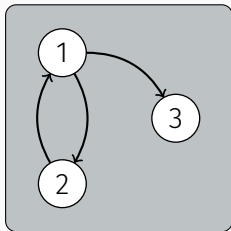


Algebraic Graphs with Class

Christoph Madlener

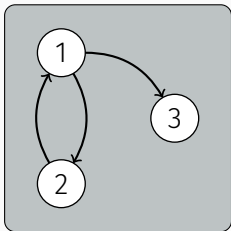
01.06.2021

Introduction



G_1

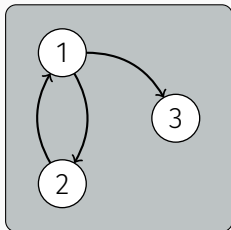
Introduction



G_1

$$G = (V, E) \text{ s.t. } E \subseteq V \times V$$

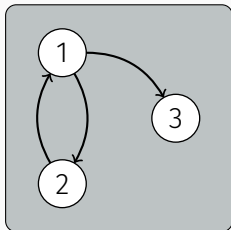
Introduction



$$G_1 = \left(\{1, 2, 3\}, \{(1, 2), (1, 3), (2, 1)\} \right)$$

$$G = (V, E) \text{ s.t. } E \subseteq V \times V$$

Introduction



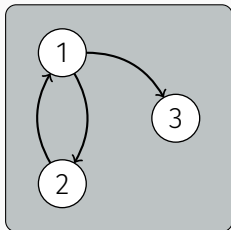
$$G = (V, E) \text{ s.t. } E \subseteq V \times V$$

$$G_1 = \left(\{1, 2, 3\}, \{(1, 2), (1, 3), (2, 1)\} \right)$$

In Haskell?

```
data G a = G { vs :: Set a, es :: Set (a,a) }
```

Introduction



$$G = (V, E) \text{ s.t. } E \subseteq V \times V$$

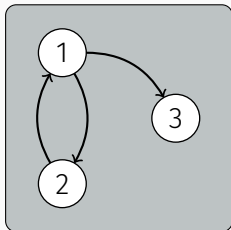
$$G_1 = (\{1, 2, 3\}, \{(1, 2), (1, 3), (2, 1)\})$$

In Haskell?

```
data G a = G { vs :: Set a, es :: Set (a,a) }
```

```
g1 = G [1,2,3] [(1,2), (1,3), (2,1)]
```

Introduction



$$G = (V, E) \text{ s.t. } E \subseteq V \times V$$

$$G_1 = \left(\{1, 2, 3\}, \{(1, 2), (1, 3), (2, 1)\} \right)$$

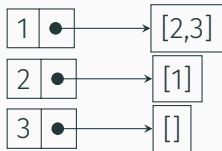
In Haskell?

```
data G a = G { vs :: Set a, es :: Set (a,a) }
```

```
g1 = G [1,2,3] [(1,2), (1,3), (2,1)]
```

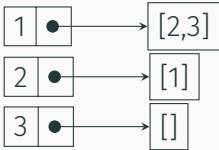
```
g2 = G [1,2] [(1,3)]       $E \not\subseteq V \times V$ 
```

containers
adjacency lists



containers

adjacency lists



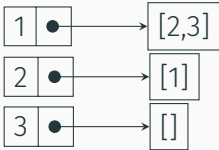
fgl

inductive graphs

- inductive datatype: Context of a vertex + Graph

containers

adjacency lists



$E \subseteq V \times V?$

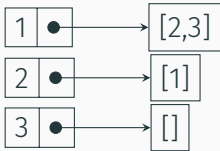
fgl

inductive graphs

- inductive datatype: Context of a vertex + Graph

containers

adjacency lists



$E \subseteq V \times V?$

- partial functions \rightarrow runtime errors

fgl

inductive graphs

- inductive datatype: Context of a vertex + Graph

Algebraic Graphs

- complete and consistent graph representation
- simple construction primitives (*“the core”*)

Algebraic Graphs

- complete and consistent graph representation
- simple construction primitives (*“the core”*)

Achieved by the datatype

```
data Graph a = Empty
             | Vertex a
             | Overlay (Graph a) (Graph a)
             | Connect (Graph a) (Graph a)
```

