

Problem 1.

$$S_{ij} = S_{ji}$$

$$S'_{ij} = d_{ik} d_{jl} S_{kl} = d_{ik} d_{jl} S_{lk} = S'_{ji} \quad \text{Q.E.D.}$$

Problem 2.

$$\Pi'_{ij} = d_{ik} d_{jl} \Pi_{kl} = d_{ik} \Pi_{kl} d_{lj}^T = (d \Pi d^T)_{ij}$$

$$\Rightarrow \Pi' = d \Pi d^T$$

Problem 3.

$$d = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}, \quad \epsilon_{ij} = -\epsilon_{ji}, \quad \epsilon_{12} = 1$$

$$\Rightarrow \epsilon = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad d^T = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\epsilon'_{ij} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} =$$

$$= \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \sin \theta & \cos \theta \\ -\cos \theta & \sin \theta \end{pmatrix} =$$

$$= \begin{pmatrix} \cos \theta \sin \theta - \cos \theta \sin \theta & \cos^2 \theta + \sin^2 \theta \\ -\sin^2 \theta - \cos^2 \theta & \cos \theta \sin \theta - \cos \theta \sin \theta \end{pmatrix} =$$

$$= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \epsilon_{ij} \quad \text{Q.E.D.}$$

Problem 4.

1. $C_{ijkl} = A_{ij} B_{kl}$ ~~has~~ has n^4 components.

$$\cancel{C_{ijkl}} \quad C'_{ijkl} = A'_{ij} B'_{kl} = d_{is} d_{jt} A_{st} d_{km} d_{ln} B_{mn} =$$

$$= d_{is} d_{jt} d_{km} d_{ln} C_{stmn} \Rightarrow C \text{-Tensor of rank 4}$$

$$2. D_{il} = \sum_j C'_{ijjl} = \sum_j A'_{ij} B'_{jl} = \sum_j d_{is} d_{jt} A_{st} d_{jm} d_{ln} C_{lmns} =$$

$$= \sum_j d_{is} d_{jt} d_{jm} d_{ln} C_{lmns} = \sum_j d_{is} d_{jt} d_{jm} d_{ln} C_{lmns} =$$

$$= d_{is} d_{jt} D_{ms} \quad \text{Q.E.D.}$$

Problem 5.

$$\frac{\partial \psi}{\partial x_i} = \frac{\partial \psi}{\partial x_e} \frac{\partial x_e}{\partial x_i} \quad \psi = \psi(x_1, x_2, x_3), \quad D_{ij} = \frac{\partial^2 \psi}{\partial x_i \partial x_j};$$

$$\frac{\partial \psi}{\partial x_i} = \frac{\partial \psi}{\partial x_e} \frac{\partial x_e}{\partial x_i}$$

$$x_i = (d^{-1})_{ij} x_j$$

$$r^2 = x^T \cdot x = (x^T)^T \cdot x = 0$$

$$\Rightarrow x^T d^T dx = x^T \cdot x \Rightarrow d^T d = E \Rightarrow d^T = d^{-1}$$

$$\frac{\partial}{\partial x_i} \left(\frac{\partial \psi}{\partial x_j} \right) = \frac{\partial}{\partial x_i} \left(\frac{\partial \psi}{\partial x_e} \frac{\partial x_e}{\partial x_j} \right) =$$

$$= \frac{\partial}{\partial x_k} \left(\frac{\partial \psi}{\partial x_e} \frac{\partial x_e}{\partial x_j} \right) \frac{\partial x_k}{\partial x_i} = \left[\frac{\partial^2 \psi}{\partial x_k \partial x_e} \frac{\partial x_e}{\partial x_j} \frac{\partial x_k}{\partial x_i} + \frac{\partial \psi}{\partial x_e} \frac{\partial x_k}{\partial x_i} \frac{\partial^2 x_e}{\partial x_j \partial x_k} \right]$$

