



 <b>Date:</b>		<b>Topic: Intelligent Sound Control</b>	<b>Time Required: 90 minutes</b>
 <b>Learning Target/Objectives:</b> <ul style="list-style-type: none"> <li>• <b>I can</b> successfully configure the Arduino IDE to compile and upload acoustic-recognition code to a robotic controller .</li> <li>• <b>I can</b> explain how a sound sensor converts physical sound waves (intensity) into electrical signals to trigger specific robotic action groups.</li> <li>• <b>I can</b> modify and verify program parameters to re-route a robot's destination based on auditory input.</li> </ul>			
 <b>Vocabulary:</b> <ul style="list-style-type: none"> <li>• <b>Sound Intensity</b></li> <li>• <b>Acoustic Detection</b></li> <li>• <b>Analog Signal</b></li> <li>• <b>Ambient Noise</b></li> <li>• <b>Threshold Value</b></li> <li>• <b>Action Group</b></li> </ul>		 <b>Guiding Questions:</b> <ul style="list-style-type: none"> <li>• Why does the lesson recommend operating the robot in a quiet environment?</li> <li>• How does the robot distinguish between a deliberate command (a clap) and random background noise?</li> <li>• In what ways could an engineer adjust the code if the sound sensor was too sensitive or not sensitive enough?</li> </ul>	
 <b>Lesson Design Details:</b> <ul style="list-style-type: none"> <li>• <b>Activity 1: The Ambient Noise Audit</b> <ul style="list-style-type: none"> <li>○ <b>Focus:</b> Students use the Serial Monitor in the IDE to observe the "raw data" from the sound sensor in a quiet room versus a noisy room. They must determine the best "Threshold Value" for their specific classroom.</li> </ul> </li> <li>• <b>Activity 2: Sound Trigger Transport</b> <ul style="list-style-type: none"> <li>○ <b>Focus:</b> Students set up the map and blocks. They must successfully move a block from the right side to a new position using exactly one clap near the sensor .</li> </ul> </li> <li>• <b>Activity 3: The "Middle Pick" Code Edit</b> <ul style="list-style-type: none"> <li>○ <b>Focus:</b> Students locate line 80 in <code>sound_control.ino</code>. They must change the code from <code>(12+result)</code> to <code>(13+result)</code>, re-upload, and verify that the arm now picks up the middle block.</li> </ul> </li> </ul>			

### Key Points (Vocabulary):

- **Sound Intensity:** The measurable amount of acoustic energy in a given environment, used as a trigger for the sensor.
- **Acoustic Detection:** The process by which the sensor identifies specific sounds, such as claps, to initiate a command.
- **Analog Signal:** A continuous signal that varies in intensity, often converted by the sensor into a value the robot can process.
- **Ambient Noise:** Background sounds that may interfere with the accuracy of the sound sensor.
- **Threshold Value:** The programmed level of sound intensity required to "activate" a robotic response.
- **Action Group:** A pre-programmed sequence of robotic movements (e.g., picking up a block) stored in the controller.

### Key Points of Instruction

- **Environmental Awareness:** Emphasize that "Ambient Noise" is a major variable. Teach students that a classroom with 30 students will likely trigger the sensor accidentally unless they are in a controlled setting.
- **The "Wait for Verification" Rhythm:** Students must watch for "Done compiling" before they attempt to "Upload." If they pull the cable early, the robotic brain will be empty .
- **Code Arithmetic:** Explain that `(12+result)` in the code isn't just random; it is a mathematical way to select a specific "folder" or action group in the robot's memory.
- **Signal Proximity:** Instruct students to clap close to the controller initially to ensure the sensor reaches its "programmed detected value".

### Teacher's Cheat Sheet

Feature	Technical Requirement / Value
Board Type	Arduino / Genuino Uno
Code File	sound_control.ino
Upload Path	Tools -> Port -> Select COM Port
Right Grab Code	<code>(12+result)</code>
Middle Grab Code	<code>(13+result)</code>

<b>Trigger Event</b>	Single clap close to controller
<b>Visual Confirmation</b>	Done compiling -> Done uploading

<b>Category</b>	<b>Standard Organization</b>	<b>Standard/Benchmark Code and Description</b>
<b>Computer Science</b>	NCSOS	HS-CS-03: Illustrate the ways computing systems implement logic, input, and output through hardware components 1.
<b>Technology</b>	ITEEA	STEL-2R: Follow step-by-step instructions to safely use systems and troubleshoot common problems 2.
<b>Engineering</b>	ITEEA	STEL-2V: Analyze the stability of a technological system and how it is influenced by components in the feedback loop 3.
<b>Digital Literacy</b>	ISTE	1.5.d: Students understand how automation works and use algorithmic thinking to develop a sequence of steps 4444.
<b>Science</b>	NCSOS	PHY.2.1.2: Explain the concepts of sound and wave motion.