

## Curs 9

Ecuatii liniare pe  $\mathbb{R}^n$  cu coeficienti constante

Structura solutilor in cazul general

Lemă  $A \in L(\mathbb{R}, \mathbb{R}^n)$   $\frac{dx}{dt} = A x, \lambda \in \sigma(A) \quad P_j \in \mathbb{C}^n$

$$\Psi(t) := e^{\lambda t} \sum_{j=0}^{m-1} P_j t^j$$

Atunci  $\dot{\Psi}(t) \equiv A \Psi(t) \Leftrightarrow \int (A - \lambda I_m)^m P_0 = 0$

$$P_j = \frac{1}{j!} (A - \lambda I_m)^j \cdot P_0, j=1, \dots, m-1$$

Dem  $\dot{\Psi}(t) \equiv A \Psi(t)$

~~$$\lambda e^{\lambda t} \sum_{j=0}^{m-1} P_j t^j + e^{\lambda t} \sum_{j=1}^{m-1} j P_j t^{j-1} \equiv A e^{\lambda t} \sum_{j=0}^{m-1} P_j t^j$$~~

~~$$\lambda \sum_{j=0}^{m-1} P_j t^j + \sum_{j=0}^{m-2} (j+1) P_{j+1} t^j = A \sum_{j=0}^{m-1} P_j t^j$$~~

$$j = \overline{0, m-2} \quad \lambda \cdot P_j + (j+1) P_{j+1} = A \cdot P_j$$

$$j = m-1 \quad \lambda \cdot P_{m-1} = A \cdot P_{m-1}$$

$$j = \overline{0, m-2} \quad P_{j+1} = \frac{1}{j+1} (A - \lambda I_m) \cdot P_j = \frac{1}{(j+1)} \cdot \frac{1}{j} \cdot$$

$$(A - \lambda I_m)^2 P_{j+1} = \dots = \frac{1}{(j+1)!} (A - \lambda I_m)^{j+1} \cdot P_0$$

$$j = m-1 \quad (A - \lambda I_m) P_{m-1} = 0$$

$$P_{m-1} = \frac{1}{(m-1)!} (A - \lambda I_m)^{m-1} \cdot P_0 \quad \left\{ \Rightarrow \frac{1}{(m-1)!} (A - \lambda I_m)^m \cdot P_0 = 0 \right.$$

Teorema asupra forma canonica Jordam a unei matrice

$\forall A \in M_m(\mathbb{C}) \exists C \in M_n(\mathbb{C}) \det C \neq 0$  a.t.

$$\begin{pmatrix} 1 & 0 & \dots & 0 \end{pmatrix}$$

$$\begin{pmatrix} \lambda_1 & 1 & \dots & 0 \end{pmatrix}$$

celula

unde  $\lambda_n \in \sigma(A)$

$$s_{\lambda_n} = \dim J_{\lambda_n} \leq \text{multiplicitatea } (\lambda_n) = m_{\lambda_n}$$

$$\sum_{\lambda_n=\lambda} \dim J_{\lambda_n} = m_{\lambda_n}$$

Forma echivalentă

$$\forall A \in L(\mathbb{R}^n, \mathbb{R}^m) \exists B_J = \{ b_n^s; s=1, s_n, n=1, p \}$$

$\subset \mathbb{C}^m$  baza canonica Jordan a.<sup>↑</sup>  $\dim$  celulei Jordan

$$\text{a)} \forall n=1, p \exists \lambda_n \in \sigma(A)$$

$$\cancel{A \cdot b_n^1 = \lambda_n b_n^1 + b_n^2}$$

$$A b_n^2 = \lambda_n b_n^2 + b_n^3$$

$$A b_n^{s_{n-1}} = \lambda_n b_n^{s_{n-1}} + b_n^{s_n}$$

$$A b_n^{s_n} = \lambda_n b_n^{s_n}$$

$$\text{2)} s_n \leq m_{\lambda_n} \sum_{\lambda_n=\lambda} s_n = m_{\lambda} \quad \forall \lambda \in \sigma(A)$$

$$\text{3)} \text{Dacă } \lambda_n \in \mathbb{R} \Rightarrow b_n^s \in \mathbb{R}^m, \text{ dacă } \Im \lambda_n > 0 \text{ și } \lambda_n = \overline{\lambda}$$

atunci  $b_n^s = \overline{b_n^s}$

C)  $A \in L(\mathbb{R}^n, \mathbb{R}^m)$  B)  $\subset \mathbb{C}^m$  baza canonica Jordan

Atunci  $B_J = \{ b_n^s; \lambda_n \in \mathbb{R}, s=1, s_n \} \cup$

$\cup \{ R_e(b_n^s), I_m(b_n^s); \Im \lambda_n > 0, s=1, s_n \} \subset \mathbb{R}^m$  baza

(woma pe  $\mathbb{R}^n$  a bazei canonice Jordan)

$$\sum_{\substack{\lambda_n \in \mathbb{R} \\ S=1, S_R}} c_n^S b_n^S + \sum_{\substack{\lambda_n > 0 \\ S=1, S_R}} [c_n^S R_p(b_n^S) + k_n^S j_m(b_n^S)] = 0$$

$$\Rightarrow c_n^S = k_n^S = 0 \quad \forall S, \forall n$$

$$b_n^S = R_p(b_n^S) + i \cdot j_m(b_n^S)$$

$$\overline{b_n^S} = R_p(b_n^S) - i \cdot j_m(b_n^S)$$

$$R_p(b_n^S) = \frac{1}{2}(b_n^S + \overline{b_n^S})$$

$$j_m(b_n^S) = \frac{1}{2i} \cdot (b_n^S - \overline{b_n^S})$$

$$\sum_{\substack{\lambda_n \in \mathbb{R} \\ S=1, S_R}} c_n^S b_n^S + \sum_{\substack{\lambda_n > 0 \\ S=1, S_R}} c_n^S \frac{1}{2} (b_n^S - \overline{b_n^S}) + k_n^S \frac{1}{2i} (b_n^S - \overline{b_n^S}) = 0$$

$$\sum_{\substack{\lambda_n \in \mathbb{R} \\ S=1, S_R}} c_n^S b_n^S + \sum_{\substack{\lambda_n > 0 \\ S=1, S_R}} \left[ \left( \frac{c_n^S}{2} + \frac{k_n^S}{2i} \right) b_n^S + \left( \frac{c_n^S}{2} - \frac{k_n^S}{2i} \right) \overline{b_n^S} \right] = 0 \xrightarrow{\text{baza}}$$

$$\Rightarrow c_1^S = 0 \quad \lambda_1 \in \mathbb{R} \quad \left. \begin{array}{l} \frac{c_n^S}{2} + \frac{k_n^S}{2i} = 0 \quad \lambda_n > 0 \\ \frac{c_n^S}{2} - \frac{k_n^S}{2i} = 0 \end{array} \right. \Rightarrow \quad \begin{array}{l} S=1, S_R \\ S=1, S_R \end{array}$$

$$\Rightarrow c_n^S = k_n^S = 0 \quad \lambda_n > 0 \quad \begin{array}{l} \lambda_n > 0 \\ S=1, S_R \end{array}$$

(2)  $A \in L(\mathbb{R}^m, \mathbb{R}^n)$   $B_J \subset \mathbb{C}^n$  baza canonica Jordam

$$\lambda \in \sigma(A) \quad B_J^\lambda := \{ b_n^S \mid \lambda_n = \lambda, S=1, S_R \}$$

$$\text{Atunci: 1) } \text{card}(B_J^\lambda) = m_\lambda$$

$$2) (A - \lambda i_m)^m \lambda_n^S = 0 \quad \forall b_n^S \in B_J^\lambda$$

linear indep.

