
);
```

SLIP\_create\_default\_options creates and returns a pointer to a SLIP\_options struct with default parameters upon successful allocation, which are discussed in Section 6.3. To safely free the SLIP\_options\* option structure, simply use SLIP\_FREE(option). All functions that require SLIP\_options \*option as an input argument can have a NULL pointer passed instead. In this case, the default value of the corresponding command option is used. For example, if a NULL pointer is passed to the symbolic analysis routines, COLAMD is used. As a result, defaults are desired, the SLIP\_options struct need not be allocated. Returns NULL if SLIP LU has not been initialized.

## 7 The SLIP\_matrix object

All matrices for SLIP LU are stored as a SLIP\_matrix object (a pointer to a struct). The matrix can be held in three formats: CSC, triplet or dense matrix (as discussed in Section 7.1) with entries stored as 5 different types: mpz\_t, mpq\_t, mpfr\_t, int64\_t and double (as discussed in Section 7.2). This gives a total of 15 different combinations of matrix format and entry type. Note that not all functions accept all 15 matrix types. Indeed, most functions expect the input matrix A to be a CSC mpz\_t matrix while vectors (such as x and b) are in dense format.

## 7.1 SLIP\_kind: enum for matrix formats

The SLIP LU library provides three available matrix formats: sparse CSC (compressed sparse column), sparse triplet and dense.

0	SLIP_CSC	Matrix is in compressed sparse column format.
1	SLIP_TRIPLET	Matrix is in sparse triplet format.
2	SLIP_DENSE	Matrix is in dense format.

## 7.2 SLIP\_type: enum for data types of matrix entry

The SLIP LU library provides five data types for matrix entries: mpz\_t, mpq\_t, mpfr\_t, int64\_t and double.

0	SLIP_MPZ	Matrix entries are in mpz_t type: an integer of arbitrary size.
1	SLIP_MPQ	Matrix entries are in mpq_t type: a rational number with
		arbitrary-sized integer numerator and denominator.
2	SLIP_MPFR	Matrix entries are in mpfr_t type: a floating-point number
		of arbitrary precision.
3	SLIP_INT64	Matrix entries are in int64_t type.
4	SLIP_FP64	Matrix entries are in double type.

#### 7.3 SLIP\_matrix structure

A matrix SLIP\_matrix \*A has the following components:

- A->m: Number of rows in the matrix. Data Type: int64\_t.
- A->n: Number of columns in the matrix. Data Type: int64\_t.
- A->nz: The number of nonzeros in the matrix A, if A is a triplet matrix (ignored for matrices in CSC or dense formats). Data Type: int64\_t.
- A->nzmax: The allocated size of the vectors A->i, A->j and A->x. Note that
   A->nzmax ≥ nnz(A), where nnz(A) is the return value of SLIP\_matrix\_nnz(A, option).
   Data Type: int64\_t.
- A->kind: Indicating the kind of matrix A: CSC, triplet or dense. Data Type: SLIP\_kind.
- A->type: Indicating the type of entries in matrix A: mpz\_t, mpq\_t, mpfr\_t, int64\_t or double. Data Type: SLIP\_type.
- A->p: An array of size A->n+1 which contains column pointers of A, if A is a CSC matrix (NULL for matrices in triplet or dense formats). Data Type: int64\_t\*.
- A->p\_shallow: A boolean indicating whether A->p is shallow. Data Type:
- A->i: An array of size A->nzmax which contains the row indices of the nonzeros in A, if A is a CSC or triplet matrix (NULL for dense matrices). The matrix is zero-based, so row indices are in the range of [0, A->m-1]. Data Type: int64\_t\*.
- A->i\_shallow: A boolean indicating whether A->i is shallow. Data Type: bool.

- A->j: An array of size A->nzmax which contains the column indices of the nonzeros in A, if A is a triplet matrix (NULL for matrices in CSC or dense formats). The matrix is zero-based, so column indices are in the range of [0, A->n-1]. Data Type: int64\_t\*.
- A->j\_shallow: A boolean indicating whether A->j is shallow. Data Type: bool.
- A->x: An array of size A->nzmax which contains the numeric values of the matrix. This array is a union, and must be accessed via one of: A->x.mpz, A->x.mpq, A->x.mpfr, A->x.int64, or A->x.fp64, depending on the A->type parameter. Data Type: union.
- A->x\_shallow: A boolean indicating whether A->x is shallow. Data Type: bool.
- A->scale: A scaling parameter for matrix of mpz\_t type. For all matrices whose entries are stored in data type other than mpz\_t, A->scale = 1. This is used to ensure that entry can be represented as an integer in an mpz\_t matrix if these entries are converted from non-integer type data (such as double, variable precision floating point, or rational). Data Type: mpq\_t.

Specifically, for different kinds of A of size  $A->m \times A->n$  with nz nonzero entries, its components are defined as:

- (0) SLIP\_CSC: A sparse matrix in CSC (compressed sparse column) format. A->p is an int64\_t array of size A->n+1, A->i is an int64\_t array of size A->nzmax (with  $nz \leq A->nzmax$ ), and A->x.TYPE is an array of size A->nzmax of matrix entries (TYPE is one of mpz, mpq, mpfr, int64, or fp64). The row indices of column j appear in A->i [A->p [j] ... A->p [j+1]-1], and the values appear in the same locations in A->x.TYPE. The A->j array is NULL. A->nz is ignored; the number of entries in A is given by A->p [A->n]. Row indices need not be sorted in each column, but duplicates cannot appear.
- (1) SLIP\_TRIPLET: A sparse matrix in triplet format. A->i and A->j are both int64\_t arrays of size A->nzmax, and A->x.TYPE is an array of values of the same size. The kth tuple has row index A->i [k], column index A->j [k], and value A->x.TYPE [k], with 0 ≤ k < A->nz. The A->p array is NULL. Triplets can be unsorted, but duplicates cannot appear.

• (2) SLIP\_DENSE: A dense matrix. The integer arrays  $A \rightarrow p$ ,  $A \rightarrow i$ , and  $A \rightarrow j$  are all NULL.  $A \rightarrow x$ . TYPE is a pointer to an array of size  $A \rightarrow m^*A \rightarrow n$ , stored in column-oriented format. The value of A(i,j) is  $A \rightarrow x$ . TYPE [p] with  $p = i + j + A \rightarrow m$ .  $A \rightarrow nz$  is ignored; the number of entries in A is  $A \rightarrow m \times A \rightarrow n$ .

A may contain shallow components, A->p, A->i, A->j, and A->x. For example, if A->p\_shallow is true, then a non-NULL A->p is a pointer to a read-only array, and the A->p array is not freed by SLIP\_matrix\_free. If A->p is NULL (for a triplet or dense matrix), then A->p\_shallow has no effect.

To simplify the access the entries in A, SLIP LU package provides the following macros (Note that the TYPE parameter in the macros is one of: mpz, mpq, mpfr, int64 or fp64):

- SLIP\_1D(A,k,TYPE): used to access the kth entry in SLIP\_matrix \*A using 1D linear addressing for any matrix kind (CSC, triplet or dense), in any type with TYPE specified corresponding
- SLIP\_2D(A,i,j,TYPE): used to access the (i,j)th entry in a dense SLIP\_matrix \*A.

The SLIP LU package has a set of functions to allocate, copy(convert), query and destroy a SLIP LU matrix, SLIP\_matrix, as shown in the following table.

function name	description	section
SLIP_matrix_allocate	allocate a $m$ -by- $n$ SLIP_matrix	7.4
SLIP_matrix_free	destroy a SLIP_matrix and free its al-	7.5
	located memory	
SLIP_matrix_copy	make a copy of a matrix, into another	7.6
	kind and/or type	
SLIP_matrix_nnz	get the number of entries in a matrix	7.7

#### 7.4 SLIP\_matrix\_allocate: allocate a m-by-n SLIP\_matrix