Empty (ε) & Vertex

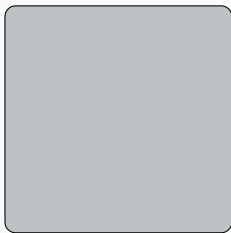
Empty - ε



$$\text{Empty} = \varepsilon = (\emptyset, \emptyset)$$

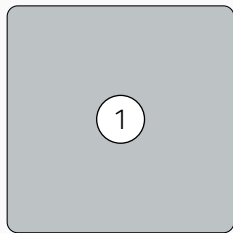
Empty (ε) & Vertex

Empty - ε



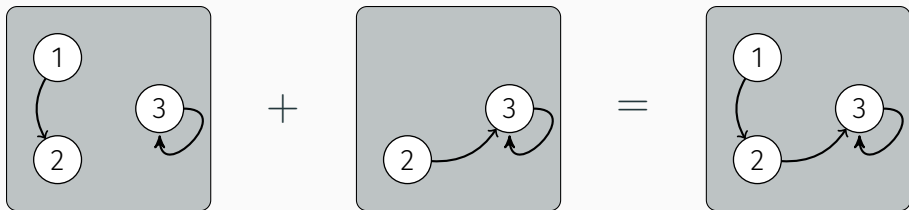
Empty $= \varepsilon = (\emptyset, \emptyset)$

Vertex



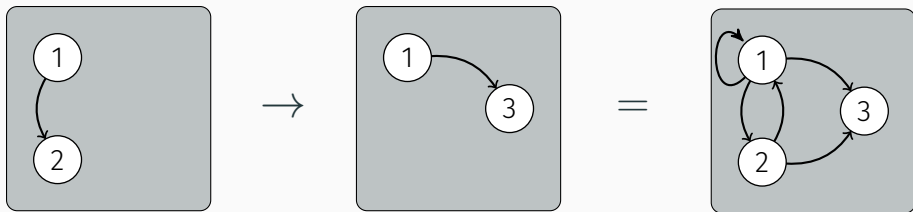
Vertex 1 $= (\{1\}, \emptyset)$

Overlay (+)



$$(V_1, E_1) + (V_2, E_2) := (V_1 \cup V_2, E_1 \cup E_2)$$

Connect (\rightarrow / $*$)



$$(V_1, E_1) \rightarrow (V_2, E_2) := (V_1 \cup V_2, E_1 \cup E_2 \cup V_1 \times V_2)$$

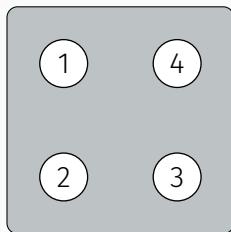
Graph Construction

```
vertices :: [a] -> Graph a  
vertices = foldr Overlay Empty . map Vertex
```

Graph Construction

```
vertices :: [a] -> Graph a  
vertices = foldr Overlay Empty . map Vertex
```

`vertices [1,2,3,4]` $=$



Graph Construction

```
edge :: a -> a -> Graph a
```

```
edge u v = Connect (Vertex u) (Vertex v)
```

Graph Construction

```
edge :: a -> a -> Graph a
```

```
edge u v = Connect (Vertex u) (Vertex v)
```

```
edges :: [(a,a)] -> Graph a
```

```
edges = foldr Overlay Empty . map (uncurry edge)
```

Graph Construction

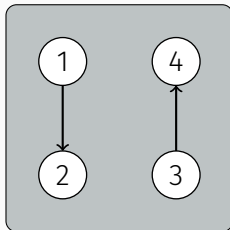
```
edge :: a -> a -> Graph a
```

```
edge u v = Connect (Vertex u) (Vertex v)
```

```
edges :: [(a,a)] -> Graph a
```

```
edges = foldr Overlay Empty . map (uncurry edge)
```

```
edges [(1,2),(3,4)] =
```



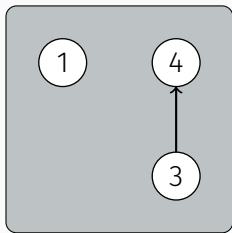
Graph Construction

```
graph :: [a] -> [(a,a)] -> Graph a  
graph vs es = Overlay (vertices vs) (edges es)
```

