

Lecture 16 Analog Filter Design

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— Recall from 2714 the 4 basic frequency selective Filters:
lowPASS, HighPASS, BANDPASS, and BANDSTOP.

— Recall also that the ideal versions of these are non-realizable because they are non-causal (violate Paley-Wiener conditions)

Ex. Ideal lowPASS Filter has $H(\omega) = \begin{cases} 1 & |\omega| < \omega_c \\ 0 & \text{else.} \end{cases}$

TAKING the inverse Fourier transform

$$h(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(\omega) e^{j\omega t} d\omega = \frac{1}{2\pi} \int_{-\omega_c}^{\omega_c} e^{j\omega t} d\omega = \frac{1}{2\pi} \left[\frac{1}{j\omega} e^{j\omega t} \right]_{-\omega_c}^{\omega_c}$$

$$= \frac{1}{2\pi j t} \left[e^{j\omega_c t} - e^{-j\omega_c t} \right] = \frac{1}{\pi t} \sin(\omega_c t)$$

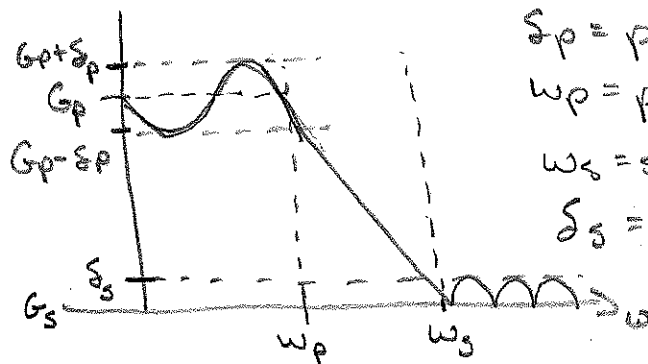
This impulse response $\neq 0$ for $t < 0$, thus is non-causal and physically unrealizable.

— Paley-Wiener conditions state a causal filter

- can have $H(\omega) = 0$ at only a finite number of frequencies
- cannot have $H(\omega) = 0$ over any finite range of frequencies
- transition from passband to stopband cannot be zero
- cannot specify $|H(\omega)|$ and $\angle H(\omega)$ independently.

— In practice Filters are specified by one or more pass bands, transition bands, and stop bands.

• lowpass $|H(j\omega)|$



G_p = pass band Gain (usually 1)

δ_p = pass band ripple

ω_p = pass band frequency

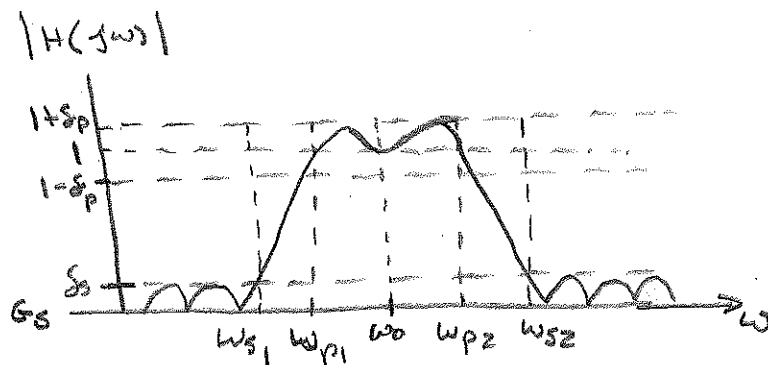
ω_s = stop band frequency

δ_s = stop band ripple.

$\omega_s - \omega_p$ = transition BAND.

BANDPASS

162



- We can focus on design of just lowpass filters since we can transform a lowpass $H_{LP}(\omega)$ into the others

$$H_{HP}(\omega) = 1 - H_{LP}(\omega) \quad H_{BP}(\omega) = \frac{1}{2} H_{LP}(\omega - \omega_0) + \frac{1}{2} H_{LP}(\omega + \omega_0)$$

$$H_{BS}(\omega) = 1 - H_{BP}(\omega)$$

- generally G_p, δ_s, δ_p are specified in dB, frequencies in rad/s or Hz.

