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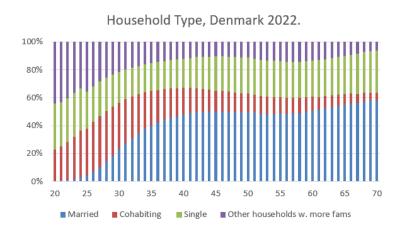
2023

Empirical Motivation

Introduction

•0

Many people live in couples



Introduction

• Unitary model until now The couple acted as one unit

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- There are ∞ many ways of modeling household decisions Some large and some small differences

• I will focus on some main types of models Give an idea of the main similarities and differences

Introduction

- Unitary model until now The couple acted as one unit
- There are ∞ many ways of modeling household decisions Some large and some small differences
- I will focus on some main types of models Give an idea of the main similarities and differences
- Remember: Models are abstractions, hopefully usefull...
- Notation on dynamic models differ from Chiappori and Mazzocco (2017) Based on lecture note

Dynamic Models

Outline

- Static Models
 - Setting
 - Unitary Model
 - Non-cooperative
 - Cooperative: Collective

- 2 Dynamic Models
 - Full Commitment
 - Limited Commitment

Production Technology

- **Superscript:** individual (1,2), **subscript:** element
- **Private** goods (h = 1, ..., n) produced as

$$q_h = q_h^1 + q_h^2 = f_h(x_h, d_h)$$
 (1)

where

 x_h : market goods inputs $d_h = (d_h^1, d_h^2)$: time inputs

Production Technology

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- **Private** goods (h = 1, ..., n) produced as

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where

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• **Public** goods (k = 1, ..., N) produced as

$$Q_k = F_k(X_k, D_k) (2)$$

where

 X_k : market goods inputs $D_k = (D_{\nu}^1, D_{\nu}^2)$: time inputs

Preferences: Utility and Felicity Function

Individual utility function

$$U^{i}(Q, q^{1}, q^{2}, I^{1}, I^{2})$$

Dynamic Models

where I^{i} is leisure time $T^i = h^i + l^i + \sum_{k=1}^N D^i_k + \sum_{h=1}^n d^i_h$ is available time hi is hours worked

Preferences: Utility and Felicity Function

Caring preferences:

Care not about the allocation of partner but only their welfare:

$$U^{i}(Q, q^{1}, q^{2}, l^{1}, l^{2}) = W^{i}(u^{1}(Q, q^{1}, l^{1}), u^{2}(Q, q^{2}, l^{2}))$$

Dynamic Models

where

 $u^{i}(Q, q^{i}, l^{i})$ is called the *felicity* function

Preferences: Utility and Felicity Function

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Dynamic Models

where

 $u^{i}(Q, q^{i}, l^{i})$ is called the *felicity* function

Egotistic preferences:

Care not about the partner:

$$U^{i}(Q, q^{1}, q^{2}, l^{1}, l^{2}) = F^{i}(u^{i}(Q, q^{i}, l^{i}), a)$$

where a can contain marital status etc.

Budget Constraint

Budget constraint

$$p'\left(\sum_{k=1}^{N} X_k + \sum_{h=1}^{n} x_h\right) = \sum_{i=1}^{2} (y^i + w^i h_i)$$
 (3)

where

p is vector of market prices yⁱ is non-market income. w^i is wage rate

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Dynamic Models

where

p is vector of market prices yⁱ is non-market income.

 w^i is wage rate

• Can be written as in Chiappori and Mazzocco (2017)

$$p'\left(\sum_{k=1}^{N}X_{k}+\sum_{h=1}^{n}x_{h}\right)+\sum_{i=1}^{2}w^{i}(I^{i}+\sum_{k=1}^{N}D_{k}^{i}+\sum_{h=1}^{n}d_{n}^{i})=\underbrace{\sum_{i=1}^{2}(y^{i}+w^{i}T^{i})}_{Y \text{ (pot. inc.)}}$$

(note that $T^{i} = h^{i} + l^{i} + \sum_{k=1}^{N} D_{k}^{i} + \sum_{h=1}^{n} d_{n}^{i}$, they miss l^{i} on p. 989)

