EE 127AT/227AT 9/19/2018

Instructors: L. El Ghaoui, A. Bayen

GSI: P. Hidalgo-Gonzalez

## Discussion #4 Solutions

Exercise 1 (Minimizing a quadratic function) Consider the unconstrained optimization problem

 $p^* = \min_{x} \ \frac{1}{2} x^{\mathsf{T}} Q x - c^{\mathsf{T}} x$ 

where  $Q = Q^{\top} \in \mathbb{R}^{n,n}$ ,  $Q \succeq 0$ , and  $c \in \mathbb{R}^n$  are given. The goal of this exercise is to determine the optimal value  $p^*$  and the set of optimal solutions,  $\mathcal{X}^{\text{opt}}$ , in terms of c and the eigenvalues and eigenvectors of the (symmetric) matrix Q.

- 1. Assume that  $Q \succ 0$ . Show that the optimal set is a singleton, and that  $p^*$  is finite. Determine both in terms of Q, c.
- 2. Assume from now on that Q is not invertible. Assume further that Q is diagonal:  $Q = \operatorname{diag}(\lambda_1, \ldots, \lambda_n)$ , with  $\lambda_1 \geq \ldots \geq \lambda_r > \lambda_{r+1} = \ldots = \lambda_n = 0$ , where r is the rank of Q  $(1 \leq r < n)$ . Solve the problem in that case.
- 3. Now we do not assume that Q is diagonal anymore. Under what conditions (on Q, c) is the optimal value finite? Make sure to express your result in terms of Q and c, as explicitly as possible.

## Solution 1

1. When  $Q \succ 0$ , it admits a Cholesky decomposition  $Q = R^{\top}R$ , with R upper-triangular and invertible. We can define the new variable  $\bar{x} = Rx$ , which leads to the problem

$$\min_{\bar{x}} \ \frac{1}{2} \bar{x}^{\top} \bar{x} - \bar{c}^{\top} \bar{x},$$

where  $\bar{c} = (R^{-1})^{\top} c$ . We can express the objective in the above problem as

$$\frac{1}{2}\|\bar{x} - \bar{c}\|_2^2 - \|\bar{c}\|_2^2,$$

from which it is clear that the unique minimizer is  $\bar{x} = \bar{c}$ . In terms of the x-variable, the unique solution is  $x = R^{-1}\bar{c} = Q^{-1}c$ .

The same result can be obtained by invoking the fact that the minimizers of a convex differentiable function f without any constraints, are characterized by the optimality condition  $\nabla f(x) = 0$ . In our case, we have  $\nabla f(x) = Qx - c$ .

2. The objective function writes

$$f(x) = \sum_{i=1}^{r} \left( \frac{1}{2} \lambda_i x_i^2 - c_i x_i \right) + \sum_{i=r+1}^{n} c_i x_i.$$

If any element  $c_i$ , i = r + 1, ..., n, is non-zero, the optimal value is  $-\infty$ . Otherwise, that is, when c is in the range of Q, the optimal value is obtained with  $x_i = c_i/\lambda_i$ , i = 1, ..., r, and the other variables  $x_{r+1}, ..., x_n$  free. That value is

$$p^* = -\frac{1}{2} \sum_{i=1}^r \frac{c_i^2}{\lambda_i}.$$

3. We use the eigenvalue decomposition of Q:  $Q = U\Lambda U^{\top}$ , with  $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$ . The problem is more conveniently formulated in terms of the new variable  $\bar{x} = U^{\top}x$ :

$$p^* = \min_{\bar{x}} \ \frac{1}{2} \bar{x}^\top \Lambda \bar{x} - \bar{c}^\top \bar{x},$$

with  $\bar{c} \doteq Uc$ .

Assuming as before  $\lambda_1 \geq \ldots \geq \lambda_r > \lambda_{r+1} = \ldots = \lambda_n = 0$ , where r is the rank of Q  $(1 \leq r < n)$ , we are lead to the similar conclusions. In particular, the optimal value is finite if and only if the last n-r components of  $\bar{c}$  are zero. This means that c must be in the range of Q, in order for the value to be finite.

Exercise 2 (Schur complement. Bonus problem, only solved in discussion.) Let  $A \in \mathbb{R}^{p \times p}$ ,  $C = C^{\top} \in \mathbb{R}^{q \times q}$ , C invertible,  $B \in \mathbb{R}^{p \times q}$  and p + q = n. Let

$$M = \left[ \begin{array}{cc} A & B \\ B^\top & C \end{array} \right]$$

1. Prove

$$M = \left[ \begin{array}{cc} A & B \\ B^\top & C \end{array} \right] = \left[ \begin{array}{cc} I & BC^{-1} \\ 0 & I \end{array} \right] \left[ \begin{array}{cc} A - BC^{-1}B^\top & 0 \\ 0 & C \end{array} \right] \left[ \begin{array}{cc} I & BC^{-1} \\ 0 & I \end{array} \right]^\top$$

2. Prove that  $C \succ 0$  and  $A - BC^{-1}B^{\top} \succ 0 \rightarrow M \succ 0$ 

Some extra solved problems:

Exercise 3 (Orthogonal Matrix) Consider the matrix

$$A = \left[ \begin{array}{rrr} -1 & 4 & -6 \\ 2 & -2 & -6 \\ 2 & 4 & 3 \end{array} \right].$$

- 1. Show that the columns of  $A = [a_1, a_2, a_3]$  are mutually orthogonal, that is,  $a_i^T a_j = 0$  when  $i \neq j$ .
- 2. Show that we can write A = BD, with B a matrix with mutually orthogonal columns, each having unit Euclidean norm; and D a diagonal matrix with positive diagonal elements. *Hint*: for every i = 1, 2, 3, express  $a_i$  as  $d_ib_i$ , with scalar  $d_i > 0$  and  $b_i$  a unit-norm vector.
- 3. Find a singular value decomposition of A. Is it unique?

