

AFDMC-TBF

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I. PROGRESS 2-26: SOME UNDERSTANDING ABOUT CORRELATOR.F90

A. the 15 operators in F_{ij}

The trial wave function can be written as

$$\langle \Psi_T | RS \rangle = \langle \Phi | \left[\prod_{i < j} f_c(r_{ij}) \right] \left[1 + \sum_{i < j} F_{ij} + \sum_{i < j < k} F_{ijk} \right] | RS \rangle. \quad (1)$$

For example, v6' interaction for the F_{ij} , we can write down

$$u_{ij}^1 + u_{ij}^2 \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j + u_{ij}^3 \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + u_{ij}^4 \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j + u_{ij}^5 (3\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} - \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j) + u_{ij}^6 (3\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} - \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j) \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j, \quad (2)$$

for convenience just mark $\hat{\mathbf{r}}_{ij}$ as $\hat{\mathbf{r}}$.

the 4 and 6 operators can be combined as

$$\tau_{i\gamma} \tau_{j\gamma} \sigma_{i\alpha} \sigma_{j\beta} \underbrace{[(u_{ij}^4 - u_{ij}^6) \delta_{\alpha\beta} + 3u_{ij}^6 r_\alpha r_\beta]}_{\equiv A_{\alpha\beta}} = \lambda_\eta (\tau_{i\gamma} \sigma_{i\alpha} \phi_{\alpha\eta}) (\tau_{j\gamma} \sigma_{j\beta} \phi_{\beta\eta}), \quad (3)$$

where the eigenvector matrix ϕ is orthogonal ($\phi^T \phi = \mathbb{1}$) and eigenvalues are $\lambda_{1,2,3}$,

$$A\phi = \phi \text{diag}(\lambda_1, \lambda_2, \lambda_3). \quad (4)$$

The eigenvectors and eigenvalues can be calculated by using the matrixmod module.

In the code, the accordingly operators are

$$\hat{O}^4 = \tau_x [\sigma_x \text{vec}(1, 1) + \sigma_y \text{vec}(2, 1) + \sigma_z \text{vec}(3, 1)] = \tau_x \sigma_\alpha \phi_{\alpha 1} \quad (5)$$

$$\hat{O}^5 = \tau_y [\sigma_x \text{vec}(1, 1) + \sigma_y \text{vec}(2, 1) + \sigma_z \text{vec}(3, 1)] = \tau_y \sigma_\alpha \phi_{\alpha 1} \quad (6)$$

$$\hat{O}^6 = \tau_z [\sigma_x \text{vec}(1, 1) + \sigma_y \text{vec}(2, 1) + \sigma_z \text{vec}(3, 1)] = \tau_z \sigma_\alpha \phi_{\alpha 1} \quad (7)$$

$$\hat{O}^7 = \tau_x [\sigma_x \text{vec}(1, 2) + \sigma_y \text{vec}(2, 2) + \sigma_z \text{vec}(3, 2)] = \tau_x \sigma_\alpha \phi_{\alpha 2} \quad (8)$$

$$\hat{O}^8 = \tau_y [\sigma_x \text{vec}(1, 2) + \sigma_y \text{vec}(2, 2) + \sigma_z \text{vec}(3, 2)] = \tau_y \sigma_\alpha \phi_{\alpha 2} \quad (9)$$

$$\hat{O}^9 = \tau_z [\sigma_x \text{vec}(1, 2) + \sigma_y \text{vec}(2, 2) + \sigma_z \text{vec}(3, 2)] = \tau_z \sigma_\alpha \phi_{\alpha 2} \quad (10)$$

$$\hat{O}^{10} = \tau_x [\sigma_x \text{vec}(1, 3) + \sigma_y \text{vec}(2, 3) + \sigma_z \text{vec}(3, 3)] = \tau_x \sigma_\alpha \phi_{\alpha 3} \quad (11)$$

$$\hat{O}^{11} = \tau_y [\sigma_x \text{vec}(1, 3) + \sigma_y \text{vec}(2, 3) + \sigma_z \text{vec}(3, 3)] = \tau_y \sigma_\alpha \phi_{\alpha 3} \quad (12)$$

$$\hat{O}^{12} = \tau_z [\sigma_x \text{vec}(1, 3) + \sigma_y \text{vec}(2, 3) + \sigma_z \text{vec}(3, 3)] = \tau_z \sigma_\alpha \phi_{\alpha 3}. \quad (13)$$

Obviously, $\phi_{\alpha\beta} = \text{vec}(\alpha, \beta)$.