Denum 1) & 3) immediat dim T

$$2) Ab_n^1 = \lambda b_n^1 + b_n^2 \Rightarrow b_n^2 = (A - \lambda i_m) b_n^1$$

$$Ab_n^2 = \lambda b_n^2 + b_n^3 \Rightarrow b_n^3 = (A - \lambda i_m) b_n^2 = (A - \lambda i_m)$$

$$Ab_n^{s_{r-1}} = \lambda b_n^{s_{r-1}} + b_n^{s_r}$$

$$Ab_n^{s_r} = \lambda b_n^{s_r}$$

$$b_n^{s_r} = (A - \lambda i_m) b_n^{s_{r-1}} = -(A - \lambda i_m)$$

$$(A - \lambda i_m) b_n^{s_r} = 0.$$

$$\Rightarrow (A - \lambda i_m)(A - \lambda i_m)^{s_{r-1}} b_n^1 = 0$$

$$(A - \lambda i_m)^{s_r} b_n^1 = 0 \quad \Rightarrow (A - \lambda i_m)^{m_\lambda} b_n^1 = 0.$$

$$s_r \leq m_\lambda$$

$$(A - \lambda i_m)^{m_\lambda} b_n^s = (A - \lambda i_m)^{m_\lambda} \cdot (A - \lambda i_m)^{s-1} b_n^1 =$$

$$= (A - \lambda i_m)^{m_\lambda + s-1} b_n^1 = 0.$$

T (Structura soluției cazul general)

$$A \in L(\mathbb{R}^n, \mathbb{R}^n) \quad \frac{d\mathbf{x}}{dt} = A \mathbf{x}$$

Atunci: 1.  $\forall \lambda \in \sigma(A) \cap \mathbb{R} \quad m_\lambda = m \geq 1 \quad \exists P_j \in \mathbb{R}^{n \times n}$

$$\varphi_{\lambda e}(t) = e^{\lambda t} \cdot \sum_{j=0}^{m-1} P_j t^j, \quad l = \overline{1, m}$$

$\{\varphi_{\lambda e}(t)\}_{l=\overline{1, m}} \subset S_A$  linier independent

2.  $\forall \lambda \in \sigma(A) \quad \operatorname{Im} \lambda > 0 \quad m_\lambda = m \geq 1 \quad \exists P_j \in \mathbb{C}^{n \times n}$

$$\varphi_{\lambda e}(t) = \operatorname{Re} \left( e^{\lambda t} \sum_{j=0}^{m-1} P_j \lambda e^{js} \right), \quad l = \overline{1, m}$$

$\{ \Phi_{\lambda e}(t), \Psi_{\lambda e}(t) \}_{l=\overline{1,m}} \subset S_A$  liniar independente

3.  $\{ \Psi_{\lambda e}(t) \}_{\lambda \in \sigma(A)} \subset S_A$  sistem fundamental de solutii (bază în spațiul soluției)

$$\boxed{\text{Derm}} \quad A \in L(\mathbb{R}^n, \mathbb{R}^m) \rightarrow B_j = \{ b_{\lambda}^j \}_{\lambda \in \sigma(A)}, S = \overline{1, S_n}, r = \overline{1, p} \}$$

$\subset \mathbb{C}^n$  bază canonică Jordan

1. Fie  $\lambda \in \sigma(A) \cap \mathbb{R}$   $m_\lambda = m \geq 1$

Fie  $B_j^{\lambda} = \{ b_{\lambda}^j \}; \lambda_1 = \lambda, S = \overline{1, S_n}, r = \overline{1, m} \} \stackrel{\text{not}}{=} \{ P_0^{\lambda_1}, \dots, P_{m-1}^{\lambda_m} \}$   
liniar independent

$$P_j^{\lambda} := \frac{1}{j!} (A - \lambda I_m)^j P_0^{\lambda}, j = \overline{1, m-1}, l = \overline{1, m}$$

$$(C2) \Rightarrow (A - \lambda I_m)^m P_0^{\lambda} = 0, l = \overline{1, m}$$

$$\text{Fie } \Psi_{\lambda e}(t) = e^{\lambda t} \sum_{j=0}^{m-1} P_j^{\lambda} t^j$$

$\left\{ \begin{array}{l} \text{liniar} \\ \Rightarrow \end{array} \right.$

$$\Rightarrow \Psi_{\lambda e}(t) = A \cdot \Phi_{\lambda e}(t)$$

$$\Rightarrow \Psi_{\lambda e}(t) \in S_A \quad l = \overline{1, m}$$

$\{ \Psi_{\lambda e}(t) \}_{l=\overline{1,m}} \subset S_A$  liniar independente

$\Updownarrow$  PROP (Sol. liniar independente)

$\{ \Psi_{\lambda e}(t) \}_{l=\overline{1,m}} \subset \mathbb{R}^m$  liniar independente

$\{ P_{\lambda}^{\lambda e} \}_{l=\overline{1,m}}$  liniar independente

2.  $\lambda \in \sigma(A)$   $\operatorname{Im} \lambda > 0$   $m_\lambda = m \geq 1$

$$\frac{P_{\lambda e}}{j!} := \frac{1}{j!} (A - \lambda i_m)^j P_{\lambda m} \quad j = \overline{1, m-1}, \quad l = \overline{1, m}$$

Lemā  $\Rightarrow \psi_{\lambda e}(t) \equiv A \psi_{\lambda e}(t)$

$$\begin{aligned} \psi_{\lambda e}(t) &= \underbrace{\operatorname{Re}(\psi_{\lambda e}(t))}_{\psi_{\lambda e}(t)} + i \cdot \underbrace{\operatorname{Im}(\psi_{\lambda e}(t))}_{\psi_{\lambda e}^i(t)} = \psi_{\lambda e}(t) + i \cdot \psi_{\lambda e}^i(t) \end{aligned}$$

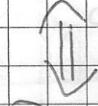
$$\underbrace{\psi'_{\lambda e}(t)}_{\psi_{\lambda e}'(t)} + i \cdot \underbrace{\psi''_{\lambda e}(t)}_{\psi_{\lambda e}''(t)} \equiv A \underbrace{\psi_{\lambda e}(t)}_{\psi_{\lambda e}(t)} + i \cdot A \underbrace{\psi_{\lambda e}(t)}_{\psi_{\lambda e}(t)}$$

$$\Rightarrow \psi'_{\lambda e}(t) \equiv A \psi_{\lambda e}(t)$$

$$\psi'_{\lambda e}(t) \equiv A \cdot \psi_{\lambda e}(t) \Rightarrow \psi_{\lambda e}(\cdot), \psi_{\lambda e}'(\cdot) \in S_{\lambda} \quad \forall e = \overline{1, m}$$

$\{ \psi_{\lambda e}(\cdot), \psi_{\lambda e}'(\cdot) \} \subset S_{\lambda}$  linear indep.

$\overbrace{\quad}^{l=1, m}$



PROP (sol linear independent)

$$\{ \psi_{\lambda e}(0), \psi'_{\lambda e}(0) \}_{l=1, m} \subset \mathbb{R}^n \text{ linear indep.}$$

$$\{ \operatorname{Re}(P_{\lambda e}), \operatorname{Im}(P_{\lambda e}) \}_{l=1, m}$$

$$\{ \operatorname{Re}(b_n^S), \operatorname{Im}(b_n^S) \}_{l=1, m} \subset \mathbb{C}^n \text{ linear indep.}$$

(c1) (c2)

3. n solutie  $\Rightarrow$  E sufficient sa verificam doar linear independenta

Sup?

C. Danner, Universitatea

$\{ \varphi_{\lambda}(\cdot) \}_{\lambda \in \sigma(A)} \subset \mathbb{C}^n$  linier independente  
 $\lambda = \lambda_1, \dots, \lambda_n$

"  
 $\{ b_{\lambda}^s \}_{\lambda \in \sigma(A), s=1, \dots, m_{\lambda}} \subset \mathbb{R}^n$  linier independente C

Algoritm

$$\frac{dx}{dt} = Ax$$

1. Rezolvăm ec. caracteristică  $\det(A - \lambda i_m) = 0 \rightarrow \sigma(A)$

$$\sigma(A) : (\lambda, m_{\lambda})$$

↳ ordinea multiplicității a răd.  $\lambda$

2. Dacă  $\lambda \in \sigma(A) \cap \mathbb{R}$ ,  $m_{\lambda} = 1$  cază  $u_{\lambda} \in \mathbb{R}^n \setminus \{0\}$

$$a. \uparrow (A - \lambda i_m) u_{\lambda} = 0.$$

$$\text{Serie sol } \varphi_{\lambda}(t) = e^{\lambda t} \cdot u_{\lambda}$$

3. Dacă  $\lambda \in \sigma(A) \cap \mathbb{R}$ ,  $m_{\lambda} = m > 1$

Cază  $\{ P_{\lambda}^{(1)}, \dots, P_{\lambda}^{(m)} \} \subset \text{Ker}(A - \lambda \cdot i_m)^m$  linier independentă  
 $(\text{în } \mathbb{R}^n)$

$$\text{Serie } P_{\lambda}^{(e)} = \frac{1}{j!} (A - \lambda \cdot i_m)^j P_{\lambda}^{(e)} \quad P_{\lambda}^{(e)} \Rightarrow j = \overline{1, m-1}, \quad e = \overline{1, m}$$

$$\text{Serie sol } P_{\lambda(e)}(t) = e^{\lambda t} \sum_{j=0}^{m-1} P_{\lambda}^{(e)} t^j \quad e = \overline{1, m}$$

