



 Date:		Topic: Wireless Controller	Time Required: 45 minutes
 Learning Target/Objectives: <ul style="list-style-type: none"> • I can successfully pair a wireless controller with a robotic arm by following a technical hardware sequence. • I can distinguish between and switch between Action Group Mode and Single Servo Mode to execute specific robotic tasks. • I can troubleshoot connection failures and manage energy constraints like "Sleep Mode" in a wireless system. 			
 Vocabulary: <ul style="list-style-type: none"> • Receiver • Pairing • Action Group Mode • Single Servo Mode • Combination Key • Sleep Mode 		 Guiding Questions: <ul style="list-style-type: none"> • Why does a robot require a "receiver" plugged into its board rather than just having a built-in sensor? • What are the advantages of using "Action Group Mode" for repetitive industrial tasks versus using "Single Servo Mode"? • How does the "Sleep Mode" timer contribute to the sustainability and efficiency of the robotic system? 	
 Lesson Design Details: <ul style="list-style-type: none"> • Activity 1: The Pairing Protocol Race <ul style="list-style-type: none"> ○ Focus: Students compete in teams to successfully pair their controller. They must document the LED states from "Flashing" to "Steady On". • Activity 2: The Action Group Mystery <ul style="list-style-type: none"> ○ Focus: In Action Group Mode, students press buttons (Up, Down, L1, R1) and must describe the "physical job" the robot is performing for each number (e.g., "Grip to right"). • Activity 3: Precision Manual Pilot <ul style="list-style-type: none"> ○ Focus: Students switch to Single Servo Mode and must navigate the arm to touch a specific target using only manual servo controls. 			

Key Points (Vocabulary):

- **Receiver:** The hardware component that plugs into the robot board to capture signals from the wireless controller.
- **Pairing:** The process of establishing a dedicated communication link between the controller and the robot.
- **Action Group Mode:** A pre-programmed mode where a single button press executes a complex sequence of movements.
- **Single Servo Mode:** A manual control mode where buttons rotate individual motors one at a time.
- **Combination Key:** Pressing two or more buttons (like Select and Start) in a specific order to trigger a hidden function or mode change.
- **Sleep Mode:** A power-saving state the controller enters after periods of inactivity to preserve battery life.

Key Points of Instruction

- **Polarity Awareness:** Remind students that inserting AAA batteries incorrectly (ignoring positive and negative poles) can prevent the controller from powering on.
- **Visual Status Cues:** Teach students to look for "Steady On" LEDs. If lights are flashing, the pairing is incomplete.
- **The "Mode" Toggle:** If students only see one color light (red or green) instead of both, they must use the "MODE" key to fix the status.
- **Combination Logic:** Mode switching requires a specific rhythm: press and hold "SELECT" first, then tap "START".

Teacher's Cheat Sheet

Feature	Data / Instruction
Batteries	2 pieces of AAA (Self-prepared)
Pairing Status	Red and Green LEDs = Steady On
Sleep Mode (Unconnected)	Activates after 30 seconds
Sleep Mode (Connected)	Activates after 5 minutes of no use

Wake Up Command	Press "START" key
Mode Switch Sound	Listen for a "Beep" sound
Switch Sequence	SELECT (Hold) then START
Reset/Initial Stance	Press "START" once in Action Group Mode

Category	Standard Organization	Standard/Benchmark Code and Description
Technology	ITEEA	STEL-2R: Follow step-by-step instructions to safely use systems and troubleshoot common problems
Computer Science	NCSOS	HS-CS-02: Design and implement strategies for troubleshooting hardware and software problems
Engineering	ITEEA	STEL-3H: Optimize a system by identifying and managing various constraints
Digital Literacy	ISTE	1.1 Empowered Learner: Students leverage technology to take an active role in choosing, achieving, and demonstrating competency in their learning goals
Science	NCSOS	PHY.2.2.3: Analyze the relationship between components in a DC circuit, such as batteries and poles