On the other hand, the eigenvalues and eigenvector have their physical meaning and can be calculated directly. It is that,

$$\begin{aligned} & u_{ij}^4 \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j + u_{ij}^6 (3\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} - \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j) \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j \\ &= \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j [(u_{ij}^4 - u_{ij}^6) \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + 3u_{ij}^6 \boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij}], \end{aligned} \quad (14)$$

for the inner part, $(u_{ij}^4 - u_{ij}^6) \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + 3u_{ij}^6 \boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij}$, we can choose three basic directions (just like the x, y, z directions in the cartesian coordinates), $\hat{\mathbf{r}}$, $\hat{\mathbf{r}}_{\perp 1}$ and $\hat{\mathbf{r}}_{\perp 2}$, and they are perpendicular with each other. For a given direction $\hat{\mathbf{r}}$, the two perpendicular directions $\hat{\mathbf{r}}_{\perp 1}$ and $\hat{\mathbf{r}}_{\perp 2}$ can be easily chosen. Then for the inner part, we have

$$\begin{aligned} \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j &= (\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}})(\boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}) + (\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{\perp 1})(\boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{\perp 1}) + (\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{\perp 2})(\boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{\perp 2}) \\ &= \sigma_{i\alpha} r_\alpha \sigma_{j\beta} r_\beta + \sigma_{i\alpha} r_{\perp 1\alpha} \sigma_{j\beta} r_{\perp 1\beta} + \sigma_{i\alpha} r_{\perp 2\alpha} \sigma_{j\beta} r_{\perp 2\beta} \end{aligned} \quad (15)$$

and

$$\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} = \sigma_{i\alpha} r_\alpha \sigma_{j\beta} r_\beta, \quad (16)$$

where the α, β go through x, y, and z components. Combining those results, the inner part can be written as

$$\begin{aligned} & (u_{ij}^4 - u_{ij}^6) \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + 3u_{ij}^6 \boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} \\ &= (u_{ij}^4 + 2u_{ij}^6) (\sigma_{i\alpha} r_\alpha) (\sigma_{j\beta} r_\beta) \\ &+ (u_{ij}^4 - u_{ij}^6) (\sigma_{i\alpha} r_{\perp 1\alpha}) (\sigma_{j\beta} r_{\perp 1\beta}) \\ &+ (u_{ij}^4 - u_{ij}^6) (\sigma_{i\alpha} r_{\perp 2\alpha}) (\sigma_{j\beta} r_{\perp 2\beta}). \end{aligned} \quad (17)$$

Then we have

$$\begin{aligned} & u_{ij}^4 \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j + u_{ij}^6 (3\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} - \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j) \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j \\ &= \boldsymbol{\tau}_i \cdot \boldsymbol{\tau}_j [(u_{ij}^4 - u_{ij}^6) \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + 3u_{ij}^6 \boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij}] \\ &= (u_{ij}^4 + 2u_{ij}^6) [\tau_{i\gamma} (\sigma_{i\alpha} r_\alpha)] [\tau_{j\gamma} (\sigma_{j\beta} r_\beta)] \\ &+ (u_{ij}^4 - u_{ij}^6) [\tau_{i\gamma} (\sigma_{i\alpha} r_{\perp 1\alpha})] [\tau_{j\gamma} (\sigma_{j\beta} r_{\perp 1\beta})] \\ &+ (u_{ij}^4 - u_{ij}^6) [\tau_{i\gamma} (\sigma_{i\alpha} r_{\perp 2\alpha})] [\tau_{j\gamma} (\sigma_{j\beta} r_{\perp 2\beta})], \end{aligned} \quad (18)$$

and compare with Eq.(3), we will know that

$$\begin{aligned} r_\alpha &= \phi_{\alpha 1} \\ \lambda_1 &= u_{ij}^4 + 2u_{ij}^6 \\ r_{\perp 1\alpha} &= \phi_{\alpha 2} \\ \lambda_2 &= u_{ij}^4 - u_{ij}^6 \\ r_{\perp 2\alpha} &= \phi_{\alpha 3} \\ \lambda_3 &= u_{ij}^4 - u_{ij}^6 = \lambda_2. \end{aligned} \quad (19)$$