4. Dacă  $\lambda = \alpha + i\beta \in \sigma(A)$ ,  $\beta > 0$ ,  $m_{\lambda} = 1$ .

Cază  $u_{\lambda} \in \mathbb{C}^n \setminus \{0\}$  a.  $(A - \lambda i_m) u_{\lambda} = 0$ .

$$\text{Serie sol } \varphi_{\lambda}(t) = R_e(e^{\lambda t}, u_{\lambda})$$

$$\varphi_{\lambda}(t) = J_m(e^{\lambda t}, u_{\lambda})$$

5. Dacă  $\lambda = \alpha + i\beta \in \sigma(A)$ ,  $\beta > 0$ ,  $m_{\lambda} = m > 1$

$$\text{Serie } P_j^{\lambda e} = \frac{1}{j!} (\lambda - \pi_{(m)})^j P_0^{\lambda e}, j=1, m-1, \ell=\overline{1, m}$$

Serie soluție:

$$\varphi_{\lambda e}(t) = \operatorname{Re} \left( e^{\lambda t} \sum_{j=0}^{m-1} P_j^{\lambda e} t^j \right), \ell=\overline{1, m}$$

$$\varphi_{\lambda e}(t) = \operatorname{Im} \left( e^{\lambda t} \sum_{j=0}^{m-1} P_j^{\lambda e} t^j \right)$$

$$6. \text{ Recunoscerea } \{P_{\lambda e}(\cdot)\}_{\lambda \in \sigma(A)} = \sum_{\ell=1, m_2}^m \{ \varphi_\ell(\cdot), \varphi_2(\cdot), \dots, \varphi_m(\cdot) \} \text{ sistem fundamental de soluții}$$

$$= \{ \varphi_1(\cdot), \varphi_2(\cdot), \dots, \varphi_m(\cdot) \}$$

$$\text{Serie soluția generală } \vartheta(t) = \sum_{i=1}^n c_i \varphi_i(t), c_i \in \mathbb{R}, i=\overline{1, n}$$

Ecuatii diferențiale afine pe  $\mathbb{R}^n$

Def A(\cdot): I ⊂ R → L(R^n, R^n), b(\cdot): I → R^n def

$$\frac{d\boldsymbol{x}}{dt} = A(t) \boldsymbol{x} + b(t)$$

In coordinate (B ∈ R^n bază) A\_B(t) = (a\_ij(t))\_{i,j=\overline{1, n}}

$$b(t) = \begin{pmatrix} b_1(t) \\ \vdots \\ b_n(t) \end{pmatrix}, \frac{d\boldsymbol{x}_i}{dt} = \sum_{j=1}^n a_{ij}(t) \boldsymbol{x}_j + b_i(t), i=\overline{1, n}$$

(sistem de ecuatii afine)

Dacă n=1, L(R, R) ⊂ R → x' = a(t)x + b(t),  
 $a(\cdot), b(\cdot): I \subset R \rightarrow R$  (ecuatie afină scalară)

Metoda variatiilor constanteelor

T(E.U.G)

$$\frac{dx}{dt} = A(t)x + b(t)$$

Atunci  $\forall (t_0, x_0) \in I \times \mathbb{R}^n$   $\exists!$   $\varphi(\cdot) : I \rightarrow \mathbb{R}^n$  soluție cu  
 $\varphi(t_0) = x_0$ .

Dem:  $f(t, x) = A(t)x + b(t)$   
 $\begin{cases} f(t, \cdot) \\ A(\cdot), b(\cdot) \end{cases}$

$\begin{cases} f(t, \cdot) \text{ cont local lipschitz } (\underline{I}) \\ A(\cdot), b(\cdot) \end{cases} \xrightarrow{\text{Cauchy- lipschitz}} \text{EUL pe } I \times \mathbb{R}^n$

$\Leftrightarrow T.U.G$

$$\|f(t, x)\| = \|A(t)x + b(t)\| \leq \|A(t)\| \cdot \|x\| + \|b(t)\|$$

$A(\cdot), b(\cdot)$

adică  $C.A \Rightarrow \begin{cases} T \\ E.G \end{cases} \Rightarrow E.G$

$$S := \left\{ \varphi(\cdot) : I \rightarrow \mathbb{R}^n ; \varphi(\cdot) \text{ soluție } \dot{x} = A(t)x + b(t) \right\}$$

$A(\cdot), b(\cdot)$

## Seminar 9

### Algoritm (casul general)

$$\frac{dx}{dt} = Ax$$

1 Rezolvă ec. caracteristică

$$\det(A - \lambda I_m) = 0 \rightarrow S(A) : (\lambda, m_\lambda)$$

2 Dacă  $\lambda \in S(A) \cap \mathbb{R}$ ,  $m_\lambda = 1$  cază  $u_\lambda \in \mathbb{R}^n$

$$(A - \lambda I_m) u_\lambda = 0$$

$$\text{Scrue sol } \varphi_\lambda(t) = e^{\lambda t} \cdot u_\lambda$$

3. Dacă  $\lambda \in S(A) \cap \mathbb{R}$ ,  $m_\lambda = m > 1$

Cază  $\{P_0^{\lambda_1}, P_0^{\lambda_m}\} \subset \ker(A - \lambda I_m)^m$  linicor indep  
(în  $\mathbb{R}^n$ )

$$\text{Scrue } P_j^{\lambda e} = \frac{1}{j!} (A - \lambda I_m)^j P_0^{\lambda e}, j = \overline{1, m-1}, e = \overline{1, m}$$

$$\text{Scrue soluții } \varphi_{\lambda, e}(t) = e^{\lambda t} \sum_{j=0}^{m-1} P_j^{\lambda e} t^j, e = \overline{1, m}$$

4. Dacă  $\lambda = \alpha + i\beta \in S(A)$ ,  $\beta > 0$ ,  $m_\lambda = 1$

Cază  $u_\lambda \in \mathbb{C}^n \setminus \{0\}$  a.t.  $(A - \lambda I_m) u_\lambda = 0$ .

$$\text{Scrue sol } \varphi_{\lambda}(t) = \operatorname{Re}(e^{\lambda t} \cdot u_\lambda), \varphi_{\bar{\lambda}}(t) = \operatorname{Im}(e^{\lambda t} \cdot u_\lambda)$$

5 Dacă  $\lambda = \alpha + i\beta \in S(A)$ ,  $\beta > 0$ ,  $m_\lambda = m > 1$

Cază  $\{P_0^{\lambda_1}, P_0^{\lambda_m}\} \subset \ker(A - \lambda I_m)^m$  linicor nule  
(în  $\mathbb{C}^n$ )

$$\text{Scrue } P_j^{\lambda e} = \frac{1}{j!} (A - \lambda I_m)^j P_0^{\lambda e}, j = \overline{1, m-1}, e = \overline{1, m}$$

$$\text{Scrue soluții } \varphi_{\lambda, e}(t) = \operatorname{Re}(e^{\lambda t} \sum_{j=0}^{m-1} P_j^{\lambda e} t^j)$$

6 Rezolvarea ecuației diferențiale  $\dot{x}_i(t) = \lambda_i x_i(t)$ , unde  $\lambda_i \in \mathbb{C}$

Sistem fundamental de soluție:

Serie sol. generală  $\Psi(t) = \sum_{i=1}^m c_i \varphi_i(t)$ ,  $c_i \in \mathbb{R}$

