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Lecture 04e Tangent to a Curve



Lecture is on YouTube

The YouTube video entitled 'Tangent to a Curve' that covers this lecture is located at https://youtu.be/H367um_Aho.

Outline

-Tangent to a Curve

Tangent to a Curve

Consider a curve in space that is parameterized by t and is described by $\vec{r}(t)$ (see YouTube video entitled 'Parameterizing Curves'). As we discussed previously, provided that $\vec{r}(t)$ is differentiable, the derivative of this is given by (see YouTube video entitled 'Scalar Functions, Vector Functions, and Vector Derivatives')

$$\vec{r}'(t) = \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t}$$

We can now show that this is effectively the vector tangent to the curve at point $P = \vec{r}(t)$.

If the curve is parameterized (ie $C = \vec{r}(t)$) from geometry in Figure 180 (see below), we see that a tangent vector can be obtained by looking at the vector difference $\vec{r}(t + \Delta t) - \vec{r}(t)$ as Δt becomes small.

tangent vector at point $P = \vec{r}(t)$ is given by $\lim_{\Delta t \rightarrow 0} \vec{r}(t + \Delta t) - \vec{r}(t)$

If we scale (AKA multiply) this vector by the amount $1/\Delta t$, we have a tangent vector at point P given as $\lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t}$. Comparing this with the previous expression for the derivative of the curve at point $P = \vec{r}(t)$, we see that they are the same. So we conclude that

$\vec{r}'(t)$ = a tangent vector to the curve at $P = \vec{r}(t)$

If we would like the unit tangent vector, we simply need to normalize this vector

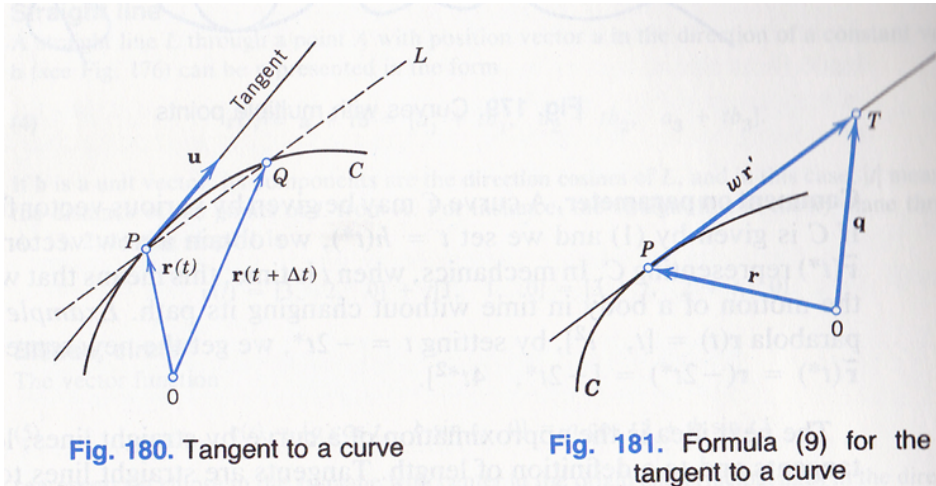
$$\bar{u}(t) = \frac{1}{|\bar{r}'(t)|} \bar{r}'(t) \quad (\text{unit tangent vector at point } P = \bar{r}(t)) \quad (\text{Eq.8})$$

Therefore, if we would like a point along this tangent line, we can find it using

$$T = \bar{q} = \bar{r}(t) + w \bar{u}(t) \quad (\text{Eq.9})$$

where $\bar{u}(t)$ = unit tangent vector at point $P = \bar{r}(t)$ given by Eq.8

w = parameter determining the distance between $P = \bar{r}(t)$ and $\bar{q}(w)$



Example 3: 3D Elliptical helix

Consider our previous example from the 'Parameterizing Curves' video.

$$\bar{r}(t) = \begin{pmatrix} a \cos(t) \\ b \sin(t) \\ c t \end{pmatrix}$$

$$\text{In[1]:= } \mathbf{r[t_]} = \begin{pmatrix} \mathbf{a \cos[t]} \\ \mathbf{b \sin[t]} \\ \mathbf{c t} \end{pmatrix};$$

Let us compute the tangent to this curve using

$$\bar{r}'(t) = \frac{d}{dt}[\bar{r}(t)]$$

$$\text{In[2]:= } \mathbf{rPrime[t_]} = \mathbf{D[r[t], t];}$$

$$\mathbf{rPrime[t]} \text{ // MatrixForm}$$

Out[3]//MatrixForm=

$$\begin{pmatrix} -a \sin[t] \\ b \cos[t] \\ c \end{pmatrix}$$

Using the same constants as the previous example ($a = 3$, $b = 1.2$, and $c = 1.2$) yields

```
In[4]:= replaceString = {a → 3, b → 1.2, c → 1.2};
```

```
Manipulate[
  (*Plot the point of interest*)
  P = r[tC] /. replaceString;

  (*Compute the tip of the tangent vector*)
  u = rPrime[tC] /. replaceString;

  (*Draw on a single figure*)
  Show[
    (*Plot the curve*)
    ParametricPlot3D[{r[t][[1, 1]] /. replaceString,
      r[t][[2, 1]] /. replaceString, r[t][[3, 1]] /. replaceString}, {t, 0, 10},

    (*Plot Options*)
    AxesLabel → {"x", "y", "z"},
    PlotRange → {{-4, 4}, {-4, 4}, {0, 13}},
    PlotLabel → "|| $\vec{u}$ || = " <> ToString[Norm[u]]],

    (*Plot the point of interest*)
    Graphics3D[
      {
        AbsolutePointSize[15], Green, Point[{P[[1, 1]], P[[2, 1]], P[[3, 1]]}]
      }
    ],

    (*Plot the curve tangent (draw an arrow from P to T=P+ $\vec{u}$ *)
    Graphics3D[
      {
        Magenta, Arrow[{P[[1, 1]], P[[2, 1]], P[[3, 1]]},
          {P[[1, 1]] + u[[1, 1]], P[[2, 1]] + u[[2, 1]], P[[3, 1]] + u[[3, 1]]}]
      }
    ]
  ],
  {tC, 0, 10}]
```

Out[5]=