```
SLIP_info SLIP_matrix_allocate
    SLIP_matrix **A_handle, // matrix to allocate
   SLIP_kind kind,
                           // CSC, triplet, or dense
   SLIP_type type,
                            // mpz, mpq, mpfr, int64, or double (fp64)
                            // # of rows
    int64_t m,
    int64_t n,
                           // # of columns
                            // max # of entries
    int64_t nzmax,
    bool shallow,
                            // if true, matrix is shallow. A->p, A->i,
                            // A->j, A->x are all returned as NULL and must
                            // be set by the caller. All A->*_shallow are
                            // returned as true.
                            // If true, and the data types are mpz, mpq, or
    bool init,
                            // mpfr, the entries are initialized (using the
                            // appropriate SLIP_mp*_init function). If
                            // false, the mpz, mpq, and mpfr arrays are
                            // allocated but not initialized.
    const SLIP_options *option
);
```

SLIP\_matrix\_allocate allocates memory space for a m-by-n SLIP\_matrix whose kind (CSC, triplet or dense) and data type (mpz, mpq, mpfr, int64 or fp64) is specified. If shallow is true, all components (A->p, A->i, A->j, A->x) are returned as NULL, and their shallow flags are all true. The pointers A->p, A->i, A->j, and/or A->x can then be assigned from arrays in the calling application.

If shallow is false, the appropriate individual arrays are allocated (via SLIP\_calloc). The second boolean parameter is used if the entries are mpz\_t, mpq\_t, or mpfr\_t. Specifically, if init is true, the individual entries within A->x.TYPE are initialized using the appropriate SLIP\_mp\*\_init) function. Otherwise, if init is false, the A->x.TYPE array is allocated (via SLIP\_calloc) and left that way. They are not otherwise initialized, and attempting to access the values of these uninitialized entries will lead to undefined behavior. Returns SLIP\_PANIC if SLIP LU has not been initialized.

### 7.5 SLIP\_matrix\_free: free a SLIP\_matrix

```
SLIP_info SLIP_matrix_free
(
    SLIP_matrix **A_handle, // matrix to free
    const SLIP_options *option
```

);

SLIP\_matrix\_free frees the SLIP\_matrix \*A. Note that the input of the function is the pointer to the pointer of a SLIP\_matrix structure. This is because this function internally sets the pointer of a SLIP\_matrix to be NULL to prevent potential segmentation fault that could be caused by double free. If default settings are desired, option can be input as NULL.

## 7.6 SLIP\_matrix\_copy: make a copy of a SLIP\_matrix

SLIP\_matrix\_copy creates a SLIP\_matrix \*C which is a modified copy of a SLIP\_matrix \*A. This function can convert between any pair of the 15 kinds of matrices, so the new matrix C can be of any type or kind different than A. On input C must be non-NULL, and the value of \*C is ignored; it is overwritten, output with the matrix C, which is a copy of A of kind kind and type type.

The input matrix is assumed to be valid. It can be checked first with SLIP\_matrix\_check (Section 7.8), if desired. Results are undefined for an invalid input matrix A. Returns SLIP\_PANIC if SLIP LU has not been initialized.

## 7.7 SLIP\_matrix\_nnz: get the number of entries in a SLIP\_matrix

SLIP\_matrix\_nnz returns the number of entries in a SLIP\_matrix \*A. For details regarding how the number of entries is obtained for different kinds of matrices, refer to Section 7. For any matrix with invalid dimension(s), this function returns -1. If default settings are desired, option can be input as NULL. Returns -1 if SLIP LU has not been initialized.

#### 7.8 SLIP\_matrix\_check: check and print a SLIP\_matrix