Graph Construction

```
graph :: [a] -> [(a,a)] -> Graph a  
graph vs es = Overlay (vertices vs) (edges es)
```

graph [1] [(3,4)] =



Graph Transformation - Functor

Functor

```
instance Functor Graph where
```

```
...
```

```
fmap f (Vertex u) = Vertex (f u)
```

```
...
```

Graph Transformation - Functor

Functor

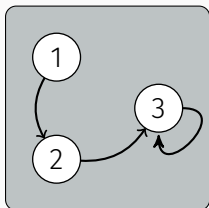
```
instance Functor Graph where
```

```
...
```

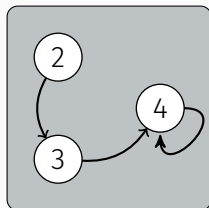
```
fmap f (Vertex u) = Vertex (f u)
```

```
...
```

fmap (+1)



=



Graph Transformation - Merging Vertices

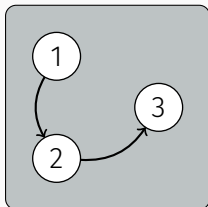
```
mergeVs :: (a -> Bool) -> a -> Graph a -> Graph a  
mergeVs p v = fmap $ \u -> if p u then v else u
```

Graph Transformation - Merging Vertices

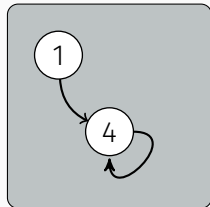
```
mergeVs :: (a -> Bool) -> a -> Graph a -> Graph a
```

```
mergeVs p v = fmap $ \u -> if p u then v else u
```

```
mergeVs (>1) 4
```



=



Graph Transformation - Monad

```
instance Monad Graph where
```

```
...
```

```
(Vertex u) >>= f = f u
```

```
...
```

Graph Transformation - Monad

```
instance Monad Graph where
    ...
    (Vertex u) >>= f = f u
    ...

splitVertex :: (a -> Bool) -> [a] -> Graph a
splitVertex p vs = g >>= \u -> if p u
                                then vertices vs
                                else Vertex u
```

Graph Transformation - Monad

```
instance Monad Graph where
```

```
...
```

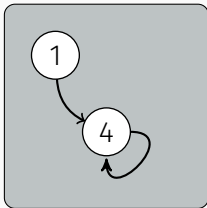
```
(Vertex u) >>= f = f u
```

```
...
```

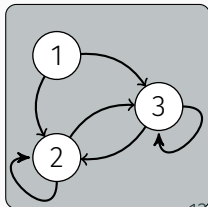
```
splitVertex :: (a -> Bool) -> [a] -> Graph a
```

```
splitVertex p vs = g >>= \u -> if p u  
                        then vertices vs  
                        else Vertex u
```

```
splitVertex 4 [2,3]
```



=



Graph Transformation - MonadPlus

```
instance Graph MonadPlus where
  mzero = Empty
  mplus = Overlay
```


Graph Transformation - MonadPlus

```
instance Graph MonadPlus where
    mzero = Empty
    mplus = Overlay

induce :: (a -> Bool) -> Graph a -> Graph a
induce = mfilter
```

Graph Transformation - MonadPlus

```
instance Graph MonadPlus where
```

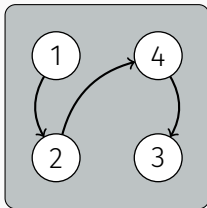
```
  mzero = Empty
```

```
  mplus = Overlay
```

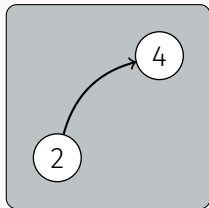
```
induce :: (a -> Bool) -> Graph a -> Graph a
```

```
induce = mfilter
```

`induce even`



=



Overlay (+) and connect (\rightarrow) almost form a semiring over graphs

Overlay (+) and connect (\rightarrow) almost form a semiring over graphs

- $(\mathcal{G}, +, \varepsilon)$ is an idempotent, commutative monoid

Overlay (+) and connect (\rightarrow) almost form a semiring over graphs

- $(\mathcal{G}, +, \varepsilon)$ is an idempotent, commutative monoid
- $(\mathcal{G}, \rightarrow, \varepsilon)$ is a monoid