$$\text{Because } \frac{\partial x_e}{\partial x_k} = \delta_{ek} \Rightarrow \frac{\partial}{\partial x_j} \left(\frac{\partial x_e}{\partial x_k} \right) = 0$$

$$\Rightarrow \frac{\partial^2 \psi}{\partial x_i \partial x_j} = \frac{\partial x_e}{\partial x_j} \frac{\partial x_k}{\partial x_i} \frac{\partial^2 \psi}{\partial x_k \partial x_e} =$$

$$= (d^{-1})_{ej} (d^{-1})_{ki} \frac{\partial^2 \psi}{\partial x_k \partial x_e} = d_{ik} d_{je} \frac{\partial^2 \psi}{\partial x_k \partial x_e} \Rightarrow$$

$$\Rightarrow D'_{ij} = d_{ik} d_{je} D_{ek} \Rightarrow P\text{-Tensor of rank 2. Q.E.D.}$$

Problem 6.

$$A = \begin{pmatrix} 0 & \omega_3 & -\omega_2 \\ -\omega_3 & 0 & \omega_1 \\ \omega_2 & -\omega_1 & 0 \end{pmatrix}, \quad \omega_k = \frac{1}{2} A_{ij} \varepsilon_{ijk}$$

$$\omega'_k = \frac{1}{2} A'_{ij} \varepsilon_{ijk} = \frac{1}{2} d_{im} d_{jn} d_{ir} d_{js} d_{kt} A_{mn} \varepsilon_{rst} =$$

$$= \frac{1}{2} d_{mi}^T d_{in} \cdot d_{nj}^T d_{js} d_{kt} A_{mn} \varepsilon_{rst} =$$

$$= \frac{1}{2} \delta_{mp} \delta_{ns} d_{kt} A_{mn} \varepsilon_{rst} = \frac{1}{2} d_{kt} A_{ij} \varepsilon_{ijt}$$

$$= d_{kt} \omega_t = \frac{1}{2} d_{kt} \omega_t \quad \text{Q.E.D.}$$

Problem 4. 3)

$$P' = D'_{ii} = d_{ik} d_{ie} P_{ke} = d_{ki}^T d_{ie} P_{ke} =$$

$$= \delta_{ke} P_{ke} = P_{ii} = P \quad \text{Q.E.D.}$$

Problem 7.

$$1. \sum_j A_{ij} \delta_{jk} = A_{ik} \quad , \quad \sum_i A_{ij} \delta_{ik} = A_{kj}$$

$$\sum_{ij} A_{ij} \delta_{ij} = A_{ii} = A_{11} + A_{22} + A_{33}$$

$$2. \sum_k \delta_{ik} \delta_{kj} = \delta_{ij} \quad , \quad \sum_{ik} \delta_{ik} \delta_{ik} = 3, \quad \sum_{ik} \delta_{ik} \delta_{ki} = 3$$

Problem 8.

$$\epsilon_{ij} = \begin{vmatrix} \delta_{1i} & \delta_{1j} \\ \delta_{2i} & \delta_{2j} \end{vmatrix} \quad , \quad \epsilon_{lm} = \begin{vmatrix} \delta_{1l} & \delta_{1m} \\ \delta_{2l} & \delta_{2m} \end{vmatrix}$$

$$\epsilon_{ij} \epsilon_{lm} = \det \left[\begin{pmatrix} \delta_{1i} & \delta_{1j} \\ \delta_{2i} & \delta_{2j} \end{pmatrix} \begin{pmatrix} \delta_{1l} & \delta_{1m} \\ \delta_{2l} & \delta_{2m} \end{pmatrix} \right] = \begin{vmatrix} \det A^T = \det A & \\ \det AB = \det A \cdot \det B & \end{vmatrix}$$

$$= \begin{vmatrix} \delta_{1i} \delta_{1l} + \delta_{2i} \delta_{2l} & \delta_{1i} \delta_{1m} + \delta_{2i} \delta_{2m} \\ \delta_{1j} \delta_{1l} + \delta_{2j} \delta_{2l} & \delta_{1j} \delta_{1m} + \delta_{2j} \delta_{2m} \end{vmatrix} = \begin{vmatrix} \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl} & \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl} \\ \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl} & \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl} \end{vmatrix} =$$

$$= \begin{vmatrix} \delta_{il} & \delta_{im} \\ \delta_{jl} & \delta_{jm} \end{vmatrix} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl} \quad \text{Q.E.D.}$$