Ex: Să se determine soluția generală:

$$\begin{cases} \dot{x} = x - y + z \\ \dot{y} = x + y - z \\ \dot{z} = 2x - y \end{cases} \quad A = \begin{pmatrix} 1 & -1 & 1 \\ 1 & 1 & -1 \\ 0 & -1 & 2 \end{pmatrix}$$

$$\begin{aligned} \det(A - \lambda I_3) &= \begin{vmatrix} 1-\lambda & -1 & 1 \\ 1 & 1-\lambda & -1 \\ 0 & -1 & 2-\lambda \end{vmatrix} = \\ &= (1-\lambda)^2 \cdot (2-\lambda) - 1 - 1 + \lambda + 2 - \lambda \\ &= (1-\lambda)^2 \cdot (2-\lambda) \end{aligned}$$

$$\lambda_1 = 2$$

$$\lambda_2 = \lambda_3 = 1$$

$$\lambda = 2 \Rightarrow \text{u.a.t } A - 2I_3 \cdot u = 0, \text{ unde } u = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$\begin{pmatrix} -1 & -1 & 1 \\ 1 & -1 & -1 \\ 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} -a - b + c = 0 \\ a - b - c = 0 \\ -b = 0 \end{cases} \Rightarrow a = c, b = 0$$

$$\Rightarrow \begin{pmatrix} a \\ 0 \\ a \end{pmatrix}, a = 1$$

$$\text{Soluția } \varphi_1(t) = e^{2t} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$n=1, m_\lambda = 2$$

$$(A - i_3)^2 = \begin{pmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & -1 & 2 \\ 0 & 0 & 0 \\ -1 & -1 & 2 \end{pmatrix}$$

$$P_0 = ? \text{ a. } \uparrow (A - i_3)^2 \cdot P_0 = 0, P_0 = \begin{pmatrix} a \\ b \\ c \end{pmatrix} \Rightarrow$$

$$\Rightarrow \begin{pmatrix} -1 & -1 & 2 \\ 0 & 0 & 0 \\ -1 & -1 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow a+b=2c \Rightarrow c = \frac{a+b}{2}$$

$$\Rightarrow P_0 = \begin{pmatrix} a \\ b \\ \frac{a+b}{2} \end{pmatrix}$$

$$P_{01} = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \quad P_{02} = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}$$

$$P_j = \frac{1}{j!} (A - i_3)^j P_0, j=1$$

$$P_{11} = (A - i_3) \cdot P_{01} \quad P_{12} = (A - i_3) \cdot P_{02}$$

$$P_{11} = \begin{pmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$P_{12} = \begin{pmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix}$$

$$\varphi_2(t) = e^t (P_{01} + t \cdot P_{11})$$

$$\varphi_3(t) = e^t (P_{02} + t \cdot P_{12})$$

$$\varphi_2(t) = e^t \begin{pmatrix} 2+t \\ t \\ 1+t \end{pmatrix}$$

$$\varphi_3(t) = e^t \begin{pmatrix} -t \\ 2-t \\ 1-t \end{pmatrix}$$

$$2) \begin{cases} x' = 4x - y \\ y' = 3x + y - z \\ z' = x + z \end{cases}$$

$$A = \begin{pmatrix} 4 & -1 & 0 \\ 3 & 1 & -1 \\ 1 & 0 & 1 \end{pmatrix}$$

$$\det(A - \lambda \cdot i_3) = \begin{vmatrix} 4-\lambda & -1 & 0 \\ 3 & 1-\lambda & -1 \\ 1 & 0 & 1-\lambda \end{vmatrix} =$$

$$\begin{aligned} &= (4-\lambda)(1-\lambda)^2 + 1 + 3(1-\lambda) \\ &= (1-\lambda)(3 + (4-\lambda)(1-\lambda)) + 1 \\ &= -\lambda^3 + 6\lambda^2 - 12\lambda + 8 = (2-\lambda)^3 \end{aligned}$$

$$\lambda = 2 \quad m_\lambda = 3$$

$$(A - 2J_3)^3 = ?$$

$$(A - 2J_3)^2 = \begin{pmatrix} 2 & -1 & 0 \\ 3 & -1 & -1 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} 2 & -1 & 0 \\ 3 & -1 & -1 \\ 1 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & -1 & 1 \\ 2 & -2 & 2 \\ 9 & -1 & 1 \end{pmatrix}$$

$$(A - 2J_3)^3 = \begin{pmatrix} 2 & -1 & 0 \\ 3 & -1 & -1 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & -1 & 1 \\ 2 & -2 & 2 \\ 1 & -1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(A - 2J_3)^3 = 0 \Rightarrow (A - 2J_3)^3 \cdot P_0 = 0, \forall P_0 \in \mathbb{R}^3$$

$$P_{01} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad P_{02} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad P_{03} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rightarrow \begin{array}{l} \text{linear} \\ \text{indep.} \\ (\text{base canonic}) \end{array}$$

$$P_j = \frac{1}{j!} (A - 2J_3)^j \cdot P_0, j=1, 2$$

$$P_{11} = (A - 2J_3) \cdot P_{01} = \begin{pmatrix} 2 & -1 & 0 \\ 3 & -1 & -1 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix}$$

$$P_{12} = \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix} \quad P_{13} = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$P_{21} = \frac{1}{2} \cdot (A - \lambda_3)^2 \cdot P_{01} = \frac{1}{2} \begin{pmatrix} 1 & 1 & 1 \\ 2 & -2 & 2 \\ 1 & -1 & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

$$P_{22} = \frac{1}{2} \begin{pmatrix} -1 \\ -2 \\ -1 \end{pmatrix} \quad P_{23} = \frac{1}{2} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

$$\varphi_1(t) = e^{2t}(P_{01} + t \cdot P_{11} + t^2 \cdot P_{21}(t)) = e^{2t}(P_{02} + t \cdot P_{12} + t^2 \cdot P_{22})$$

$$\varphi_3(t) = e^{2t}(P_{03} + t \cdot P_{13} + t^2 \cdot P_{23})$$

$$\varphi_1(t) = e^{2t} \begin{pmatrix} 1 + 2t + t^2 \cdot \frac{1}{2} \\ 3t + t^2 \\ t + t^2 \cdot \frac{1}{2} \end{pmatrix}$$

$$\varphi_2(t) = e^{2t} \begin{pmatrix} -t - \frac{1}{2}t^2 \\ 1 - t - t^2 \\ -t \cdot \frac{1}{2} \end{pmatrix}$$

$$\varphi_3(t) = e^{2t} \begin{pmatrix} t^2 \cdot \frac{1}{2} \\ -t + t^2 \\ -1 - t + \frac{1}{2}t^2 \end{pmatrix}$$

$$3) \begin{cases} x' = 2x + y \\ \quad \quad \quad \end{cases}$$

$$\begin{cases} y' = 2y + 4z \\ z' = x - 2 \end{cases}$$

$$4) \begin{cases} x' = 2x + y \\ \quad \quad \quad \end{cases}$$

$$\begin{cases} y' = 4y - 2x \\ \quad \quad \quad \end{cases}$$

$$A = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 4 & 0 \\ 1 & -1 & 2 \end{pmatrix} \quad \det(A - i_2 \cdot \lambda) = \begin{vmatrix} 2-\lambda & 1 & 0 \\ 0 & 4-\lambda & 0 \\ 1 & -1-\lambda & 2 \end{vmatrix}$$

$$= (2-\lambda)(-1-\lambda) - 1 = -2 - 2\lambda + \lambda + \lambda^2 - 1$$

$$A = \begin{pmatrix} 2 & 1 \\ -1 & 4 \end{pmatrix} \quad \det(A - \lambda \cdot I_2) = \begin{vmatrix} 2-\lambda & 1 \\ -1 & 4-\lambda \end{vmatrix} =$$

$$= (2-\lambda)(4-\lambda) + 1 = (\lambda-3)^2$$

$$\lambda_{1,2} = 3$$

$$\lambda = 3, \quad m_\lambda = 2$$

$$(A - 3I_2)^2 = \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$(A - 3I_2)^2 \cdot P_0 = 0, \quad \forall P_0 \in \mathbb{R}^2$$

$$P_{01} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad P_{02} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$P_j = \frac{1}{j} (A - 3I_2)^j \cdot P_0, \quad j = 1$$

$$P_{11} = (A - 3I_2) \cdot P_{01} \quad P_{12} = (A - 3I_2) \cdot P_{02}$$

$$P_{11} = \begin{pmatrix} -1 \\ -1 \end{pmatrix} \quad P_{12} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\varphi_1 = e^{3t} \cdot (P_{11} + t \cdot P_{11}) = \begin{pmatrix} 1-t \\ -t \end{pmatrix} \cdot e^{3t}$$

$$\varphi_2 = e^{3t} \cdot (P_{12} + t \cdot P_{12}) = \begin{pmatrix} t \\ 1+t \end{pmatrix} \cdot e^{3t}$$

A doua metoda (recomandată pt. dimensiunile 2)

$$y = x' - 2x$$

$$(x' - 2x)' = 4(x' - 2x)' - 2 =, \quad x'' - 2x' = 4x' - 8x - x$$

$$\Rightarrow x'' - 6x' + 9x = 0$$

$$\lambda^2 - 6\lambda + 9 = 0 \Rightarrow (\lambda - 3)^2 = 0$$

$$\begin{aligned}
 y(t) &= 3 \cdot c_1 \cdot e^{3t} + c_2 \cdot e^{3t} + 3 \cdot c_2 t \cdot e^{3t} - 2c_1 e^{3t} - \\
 &\quad - 2c_2 t e^{3t} \\
 &= ((c_1 + c_2) \cdot e^{3t} + c_2 t e^{3t})
 \end{aligned}$$

$$\begin{cases} 
 x' = 5x + 3y \\ 
 y' = -3x - y 
 \end{cases}$$

$$\begin{cases} 
 x' = 2y - 3x \\ 
 y' = y - 2x 
 \end{cases}$$

Curs 10

Ecuatii affine pe  $\mathbb{R}^n$

PROP (Naturitatea solutiilor)