```
SLIP_info SLIP_matrix_check  // returns a SLIP_LU status code
(
    const SLIP_matrix *A,  // matrix to check
    const SLIP_options* option  // defines the print level
);
```

SLIP\_matrix\_check checks the validity of a SLIP\_matrix \*A in any of the 15 different matrix types (CSC, triplet, dense) × (mpz, mpq, mpfr, int64, fp64). The print level can be changed via option->print\_level (refer to Section 6 for more details). If default settings are desired, option can be input as NULL. Returns SLIP\_PANIC if SLIP LU has not been initialized.

## 8 Primary Computational Routines

These routines perform symbolic analysis, compute the LU factorization of the matrix A, and solve Ax = b using the factorization of A.

## 8.1 SLIP\_LU\_analysis structure

The SLIP\_LU\_analysis data structure is used for storing the column permutation for LU and the estimate of the number of nonzeros that may appear in L and U. This need not be modified or accessed in the user application; it simply needs to be passed in directly to the other functions that take it as in input parameter. A SLIP\_LU\_analysis structure has the following components:

- S->q: The column permutation stored as a dense int64\_t vector of size n+1, where n is the number of columns of the analyzed matrix. Currently this vector is obtained via COLAMD, AMD, or is set to no ordering (i.e., [0, 1, ..., n-1]).
- S->lnz: An int64\_t which is an estimate of the number of nonzeros in L. S->lnz must be in the range of  $[n, n^2]$ . If S->lnz is too small, the program may waste time performing extra memory reallocations. This is set during the symbolic analysis.
- S->unz: An int64\_t which is an estimate of the number of nonzeros in U. S->unz must be in the range of  $[n, n^2]$ . If S->unz is too small, the program may waste time performing extra memory reallocations. This is set during the symbolic analysis.

The SLIP LU package provides the following functions to create and destroy a SLIP\_LU\_analysis object:

function/macro name	description	section
SLIP_LU_analyze	create SLIP_LU_analysis object	8.2
SLIP_LU_analysis_free	destroy SLIP_LU_analysis object	8.3

### 8.2 SLIP\_LU\_analyze: perform symbolic analysis

SLIP\_LU\_analyze performs the symbolic ordering for SLIP LU. Currently, there are three options: no ordering, COLAMD, or AMD, which are passed in by SLIP\_options \*option. For more details, refer to Section 6.

The SLIP\_LU\_analysis \*S is created by calling SLIP\_LU\_analyze(&S, A, option) with SLIP\_matrix \*A properly initialized as CSC matrix and option be NULL if default ordering (COLAMD) is desired. The value of S is ignored on input. On output, S is a pointer to the newly created symbolic analysis object and SLIP\_OK is returned upon successful completion, or S = NULL with error status returned if a failure occurred. Returns SLIP\_PANIC if SLIP LU has not been initialized.

The analysis S is freed by SLIP\_LU\_analysis\_free.

## 8.3 SLIP\_LU\_analysis\_free: free SLIP\_LU\_analysis structure

```
SLIP_info SLIP_LU_analysis_free
(
    SLIP_LU_analysis **S, // Structure to be deleted
    const SLIP_options *option
);
```

SLIP\_LU\_analysis\_free frees a SLIP\_LU\_analysis structure. Note that the input of the function is the pointer to the pointer of a SLIP\_LU\_analysis structure. This is because this function internally sets the pointer of a SLIP\_LU\_analysis to be NULL to prevent potential segmentation fault that could be caused by double free. If default settings are desired, option can be input as NULL. Returns SLIP\_PANIC if SLIP LU has not been initialized.

### 8.4 SLIP\_LU\_factorize: perform LU factorization

```
SLIP_info SLIP_LU_factorize
    // output:
   SLIP_matrix **L_handle,
                                // lower triangular matrix
    SLIP_matrix **U_handle,
                                // upper triangular matrix
   SLIP_matrix **rhos_handle, // sequence of pivots
    int64_t **pinv_handle,
                                // inverse row permutation
    // input:
                                 // matrix to be factored
    const SLIP_matrix *A,
    const SLIP_LU_analysis *S,
                                 // column permutation and estimates
                                 // of nnz in L and U
    const SLIP_options* option
);
```

SLIP\_LU\_factorize performs the SLIP LU factorization. This factorization is done via n (number of rows or columns of the square matrix A) iterations of the sparse REF triangular solve function. The overall factorization is PAQ = LDU. This routine allows the factorization and solve to be split into separate phases. For example codes, refer to either SLIP\_LU/Demos/SLIPLU.c or Section 10.3.

On input, L, U, rhos, and pinv are undefined and ignored. A must be a CSC mpz matrix. Default settings are used if option is input as NULL.

Upon successful completion, the function returns SLIP\_OK, and L and U are lower and upper triangular matrices, respectively, which are CSC matrices of type mpz. rhos contains the sequence of pivots as an n-by-1 dense vector of type mpz.

After factorizing the matrix, the determinant of A can be obtained from rhos [n-1] and A->scale as follows:

```
mpq_t determinant ;
SLIP_mpq_init (determinant) ;
SLIP_mpq_set_z (determinant, rhos->x.mpz[rhos->n-1]) ;
SLIP_mpq_div (determinant, determinant, A->scale) ;
```

The output array pinv contains the inverse row permutation (that is, the row index in the permuted matrix PA. For the *i*th row in A, pinv[i] gives the row index in PA).

Returns SLIP\_PANIC if SLIP LU has not been initialized. Otherwise, if another error occurs, L, U, rhos, and pinv are all returned as NULL, and an error code will be returned correspondingly.

## 8.5 SLIP\_LU\_solve: solve the linear system Ax = b