• **Income pooling:** non-labor income, y^i , enters identically for both

Unitary Model

 Unitary model, households solve (conditional on potential income, $Y = \sum_{i=1}^{2} (v^{i} + w^{i} T^{i})$)

$$\max_{X,x,l^{1},l^{2},d^{1},d^{2},D^{1},D^{2}} U^{H}(Q,q,l^{1},l^{2})$$
s.t.
$$Q_{k} = F_{k}(X_{k},D_{k}), k = 1,...,N$$

$$q_{h} = q_{h}^{1} + q_{h}^{2} = f_{h}(x_{h},d_{h}), h = 1,...,n$$

$$Y = p' \left(\sum_{k=1}^{N} X_k + \sum_{h=1}^{n} x_h \right) + \sum_{i=1}^{2} w^i (I^i + \sum_{k=1}^{N} D_k^i + \sum_{h=1}^{n} d_n^i)$$

where $U^H(Q, q, l^1, l^2)$ is some household-level utility function

Unitary Model

• Unitary model, households solve (conditional on *potential* income, $Y = \sum_{i=1}^{2} (y^i + w^i T^i)$)

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where
$$U^H(Q, q, l^1, l^2)$$
 is *some* household-level utility function

Rationalized via

Samuelson's welfare index Becker's rotten kid (we skip) Transferable Utility (TU)

Unitary Motivation: Samuelson's welfare index

Samuelson's welfare index

$$U^H(Q, q, l^1, l^2) = \max_{q_1, q_2} W(u^1(Q, q^1, l^1), u^2(Q, q^2, l^2))$$
 s.t.
$$q = q_1 + q_2$$

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Dynamic Models

Example could be

$$W(u^{1}(Q, q^{1}, l^{1}), u^{2}(Q, q^{2}, l^{2})) = \frac{\lambda}{2}u^{1}(Q, q^{1}, l^{1}) + (1 - \frac{\lambda}{2})u^{2}(Q, q^{2}, l^{2})$$

where

 λ is a constant weight on each member's utility; "power"

Unitary Motivation: Samuelson's welfare index

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where

 λ is a constant weight on each member's utility; "power"

• Arbitrary that households should have some W()... but this example is a special form of the "collective model" below [nice]

Unitary Motivation: Transferable Utility

 TU: If there exists a Pareto frontier. such that a cardinal transformation, k() gives

$$k(u^{1}(Q, q^{1}, l^{1})) + k(u^{2}(Q, q^{2}, l^{2})) = K(p, w, Y)$$

Dynamic Models

 \rightarrow utility possibility frontier has a slope of -1,

$$k(u^{1}(Q, q^{1}, l^{1})) = K(p, w, Y) - k(u^{2}(Q, q^{2}, l^{2}))$$

• Then we can describe the optimization problem using $U^H(Q, q, I^1, I^2)$

Unitary Motivation: Transferable Utility

• TU: If there exists a Pareto frontier, such that a *cardinal transformation*, k() gives

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- Then we can describe the optimization problem using $U^H(Q, q, l^1, l^2)$
- **Example:** Conditional on Y,

$$U^{m\star}(\overline{u}^f) = \max_{c^m} U^m(c^m) = \sqrt{c^m}$$
s.t.
$$Y = c^m + c^f$$

$$\overline{u}^f = U^f(c^f) = \sqrt{c^f}$$

gives $U^{m\star}(\overline{u}^f)^2 = \text{constant}(Y) - (\overline{u}^f)^2$.

Unitary Model: Not Consistent with Data

- Two testable implications
 - 1. Income pooling (source of non-labor income does not matter for behavior)

Dynamic Models

2. Slutsky symmetry (commodity prices affect members' demand similarly)

Unitary Model: Not Consistent with Data

- Two testable implications
 - 1. Income pooling (source of non-labor income does not matter for behavior)

Dynamic Models

- 2. Slutsky symmetry (commodity prices affect members' demand similarly)
- Almost always rejected see Chiappori and Mazzocco (2017, p. 1022)
- Alternatives have been proposed Non-cooperative Cooperative (collective)

Non-Cooperative

Non-cooperative models:

A game with two players Nash equilibrium

$$\max_{Q^1,q^1,I^1} u^1(Q^1+Q^2,q^1,q^2,I^1,I^2)$$
 s. t. $PQ^1+p'q^1=Y^1$

and

• **Generally not efficient:** Partner's gains not internalized.