Sol. ec. liniare  $\downarrow$

Sol. particulară a ec. affine

$$S_{A(\cdot), b(\cdot)} = S_{A(\cdot)}^{\downarrow} + \{ \varphi_0(\cdot) \}, \quad \varphi_0(\cdot) \in S_{A(\cdot), b(\cdot)}$$

$$\text{Dem } \parallel \text{ Fie } \varphi_0(\cdot) \in S_{A(\cdot), b(\cdot)} \xrightarrow{?} \varphi(\cdot) - \varphi_0(\cdot) \in S_{A(\cdot)}$$

$$\varphi(t) \equiv A(t)\varphi(t) + b(t)$$

$$\varphi'(t) \equiv A(t)\varphi(t) + b(t)$$

$$(\varphi - \varphi_0)'(t) \equiv A(t)(\varphi(t) - \varphi_0(t)) \equiv A(t)(\varphi - \varphi_0)(t), \text{ i.e. } (\varphi - \varphi_0)(\cdot) \in S_{A(\cdot)}$$

$$\parallel \text{ Fie } \varphi_0(\cdot) \in S_{A(\cdot), b(\cdot)}, \text{ si fie } \psi(\cdot) \in S_{A(\cdot)} \xrightarrow{?} \psi(\cdot) + \varphi_0(\cdot) \in S_{A(\cdot), b(\cdot)}$$

$$\varphi_0(t) \equiv A(t)\varphi_0(t) + b(t)$$

$$\psi(t) \equiv A(t)\psi(t)$$

$$\varphi'_0(t) + \psi'(t) \equiv A(t)(\varphi_0(t) + \psi(t)) + b(t) \equiv A(t)(\psi + \varphi_0)(t) + b(t)$$

$$(\psi + \varphi_0)(t)$$

Concluzie Fie  $\{ \bar{\varphi}_1(\cdot), \dots, \bar{\varphi}_n(\cdot) \} \subset S_{A(\cdot)}$  sistem fundamental de

solutii pt. ec. liniara asociata  $\frac{d\bar{x}}{dt} = A(t)\bar{x}$  si fie  $\varphi_0(\cdot) \in S_{A(\cdot), b(\cdot)}$

Astfel  $\varphi(\cdot) \in S_{A(\cdot), b(\cdot)} \iff \exists c_1, \dots, c_n \in \mathbb{R} \text{ a.t.}$

$$\varphi(t) = \sum_{i=1}^n c_i \bar{\varphi}_i(t) + \varphi_0(t) \quad \text{solutie generala a ec. affine}$$

T (Principiul variației constanțelor)

Fie  $X(\cdot) : I \rightarrow M_m(\mathbb{R})$  matrice fundamentală de soluții pt. ec. liniară asociată  $\frac{d\bar{x}}{dt} = A(t)\bar{x}$ .

Astfel  $\varphi(\cdot) \in S_{A(\cdot), b(\cdot)} \iff \exists C(\cdot) \text{ primitive a funcțiilor}$

Dacă  $\psi(t) \in S_{A(\cdot), b(\cdot)}$

Fie  $c(t) := X^{-1}(t) \psi(t) \Rightarrow \psi(t) = X(t) \cdot c(t)$

$\psi(t)$  soluție  $\Rightarrow \psi'(t) = A(t) \cdot c(t) + b(t)$

$$\Rightarrow \underbrace{X'(t)c(t) + X(t)c'(t)}_{\|} \equiv A(t)X(t)c(t) + b(t)$$

$$A(t)X(t)c(t)$$

$$X(t)c'(t) \equiv b(t) \Rightarrow c'(t) = \cancel{X^{-1}(t)b(t)}$$

$$\Leftrightarrow \psi'(t) \equiv X(t) \cdot c(t) \Rightarrow \psi'(t) \equiv \underbrace{X'(t)c(t) + X(t)c'(t)}_{\|} + \underbrace{X(t) \cdot \cancel{X^{-1}(t)}}_{\|}$$

$$= A(t)\psi(t) + b(t)$$

Concluzie: Fie  $\{\bar{\varphi}_1(\cdot), \dots, \bar{\varphi}_n(\cdot)\} \subset S_{A(\cdot)}$  sistem fundamental de soluții pt. ec. liniară asociată  $\frac{d\vec{x}}{dt} = A(t)\vec{x}$ .

Atunci  $\psi(t) \in S_{A(\cdot), b(\cdot)} \Leftrightarrow \exists c(\cdot) = \begin{pmatrix} c_1(\cdot) \\ \vdots \\ c_n(\cdot) \end{pmatrix}$  primitivă

funcției  $t \rightarrow (\text{col}(\bar{\varphi}_1(t), \dots, \bar{\varphi}_n(t)))^{-1} \cdot b(t)$  a.?

$$\psi(t) = \sum_{i=1}^n c_i(t) \cdot \bar{\varphi}_i(t)$$

Dacă  $\{\bar{\varphi}_1(\cdot), \dots, \bar{\varphi}_n(\cdot)\} \subset S_{A(\cdot)}$  sistem fundamental

Soluție  $\Rightarrow X(t) = \text{col}(\bar{\varphi}_1(t), \dots, \bar{\varphi}_n(t))$ ,  $t \in I$  matrice fundamentală de soluții  $X(t)c(t) = \text{col}(\bar{\varphi}_1(t), \dots, \bar{\varphi}_n(t))$

$$= \sum_{i=1}^m c_i(t) \bar{\varphi}_i(t) + \mathbb{T} \Rightarrow g.e.d$$

Algorithm (metoda variației constanțelor pt. ec. afine pe

$$\frac{d\vec{x}}{dt} = A(t)\vec{x} + b(t)$$

1 Consideră ec. liniară asociată  $\frac{d\vec{x}}{dt} = A(t)\vec{x}$

Serie soluția generală  $\bar{x}(t) = \sum_{i=1}^m c_i \bar{\varphi}_i(t)$

2. (Variația constanțelor propriu-zise)

Căută soluții de forma  $x(t) = \sum_{i=1}^m c_i(t) \cdot \bar{\varphi}_i(t)$

$$x(t) \text{ sol} \Rightarrow \sum_{i=1}^m c_i(t) \bar{\varphi}_i(t) = b(t) \Rightarrow c_i(t) = \dots, i=1, n \\ \Rightarrow c_i(t) = \dots, i=1, n \\ \Rightarrow x(t) = \dots$$

Ecuții diferențiale liniare de ordin superior

Def:  $a_1(\cdot), \dots, a_n(\cdot) : I \subseteq \mathbb{R} \rightarrow \mathbb{R}$  def  $x^{(n)} = \sum_{j=1}^n a_j(t) x^{(n-j)}$  (1)

Metoda generală de studiu (sistemul canonice asociat)

$$\begin{aligned} \frac{dx_1}{dt} &= x_2 \\ \frac{dx_2}{dt} &= x_3 \\ &\dots \\ \frac{dx_{n-1}}{dt} &= x_n \\ \frac{dx_n}{dt} &= \sum_{j=1}^n a_j(t) x_{n-j+1} \end{aligned} \quad \begin{aligned} \vec{x} &= \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix} \\ A(t) &= \begin{pmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ a_{n-1}(t) & \dots & a_n(t) \end{pmatrix} \end{aligned}$$

Matrice comparsion  
not  $\equiv \text{comp}(a_1(t), \dots, a_n(t))$

$$(2) \quad \frac{d\vec{x}}{dt} = A(t) \vec{x}$$

PROP (de echivalență)

$\varphi(\cdot)$  sol a ec(1)  $\Leftrightarrow \varphi(\cdot) = (\varphi_1(\cdot), \dots, \varphi_{n-1}(\cdot))$  este soluție

a ec. (2)

T(E.U.G)

Fie  $a_1(\cdot), \dots, a_n(\cdot) : I \subseteq \mathbb{R} \rightarrow \mathbb{R}$  cont def  $x^{(n)} = \sum_{j=1}^n a_j(t) x^{(n-j)}$

sol. cu  $\varphi(t_0) = x_0$ ,  $\varphi'(t_0) = x_0'$ , ...,  $\varphi^{(n-1)}(t_0) = x_0^{(n-1)}$ ,  $\varphi^{(n)}(t_0) = x_0^{(n)}$ .