```
SLIP_info SLIP_LU_solve
                                // solves the linear system LD^{(-1)}U x = b
    // Output
   SLIP_matrix **X_handle,
                                // rational solution to the system
    // input:
    const SLIP_matrix *b,
                                // right hand side vector
    const SLIP_matrix *A,
                                // Input matrix
                                // lower triangular matrix
    const SLIP_matrix *L,
    const SLIP_matrix *U,
                                // upper triangular matrix
    const SLIP_matrix *rhos,
                                // sequence of pivots
    const SLIP_LU_analysis *S, // symbolic analysis struct
                                // inverse row permutation
    const int64_t *pinv,
    const SLIP_options* option
);
```

SLIP\_LU\_solve obtains the solution of mpq\_t type to the linear system Ax = b upon a successful factorization. This function may be called after a successful return from SLIP\_LU\_factorize, which computes L, U, rhos, and pinv.

On input, SLIP\_matrix \*x is undefined. A, L and U must be CSC mpz\_t matrices while b and rhos must be dense mpz\_t matrices. All matrices must have matched dimensions: the matrices L and U must be square lower and upper triangular matrices the same size as A, and rhos must be a dense n-by-1 vector. The input matrix b must have same number of rows as A. Default settings are used if option is input as NULL.

Upon successful completion, the function returns SLIP\_OK, and x contains the solution of mpq\_t type with dense format to the linear system Ax = b. If desired, option->check can be set to true to enable a post-check of the solution of this function. However, this is intended for debugging only; the SLIP LU library is guaranteed to return the exact solution. Otherwise (in case of error occurred), the function returns corresponding error code.

This function is primarily for applications that require intermediate results. For additional information, refer to either SLIP\_LU/Demos/SLIPLU.c or Section 10.3. Returns SLIP\_PANIC if SLIP LU has not been initialized.

#### 8.6 SLIP\_backslash: solve Ax = b

SLIP\_backslash solves the linear system Ax = b and returns the solution as a dense matrix of mpq\_t, mpfr\_t or double numbers. This function performs symbolic analysis, factorization, and solving all in one line. It can be thought of as an exact version of MATLAB sparse backslash.

On input, SLIP\_matrix \*x is undefined. type must be one of: SLIP\_MPQ, SLIP\_MPFR or SLIP\_FP64 to specify the data type of the solution entries. A should be a square CSC mpz\_t matrix while b should be a dense mpz\_t matrix. In addition, A->m should be equal to b->m. Default settings are used if option is input as NULL.

Upon successful completion, the function returns SLIP\_OK, and x contains the solution of data type specified by type to the linear system Ax = b. If desired, option->check can be set to true to enable solution checking process in this function. However, this is intended for debugging only; SLIP LU library is guaranteed to return the exact solution. Otherwise (in case of error occurred), the function returns corresponding error code.

Returns SLIP\_PANIC if SLIP LU has not been initialized.

For a complete example, refer to SLIP\_LU/Demos/example.c, SLIP\_LU/Demos/example2.c, or Section 10.2.

## 9 SLIP LU wrapper functions for GMP and MPFR

SLIP LU provides a wrapper class for all GMP and MPFR functions used by SLIP LU. The wrapper class provides error-handling for out-of-memory conditions that are not handled by the GMP and MPFR libraries. These wrapper functions are used inside all SLIP LU functions, wherever any GMP or MPFR functions are used. These functions may also be called by the end-user application.

Each wrapped function has the same name as its corresponding GMP/MPFR function with the added prefix SLIP\_. For example, the default GMP function mpz\_mul is changed to SLIP\_mpz\_mul. Each SLIP GMP/MPFR function returns SLIP\_OK if successful or the correct error code if not. The following table gives a brief list of each currently covered SLIP GMP/MPFR function. For a detailed description of each function, refer to SLIP\_LU/Source/SLIP\_gmp.c.

If additional GMP and MPFR functions are needed in the end-user application, this wrapper mechanism can be extended to those functions. Below are instructions on how to do this.

Given a GMP function void gmpfunc(TYPEa a, TYPEb b, ...), where TYPEa and TYPEb can be GMP type data (mpz\_t, mpq\_t and mpfr\_t, for example) or non-GMP type data (int, double, for example), and they need not to be the same. A wrapper for a new GMP or MPFR function can be created by following this outline:

```
SLIP_info SLIP_gmpfunc
    TYPEa a,
    TYPEb b,
)
{
    // Start the GMP Wrappter
    // uncomment one of the following:
    // If this function is not modifying any GMP/MPFR type variable, then use
    //SLIP_GMP_WRAPPER_START;
    // If this function is modifying mpz_t type (say TYPEa = mpz_t), then use
    //SLIP_GMPZ_WRAPPER_START(a) ;
    // If this function is modifying mpq_t type (say TYPEa = mpq_t), then use
    //SLIP_GMPQ_WRAPPER_START(a) ;
    // If this function is modifying mpfr_t type (say TYPEa = mpfr_t), then use
    //SLIP_GMPFR_WRAPPER_START(a) ;
    // Call the GMP function
    gmpfunc(a,b,...);
    //Finish the wrapper and return ok if successful.
    SLIP_GMP_WRAPPER_FINISH;
    return SLIP_OK;
}
```

Note that, other than SLIP\_mpfr\_fprintf, SLIP\_gmp\_fprintf, SLIP\_gmp\_printf and SLIP\_gmp\_fscanf, all of the wrapped GMP/MPFR functions always return SLIP\_info to the caller. Therefore, for some GMP/MPFR functions that have their

own return value. For example, for int mpq\_cmp(const mpq\_t a, const mpq\_t b), the return value becomes a parameter of the wrapped function. In general, a GM-P/MPFR function in the form of TYPEr gmpfunc(TYPEa a, TYPEb b, ...), the wrapped function can be constructed as follows:

MPFR Function	SLIP_MPFR Function	Description
		Description
n = mpfr_asprintf(&buff, fmt,)	n = SLIP_mpfr_asprintf(&buff, fmt,)	Print format to allocated string
mpfr_free_str(buff)	SLIP_mpfr_free_str(buff)	Free string allocated by MPFR
mpfr_init2(x, size)	SLIP_mpfr_init2(x, size)	Initialize x with size bits
mpfr_set(x, y, rnd)	SLIP_mpfr_set(x, y, rnd)	x = y
mpfr_set_d(x, y, rnd)	SLIP_mpfr_set_d(x, y, rnd)	x = y (double)
mpfr_set_q(x, y, rnd)	SLIP_mpfr_set_q(x, y, rnd)	$x = y \; (\texttt{mpq\_t})$
<pre>mpfr_set_z(x, y, rnd)</pre>	SLIP_mpfr_set_z(x, y, rnd)	$x = y \; (\texttt{mpz\_t})$
<pre>mpfr_get_z(x, y, rnd)</pre>	<pre>SLIP_mpfr_get_z(x, y, rnd)</pre>	$(\mathtt{mpz\_t}) \ x = y$
x = mpfr_get_d(y, rnd)	<pre>SLIP_mpfr_get_d(x, y, rnd)</pre>	(double) $x = y$
mpfr_mul(x, y, z, rnd)	SLIP_mpfr_mul(x, y, z, rnd)	x = y * z
<pre>mpfr_mul_d(x, y, z, rnd)</pre>	SLIP_mpfr_mul_d(x, y, z, rnd)	x = y * z
<pre>mpfr_div_d(x, y, z, rnd)</pre>	SLIP_mpfr_div_d(x, y, z, rnd)	x = y/z
<pre>mpfr_ui_pow_ui(x, y, z, rnd)</pre>	SLIP_mpfr_ui_pow_ui(x, y, z, rnd)	$x = y^z$
mpfr_log2(x, y, rnd)	SLIP_mpfr_log2(x, y, rnd )	$x = \log_2(y)$
mpfr_free_cache()	SLIP_mpfr_free_cache()	Free cache after log2
GMP Function	SLIP_GMP Function	Description
n = gmp_fscanf(fp, fmt,)	n = SLIP_gmp_fscanf(fp, fmt,)	Read from file fp
mpz_init(x)	SLIP_mpz_init(x)	Initialize x
mpz_init(x) mpz_init2(x, size)	SLIP_mpz_init2(x, size)	Initialize x Initialize x to size bits
mpz_initz(x, size) mpz_set(x, y)	SLIP_mpz_init2(x, size) SLIP_mpz_set(x, y)	$x = y \text{ (mpz_t)}$
mpz_set(x, y) mpz_set_ui(x, y)	- •	$x = y \text{ (mpz_t)}$ x = y  (signed int)
	SLIP_mpz_set_ui(x, y)	x = y (signed int) x = y (unsigned int)
mpz_set_si(x, y)	SLIP_mpz_set_si(x, y)	
mpz_set_d(x, y)	SLIP_mpz_set_d(x, y)	x = y (double)
x = mpz_get_d(y)	SLIP_mpz_get_d(x, y)	x = y (double out)
mpz_set_q(x, y)	SLIP_mpz_set_q(x, y)	$x = y \; (\texttt{mpz\_t})$
mpz_mul(x, y, z)	SLIP_mpz_mul(x, y, z)	x = y * z
mpz_add(x, y, z)	SLIP_mpz_add(x, y, z)	x = y + z
mpz_addmul(x, y, z)	SLIP_mpz_addmul(x, y, z)	x = x + y * z
mpz_submul(x, y, z)	SLIP_mpz_submul(x, y, z)	x = x - y * z
mpz_divexact(x, y, z)	SLIP_mpz_divexact(x, y, z)	x = y/z
gcd = mpz_gcd(x, y)	SLIP_mpz_gcd(gcd, x, y)	gcd = gcd(x, y)
<pre>lcm = mpz_lcm(x, y)</pre>	SLIP_mpz_lcm(lcm, x, y)	lcm = lcm(x, y)
mpz_abs(x, y)	SLIP_mpz_abs(x, y)	x =  y
$r = mpz_cmp(x, y)$	SLIP_mpz_cmp(r, x, y)	r = 0  if  x = y
		$r \neq 0 \text{ if } x \neq y$
r = mpz_cmpabs(x, y)	SLIP_mpz_cmpabs(r, x, y)	r=0  if   x = y
		$r \neq 0 \text{ if }  x  \neq  y $
r = mpz_cmp_ui(x, y)	SLIP_mpz_cmp_ui(r, x, y)	r = 0  if  x = y
		$r \neq 0 \text{ if } x \neq y$
sgn = mpz_sgn(x)	SLIP_mpz_sgn(sgn, x)	sgn = 0  if  x = 0
<pre>size = mpz_sizeinbase(x, base)</pre>	<pre>SLIP_mpz_sizeinbase(size, x, base)</pre>	size of x in base
<pre>mpq_init(x)</pre>	SLIP_mpq_init(x)	Initialize x
<pre>mpq_set(x, y)</pre>	<pre>SLIP_mpq_set(x, y)</pre>	x = y
<pre>mpq_set_z(x, y)</pre>	SLIP_mpq_set_z(x, y)	x = y  (mpz)
mpq_set_d(x, y)	SLIP_mpq_set_d(x, y)	x = y  (double)
<pre>mpq_set_ui(x, y, z)</pre>	SLIP_mpq_set_ui(x, y, z)	x = y/z (unsigned int)
<pre>mpq_set_num(x, y)</pre>	SLIP_mpq_set_num(x, y)	num(x) = y
<pre>mpq_set_den(x, y)</pre>	SLIP_mpq_set_den(x, y)	den(x) = y
<pre>mpq_get_den(x, y)</pre>	SLIP_mpq_get_den(x, y)	x = den(y)
x = mpq_get_d(y)	SLIP_mpq_get_d(x, y)	(double) $x = y$
mpq_abs(x, y)	SLIP_mpq_abs(x, y)	x =  y
mpq_add(x, y, z)	SLIP_mpq_add(x, y, z)	x = y + z
mpq_mul(x, y, z)	SLIP_mpq_mul(x, y, z)	x = y * z
mpq_div(x, y, z)	SLIP_mpq_div(x, y, z)	x = y/z
$r = mpq\_cmp(x, y)$	SLIP_mpq_cmp(r, x, y)	r = 0 if $x = y$
11-15-77	- 1 1- 1 · 7 ·-7 J/	$r \neq 0 \text{ if } x \neq y$
r = mpq_cmp_ui(x, n, d)	SLIP_mpq_cmp_ui(r, x, n, d)	$r \neq 0$ if $x \neq g$ r = 0 if $x = n/d$
	28	$r \neq 0 \text{ if } x = n/d$
r = mpq_equal(x, y)	SLIP_mpq_equal(r, x, y)	r = 0  if  x = y
		$ \begin{array}{c} r = 0 \text{ if } x = y \\ r \neq 0 \text{ if } x \neq y \end{array} $
		, 7 0 11 4 7 9

## 10 Using SLIP LU in C

Using SLIP LU in C has three steps:

- 1. initialize and populate data structures,
- 2. perform symbolic analysis, factorize the matrix A and solve the linear system for each b vector, and
- 3. free all used memory and finalize.

Step 1 is discussed in Section 10.1. For Step 2, performing symbolic analysis and factorizing A and solving the linear Ax = b can be done in one of two ways. If only the solution vector x is required, SLIP LU provides a simple interface for this purpose which is discussed in Section 10.2. Alternatively, if the L and U factors are required, refer to Section 10.3. Finally, step 3 is discussed in Section 10.4. For the remainder of this section,  $\mathbf{n}$  will indicate the dimension of A (that is,  $A \in \mathbb{Z}^{n \times n}$ ) and  $\mathbf{n}$  numres will indicate the number of right hand side vectors being solved (that is, if  $\mathbf{n}$  numres  $\mathbf{n}$ , then  $\mathbf{n}$  is  $\mathbf{n}$ .

## 10.1 SLIP LU initialization and population of data structures

This section discusses how to initialize and populate the global data structures required for SLIP LU.

#### 10.1.1 Initializing the environment

SLIP LU is built upon the GNU Multiple Precision Arithmetic (GMP) [7] and GNU Multiple Precision Floating Point Reliable (MPFR) [6] libraries and provides wrappers to all GMP/MPFR functions it uses. This allows SLIP LU to properly handle memory management failures, which GMP/MPFR does not handle. To enable this mechanism, SLIP LU requires initialization. The following must be done before using any other SLIP LU function:

```
SLIP_initialize ( ) ;
// or SLIP_initialize_expert (...); if custom memory functions are desired
```

#### 10.1.2 Initializing data structures

SLIP LU assumes three specific input options for all functions. These are:

- SLIP\_matrix\* A and SLIP\_matrix \*b: A contains the input coefficient matrix, while b contains the right hand side vector(s) of the linear system Ax = b. If the input matrix was already an integer matrix, A is the user's input and A->scale=1. Otherwise, the input matrix is not integer and A contains the user's scaled input matrix. b is handled in the same way.
- SLIP\_LU\_analysis\* S: S contains the column permutation used for A as well as estimates of the number of nonzeros in L and U.
- SLIP\_options\* option: option contains various control options for the factorization including column ordering used, pivot selection scheme, and others. For a full list of the contents of the SLIP\_options structure, refer to Section 6. If default settings are desired, option can be set to NULL.

#### 10.1.3 Populating data structures

Of the three data structures discussed in Section 10.1.2, S is constructed during symbolic analysis (Section 8.2), and option is an optional parameter for selecting non-default parameters. Refer to Section 6 for the contents of option.

SLIP LU allows the input numerical data for A and b to come in one of 5 types: int64\_t, double, mpfr\_t, mpq\_t, and mpz\_t. Moreover, both A and b can be stored in CSC form, sparse triplet form or dense form. CSC form is discussed in Section 1. The triplet form stores the contents of the matrix A in three arrays i, j, and x where the kth nonzero entry is stored as A(i[k], j[k]) = x[k]. SLIP LU stores its dense matrices in in column-oriented format, that is, the (i, j)th entry in A is A->x.TYPE[p] with p = i + j\*A->m.

If the data for matrices are in file format to be read, refer to SLIP\_LU/Demo/example2.c on how to read in data and construct A and b. If the data for matrices are already stored in vectors corresponding to CSC form, sparse triplet form or dense form, allocate a shallow SLIP\_matrix and assign vectors accordingly, then use SLIP\_matrix\_copy to get a SLIP\_matrix in the desired kind and type. For more details, refer to SLIP\_LU/Demo/example.c. In a case when A is available in format other than CSC mpz, and/or b is available in format other than dense mpz, the following code snippet shows how to get A and b in a required format.

