



The Design and Evaluation of a Four Degree-Of-Freedom Cooperative Handheld Robotic Device in a Simplified 3D Construction Environment

By Chris Meehan

Supervised by

Dr. Walterio Mayol-Cuevas

Department of Computer Science

University of Bristol

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- [1] S.J. Anderson, S.C. Peters, T.E. Pilutti, E.H. Tseng, and K. Iagnemma. Semi-autonomous avoidance of moving hazards for passenger vehicles. In *ASME 2010 Dynamic Systems and Control Conference*, pages 141–148. American Society of Mechanical Engineers, 2010.

9 Appendix

9.1 CAD Drawings