Cooperative: Collective

• Collective model: Pareto efficient allocations (def)

Cooperative: Collective

Collective model: Pareto efficient allocations (def)
 Typically formulated as

$$\begin{aligned} \max_{X,x,l^1,l^2,d^1,d^2,D^1,D^2} & \lambda(z) u^1(Q,q^1,l^1) + (1-\lambda(z)) u^2(Q,q^2,l^2) \\ \text{s.t.} & Q_k = F_k(X_k,D_k), \ k=1,\dots,N \\ & q_h = q_h^1 + q_h^2 = f_h(x_h,d_h), \ h=1,\dots,n \\ & Y = p'\left(\sum_{k=1}^N X_k + \sum_{h=1}^n x_h\right) + \sum_{i=1}^2 w^i(l^i + \sum_{k=1}^N D_k^i + \sum_{h=1}^n d_n^i) \end{aligned}$$

Distribution factors: z

Anything that affect power, such as p, w, y.

Cannot be endogenous: Over-investment in power \rightarrow inefficient.

Cooperative: Collective

 Collective model: Pareto efficient allocations (def) Typically formulated as

$$\max_{X,x,l^1,l^2,d^1,d^2,D^1,D^2} \lambda(z) u^1(Q,q^1,l^1) + (1-\lambda(z)) u^2(Q,q^2,l^2)$$
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$$Y = p'\left(\sum_{k=1}^N X_k + \sum_{h=1}^n x_h\right) + \sum_{i=1}^2 w^i(l^i + \sum_{k=1}^N D_k^i + \sum_{h=1}^n d_n^i)$$

- Distribution factors: z
 - Anything that affect power, such as p, w, y.
- Cannot be endogenous: Over-investment in power \rightarrow inefficient.
- **Unitary model** is nested, $\lambda(z) = \text{constant} \rightarrow \text{unitary model}$

Outline

- - Setting
 - Unitary Model
 - Non-cooperative

- Dynamic Models
 - Full Commitment.
 - Limited Commitment

- All comes down to how the bargaining weight is updated.
- My slides combine Chiappori and Mazzocco (2017)
 with Theloudis, Velilla, Chiappori, Giménez-Nadal and Molina (2022)
 and own lecture note

Dynamic Models

General Setup: Choices

- Period t = 0: Individuals A and B become a couple
- Periods t > 0: As a couple, they decide on
 - private consumption, c_t^A and c_t^B (and thus savings, a_t)
 - labor supply, I_t^A , $I_t^B \in \{0, 0.75, 1\}$
 - whether to split up (no re-partnering for simplicity)
- Period T: both die with certainty

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- Inter-temporal budget constraint of couple

$$a_t + c_t^A + c_t^B = Ra_{t-1} + w^A I_t^A + w^B I_t^B$$

Dynamic Models

with $a_t > 0 \ \forall t$. Will leave this out in couples problem.

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with $a_t \geq 0 \ \forall t$. Will leave this out in couples problem.

• Example throughout, but apply more generally.

General Setup: Utility

• Individual utility is for $j \in \{A, B\}$

$$u^{j}(c_{t}^{j}, l_{t}^{j})$$

Dynamic Models

Household utility is weighted sum

$$U(c_t^A, c_t^B, I_t^A, I_t^B; \psi_t, \mu_t) = \mu_t u^A(c_t^A, I_t^A) + (1 - \mu_t) u^B(c_t^B, I_t^B) + \psi_t$$

where match quality/"love" is

$$\psi_t = \psi_{t-1} + \varepsilon_t$$
, $\varepsilon \sim iid\mathcal{N}(0, \sigma_{\varepsilon}^2)$

and μ_t is the **bargaining power** of agent A

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$$\psi_t = \psi_{t-1} + \varepsilon_t$$
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and μ_t is the **bargaining power** of agent A

