

 Date:	Topic: Intelligent Sound Control	Time Required: 90 minutes		
🎯 Learning Target/Objectives:				
<ul style="list-style-type: none">• I can successfully configure the Arduino IDE to compile and upload acoustic-recognition code to a robotic controller .• I can explain how a sound sensor converts physical sound waves (intensity) into electrical signals to trigger specific robotic action groups.• I can modify and verify program parameters to re-route a robot's destination based on auditory input.				
 Vocabulary:	 Guiding Questions:			
<ul style="list-style-type: none">• Sound Intensity• Acoustic Detection• Analog Signal• Ambient Noise• Threshold Value• Action Group				
📚 Lesson Design Details:				
<ul style="list-style-type: none">• Activity 1: The Ambient Noise Audit<ul style="list-style-type: none">○ Focus: Students use the Serial Monitor in the IDE to observe the "raw data" from the sound sensor in a quiet room versus a noisy room. They must determine the best "Threshold Value" for their specific classroom.• Activity 2: Sound Trigger Transport<ul style="list-style-type: none">○ Focus: Students set up the map and blocks. They must successfully move a block from the right side to a new position using exactly one clap near the sensor .• Activity 3: The "Middle Pick" Code Edit<ul style="list-style-type: none">○ Focus: Students locate line 80 in <code>sound_control.ino</code>. They must change the code from <code>(12+result)</code> to <code>(13+result)</code>, re-upload, and verify that the arm now picks up the middle block.				

Key Points (Vocabulary):

- Sound Intensity: The measurable amount of acoustic energy in a given environment, used as a trigger for the sensor.
- Acoustic Detection: The process by which the sensor identifies specific sounds, such as claps, to initiate a command.
- Analog Signal: A continuous signal that varies in intensity, often converted by the sensor into a value the robot can process.
- Ambient Noise: Background sounds that may interfere with the accuracy of the sound sensor.
- Threshold Value: The programmed level of sound intensity required to "activate" a robotic response.
- Action Group: A pre-programmed sequence of robotic movements (e.g., picking up a block) stored in the controller.

Key Points of Instruction

- **Environmental Awareness:** Emphasize that "Ambient Noise" is a major variable. Teach students that a classroom with 30 students will likely trigger the sensor accidentally unless they are in a controlled setting.
- **The "Wait for Verification" Rhythm:** Students must watch for "Done compiling" before they attempt to "Upload." If they pull the cable early, the robotic brain will be empty .
- **Code Arithmetic:** Explain that `(12+result)` in the code isn't just random; it is a mathematical way to select a specific "folder" or action group in the robot's memory.
- **Signal Proximity:** Instruct students to clap close to the controller initially to ensure the sensor reaches its "programmed detected value".

Teacher's Cheat Sheet

Feature	Technical Requirement / Value
Board Type	Arduino / Genuino Uno
Code File	<code>sound_control.ino</code>
Upload Path	Tools -> Port -> Select COM Port
Right Grab Code	<code>(12+result)</code>
Middle Grab Code	<code>(13+result)</code>

Trigger Event	Single clap close to controller
Visual Confirmation	Done compiling -> Done uploading

Category	Standard Organization	Standard/Benchmark Code and Description
Computer Science	NCSOS	HS-CS-03: Illustrate the ways computing systems implement logic, input, and output through hardware components 1.
Technology	ITEEA	STEL-2R: Follow step-by-step instructions to safely use systems and troubleshoot common problems 2.
Engineering	ITEEA	STEL-2V: Analyze the stability of a technological system and how it is influenced by components in the feedback loop 3.
Digital Literacy	ISTE	1.5.d: Students understand how automation works and use algorithmic thinking to develop a sequence of steps 4444.
Science	NCSOS	PHY.2.1.2: Explain the concepts of sound and wave motion.