Overlay (+) and connect (\rightarrow) almost form a semiring over graphs

- $(\mathcal{G}, +, \varepsilon)$ is an idempotent, commutative monoid
- $(\mathcal{G}, \rightarrow, \varepsilon)$ is a monoid
- \rightarrow distributes over $+$

Overlay (+) and connect (\rightarrow) almost form a semiring over graphs

- $(\mathcal{G}, +, \varepsilon)$ is an idempotent, commutative monoid
- $(\mathcal{G}, \rightarrow, \varepsilon)$ is a monoid
- \rightarrow distributes over $+$
- “shared” identity ε

Overlay (+) and connect (\rightarrow) almost form a semiring over graphs

- $(\mathcal{G}, +, \varepsilon)$ is an idempotent, commutative monoid
- $(\mathcal{G}, \rightarrow, \varepsilon)$ is a monoid
- \rightarrow distributes over $+$
- “shared” identity ε
- no “zero” for \rightarrow (i.e. $g \rightarrow 0 = 0$)

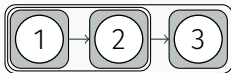
Additional axiom for algebra of graphs

$$x \rightarrow y \rightarrow z = x \rightarrow y + x \rightarrow z + y \rightarrow z$$

Decomposition

Additional axiom for algebra of graphs

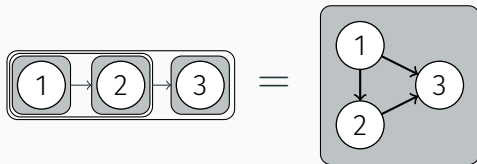
$$x \rightarrow y \rightarrow z = x \rightarrow y + x \rightarrow z + y \rightarrow z$$



Decomposition

Additional axiom for algebra of graphs

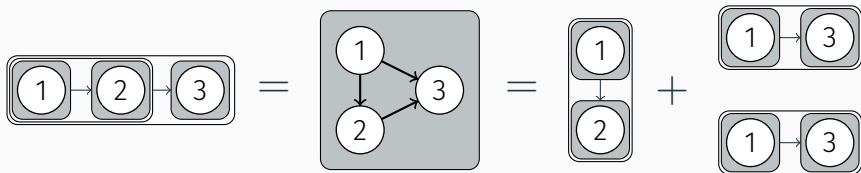
$$x \rightarrow y \rightarrow z = x \rightarrow y + x \rightarrow z + y \rightarrow z$$



Decomposition

Additional axiom for algebra of graphs

$$x \rightarrow y \rightarrow z = x \rightarrow y + x \rightarrow z + y \rightarrow z$$



Subgraph Relation

Define subgraphs in terms of $(+)$ and equality:

$$x \sqsubseteq y \iff x + y = y$$

Obtain other classes of graphs by modifying the set of axioms:

Obtain other classes of graphs by modifying the set of axioms:

- Undirected graphs: \leftrightarrow is commutative ($x \leftrightarrow y = y \leftrightarrow x$)

Obtain other classes of graphs by modifying the set of axioms:

- Undirected graphs: \leftrightarrow is commutative ($x \leftrightarrow y = y \leftrightarrow x$)
- Reflexive graphs: $x = x \rightarrow x$

Obtain other classes of graphs by modifying the set of axioms:

- Undirected graphs: \leftrightarrow is commutative ($x \leftrightarrow y = y \leftrightarrow x$)
- Reflexive graphs: $x = x \rightarrow x$
- Transitive graphs:

$$y \neq \varepsilon \Rightarrow (x \rightarrow y) + (y \rightarrow z) + (x \rightarrow z) = (x \rightarrow y) + (y \rightarrow z)$$

Obtain other classes of graphs by modifying the set of axioms:

- Undirected graphs: \leftrightarrow is commutative ($x \leftrightarrow y = y \leftrightarrow x$)
- Reflexive graphs: $x = x \rightarrow x$
- Transitive graphs:

$$y \neq \varepsilon \Rightarrow (x \rightarrow y) + (y \rightarrow z) + (x \rightarrow z) = (x \rightarrow y) + (y \rightarrow z)$$