Bem Prop. de echivalență + T(E \cup G) pt. ec. liniare pe  $\mathbb{R}^n$  aplicată ec. (2)

$S := \{ \varphi(\cdot) : I \rightarrow \mathbb{R}; \varphi(\cdot) \text{ soluție a ec. } X = \sum_{j=1}^m a_j(t) x_j^{(n-j)} \}$

T (spațiul soluțiilor)

Fie  $a_1(\cdot), \dots, a_m(\cdot) : I \subseteq \mathbb{R} \rightarrow \mathbb{R}$  cont. def.  $X = \sum_{j=1}^m a_j(t) x_j^{(n-j)}$

Așa că  $S \subset C(I, \mathbb{R})$  subsp. vectorial dim(S)

$A(t) = \text{comp}(a_1(t), \dots, a_m(t))$

$T: S \xrightarrow{a_1(\cdot), \dots, a_m(\cdot)} A(\cdot) \quad T(\varphi(\cdot)) = \begin{pmatrix} \varphi(\cdot) \\ \varphi'(\cdot) \\ \vdots \\ \varphi^{(n-1)}(\cdot) \end{pmatrix} (= \varphi(\cdot), \varphi'(\cdot), \dots, \varphi^{(n-1)}(\cdot))$

T. liniară și bijecțivă dim(S<sub>A(\cdot)</sub>) = m  $\Rightarrow$  g.e.d

Dif.  $\{ \varphi_1(\cdot), \dots, \varphi_m(\cdot) \} \subset S_{a_1(\cdot), \dots, a_m(\cdot)}$  bază sau sistem fundamental de soluție.

Dacă  $\{ \varphi_1(\cdot), \dots, \varphi_m(\cdot) \} \subset S_{a_1(\cdot), \dots, a_m(\cdot)}$  este fundamental de soluție  $\varphi(\cdot) = S_{a_1(\cdot), \dots, a_m(\cdot)} \Leftrightarrow$

$\exists c_1, \dots, c_m \in \mathbb{R}$  a.t.  $\varphi(t) = \sum_{i=1}^m c_i \varphi_i(t)$

soluție generală

Ecuatii liniare de ordinul superior cu coeficienți constanți

Dif.  $a_1, \dots, a_m \in \mathbb{R}$  def.  $X = \sum_{j=1}^m a_j x_j^{(n-j)}$

Caz particular:  $a_j(t) \equiv a_j \in \mathbb{R}, j = 1, \dots, n$

Sistem echivalent asociat:

$$(2) \begin{cases} \frac{dx_1}{dt} = x_2 \\ \vdots \\ \frac{dx_{n-1}}{dt} = x_n \\ \frac{dx_n}{dt} = \sum_{j=1}^m a_j x_{n-j+1} \end{cases}$$

$$X = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix}$$

$$\begin{aligned} A &= \text{comp}(a_1, \dots, a_m) = \\ &= \begin{pmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & 1 \\ 0 & 0 & 0 & \dots & a_1 \end{pmatrix} \end{aligned}$$

$$(2) \frac{dX}{dt} = AX$$

Prop  $\sigma(\text{comp}(a_1, \dots, a_m)) = \{\lambda \in \mathbb{C}; \lambda^m = \sum_{j=1}^m a_j \lambda^{m-j}\} =: \sigma(a_1, \dots, a_m)$

spectral

Def:  $\text{CP}(\sigma(a_1, \dots, a_m)) = \left\{ \varphi(t) = \sum_{j=1}^m e^{\lambda_j t} P_j(t) + \sum_{j=p+1}^k e^{2\lambda_j t} Q_j(t) \right\}$

cu polinoame

•  $(P_j(t) \cos \beta_j t + Q_j(t) \sin \beta_j t)$ , unde

$$\sigma(a_1, \dots, a_m) = S \lambda_i, \lambda_i \in \mathbb{R}, \lambda_{e+i} = \lambda_{e-i} + i \cdot \beta_{e+1}, \overline{\lambda_{e+1}}$$

$\lambda_R = \lambda_{\bar{R}} + i \cdot \beta_R, \lambda_R \rightarrow$  cu ordinale de multiplicitate  $m_1, \dots, m_p$

și  $P_j(t), Q_j(t)$  sunt polinoame de grad  $\leq m_j - 1$

### T (structura soluției)

$$S_{a_1, \dots, a_m} = \text{CP}(\sigma(a_1, \dots, a_m))$$

$$\text{Def: } S_{a_1, \dots, a_m} \subseteq S_A \subseteq \text{CP}(\sigma(a_1, \dots, a_m))$$

↓ prop. de echivalență ↓ T (struc. sol) ↓  
 dim = m dim = m

### Algoritm

$$x^{(m)} = \sum_{j=1}^m a_j x^{(n-j)} \quad a_1, \dots, a_m \in \mathbb{R}$$

1. Rezolvă ec. caracteristică  $x^n = \sum_{j=1}^m a_j \lambda^{n-j} \rightarrow \sigma(a_1, \dots, a_m)$

2. Pt.  $\lambda \in \sigma(a_1, \dots, a_m)$  scrie soluție

$$\varphi_{\lambda}^j(t) = \begin{cases} t^{j-1} e^{\lambda t}, & \lambda \in \mathbb{R}, j = \overline{1, m} \\ t^{j-1} e^{\alpha t} \cos \beta t & \lambda = \alpha + i\beta \\ t^{j-1} e^{\alpha t} \sin \beta t & \beta > 0 \end{cases} \quad j = \overline{1, m}$$

3. Remunerare:  $\left\{ \varphi_{\lambda}^j(t) \right\}_{\lambda \in \sigma(a_1, \dots, a_m)}$

$= \left\{ \varphi_1(\cdot), \dots, \varphi_n(\cdot) \right\}$  sistem fundamental de soluții

Soluție sol. generală  $x(t) = \sum_{i=1}^m c_i \varphi_i(t)$ ,  $c_i \in \mathbb{R}$   $i = \overline{1, n}$

### Ecuții afine de ordinul Superior

Def:  $a_1(t), \dots, a_m(t)$ ,  $b(t)$ :  $I \subseteq \mathbb{R} \rightarrow \mathbb{R}$  def  $X^{(n)} = \sum_{j=1}^n a_j(t) X^{(n-j)}$

Sistemul economic asociat

$$\frac{dx_1}{dt} = x_2$$

$$\frac{dx_2}{dt} = x_3$$

⋮

$$\frac{dx_{m-1}}{dt} = x_m$$

$$\frac{dx_m}{dt} = \sum_{j=1}^n a_j(t) x_{m-j+1} + b(t)$$

$$\vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_m \end{pmatrix} \quad A(t) = \text{comp}(a_1(t), \dots, a_m(t))$$

$$\vec{b}(t) = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ b(t) \end{pmatrix}$$

$$(2) \quad \frac{d\vec{x}}{dt} = A(t)\vec{x} + \vec{b}(t)$$

PROP (de echivalență)

$\varphi(\cdot)$  este soluție a ec. (1)  $\Leftrightarrow \varphi(\cdot) = (\varphi_1(\cdot), \dots, \varphi^{(n-1)}(\cdot))$

Sol. a ec. (2)

## T(EUG)

Fie  $a_1(\cdot), \dots, a_m(\cdot), b(\cdot) : I \rightarrow \mathbb{R}$  continue def.  $x^{(n)} = \sum_{j=1}^m a_j(t)x^{(n-j)} + b(t)$

Atunci  $\#(t_0, (x_0, x'_0, \dots, x^{(n-1)}_0)) \in \mathbb{I} \times \mathbb{R}^n \exists \varphi(\cdot) : I \rightarrow \mathbb{R}$  soluție

$$\varphi(t_0) = x_0, \varphi'(t_0) = x'_0, \dots, \varphi^{(n-1)}(t_0) = x^{(n-1)}_0$$

Dem: Prop. de echivalență + T(EUG) pt. ec. diferențială pe  $\mathbb{R}^n$   
aplicată ec. (2)

$$S = \left\{ \varphi(\cdot) : I \rightarrow \mathbb{R}, \varphi(\cdot) \text{ sol a ec. } x^{(n)} = \sum_{j=1}^m a_j(t)x^{(n-j)} + b(t) \right\}_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)}$$

PROP (varietatea soluțiilor)

$$S_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)} = S_{a_1(\cdot), \dots, a_m(\cdot)} + \{\varphi_0(\cdot)\}, \varphi_0(\cdot) \in S_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)}$$

Dem "Fixăm  $\varphi_0(\cdot) \in S_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)}$  ?"