- Design problem is to find a transfer function $H(s)$ that is stable and has $H(\omega) \approx H_{desired}(\omega)$. The most popular approach is to use particular parametric forms for the frequency response

- Example: Butterworth lowpass filters have

$$|H(j\omega)|^2 = \frac{1}{1 + \left(\frac{\omega}{\omega_c}\right)^{2N}} \quad \text{for order } N \text{ system}$$

To find the corresponding $H(s)$ we note

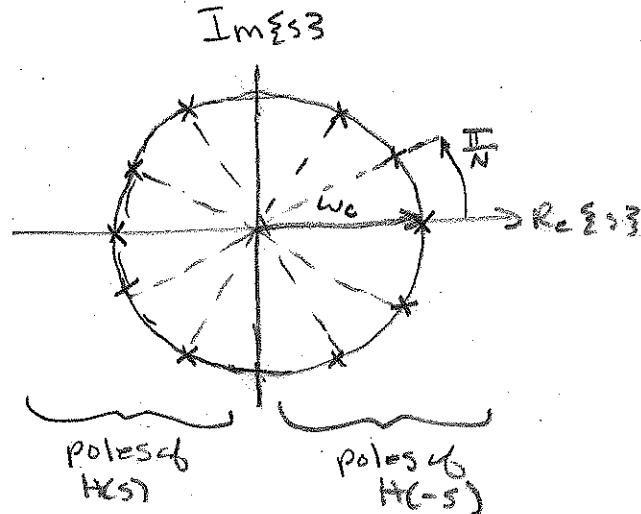
$$|H(\omega)|^2 = H(\omega) H^*(\omega)$$

Since $h(t)$ is real valued $H^*(\omega) = H(-\omega)$ thus

$$|H(\omega)|^2 = H(\omega) H(-\omega) = H(s) H(-s) \Big|_{s=j\omega}$$

$$\text{Then } H(s) H(-s) = \frac{1}{1 + \left(\frac{-s^2}{\omega_c^2}\right)^N}$$

If $H(s)$ has a pole $p_1 = \alpha_1 + j\omega_1$, then $H(-s)$ has a pole $\bar{p}_1 = -\alpha_1 - j\omega_1$, the mirror image.



• When N is odd $\left(\frac{-s^2}{\omega_c^2}\right)^N = \frac{-s^{2N}}{\omega_c^{2N}}$ and $H(s)H(-s) = \frac{-\omega_c^{2N}}{s^{2N} - \omega_c^{2N}}$

AND poles are roots of $s^{2N} - \omega_c^{2N} = 0$

or $s^{2N} = \omega_c^{2N} = \omega_c^{2N} e^{j2\pi k} \Rightarrow p_k = \omega_c e^{j\pi \frac{k}{N}}$
 $k \in 0, 1, \dots, 2N-1$

• By similar argument when N is even $p_k = \omega_c e^{j\pi \frac{2k+1}{2N}}$ $k=0, 1, \dots, 2N-1$

AND $H(s) = \frac{\omega_c^N}{\prod_k (s - p_k)}$ for $\frac{\pi}{2} < \frac{k\pi}{N} < \frac{3\pi}{2}$

- To find N we use the filter specification $\omega_p, G_p, \delta_p, \omega_s, \delta_s$ working in dB Let $A = G_p - \delta_p$ $B = \delta_s$

Substituting and solving for N (derivation skipped)

$$N \geq \frac{\log_{10} \left[\frac{(10^{-B/10} - 1)}{(10^{-A/10} - 1)} \right]^{1/2}}{\log_{10} \left(\frac{\omega_s}{\omega_p} \right)}$$

where N is next largest integer.

— Example Suppose $G_p = 1 = 0 \text{ dB}$ $\delta_p = 3 \text{ dB}$ $\omega_p = 2\pi \cdot 5000$ 16④
 $G_s = -40 \text{ dB}$ $\omega_s = 2\pi \cdot 20000$

$$\left[\frac{(10^{.40/10} - 1)}{(10^{3/10} - 1)} \right]^{1/2} = 100.2327 \quad N \geq \frac{\log_{10}(100.2327)}{\log_{10}\left(\frac{20,000}{5000}\right)} = 3.323$$

Thus $N = 4$

— Butterworth filters are maximally flat, and are well approximated by piecewise linear $H(s)$.
 — See Matlab command `butter`.

— Another Example Type I Chebyshev Filters

$$|H(\omega)|^2 = \frac{1}{1 + \epsilon^2 C_N^2\left(\frac{\omega}{\omega_p}\right)} \quad \epsilon > 0$$

where $C_N(v)$ is the Chebyshev polynomial of order N

$$C_N(v) = \cos(N \cos^{-1}(v))$$

To find the coefficients we use a recursive procedure.

$$C_{N+1}(v) = 2v C_N(v) - C_{N-1}(v) \quad \text{derivation skipped.}$$

where the base case of the recursion is

$$C_0(v) = 1 \quad C_1(v) = v$$

Thus

$$C_2(v) = 2v C_1(v) - C_0(v) = 2v(v) - 1 = 2v^2 - 1$$

$$\begin{aligned} C_3(v) &= 2v C_2(v) - C_1(v) = 2v(2v^2 - 1) - v \\ &= 4v^3 - 2v - v \\ &= 4v^3 - 3v \end{aligned}$$

etc.