• How μ_t is determined defines the different types of models:

Unitary: $\mu_t = \mu$ is a **constant number**

Full commitment: $\mu_t = \mu_0(Z)$ is a **function** (of states known i t = 0)

No commitment: μ_t is updated in each period

Limited commitment: $\mu_t = \mu_t(\bullet, \mu_{t-1})$ is a function of past power

General Setup: Recursive Formulation

• Outside option: Value of being single

$$\begin{aligned} V_{j,t}^{s}(a_{t-1}) &= \max_{c_{t}^{j}, l_{t}^{j}} u^{j}(c_{t}^{j}, l_{t}^{j}) + \beta V_{j,t+1}^{s}(a_{t}) \\ &\text{s.t.} \\ a_{t} &= Ra_{t-1} + w^{j}l_{t}^{j} - c_{t}^{j} \end{aligned}$$

Dynamic Models

where I do not allow for re-partnering $(V_{j,t}^{m o s} = V_{j,t}^s)$.

• Non-cooperation could be outside option

General Setup: Recursive Formulation

Outside option: Value of being single

$$\begin{split} \textit{\textit{V}}^{\textit{s}}_{\textit{j},t}(\textit{a}_{t-1}) &= \max_{\textit{c}_{t}^{j},\textit{l}_{t}^{j}} \textit{\textit{u}}^{\textit{j}}(\textit{c}_{t}^{j},\textit{l}_{t}^{j}) + \beta \textit{\textit{V}}^{\textit{s}}_{\textit{j},t+1}(\textit{a}_{t}) \\ &\text{s.t.} \\ \textit{a}_{t} &= \textit{\textit{R}} \textit{\textit{a}}_{t-1} + \textit{\textit{w}}^{\textit{j}}\textit{\textit{l}}_{t}^{\textit{j}} - \textit{\textit{c}}_{t}^{\textit{j}} \end{split}$$

Dynamic Models

where I do not allow for re-partnering $(V_{i,t}^{m\to s}=V_{i,t}^s)$.

- Non-cooperation could be outside option
- Partnership dissolution: Share κ_1 of wealth is transferred to agent A and $\kappa_2 = 1 - \kappa_1$ to agent B. $a_t^A = \kappa_1 a_t$ and $a_t^B = \kappa_2 a_t$

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where I do not allow for re-partnering $(V_{i,t}^{m \to s} = V_{i,t}^s)$.

- Non-cooperation could be outside option
- Partnership dissolution: Share κ_1 of wealth is transferred to agent A and $\kappa_2 = 1 - \kappa_1$ to agent B. $a_t^A = \kappa_1 a_t$ and $a_t^B = \kappa_2 a_t$
- Value of being in a couple depends on what we assume about the bargaining process.

Unitary Model

• Constant bargaining power, $\mu_t = \mu$.

Unitary Model

- Constant bargaining power, $\mu_t = \mu$.
- Value of a couple is

$$W_t(\mathbf{a}_{t-1}, \psi_t) = \max_{c_t^A, c_t^B, l_t^A, l_t^B} U(c_t^A, c_t^B, l_t^A, l_t^B, \psi_t; \mathbf{\mu}) + \beta \tilde{W}_{t+1}(\mathbf{a}_t, \psi_t)$$

Dynamic Models

the expected (w.r.t. ψ_{t+1}) continuation value is

$$\begin{split} \tilde{W}_{t+1}(a_t, \psi_t) &= \mathbb{E}_t[\max\{W_{t+1}(a_t, \psi_{t+1}) \; ; \; \underbrace{\mu V_{A,t+1}^s(a_t^A) + (1-\mu) V_{B,t+1}^s(a_t^B)}_{\text{weighted value of singlehood}}\}] \end{split}$$

Commitment Models

• Endogenously determined μ_t

FC: Full commitment, μ_t is a **constant function** We will see in Bruze, Svarer and Weiss (2015)