$$\text{Fixe } \varphi(\cdot) \in S_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)} \Rightarrow \varphi(\cdot) - \varphi_0(\cdot) \in S_{a_1(\cdot), \dots, a_m(\cdot)}$$

$$\varphi^{(n)}(t) = \sum_{j=1}^m a_j(t) \varphi^{(n-j)}(t) + b(t)$$

$$\varphi_0^{(n)}(t) = \sum_{j=1}^m a_j(t) \varphi_0^{(n-j)}(t) + b(t)$$

$$(\varphi - \varphi_0)^{(n)}(t) = \sum_{j=1}^m a_j(t)(\varphi - \varphi_0)^{(n-j)}(t) \quad \varphi - \varphi_0 \in S_{a_1(\cdot), \dots, a_m(\cdot)} ?$$

$$\geq \text{Fixe } \psi(\cdot) \in S_{a_1(\cdot), \dots, a_m(\cdot)} \quad \varphi_0(\cdot) \in S_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)} \Rightarrow$$

$$\psi(\cdot) + \varphi_0(\cdot) \in S_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)}$$

$$\psi^{(n)}(t) = \sum_{j=1}^m a_j(t) \psi^{(n-j)}(t)$$

$$\psi_0^{(n)}(t) = \sum_{j=1}^m a_j(t) \psi_0^{(n-j)}(t) + b(t)$$

Concluzie Dacă  $\{\varphi_1(\cdot), \dots, \varphi_m(\cdot)\}$  este un sistem fundamental de soluții pt. ec. lini. asociată  $X^{(m)} = \sum_{j=1}^m a_j(t) \varphi^{(n-j)}(t)$  și  $\varphi_0(\cdot)$

$\in S_{a_1(\cdot), \dots, a_m(\cdot), b(\cdot)}$  atunci  $\Psi(t) \in S_{a_1(\cdot), \dots, a_m(\cdot), b(t)}$   $\Leftrightarrow$

$$\boxed{\sum_{i=1}^m c_i \varphi_i(t) + \varphi_0(t) = \Psi(t)}$$

~~sol~~. generală

### Seminarul 10

#### Ecuatii affine pe $\mathbb{R}^n$ - Algoritm

(Metoda variației constanțelor)

$$A(\cdot): I \subseteq \mathbb{R} \rightarrow L(\mathbb{R}^n, \mathbb{R}^n)$$

$$b(\cdot): I \rightarrow \mathbb{R}^n$$

1. Considerăm ec. liniară asociată  $\frac{dx}{dt} = A(t)x$

Determinăm  $\{\varphi_1(\cdot), \dots, \varphi_m(\cdot)\}$  sistem fundamental de soluții

Obs: Dacă  $A(t) \equiv A \in L(\mathbb{R}^n, \mathbb{R}^n)$   $\rightarrow$  vezi Algoritm

$$\text{Serie sol. generală } X(t) = \sum_{i=1}^m c_i \varphi_i(t)$$

$$2. \text{ Căută sol. de formă } x(t) = \sum_{i=1}^m c_i(t) \varphi_i(t)$$

$$x(t) \text{ sol} \Rightarrow \sum_{i=1}^m c_i(t) \varphi_i(t) = b(t) \Rightarrow c_i(t) = \dots \quad i=1, \dots, m \\ \Rightarrow c_i(t) = \dots \quad i=1, \dots, m \\ \Rightarrow x(t) = \dots$$

#### Ecuatii liniare de ordin superior cu coeficienți constanți - Algoritm

$$X^{(m)} = \sum_{j=1}^m a_j X^{(n-j)} \quad a_j \in \mathbb{R}, j=1, n$$

1. Rezolvă ec. caracteristică:  $\lambda^n = \sum_{j=1}^m a_j \lambda^{n-j} \rightarrow \det(a_1, \dots, a_n)$

2 pt.  $\lambda \in \sigma(a_1, \dots, a_m)$  scrie sol

$$\varphi_\lambda^j(t) = \int t^{j-1} e^{\lambda t} \quad \lambda \in \mathbb{R}, j = \overline{1, m_\lambda}$$

$$\begin{cases} t^{j-1} e^{\lambda t} \cos \beta t \\ t^{j-1} e^{\lambda t} \sin \beta t \end{cases}$$

$$\lambda = \alpha + i\beta, \beta > 0, j = \overline{1, m_\lambda}$$

3. Rezumarează  $\left\{ \varphi_\lambda^j(\cdot) \right\}_{\lambda \in \sigma(a_1, \dots, a_m)} = \left\{ \varphi_1(\cdot), \dots, \varphi_n(\cdot) \right\}_{j = \overline{1, m_\lambda}}$  sistem

fundamental de soluții. Scrie sol generală  $x(t) = \sum_{i=1}^n c_i \varphi_i(t)$ ,  $c_i \in \mathbb{R}, i = \overline{1, n}$

Ex: Să se determine soluția generală

$$1) \begin{cases} \dot{x} = 2x - y + e^{-t} \\ \dot{y} = 3y - 2x + e^{-t} \end{cases}$$

$$\begin{cases} \bar{x}' = 2\bar{x} - \bar{y} \\ \bar{y}' = 3\bar{y} - 2\bar{x} \end{cases} \quad \begin{cases} \bar{y} = 2\bar{x} - \bar{x}' \\ \bar{y}' = 3(2\bar{x} - \bar{x}') - 2\bar{x}' \\ \bar{y}' = 6\bar{x} - 3\bar{x}' - 2\bar{x}' \\ \bar{y}' = 4\bar{x} - 3\bar{x}' \end{cases}$$

$$-\bar{x}(2\bar{x} - \bar{x}')' = 4\bar{x} - 3\bar{x}' \quad \rightarrow \text{Am găsit să}\}$$

$$2\bar{x}' - \bar{x}'' = 4\bar{x} - 3\bar{x}' \quad \left. \begin{array}{l} \text{înlocuiesc} \\ \text{direct} \end{array} \right.$$

$$-\bar{x}''' = -5\bar{x}'' + 4\bar{x}'$$

$$-\lambda^2 = -5\lambda + 4 \Leftrightarrow \lambda^2 - 5\lambda + 4$$

$$\Leftrightarrow (\lambda - 1)(\lambda - 4) = 0$$

$$\lambda_1 = 1, \lambda_2 = 4$$

$$\Rightarrow \bar{x}(t) = c_1 e^t + c_2 e^{4t}, c_1, c_2 \in \mathbb{R}$$

$$\bar{y}(t) = -(c_1 e^t + c_2 e^{4t})' + 2(c_1 e^t + c_2 e^{4t})$$

$$x(t) = c_1 e^t + c_2 e^{4t}$$

$$\int y(t) = c_1(t) e^t - 2 c_2(t) e^{4t}$$

$$\int z(t) = c_1(t) e^t + c_2(t) e^{4t}$$

$$(c_1(t) e^t + c_2(t) e^{4t})' = 2(c_1(t) e^t + c_2(t) e^{4t}) - c_1(t) e^t + 2c_2(t) e^{4t} + e^{-t}$$

$$c_1'(t) e^t + c_1(t) e^t + c_2'(t) e^{4t} + 4c_2(t) e^{4t} = \\ = 2c_1(t) e^t + c_2(t) e^{4t} - c_1(t) e^t + 2c_2(t) e^{4t} + e^{-t}$$

$$(c_1(t) e^t - 2c_2(t) e^{4t})' = 3(c_1(t) e^t - 2c_2(t) e^{4t}) - 2(c_1(t) e^t + 2c_2(t) e^{4t}) + e^{-t}$$

$$\Leftrightarrow c_1'(t) e^t + c_1(t) e^t - 2c_2'(t) e^{4t} - 8c_2(t) e^{4t} \\ = 3c_1(t) e^t - 5c_2(t) e^{4t} - 2c_1(t) e^t - 2c_2(t) e^{4t}$$

$$\Leftrightarrow c_1'(t) e^t + c_1(t) e^t - 2c_2'(t) e^{4t} - 8c_2(t) e^{4t} \\ = c_1'(t) e^t - 8c_2(t) e^{4t} + e^{-t}$$

$$\int c_1'(t) e^t + c_2'(t) e^{4t} = e^{-t}$$

$$\int c_1'(t) e^t - 2c_2'(t) e^{4t} = e^{-t}$$

$$3c_2'(t) = 0 \Rightarrow c_2'(t) = 0$$

$$c_1'(t) e^t = e^{-t} \Rightarrow c_1'(t) = e^{-2t}$$

$$c_2(t) = k_2, k_2 \in \mathbb{R}$$

$$c_1(t) = -\frac{1}{2} e^{-2t} + k_1, k_1 \in \mathbb{R}$$

$$\int x(t) = (-\frac{1}{2} e^{-2t} + k_1) e^t + k_2 e^{4t}, k_1, k_2 \in \mathbb{R}$$