## Solution 2

- 1. The columns are easily shown to be mutually orthogonal.
- 2. We have  $a_i = d_i b_i$ , where  $d_i = ||a_i||_2$ ,  $b_i = a_i/||a_i||_2$ , i = 1, 2, 3. Thus A = BD, with  $D = \text{diag}(d_1, d_2, d_3)$ , and  $B = [b_1, b_2, b_3]$ .
- 3. We note that B is a square matrix with orthonormal columns, hence  $B^TB=I$ . In addition D is diagonal and positive-definite. Hence an SVD of A is  $A=U\Sigma V^T$ , with  $U=B,\,\Sigma=D,$  and V=I. As usual, there is no unicity: we can also choose  $V=-I,\,U=-B$ .

**Exercise 4** A matrix  $A \in \mathbb{R}^{m,n}$  with rank r has singular values  $\sigma_1 > \sigma_2 > \ldots > \sigma_r > 0$ . Prove that the spectral norm satisfies  $||A||_2^2 = \sigma_1^2$ 

**Solution 3** Note that  $||Ax||_2^2 = x^{\top}A^{\top}Ax$ . Since  $A^{\top}A$  is a positive semidefinite matrix, then it can be decomposed in a basis of orthonormal eigenvectors  $\{v_i\}_{i=1}^n$  with associated eigenvalue  $\lambda_i$ . This entails that every vector x can be decomposed as:

$$x = \sum_{i=1}^{n} \alpha_i v_i$$

Then:

$$\begin{aligned} ||Ax||_2^2 &= x^\top A^\top A x \\ &= \langle x, A^\top A x \rangle \\ &= \left\langle \sum_{i=1}^n \alpha_i v_i, A^\top A \sum_{i=1}^n \alpha_i v_i \right\rangle \\ &= \left\langle \sum_{i=1}^n \alpha_i v_i, \sum_{k=1}^n \alpha_k \lambda_k v_k \right\rangle \\ &= \sum_{k=1}^n \alpha_k \alpha_k \lambda_k \langle v_k, v_k \rangle \\ &= \sum_{k=1}^n \lambda_k |\alpha_k|^2 \end{aligned}$$

Note that the fourth line occurs due to the orthogonality of the basis. Then:

$$||Ax||_2^2 = \sum_{k=1}^n \lambda_k |\alpha_k|^2$$

$$\leq \lambda_{max} \sum_{k=1}^n |\alpha_k|^2$$

$$\leq \lambda_{max} ||x||_2^2$$

This implies that:

$$||A||_2 = \sup_{x \neq 0} \frac{||Ax||_2}{||x||_2} \le \sqrt{\lambda_{max}}$$

By picking  $x=v_{max}$ , the eigenvector that has the maximum eigenvalue associated, we got that:

$$\frac{||Av_{max}||_2}{||v_{max}||_2} = \sqrt{\lambda_{max}} \frac{||v_{max}||_2}{||v_{max}||_2} = \sqrt{\lambda_{max}}$$

Then since the induced norm is the supremum of that quotient, it is clear that  $||A||_{i,2} \ge \sqrt{\lambda_{max}}$ . So from both inequalities it is straightforward that the supremum is attained at the eigenvector with the maximum eigenvalue, and hence:

$$||A||_2 = \sqrt{\lambda_{max}(A^{\top}A)} = \sigma_1(A)$$

the largest singular value of A. Squaring the equality, the result holds.

Exercise 5 (Properties of dyad.) Let  $x, y \in \mathbb{R}^n$ , both not identical to the zero vector, and  $A = xy^{\top} \in \mathbb{R}^{n,n}$ .

- 1. Determine an eigenvalue and an eigenvector of A.
- 2. We know that A has rank one. Write a proof of this fact.
- 3. What is the dimension of  $\mathcal{N}(A)$ ?
- 4. Compute a singular value decomposition of A and write it in compact form.

## Solution 4

- 1. Eigenvalue  $\lambda = y^{\top}x$  and eigenvector u = x work because,  $Au = xy^{\top}x = u\lambda$ .
- 2.  $\mathcal{R}(A) = \{z \in \mathbb{R}^n : z = Av, v \in \mathbb{R}^n\}$ . Since  $Av = xy^{\top}v = \gamma x$  for  $\gamma = y^{\top}v$ , the range of A is simply a line. Thus, there is only one linearly independent column in A.
- 3. The dimension of  $\mathcal{N}(A) = n \operatorname{rank} A = n 1$  by the fundamental theorem of linear algebra.
- 4. Take  $\sigma = \|x\|_2 \|y\|_2$ ,  $u = x/\|x\|_2$ , and  $v = y/\|y\|_2$ . Clearly,  $A = \sigma u v^{\top}$ . Moreover,  $u^{\top}u = 1$ ,  $v^{\top}v = 1$ ,  $Av = xy^{\top}y/\|y\|_2 = \sigma u$ , and  $u^{\top}A = x^{\top}xy^{\top}/\|x\|_2 = \sigma v$ . Thus,  $\sigma, u, v$  is a SVD of A.