



 Date:	Topic: Action Group Download	Time Required: 60 minutes
<div style="display: flex; align-items: flex-start;"> <div style="margin-right: 10px;">  </div> <div> Learning Target/Objectives: <ul style="list-style-type: none"> I can successfully transition the xArm PC software into debugging mode to prepare for data synchronization. I can manage multiple robotic behavior files by utilizing "Mass Open" and "Mass Download" functions to streamline hardware updates. I can verify successful data transmission between a computer and a robot by interpreting audible and visual software feedback . </div> </div>		
<div style="display: flex; align-items: flex-start;"> <div style="margin-right: 10px;">  </div> <div> Vocabulary: <ul style="list-style-type: none"> Debugging Mode Mass Open Mass Download .rob File Conflict Error Audible Reminder </div> </div>	<div style="display: flex; align-items: flex-start;"> <div style="margin-right: 10px;">  </div> <div> Guiding Questions: <ul style="list-style-type: none"> Why is it more efficient for an engineer to use "Mass Download" functions instead of transferring one movement file at a time? How does the robot's "beep" serve as a form of non-visual data feedback for the programmer? What are the mechanical risks of ignoring the software warning about connecting only one servo during specific adjustments? </div> </div>	
<div style="display: flex; align-items: flex-start;"> <div style="margin-right: 10px;">  </div> <div> Lesson Design Details: <ul style="list-style-type: none"> Activity 1: The Batch Process Challenge <ul style="list-style-type: none"> Focus: Students are given 12 separate behavior files (Wave, Bow, Grip, etc.). They must race to correctly use the "Mass Open" function to load all 12 into the software Index list. Activity 2: Feedback Loop Diagnostics <ul style="list-style-type: none"> Focus: Students perform a download and must document the exact moment the "Audible Reminder" occurs versus the "Visual Pop-up." They discuss which feedback is more reliable if the screen is turned off . Activity 3: The "No-Conflict" Inspection <ul style="list-style-type: none"> Focus: Before starting their download, students must perform a physical "Port Audit" to ensure their wiring complies with the single-servo safety warning provided in the software interface. </div> </div>		

Key Points (Vocabulary):

- **Debugging Mode:** A software state used to test, find, and fix errors in robotic code or hardware settings.
- **Mass Open:** A software command that allows a user to select and import multiple robotic action files simultaneously.
- **Mass Download:** The process of transferring a large batch of behavior data from a PC to the robot's internal memory.
- **.rob File:** The specific file format used by Hiwonder to store robotic action data.
- **Conflict Error:** A communication failure caused when more than one servo is connected during specific adjustment procedures.
- **Audible Reminder:** A "beep" sound produced by the hardware to confirm a successful digital transaction.

Key Points of Instruction

- **Hardware Handshake:** Emphasize that the robot must be physically connected via cable *before* opening the PC software to ensure the two devices can recognize each other.
- **Debugging Priority:** Students must switch to "Servo Test" mode immediately. Without this step, the "Mass Download" options will not be available.
- **The Conflict Warning:** Heavily emphasize the red text warning in the software. If students are adjusting servos, having more than one connected can cause data packet collisions.
- **Verification Logic:** Teach students that a "Download Success" pop-up is only half the battle; they must also listen for the physical "beep" from the arm to confirm the hardware received the file .

Teacher's Cheat Sheet

Control Feature	Instruction / Critical Data
Connection Type	USB tethered connection
Required Software	xArm PC (V2.8)
Initial Mode	Click Servo Test
File Range	No. 13.rob through No. 24.rob

Safety Warning	Connect ONLY ONE servo if adjusting
Success Signal 1	Auditor "Beep" from robotic arm
Success Signal 2	"Download success!" pop-up

Category	Standard Organization	Standard/Benchmark Code and Description
Computer Science	NCSOS	HS-CS-03: Illustrate the ways computing systems implement logic, input, and output through hardware components.
Technology	ITEEA	STEL-2R: Follow step-by-step instructions to safely use systems and troubleshoot common problems.
Engineering	ITEEA	STEL-3H: Optimize a system by identifying and managing various constraints.
Digital Literacy	ISTE	1.1 Empowered Learner: Students demonstrate a sound understanding of technology concepts, systems, and operations.
Computer Science	NCSOS	HS-AP-10: Create procedures with parameters to organize code and make it easier to reuse.