Similarly, the 3 and 5 operators can be combined as

$$\begin{aligned} & u_{ij}^3 \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + u_{ij}^5 (3\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} - \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j) \\ &= (u_{ij}^3 - u_{ij}^5) \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + 3u_{ij}^5 \boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} \\ &= 3u_{ij}^5 (\sigma_{i\alpha} r_\alpha) (\sigma_{j\beta} r_\beta) + (u_{ij}^3 - u_{ij}^5) [\sigma_{i\alpha} r_\alpha \sigma_{j\beta} r_\beta + \sigma_{i\alpha} r_{\perp 1\alpha} \sigma_{j\beta} r_{\perp 1\beta} + \sigma_{i\alpha} r_{\perp 2\alpha} \sigma_{j\beta} r_{\perp 2\beta}] \\ &= (u_{ij}^3 + 2u_{ij}^5) \sigma_{i\alpha} r_\alpha \sigma_{j\beta} r_\beta + (u_{ij}^3 - u_{ij}^5) \sigma_{i\alpha} r_{\perp 1\alpha} \sigma_{j\beta} r_{\perp 1\beta} + (u_{ij}^3 - u_{ij}^5) \sigma_{i\alpha} r_{\perp 2\alpha} \sigma_{j\beta} r_{\perp 2\beta}. \end{aligned} \quad (20)$$

And this gives the \hat{O}^{13} , \hat{O}^{14} and \hat{O}^{15} . That is

$$\hat{O}^{13} = \sigma_x \text{vecs}(1, 1) + \sigma_y \text{vecs}(2, 1) + \sigma_z \text{vecs}(3, 1) = \sigma_{i\alpha} r_\alpha \sigma_{j\beta} r_\beta \quad (21)$$

$$\hat{O}^{14} = \sigma_x \text{vecs}(1, 2) + \sigma_y \text{vecs}(2, 2) + \sigma_z \text{vecs}(3, 2) = \sigma_{i\alpha} r_{\perp 1\alpha} \sigma_{j\beta} r_{\perp 1\beta} \quad (22)$$

$$\hat{O}^{15} = \sigma_x \text{vecs}(1, 3) + \sigma_y \text{vecs}(2, 3) + \sigma_z \text{vecs}(3, 3) = \sigma_{i\alpha} r_{\perp 2\alpha} \sigma_{j\beta} r_{\perp 2\beta}. \quad (23)$$

On the other hand, still we can write down

$$\begin{aligned} & u_{ij}^3 \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j + u_{ij}^5 (3\boldsymbol{\sigma}_i \cdot \hat{\mathbf{r}}_{ij} \boldsymbol{\sigma}_j \cdot \hat{\mathbf{r}}_{ij} - \boldsymbol{\sigma}_i \cdot \boldsymbol{\sigma}_j) \\ &= \sigma_{i\alpha} \sigma_{j\beta} \underbrace{[3u_{ij}^5 r_\alpha r_\beta + (u_{ij}^3 - u_{ij}^5) \delta_{\alpha\beta}]}_{\equiv A_{\alpha\beta}} \\ &= \sigma_{i\alpha} A_{\alpha\beta} \sigma_{j\beta} \\ &= \sigma_{i\alpha} \psi_{\alpha\eta} \lambda_\eta \psi_{\beta\eta} \sigma_{j\beta} \\ &= \lambda_\eta (\sigma_{i\alpha} \psi_{\alpha\eta}) (\sigma_{j\beta} \psi_{\beta\eta}). \end{aligned} \quad (24)$$

Again it gives \hat{O}^{13} , \hat{O}^{14} and \hat{O}^{15} . Comparing with Eq.(20), we have

$$\begin{aligned}
r_\alpha &= \phi_{\alpha 1} \\
\lambda_1 &= u_{ij}^3 + 2u_{ij}^5 \\
r_{\perp 1\alpha} &= \phi_{\alpha 2} \\
\lambda_2 &= u_{ij}^3 - u_{ij}^5 \\
r_{\perp 2\alpha} &= \phi_{\alpha 3} \\
\lambda_3 &= u_{ij}^3 - u_{ij}^5 = \lambda_2.
\end{aligned} \tag{25}$$

Finally,

$$\hat{O}^{1,2,3} = \tau_x, \tau_y, \tau_z \tag{26}$$

just taken from $u_{ij}^2 \tau_i \cdot \tau_j = u_{ij}^2 \tau_{i\alpha} \tau_{j\alpha}$.