- Preorders (reflexive + transitive), equivalence relations (preorder + undirected)

Obtain other classes of graphs by modifying the set of axioms:

- Undirected graphs: \leftrightarrow is commutative ($x \leftrightarrow y = y \leftrightarrow x$)
- Reflexive graphs: $x = x \rightarrow x$
- Transitive graphs:

$$y \neq \varepsilon \Rightarrow (x \rightarrow y) + (y \rightarrow z) + (x \rightarrow z) = (x \rightarrow y) + (y \rightarrow z)$$

- Preorders (reflexive + transitive), equivalence relations (preorder + undirected)
- Hypergraphs

Graph Equality

Structural equality is not suitable:

```
Overlay (Vertex 1) Empty == Vertex 1
```

Structural equality is not suitable:

```
Overlay (Vertex 1) Empty == Vertex 1
```

Eq instance for Algebraic Graphs

- Current implementation: build adjacency map

Structural equality is not suitable:

```
Overlay (Vertex 1) Empty == Vertex 1
```

Eq instance for Algebraic Graphs

- Current implementation: build adjacency map
- Possible approach: *minimize* graph expressions → *Modular Graph Decomposition*

Compact Representation for Dense Graphs

Fully connected (undirected) graph

```
clique :: [a] -> Graph a
```

```
clique = foldr Connect Empty . map Vertex
```

Compact Representation for Dense Graphs

Fully connected (undirected) graph

```
clique :: [a] -> Graph a
```

```
clique = foldr Connect Empty . map Vertex
```

- Linear size representation
- quadratic in size when using e.g. adjacency map

Compact Representation for Dense Graphs

Fully connected (undirected) graph

```
clique :: [a] -> Graph a
```

```
clique = foldr Connect Empty . map Vertex
```

- Linear size representation
- quadratic in size when using e.g. adjacency map

Open question

- Can we exploit this compact representation, i.e. find algorithms that work directly on algebraic graphs?

- using Isabelle/HOL

- using Isabelle/HOL
- inductive datatype \rightarrow proofs by induction, `auto`

Formal Verification

- using Isabelle/HOL
- inductive datatype → proofs by induction, `auto`
- `quotient_type` (think `Eq` instance) based on tuple representation

- using Isabelle/HOL
- inductive datatype → proofs by induction, `auto`
- `quotient_type` (think `Eq` instance) based on tuple representation

Future work

- Minimization
- Algorithms, applications beyond graph construction/transformation

Algebraic Graphs with CLASS

```
class Graph g where
  type Vertex g
  empty :: g
  vertex :: Vertex g -> g
  overlay :: g -> g -> g
  connect :: g -> g -> g
```

Algebraic Graphs with CLASS

```
class Graph g where
  type Vertex g
  empty :: g
  vertex :: Vertex g -> g
  overlay :: g -> g -> g
  connect :: g -> g -> g
```

→ Polymorphic graph construction/transformation library

- define `locale` in Isabelle/HOL (think Haskell class + axioms)

- define `local` in Isabelle/HOL (think Haskell class + axioms)
- equational reasoning for simple statements

`vertices xs \sqsubseteq clique xs`

- define `local` in Isabelle/HOL (think Haskell class + axioms)
- equational reasoning for simple statements

`vertices xs` \sqsubseteq `clique xs`

- formal proof of completeness and consistency

- formalized material on vertex walks, reachability

- formalized material on vertex walks, reachability
- probably additional axioms required ($\varepsilon \neq \text{vertex } u$)

- formalized material on vertex walks, reachability
- probably additional axioms required ($\varepsilon \neq \text{vertex } u$)

Future work

- more graph theory (e.g. strongly connected components)
- algorithms

- formalized material on vertex walks, reachability
- probably additional axioms required ($\varepsilon \neq \text{vertex } u$)

Future work

- more graph theory (e.g. strongly connected components)
- algorithms

→ *Verified* polymorphic graph library

Conclusion

- alternative approach to graph construction/transformation
 - small core of primitives - safe and complete

Conclusion

- alternative approach to graph construction/transformation
 - small core of primitives - safe and complete
- two main directions for future work
 1. exploit compact representation/other applications of data type
 2. exploit polymorphism of type class/locale