$$\int y(t) = (-\frac{1}{2} e^{-2t} + k_1) e^t - 2k_2 e^{4t}, k_1, k_2 \in \mathbb{R}$$

$$2) \begin{cases} \dot{x} = x - y + 2\sin t \\ \dot{y} = 2x - y \end{cases}$$

$$\begin{cases} \bar{x}' = \bar{x} - \bar{y} \\ \bar{y}' = 2\bar{x} - \bar{y} \end{cases} \Rightarrow \bar{y}' = \bar{x}' + \bar{x}$$

$$\begin{cases} \bar{x}' = \bar{x} - \bar{y} \\ \bar{y}' = 2\bar{x} - \bar{y} \end{cases} \quad \text{[Redacted]}$$

$$(\bar{x} - \bar{x}')' = 2\bar{x} - \bar{x} + \bar{x}'$$

$$\cancel{\bar{x}'} - \bar{x}'' = \cancel{\bar{x}} + \bar{x}' \Rightarrow \bar{x}'' + \bar{x} = 0$$

$$\lambda^2 + 1 = 0 \Rightarrow \lambda = \pm i$$

For  $\lambda = i$

$$\Rightarrow \bar{\varphi}_1(t) = e^{it} \cdot \cos t = \cos t$$

$$\bar{\varphi}_2(t) = e^{it} \cdot \sin t = \sin t$$

$$\Rightarrow \bar{x}(t) = c_1 \cos t + c_2 \sin t$$

$$\Rightarrow \bar{y}(t) = c_1 \cos t + c_2 \sin t + c_3 \sin t - c_4 \cos t$$

$$\bar{y}(t) = c_1(\cos t + \sin t) + c_2(\sin t - \cos t)$$

$$c_1, c_2 \in \mathbb{R}$$

$$\begin{cases} x(t) = c_1(t) \cdot \cos t + c_2(t) \cdot \sin t \\ y(t) = c_1(t)(\cos t + \sin t) + c_2(t)(\cos t + \sin t) \end{cases}$$

$$(c_1(t) \cos t + c_2(t) \sin t)' = c_1(t) \cancel{\cos t} + c_2(t) \sin t -$$

$$- c_1(t) \cancel{\cos t} - c_1(t) \sin t + c_2(t) \cos t - c_2(t) \sin t + 2 \sin t$$

$$c_1'(t) \cos t - c_1(t) \sin t + c_2'(t) \sin t + c_2(t) \cos t =$$

$$-c_1(t) \sin t + c_2(t) \cos t + 2 \sin t$$

$$(c_1(t) \cos t + \sin t) + c_2(t) (\sin t - \cos t)$$

$$= 2(c_1(t) \cos t + c_2(t) \sin t) - c_1(t)(\cos t + \sin t)$$

$$- c_2(t)(\sin t - \cos t)$$

$$\Leftrightarrow c_1'(t)(\cos t + \sin t) + c_1(t)(-\sin t + \cos t)$$

$$+ c_2'(t)(\sin t - \cos t) + c_2(t)(\cos t + \sin t) =$$

$$= 2c_1(t) \cos t + 2c_2(t) \sin t - c_1(t) \cos t - c_1(t) \sin t$$

$$- c_2(t) \sin t + c_2(t) \cos t$$

$$\Leftrightarrow c_1'(t)(\cos t + \sin t) - c_1(t) \sin t + c_1(t) \cos t$$

$$+ c_2'(t)(\sin t - \cos t) + c_2(t) \cos t + c_2(t) \sin t$$

$$= c_1(t) \cos t + c_2(t) \sin t - c_1(t) \sin t + c_2(t) \cos t$$

$$\Leftrightarrow c_1'(t)(\cos t + \sin t) + c_2'(t) \sin t - \cos t = 0$$

$$\left\{ \begin{array}{l} c_1'(t) \cos t + c_2'(t) \sin t = 2 \sin t \\ c_1'(t) \cos t + c_2'(t) \sin t = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} c_1'(t) \cos t + c_2'(t) \sin t = 2 \sin t \\ c_1'(t) \sin t - c_2'(t) \cos t = -2 \sin t \end{array} \right.$$

$$\left\{ \begin{array}{l} c_1'(t) \cos^2 t + c_2'(t) \sin t \cos t = 2 \sin t \cos t \\ c_1'(t) \sin^2 t - c_2'(t) \cos t \cdot \sin t = -2 \sin^2 t \end{array} \right.$$

$$c_1'(t)(\sin^2 t + \cos^2 t) = 2 \sin t \cos t - 2 \sin^2 t$$

$$c_1'(t) = 2 \sin t \cos t - 2 \sin^2 t$$

$$c_1'(t) = 2 \sin^2 t + 2 \sin t \cos t$$

$$\Rightarrow c_1(t) = \int (2\sin t \cos t - 2\sin^2 t) dt$$

$$= \cancel{\int} (\sin 2t - \cancel{1 + \cos 2t}) dt$$

$$= -\frac{1}{2} \cos 2t - t + \frac{1}{2} \sin 2t + k_1, k_1 \in \mathbb{R}$$

$$\Rightarrow c_2(t) = \int (2 \sin^2 t + 2 \sin t \cos t) dt$$

$$= \int (1 - \cos 2t + \sin 2t) dt$$

$$= t - \frac{1}{2} \sin 2t - \frac{1}{2} \cos 2t + k_2, k_2 \in \mathbb{R}.$$

3)  $\begin{cases} x' = 2y - x + 1 \\ y' = 3y - 2x \end{cases}$

4)  $x'' + x''' = 0$        $\lambda_1 = 0, \lambda_2 = 0$   
 $\lambda^4 + \lambda^2 = 0 \Leftrightarrow \lambda^2(\lambda^2 + 1) = 0 \quad \begin{cases} \lambda_3 = i \\ \lambda_4 = -i \end{cases}$

1 råd real & dubbla, 2 råd komplexe conjugate.

$$\lambda = 0, m_\lambda = 2$$

$$\varphi_1(t) = e^{0t} \Rightarrow \varphi_1(t) = 1.$$

$$\varphi_2(t) = t \cdot e^{0t} \Rightarrow \varphi_2(t) = t$$

$$\lambda = i$$

$$\varphi_3(t) = e^{0t} \cos 1t + 1 \cdot t = \cos t$$

$$\varphi_4(t) = e^{0t} \sin 1t = \sin t$$

$$\begin{aligned} \Rightarrow x(t) &= c_1 \varphi_1(t) + c_2 \varphi_2(t) + c_3 \varphi_3(t) + c_4 \varphi_4(t) \\ &= c_1 + c_2 t + c_3 \cos t + c_4 \sin t \\ c_1, c_2, c_3, c_4 &\in \mathbb{R} \end{aligned}$$

$$5) \quad x'' - 3x' + 3x - x = 0.$$

$$x(0) = 1, \quad x'(0) = 0, \quad x''(0) = -1.$$

$$\lambda^3 - 3\lambda^2 + 3\lambda - 1 = 0$$

$$(\lambda - 1)^3 = 0, \quad \lambda = 1, \quad m_\lambda = 3$$

$$\varphi_1(t) = e^{1t} = e^t$$

$$\varphi_2(t) = t \cdot e^t$$

$$\varphi_3(t) = t^2 \cdot e^t$$

$$\Rightarrow x(t) = c_1 e^t + c_2 t \cdot e^t + c_3 t^2 \cdot e^t$$

$$c_1, c_2, c_3 \in \mathbb{R}$$

$$x(0) = c_1 \cdot e^0 = 1 \Rightarrow c_1 = 1$$

$$x'(t) = c_1 e^t + c_2 t e^t + c_2 e^t + 2c_3 t e^t + c_3 t^2 e^t \\ = e^t (c_1 + c_2) + e^t \cdot t (2c_3 + c_2) + e^t \cdot t^2$$

$$\stackrel{t=0}{=} e^0 (1 + c_2) = 0$$

$$c_2 = -1$$

$$x''(t) = e^t (c_1 + c_2) + e^t (c_2 + c_3) + e^t t (c_2 + c_3) \\ + 2c_3 t \cdot e^t + e^t t^2 c_3$$

$$= e^t (c_1 + 2c_2 + c_3) + e^t \cdot t (c_2 + 3c_3) + e^t$$

$$\stackrel{t=0}{=} e^0 (1 - 2 + 2c_3) = -1$$

$$c_3 = \underline{\underline{0}}$$

$$x(t) = e^t - t \cdot e^t \quad \cancel{- t^2 \cdot e^t}$$