So, until here, the meaning of the 15 operators in the code is clear. And the two-body correlation operator F_{ij} can be written as

$$F_{ij} = u_{ij}^1 + u_{ij}^2 \tau_{i\alpha} \tau_{j\alpha} + \lambda_\eta^{(\tau\sigma)} (\tau_{i\gamma} \sigma_{i\alpha} \phi_{\alpha\eta}) (\tau_{j\gamma} \sigma_{j\beta} \phi_{\beta\eta}) + \lambda_\eta^{(\sigma)} (\sigma_{i\alpha} \psi_{\alpha\eta}) (\sigma_{j\beta} \psi_{\beta\eta}) = u_{ij}^1 + \sum_{p=1}^{15} f_{ij}^p \hat{O}_i^p \hat{O}_j^p \tag{27}$$

B. The cartesian 39 operators

On the other hand, a traditional way is to write this interaction as 39 operators. That is, we can write down

$$F_{ij} = u_{ij}^1 + \sum_{\alpha} \tau_{i\alpha} A_{ij}^T \tau_{j\alpha} + \sum_{\alpha\beta} \sigma_{i\alpha} A_{ij}^\sigma \sigma_{j\beta} + \sum_{\alpha\beta\gamma} (\sigma_{i\alpha} \tau_{i\gamma}) A_{ij}^{\sigma\tau} (\sigma_{j\beta} \tau_{j\gamma}), \tag{28}$$

where

$$A_{ij}^T = u_{ij}^2 \tag{29}$$

$$A_{ij}^\sigma = u_{ij}^3 \delta_{\alpha\beta} + u_{ij}^5 (3\hat{r}_{ij}^\alpha \hat{r}_{ij}^\beta - \delta_{\alpha\beta}) \tag{30}$$

$$A_{ij}^{\sigma\tau} = u_{ij}^4 \delta_{\alpha\beta} + u_{ij}^6 (3\hat{r}_{ij}^\alpha \hat{r}_{ij}^\beta - \delta_{\alpha\beta}) \tag{31}$$

II. PROGRESS 2-18: SOME UNDERSTANDING ABOUT CORRELATOR.F90

A. two body correlation operator F_{ij}

The trial wave function can be written as

$$\langle \Psi_T | RS \rangle = \langle \Phi | \left[\prod_{i < j} f_c(r_{ij}) \right] \left[1 + \sum_{i < j} F_{ij} + \sum_{i < j < k} F_{ijk} \right] | RS \rangle, \quad (32)$$

Now, let us just look at $F_{ij} = \sum_p f_{ij}^p \hat{O}_{ij}^p$. For example, for v6' interaction we can write down

$$\begin{aligned} F_{ij} &= f_{ij}^1 \\ &+ \sum_{\alpha} \tau_{i\alpha} A_{ij}^{\tau} \tau_{j\alpha} \\ &+ \sum_{\alpha\beta} \sigma_{i\alpha} A_{ij}^{\sigma} \sigma_{j\beta} \\ &+ \sum_{\alpha\beta\gamma} (\sigma_{i\alpha} \tau_{i\gamma}) A_{ij}^{\sigma\tau} (\sigma_{j\beta} \tau_{j\gamma}), \end{aligned} \quad (33)$$

where

$$\begin{aligned} A_{ij}^{\tau} &= f_{ij}^2 \\ A_{ij}^{\sigma} &= f_{ij}^3 \delta_{\alpha\beta} + f_{ij}^5 (3\hat{r}_{ij}^{\alpha} \hat{r}_{ij}^{\beta} - \delta_{\alpha\beta}) \\ A_{ij}^{\sigma\tau} &= f_{ij}^4 \delta_{\alpha\beta} + f_{ij}^6 (3\hat{r}_{ij}^{\alpha} \hat{r}_{ij}^{\beta} - \delta_{\alpha\beta}). \end{aligned} \quad (34)$$