NC: No commitment, μ_t updated every period

We will just discuss today

LC: Limited commitment, μ_t updated **sometimes** \rightarrow function of past power We will see in several papers + code

Dynamic Models

- Bargaining power function is determined and agreed upon at beginning of partnership
- Bargaining power is thus a constant function

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Dynamic Models

- Z_t : **Known at beginning** of partnership, at t = 0!
 - Assume that couples can commit to this bargaining power function
 - Will e.g. not request more bargaining power from (changes in) something not in Z_t
 - If time-varying elements in Z_t : Assuming perfect foresight

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 - If time-varying elements in Z_t : Assuming perfect foresight
- How is this function determined?
 We will come back to this in a few slides

Value of being a couple is then

$$W_t(a_{t-1}, \psi_t) = \max_{c_t^A, c_t^B, I_t^A, I_t^B} U(c_t^A, c_t^B, I_t^A, I_t^B; \psi_t, \mu_0(Z_t)) + \beta \tilde{W}_{t+1}(a_t, \psi_t)$$

Dynamic Models

where expected continuation value is

$$\begin{split} \ddot{W}_{t+1}(a_t, \psi_t) &= \mathbb{E}_t \big[\max \big\{ W_{t+1}(a_t, \psi_{t+1}) \\ & ; \underbrace{\mu_0(Z_{t+1}) \, V_{A,t+1}^s(a_t^A) + (1 - \mu_0(Z_{t+1})) \, V_{B,t+1}^s(a_t^B)}_{\text{weighted value of singlehood}} \big\} \big] \end{split}$$

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• Transferable utility: Household jointly decide to divorce if

$$W_t(a_t) < \mu_0(Z_t) V_{A,t}^s(a_t^A) + (1 - \mu_0(Z_t)) V_{B,t}^s(a_t^B)$$

No constraints on individual members' utilities

Full Commitment: Determining Bargaining Power

Dynamic Models

• How could $\mu_0(Z_t)$ be determined?

Full Commitment: Determining Bargaining Power

- How could $\mu_0(Z_t)$ be determined?
- Idea 1: Nash-bargaining at the point of partnership formation

$$\begin{split} \mu_0(Z) &= \arg\max_{\mu \in [0,1]} \left(\mu \textit{W}_0(\textit{a}_{-1}) - \textit{V}^{\textit{s}}_{\textit{A},0}(\lambda \textit{a}_{-1}) \right)^{0.5} \\ & \times \left((1-\mu) \textit{W}_0(\textit{a}_{-1}) - \textit{V}^{\textit{s}}_{\textit{B},0}((1-\lambda) \textit{a}_{-1}) \right)^{0.5} \end{split}$$

Dynamic Models

• μ_0 "non-parametric" constant function of e.g. $Z = (a_{-1}, w_0^A, w_0^B)$

Full Commitment: Determining Bargaining Power

- How could $\mu_0(Z_t)$ be determined?
- Idea 1: Nash-bargaining at the point of partnership formation

$$\begin{split} \mu_0(Z) &= \arg\max_{\mu \in [0,1]} \left(\mu \, W_0(a_{-1}) - \frac{\textit{V}_{A,0}^{\textit{s}}(\lambda a_{-1})}{A_{-1}} \right)^{0.5} \\ & \times \left((1-\mu) \, W_0(a_{-1}) - \frac{\textit{V}_{B,0}^{\textit{s}}((1-\lambda) a_{-1})}{A_{-1}} \right)^{0.5} \end{split}$$

Dynamic Models

- μ_0 "non-parametric" constant function of e.g. $Z=(a_{-1},w_0^A,w_0^B)$
- Idea 2: Assume a functional form (Bruze, Svarer and Weiss, 2015)

$$\mu_0(w_t^A/w_t^B) = \frac{\exp(\alpha_0 + \alpha_1 w_t^A/w_t^B)}{1 + \exp(\alpha_0 + \alpha_1 w_t^A/w_t^B)}$$

and estimate parameters α_0 and α_1 using data. [perfect foresight assumption on wages]

• If $\alpha_1 = 0$: Similar to the unitary model.