The design procedure is then Given ϵ, N, ω_p

165

1. Find $C_N(r)$

2. substitute $r = \frac{\omega}{\omega_p}$

3. Find poles of $H(s)$ equivalent to $|H(\omega)| = \frac{1}{1 + \epsilon^2 C_N^2(\frac{\omega}{\omega_p})}$

Step 3: Similar to Butterworth

$$|H(\omega)|^2 = H(s)H(-s) \Big|_{s=j\omega} = \frac{1}{1 + \epsilon^2 C_N^2\left(\frac{s}{j\omega_p}\right)}$$

the poles of $H(s)H(-s)$ are solution to $1 + \epsilon^2 C_N^2\left(\frac{p_k}{j\omega_p}\right) = 0$
for $k=0, 1, \dots, 2N-1$. Skipping the derivation

$$p_k = j\omega_p [\cos(\alpha_k) \cosh(\beta_k) - j \sin(\alpha_k) \sinh(\beta_k)]$$

$$\text{where } \alpha_k = \frac{(2k+1)\pi}{2N} \quad \beta_k = \frac{\sinh^{-1}\left(\frac{1}{\epsilon}\right)}{N}$$

$$k=0, 1, \dots, 2N-1$$

— It remains to find N, ϵ that meet a desired specification

Again skipping derivation Let $A = G_p - S_p$ $B = G_s$

$$\epsilon = [10^{-A/10} - 1]^{1/2}$$

$$N \geq \frac{\cosh^{-1}(F)}{\cosh^{-1}(\omega_0)}$$

where

$$F = \left[\frac{10^{-B/10} - 1}{10^{-A/10} - 1} \right]^{1/2}$$

$$\omega_0 = \frac{\omega_s}{\omega_p}$$

See Matlab commands cheblord and cheby1.

- Filter Transformations. Let $G(s)$ be the TF resulting from a lowpass Design. Define

16 ⑥

$$H(\lambda) = G(s) \Big|_{s=f(\lambda)} \quad \text{as the transformed TF}$$

$$s \in \mathbb{C}, \lambda \in \mathbb{C}$$

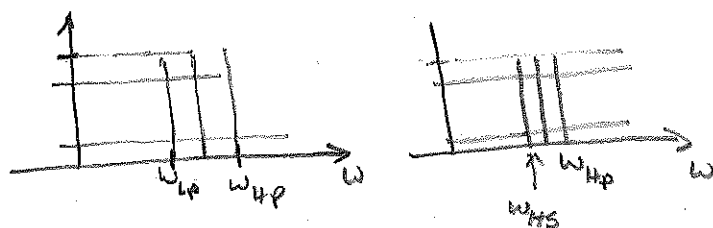
$$\therefore f: \mathbb{C} \rightarrow \mathbb{C}$$

• lowpass to highpass. Define ω_{LP} as lowpass passband edge

ω_{LS} as lowpass stopband edge

ω_{HP} as highpass passband edge

ω_{PP} as " " stopband edge



TODO! clear up notation.

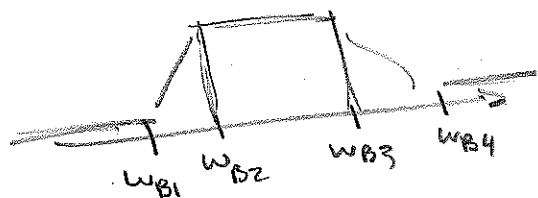
$$f(\lambda) = \frac{\omega_{LP} \omega_{HP}}{\lambda}$$

• lowpass to BANDPASS. Define ω_{B1} as stopband edge left

ω_{B2} as passband edge left

ω_{B3} as passband edge right

ω_{B4} as stopband edge right



$$f(\lambda) = \frac{\lambda^2 + \omega_0^2}{B \lambda}$$

$$\omega_0 = [\omega_{B2} \cdot \omega_{B3}]^{1/2}$$

$$B = \frac{\omega_{B3} - \omega_{B2}}{\omega_{LP}}$$