```
/* Get the matrix A. Assume that A1 is stored in CSC form
  with mpfr_t entries, while b1 is stored in triplet form
  with mpq_t entries. (for A1 and b1 in any other form,
    the exact same code will work) */

SLIP_matrix *A, *b;
// A is a copy of the A1. A is a CSC matrix with mpz_t entries
SLIP_matrix_copy(&A, SLIP_CSC, SLIP_MPZ, A1, option);
// b is a copy of the b1. b is a dense matrix with mpz_t entries.
SLIP_matrix_copy(&b, SLIP_DENSE, SLIP_MPZ, b1, option);
```

## 10.2 Simple SLIP LU routines for solving linear systems

After initializing the necessary data structures, SLIP LU obtains the solution to Ax = b using the simple interface of SLIP LU, SLIP\_backslash. The SLIP\_backslash function can return x as double, mpq\_t, or mpfr\_t with an associated precision. See Section 8.6 for more details. The following code snippet shows how to get solution as a dense mpq\_t matrix.

```
SLIP_matrix *x;
SLIP_type my_type = SLIP_MPQ; // SLIP_MPQ, SLIP_MPFR, SLIP_FP64
SLIP_backslash(&x, my_type, A, b, option);
```

On successful return, this function returns SLIP\_OK (see Section 4.2).

## 10.3 Expert SLIP LU routines

If the L and U factors from the SLIP LU factorization of the matrix A are required, the steps performed by SLIP\_backslash can be done with a sequence of calls to SLIP LU functions:

- 1. declare L, U, the solution matrix x, and others,
- 2. perform symbolic analysis,
- 3. compute the factorization PAQ = LDU,
- 4. solve the linear system Ax = b, and
- 5. convert the final solution into the final desired form.

These steps are discussed below, along with examples.

#### 10.3.1 Declare workspace

Using SLIP LU in this form requires the intermediate variables be declared, such as L, U, etc. The following code snippet shows the detailed list.

```
// A and b are in required type and ready to use
SLIP_matrix *L = NULL;
SLIP_matrix *V = NULL;
SLIP_matrix *x = NULL;
SLIP_matrix *rhos = NULL;
int64_t* pinv = NULL;
SLIP_LU_analysis* S = NULL;

// option needs no declaration if default setting is desired
// only declare option for further modification on default setting
SLIP_options *option = SLIP_create_default_options();
```

#### 10.3.2 SLIP LU symbolic analysis

The symbolic analysis phase of SLIP LU computes the column permutation and estimates of the number of nonzeros in L and U. This function is called as:

```
SLIP_LU_analyze (&S, A, option) ;
```

#### 10.3.3 Computing the factorization

The matrices L and U, the pivot sequence rhos, and the row permutation pinv are computed via the SLIP\_LU\_factorize function (Section 8.4). Upon successful completion, this function returns SLIP\_OK.

#### 10.3.4 Solving the linear system

After factorization, the next step is to solve the linear system and store the solution as a dense matrix **x** with entries of rational number mpq\_t. This solution is done via the SLIP\_LU\_solve function (Section 8.5). Upon successful completion, this function returns SLIP\_OK.

In this step, option->check can be set to true to enable the solution check process as discussed in Section 8.5. The process can verify that the solution vector x satisfies Ax = b in perfect precision intended for debugging. This step is not needed, since the solution returned is guaranteed to be exact. It appears here simply as

debugging tool, and as a verification that SLIP LU is computing its expected result. This test can fail only if it runs out of memory, or if there is a bug in the code (in which case, please notify the authors). Also, note that this process can be quite time consuming; thus it is not recommended to be used in general.

#### 10.3.5 Converting the solution vector to the final desired form

Upon completion of the above routines, the solution to the linear system is in a dense mpq\_t matrix. SLIP LU allows this to be converted into any form of matrix in the set of (CSC, sparse triplet, dense) × (mpfr\_t, mpq\_t, double) using SLIP\_matrix\_copy. The following code snippet shows how to get solution as a dense double matrix; since this involves a floating-point representation, the solution my\_x will no longer be exact, even though x is the exact solution.