No- and Limited Commitment

- My definition of "No commitment" is different from that of Mazzocco (2007)
 - I will call his setup "Limited commitment" (as is standard now)
- They are closely related: Both do not assume transferable utility
 - Only differ in how the bargaining power is updated dynamically

No- and Limited Commitment

- My definition of "No commitment" is different from that of Mazzocco (2007)
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- They are closely related: Both do not assume transferable utility
 - Only differ in how the bargaining power is updated dynamically
- We thus need to check individual "participation" constraints:
 Is it optimal for each agent to be part of the couple without receiving any utility from the other partner
- We need to define a new objects for this purpose: The value of agent j from being in the couple if μ_{t-1} is the bargaining power coming into period t

Notation: Partnership Status and Transitions

- All values are individual
- Four transition possibilities

from\to	married	single
married	$V_{j,t}^{m\to m}(\mathcal{S}_t,\mu_{t-1})$	$V_{j,t}^{m\to s}(\mathcal{S}_t,\mu_{t-1})$
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Dynamic Models

Notation: Partnership Status and Transitions

- All values are individual
- Four transition possibilities

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Value of starting in a state

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• When singlehood is absorbing (and no div. costs): $V_{i,t}^s = V_{i,t}^{m \to s}$.

Recursive Formulation

• Individual value of choice c_t^I , l_t^I while remaining in couple is

$$v_{j,t}^{m\to m}(c_t^j, l_t^j; a_{t-1}, \psi_t, \mu) = u^j(c_t^j, l_t^j) + \psi_t + \beta \mathbb{E}_t[V_{j,t}^m(a_t^j, \psi_{t+1}, \mu)]$$

Dynamic Models

where μ is some bargaining power, we will discuss in great detail.

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- 1. Conditional on remaining together, optimal choices are

$$\begin{split} \tilde{c}_{t}^{A}(\mu), \tilde{c}_{t}^{B}(\mu), \tilde{I}_{t}^{A}(\mu), \tilde{I}_{t}^{B}(\mu) &= \arg\max_{c_{t}^{A}, c_{t}^{B}, I_{t}^{A}, I_{t}^{B}} \mu v_{A, t}^{m \to m}(c_{t}^{A}, I_{t}^{A}; a_{t-1}, \psi_{t}, \mu) \\ &+ (1 - \mu) v_{B, t}^{m \to m}(c_{t}^{B}, I_{t}^{B}; a_{t-1}, \psi_{t}, \mu) \end{split}$$

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2. **Marital surplus** for agent *j* is

$$S_t^j(\mu) = \underbrace{\mathbf{v}_{j,t}^{m \to m}(\tilde{c}_t^j(\mu), \tilde{\mathbf{l}}_t^j(\mu); \mathbf{a}_{t-1}, \psi_t, \mu)}_{V_{j,t}^{m \to m}(\mathbf{a}_{t-1}, \psi_t, \mu)} - \underbrace{\mathbf{v}_{j,t}^{m \to s}(\mathbf{a}_{t-1}^j)}_{}$$

Limited Commitment: Bargaining Process

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- 3.2 If $S_t^A(\mu_{t-1}) < 0$ and $S_t^B(\mu_{t-1}) < 0$ then they divorce, $D_t^* = 1$.
- 3.3 If e.g. $S_t^A(\mu_{t-1}) < 0$ (member A not happy with current division) They re-bargain to find a new potential distribution both can accept (point 4 on next slide)

4. Let $\tilde{\mu}^A: S_t^A(\tilde{\mu}^A) = 0$ be the allocation that makes A (barely) want to remain together.

Dynamic Models

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Dynamic Models

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Dynamic Models

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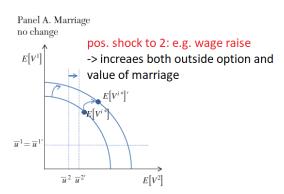
- If $S_t^B(\tilde{\mu}^A) < 0$, they divorce $(D_t^* = 1)$
- Combined the co-state evolves as