All the A matrices are real and symmetric and can be diagonalize by their real eigenvector matrices. For example,

$$A = \psi \text{diag}(\lambda_1, \lambda_2 \dots \lambda_A) \psi^{\dagger} \quad (35)$$

where λ_i are the eigenvalues of A . ψ is $n \times n$ matrix where n is the particle number, and ψ is composed of the $n \times 1$ column vectors of A . And therefore we can write down

$$A_{ij} = \sum_{k=1}^n \psi_{ik} \lambda_k \psi_{kj}^{\dagger} = \sum_{k=1}^n \psi_{ik} \lambda_k \psi_{jk}. \quad (36)$$

And then F_{ij} can be written as

$$\begin{aligned} F_{ij} &= f_{ij}^1 \\ &+ \sum_{\alpha} \sum_{k=1}^n (\tau_{i\alpha} \psi_{ik}^{\tau}) \lambda_k^{\tau} (\tau_{j\alpha} \psi_{jk}^{\tau}) \\ &+ \sum_{\alpha\beta} \sum_{k=1}^n (\sigma_{i\alpha} \psi_{ik}^{\sigma}) \lambda_k^{\sigma} (\sigma_{j\beta} \psi_{jk}^{\sigma}) \\ &+ \sum_{\alpha\beta\gamma} \sum_{k=1}^n (\sigma_{i\alpha} \tau_{i\gamma} \psi_{ik}^{\sigma\tau}) \lambda_k^{\sigma\tau} (\sigma_{j\beta} \tau_{j\gamma} \psi_{jk}^{\sigma\tau}). \end{aligned} \quad (37)$$

For a given i or j , there are 15 basic operators, which include $\tau_{\alpha}(3)$, $\sigma_{\alpha}(3)$ and $\sigma_{\alpha}\tau_{\beta}(9)$.

I have checked the code, and I found that in the correlator.f90, in subroutine v6tot, the 15 operators are,

$$\begin{aligned}\hat{O}^{1,2,3} &= \tau_x, \tau_y, \tau_z \\ \hat{O}^4 &= \tau_x[\sigma_x vec(1, 1) + \sigma_y vec(2, 1) + \sigma_z vec(3, 1)]\end{aligned}\quad (38)$$

$$\hat{O}^5 = \tau_y[\sigma_x vec(1, 1) + \sigma_y vec(2, 1) + \sigma_z vec(3, 1)] \quad (39)$$

$$\hat{O}^6 = \tau_z[\sigma_x vec(1, 1) + \sigma_y vec(2, 1) + \sigma_z vec(3, 1)] \quad (40)$$

$$\hat{O}^7 = \tau_x[\sigma_x vec(1, 2) + \sigma_y vec(2, 2) + \sigma_z vec(3, 2)] \quad (41)$$

$$\hat{O}^8 = \tau_y[\sigma_x vec(1, 2) + \sigma_y vec(2, 2) + \sigma_z vec(3, 2)] \quad (42)$$

$$\hat{O}^9 = \tau_z[\sigma_x vec(1, 2) + \sigma_y vec(2, 2) + \sigma_z vec(3, 2)] \quad (43)$$

$$\hat{O}^{10} = \tau_x[\sigma_x vec(1, 3) + \sigma_y vec(2, 3) + \sigma_z vec(3, 3)] \quad (44)$$

$$\hat{O}^{11} = \tau_y[\sigma_x vec(1, 3) + \sigma_y vec(2, 3) + \sigma_z vec(3, 3)] \quad (45)$$

$$\hat{O}^{12} = \tau_z[\sigma_x vec(1, 3) + \sigma_y vec(2, 3) + \sigma_z vec(3, 3)] \quad (46)$$

$$\hat{O}^{13} = \sigma_x vecs(1, 1) + \sigma_y vecs(2, 1) + \sigma_z vecs(3, 1) \quad (47)$$

$$\hat{O}^{14} = \sigma_x vecs(1, 2) + \sigma_y vecs(2, 2) + \sigma_z vecs(3, 2) \quad (48)$$

$$\hat{O}^{15} = \sigma_x vecs(1, 3) + \sigma_y vecs(2, 3) + \sigma_z vecs(3, 3) \quad (49)$$

- But I would like to know what exactly are those vec=fstvec, vecs=fsvec, fij, ft, fstval, fsval.
- and what exactly does v6tot do?