```
SLIP_kind my_kind = SLIP_DENSE; // SLIP_CSC, SLIP_TRIPLET or SLIP_DENSE
SLIP_type my_type = SLIP_FP64; // SLIP_MPQ, SLIP_MPFR, or SLIP_FP64
SLIP_matrix* my_x = NULL; // New output
// Create copy which is stored as my_kind and my_type:
SLIP_matrix_copy( &my_x, my_kind, my_type, x, option);
```

### 10.4 Freeing memory

As described in Section 5, SLIP LU provides a number of functions/macros to free SLIP LU objects:

- SLIP\_matrix\*: A SLIP\_matrix\* A data structure can be freed with a call to SLIP\_matrix\_free(&A, NULL);
- SLIP\_LU\_analysis\*: A SLIP\_LU\_analysis\* S data structure can be freed with a call to SLIP\_LU\_analysis\_free(&S, NULL);
- All others including SLIP\_options\*: These data structures can be freed with a call to the macro SLIP\_FREE(), for example, SLIP\_FREE(option) for SLIP\_options\* option.

After all usage of the SLIP LU routines is finished, SLIP\_finalize() must be called (Section 4.5) to finalize usage of the library.

## 10.5 Examples of using SLIP LU in a C program

The SLIP\_LU/Demo folder contains three sample C codes which utilize SLIP LU. These files demonstrate the usage of SLIP LU as follows:

- example.c: This example generates a random dense  $50 \times 50$  matrix and a random dense  $50 \times 1$  right hand side vector b and solves the linear system. In this function, the SLIP\_backslash function is used; and the output is given as a double matrix.
- example2.c: This example reads in a matrix stored in triplet format from the ExampleMats folder. Additionally, it reads in a right hand side vector from this folder and solves the associated linear system via the SLIP\_backslash function, and, the solution is given as a matrix of rational numbers.
- SLIPLU.c: This example reads in a matrix and right hand side vector from a file and solves the linear system Ax = b using the techniques discussed in Section 10.3. This file also allows command line arguments (discussed in README.md) and can be used to replicate the results from [8].

## 11 Using SLIP LU in MATLAB

After following the installation steps discussed in Section 3, using the SLIP LU factorization within MATLAB can be done via the SLIP\_backslash.m function. First, this section describes the options struct in Section 11.1. The use of the factorization is discussed in Section 11.2. The SLIP\_LU/MATLAB folder must be in your MATLAB path.

## 11.1 Optional parameter settings

The SLIP LU MATLAB interface includes an option struct as in optional input parameter that modifies behavior. If this parameter is not provided, default parameter settings are used. The elements of the option struct are listed below. Any fields not present in the struct are treated as their default values.

- option.pivot: This parameter is a string that controls the pivoting scheme used. When selecting a pivot entry in a given column, the factorization method uses one of the following pivoting strategies:
  - 'smallest': smallest pivot,
  - 'diagonal': diagonal pivot if possible, otherwise smallest pivot,
  - 'first': first nonzero pivot in each column,
  - 'tol smallest': (default) diagonal pivot with a tolerance (option.tol) for the smallest pivot,
  - 'tol largest': diagonal pivot with a tolerance (option.tol) for the largest pivot,
  - 'largest': largest pivot.

The options 'tol smallest' or 'diagonal' are most recommended for this parameter, unless the Doolittle factors are being computed, in which case 'largest' may be appropriate (due to the size of numbers in Doolittle).

- option.order: This parameter is a string controls the fill-reducing column preordering used.
  - 'none': no column ordering; factorize A as-is.
  - 'colamd': COLAMD ordering (default)

- 'amd': AMD ordering

The 'colamd' is recommended for most cases. The 'AMD' ordering is suitable if the nonzero pattern of A is mostly symmetric. In this case, option.pivot = 'diagonal' is a useful option.

- option.tol: This parameter determines the tolerance used if one of the threshold pivoting schemes is chosen. The default value is 0.1 and this parameter can take any value in the range (0, 1].
- option.solution: a string determining how x is to be returned:
  - 'double': x is converted to a 64-bit floating-point approximate solution.
     This is the default.
  - 'vpa': x is returned as a vpa array with option.digits digits (default is given by the MATLAB digits function). The result may be inexact, if an entry in x cannot be represented in the specified number of digits. To convert this x to double, use x=double(x).
  - 'char': x is returned as a cell array of strings, where x {i} = 'numerator/denominator' and both numerator and denominator are arbitrary-length strings of decimal digits. The result is always exact, although x cannot be directly used in MATLAB for numerical calculations. It can be inspected or analyzed using MATLAB string manipulation. To convert x to vpa, use x=vpa(x). To convert x to double, use x=double(vpa(x)).
- option.digits: the number of decimal digits to use for x, if option.solution is 'vpa'. Must be in range 2 to 2<sup>29</sup>.
- option.print: display the inputs and outputs (0: nothing (default), 1: just errors, 2: terse, 3: all).

#### 11.2 SLIP\_backslash.m

The SLIP\_backslash.m function solves the linear system Ax = b where  $A \in \mathbb{R}^{n \times n}$ ,  $x \in \mathbb{R}^{n \times m}$  and  $b \in \mathbb{R}^{n \times m}$ . The final solution vector(s) obtained via this function are exact prior to their conversion to double precision.

The SLIP LU function expects as input a sparse matrix A and dense set of right hand side vectors b. Optionally, option struct can be passed in. Currently, there are 2 ways to use this function outlined below:

- x = SLIP\_backslash(A,b) returns the solution to Ax = b using default settings. The solution vectors are more accurate than the solution obtained via x = A \ b. The solution x is returned as a MATLAB double matrix.
- $x = SLIP_backslash(A,b,option)$  returns the solution to Ax = b using non-default settings from the option struct.

If the result x is held as a MATLAB double matrix, in conventional floating-point representation (double), it is guaranteed to be exact only if the exact solution can be held in double without modification.

The solution x may also be returned as a MATLAB vpa array, or as a cell array of strings; See Section 11.1 for details.

## References

- [1] P. R. AMESTOY, T. A. DAVIS, AND I. S. DUFF, An approximate minimum degree ordering algorithm, SIAM Journal on Matrix Analysis and Applications, 17 (1996), pp. 886–905.
- [2] —, Algorithm 837: AMD, an approximate minimum degree ordering algorithm, ACM Transactions on Mathematical Software (TOMS), 30 (2004), pp. 381–388.
- [3] T. Davis, SuiteSparse, 2020. http://faculty.cse.tamu.edu/davis/suitesparse.html.
- [4] T. A. Davis, J. R. Gilbert, S. I. Larimore, and E. G. Ng, Algorithm 836: COLAMD, a column approximate minimum degree ordering algorithm, ACM Transactions on Mathematical Software (TOMS), 30 (2004), pp. 377–380.
- [5] \_\_\_\_\_, A column approximate minimum degree ordering algorithm, ACM Transactions on Mathematical Software (TOMS), 30 (2004), pp. 353–376.
- [6] L. Fousse, G. Hanrot, V. Lefèvre, P. Pélissier, and P. Zimmermann, MPFR: a multiple-precision binary floating-point library with correct rounding, ACM Transactions on Mathematical Software (TOMS), 33 (2007), p. 13.
- [7] T. Granlund et al., GNU MP 6.0 Multiple Precision Arithmetic Library, Samurai Media Limited, 2015.
- [8] C. Lourenco, A. R. Escobedo, E. Moreno-Centeno, and T. A. Davis, Exact solution of sparse linear systems via left-looking roundoff-error-free LU factorization in time proportional to arithmetic work, SIAM Journal on Matrix Analysis and Applications, 40 (2019), pp. 609–638.