$$\mu_t = \mu_t^{\star}(\mathcal{S}_t, \mu_{t-1}) = \begin{cases} \mu_{t-1} & \text{if } S_t^A(\mathcal{S}_t, \mu_{t-1}) \geq 0 \text{ and } S_t^B(\mathcal{S}_t, \mu_{t-1}) \geq 0 \\ \tilde{\mu}^A & \text{if } S_t^A(\mathcal{S}_t, \mu_{t-1}) < 0 \text{ and } S_t^B(\mathcal{S}_t, \tilde{\mu}^A) \geq 0 \\ \tilde{\mu}^B & \text{if } S_t^A(\mathcal{S}_t, \tilde{\mu}^B) \geq 0 \text{ and } S_t^B(\mathcal{S}_t, \mu_{t-1}) < 0 \\ \emptyset & \text{else} \end{cases}$$

$$(4)$$

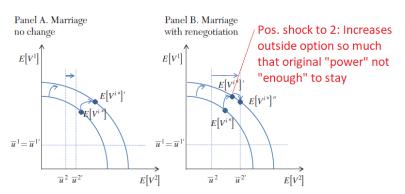
Dynamic Models

Shock to agent 2's outside option: small.



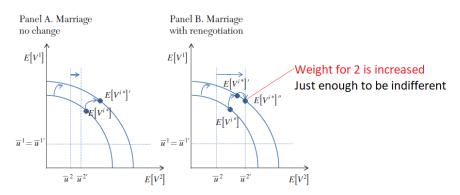
Dynamic Models

• Shock to agent 2's outside option: **medium**.



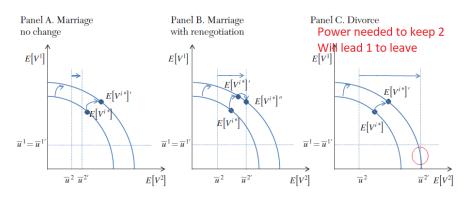
Limited Commitment: Updating Bargaining Weight

Shock to agent 2's outside option: medium.

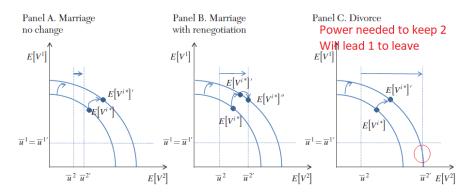


Limited Commitment: Updating Bargaining Weight

• Shock to agent 2's outside option: large.



• Shock to agent 2's outside option: large.



• See also figures 2 and 3 in lecture note.

No Commitment

• Limited commitment: Bargaining power updated if individual participation constraints violated at current bargaining position, μ_{t-1} ,

$$\mu_t = \mu_t^*(a_{t-1}, \psi_t, \mu_{t-1})$$

Dynamic Models

No Commitment

• **Limited commitment:** Bargaining power updated if individual participation constraints violated at current bargaining position, μ_{t-1} ,

$$\mu_t = \mu_t^{\star}(a_{t-1}, \psi_t, \mu_{t-1})$$

• **No commitment:** Bargaining power updated in *all periods*,

$$\mu_t = \mu_t^{\star}(a_{t-1}, \psi_t)$$

replace step 3 with e.g. [instead of the discussion before]

$$\mu_t = \arg\max_{\tilde{\mu}} S_t^A(\tilde{\mu})^{0.5} S_t^B(\tilde{\mu})^{0.5}$$

 We focus on limited commitment in the code What about initial bargaining power, μ_0 , then? Could be found through Nash bargaining:)

Next time:

Divorce Laws, Savings and Labor Supply.

Literature:

Voena (2015): "Yours, Mine, and Ours: Do Divorce Laws Affect the Intertemporal Behavior of Married Couples?"

Dynamic Models

- Read before lecture
- Reading guide:
 - Section 0: Introduction. Key
 - Section 1: US divorce law. Kev.
 - Section 2: Model. Key, but complex. Get the idea.
 - Under unilateral divorce: limited commitment model.
 - Section 3: Data and RF motivation. Get the overall results/motivation.
 - Section 4: Structural Estimation: Read fast.
 - Section 5: Counterfactual simulations. Key.

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