

Autonomous Differential Equations

Section 2.7 (Noonburg)

Definition: A differential equation of the form

$$\frac{dx}{dt} = f(x)$$

is called **autonomous**.

- An autonomous first-order equation is always separable. We can always solve them, at least implicitly. Depending on our goals, getting qualitative information about solutions may be enough.
- A constant function $x(t) \equiv r$ such that $f(r) = 0$, is called **an equilibrium solution** of the autonomous differential equation.

Example #1: Find the equilibrium solution(s) for $\frac{dx}{dt} = x + 1$.

$$f(x) = x + 1 = 0$$

$$x = -1$$

- In autonomous equations, the slopes depend only on x . Thus the slope field completely determines once slopes along any vertical line are plotted. This line is called the **phase line**.

Example #2: Consider the autonomous DE $\frac{dx}{dt} = x(x-1)^2(x-2)$.

(a) Draw a phase line.

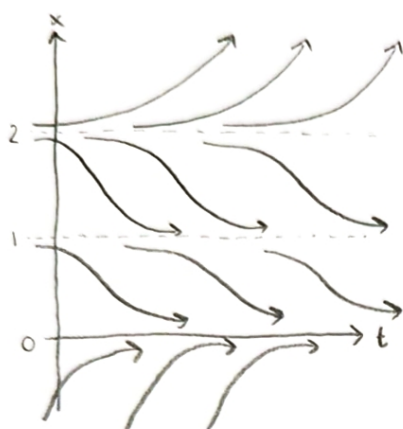
$$f(x) = x(x-1)^2(x-2) = 0$$

$$x = 0, 1, 2$$

| | | | | | | | |
|-----------------|---|---|---|---|---|---|---|
| $\frac{dx}{dt}$ | + | - | - | + | | | |
| | | | | | | | |
| x | - | 0 | + | 1 | + | 2 | + |
| $(x-1)^2$ | + | + | + | + | + | + | + |
| $(x-2)$ | - | - | - | - | - | + | + |



(b) Sketch possible solution curves.



(c) Depending on the result in part (b), determine the behaviour of the solutions as $t \rightarrow \infty$.

This depends on where we start

$$x(t_0) = x_0$$

$$\text{If } x_0 > 2, x(t) \rightarrow \infty$$

$$x_0 = 2, x(t) = 2$$

$$1 \leq x_0 < 2, x(t) \rightarrow 1$$

$$x_0 < 1, x(t) \rightarrow 0$$

NOTE: Solutions near $x = 0$ behaves very differently than the solutions near $x = 1$ or $x = 2$.

- We call $x = 2$ **an unstable equilibrium** or **a source**. If a solution starts even a tiny bit away from $x = 2$, the solution will “run away” from the equilibrium $x = 2$.



- $x = 0$ is **an asymptotically stable equilibrium** or **a sink**. If a solution starts “close” to $x = 0$, it stays “close” to $x = 0$ AND the solution will approach $x = 0$ as $t \rightarrow \infty$.



- $x = 1$ is neither a source nor a sink. Solutions approach $x = 1$ from one side and escape on the other. We call this **a semi-stable equilibrium** or **a node**.



Example #3: Consider the autonomous differential equation, $\frac{dx}{dt} = e^x(x+2)(x-3)$.

Draw a phase line for the DE and label each equilibrium point as a sink, source or node.

$$f(x) = e^x(x+2)(x-3) = 0$$

$$x = -2, 3$$

| | | | |
|-----------------|---|---|---|
| $\frac{dx}{dt}$ | + | - | + |
| e^x | + | - | + |
| $x+2$ | - | + | + |
| $x-3$ | - | - | + |

3 • source, unstable
-2 • sink, stable

If $x(1) = 0$, what happens to $x(t)$ as $t \rightarrow \infty$? $x \rightarrow -2$

If $x(1) = 4$, will there be a point such that $x(t) = 0$? No, $x \rightarrow \infty$