B. g1bval, g2bval, g3bval

As to g1bval, g2bval, g3bval, they are updating d1b, d2b and d3b accordingly.

$$d1b(s, i) = \sum_k S_{ik}^{-1} \langle k | \mathbf{r}_i | s \rangle \quad (50)$$

$$d2b(s, js, ij) = f_{ij} [sxz(s, i, i) sxz(js, j, j) - sxz(js, j, i) sxz(s, i, j)] \quad (51)$$

$$\begin{aligned}d3b(s, js, ks, i, j, k) &= \frac{f_{ij}}{probi jk(ijk)} \\ &\times \left\{ sxz(s, i, i) [sxz(js, j, j) sxz(ks, k, k) - sxz(ks, k, j) sxz(js, j, k)] \right. \\ &+ sxz(s, i, j) sxz(js, j, k) sxz(ks, k, i) - sxz(js, j, i) sxz(ks, k, k) \\ &+ \left. sxz(s, i, k) sxz(js, j, i) sxz(ks, k, j) - sxz(js, j, j) sxz(ks, k, i) \right\}\end{aligned}\quad (52)$$

and $sp(s, i) = \langle s | s_i \rangle$.

d1b is defined in order to calculate $|S^{-1}S'|$ in $|S'\rangle$. It is that

$$\begin{aligned}|S^{-1}S'| &= \sum_k S_{ik}^{-1} S'_{ki} \\ &= \sum_s \underbrace{\sum_k S_{ik}^{-1} \langle k | \mathbf{r}_i | s \rangle \langle s | O | s_i \rangle}_{smallz(i, s, i)}\end{aligned}\quad (53)$$

d2b is defined in order to calculate $|S^{-1}S''|$ in $|S''\rangle$. It is that

$$\begin{aligned}|S^{-1}S''| &= (\sum_k S_{ik}^{-1} S''_{ki}) (\sum_k S_{jk}^{-1} S''_{kj}) - (\sum_k S_{ik}^{-1} S''_{kj}) (\sum_k S_{jk}^{-1} S''_{ki}) \\ &= \sum_s \sum_{js} \langle s | O_i | s_i \rangle \langle js | O_j | s_j \rangle [sxz(s, i, i) sxz(js, j, j) - sxz(js, j, i) sxz(s, i, j)],\end{aligned}\quad (54)$$

where

$$d2b(s, js, ij) \equiv f_{ij} [sxz(s, i, i) sxz(js, j, j) - sxz(js, j, i) sxz(s, i, j)] \quad (55)$$

d3b is defined in order to calculate $|S^{-1}S'''|$ in $|S'''|$. Define $\boxed{ij} \equiv \sum_k S_{ik}^{-1} S_{kj}'''$. It is that

$$\begin{aligned}
|S^{-1}S'''| &= \boxed{ii} \left(\boxed{jj} \boxed{kk} - \boxed{jk} \boxed{kj} \right) + \boxed{ij} \left(\boxed{ji} \boxed{kk} - \boxed{jk} \boxed{ki} \right) + \boxed{ik} \left(\boxed{jj} \boxed{kj} - \boxed{jj} \boxed{ki} \right) \\
&= \sum_{s,j,s,ks} spx(s,p,i) spx(js,p,j) spx(ks,p,k) \\
&\quad \times \left\{ sxz(s,i,i) [sxz(js,j,j) sxz(ks,k,k) - sxz(ks,k,j) sxz(js,j,k)] \right. \\
&\quad + sxz(s,i,j) sxz(js,j,k) sxz(ks,k,i) - sxz(js,j,i) sxz(ks,k,k) \\
&\quad \left. + sxz(s,i,k) sxz(js,j,i) sxz(ks,k,j) - sxz(js,j,j) sxz(ks,k,i) \right\}
\end{aligned} \tag{56}$$

The part in the $\{ \}$ is related with d3b.

- But why there is f_{ij} in d2b?
- And why there is $\frac{f_{ij}}{probi j k(i j k)}$ in d3b?

C. `sinvijz`

in the note, `sinvijz` is defined as 4D `sinvijz(s,n,m,p)`, but in the code it is 3D `sinvijz(s,n,m)`.

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