Problem 9.

$$1. \epsilon_{ijk} \epsilon_{lmn} = \det \begin{pmatrix} \delta_{il} & \delta_{im} & \delta_{in} \\ \delta_{jl} & \delta_{jm} & \delta_{jn} \\ \delta_{kl} & \delta_{km} & \delta_{kn} \end{pmatrix} = \delta_{ik} (\delta_{jm} \delta_{kn} - \delta_{km} \delta_{jn}) +$$

$$+ \delta_{im} (\delta_{jn} \delta_{kl} - \delta_{jl} \delta_{kn}) + \delta_{in} (\delta_{jl} \delta_{km} - \delta_{kl} \delta_{jm})$$

$$2. \epsilon_{ijk} \epsilon_{emk} = \det \begin{pmatrix} \delta_{il} & \delta_{im} & \delta_{in} \\ \delta_{jl} & \delta_{jm} & \delta_{jn} \\ \delta_{kl} & \delta_{km} & \delta_{kn} \end{pmatrix} = \det \begin{pmatrix} \delta_{il} & \delta_{jl} & \delta_{kl} \\ \delta_{im} & \delta_{jm} & \delta_{km} \\ \delta_{ik} & \delta_{jk} & \delta_{kk} \end{pmatrix} =$$

$$= \delta_{ik} \begin{vmatrix} \delta_{jl} & \delta_{kl} \\ \delta_{jm} & \delta_{km} \end{vmatrix} - \delta_{jk} \begin{vmatrix} \delta_{il} & \delta_{kl} \\ \delta_{im} & \delta_{km} \end{vmatrix} + \delta_{kk} \begin{vmatrix} \delta_{il} & \delta_{jl} \\ \delta_{im} & \delta_{jm} \end{vmatrix} =$$

$$= \begin{vmatrix} \delta_{jl} & \delta_{il} \delta_{ke} \\ \delta_{jm} & \delta_{im} \delta_{km} \end{vmatrix} - \begin{vmatrix} \delta_{il} & \delta_{jk} \delta_{kl} \\ \delta_{im} & \delta_{jm} \delta_{km} \end{vmatrix} + 3 \begin{vmatrix} \delta_{il} & \delta_{jl} \\ \delta_{im} & \delta_{jm} \end{vmatrix} =$$

$$= \begin{vmatrix} \delta_{jl} & \delta_{il} \\ \delta_{jm} & \delta_{im} \end{vmatrix} - \begin{vmatrix} \delta_{il} & \delta_{jl} \\ \delta_{im} & \delta_{jm} \end{vmatrix} + 3 \begin{vmatrix} \delta_{il} & \delta_{jl} \\ \delta_{im} & \delta_{jm} \end{vmatrix} = \delta_{il} \delta_{jm} \delta_{im} \delta_{jl} - \delta_{im} \delta_{jl} \delta_{il} \delta_{jm} =$$

$$3. \epsilon_{ijk} \epsilon_{ljk} = \delta_{il} \delta_{jj} - \delta_{il} \delta_{jj} = 3 \delta_{il} - \delta_{il} = 2 \delta_{il}$$

$$4. \epsilon_{ijk} \epsilon_{ijk} = 2 \delta_{ii} = 2 \cdot 3 = 6$$

Problem 10.

$$A_{ij} = -A_{ji}, \quad S_{ij} = S_{ji}$$

$$\sum_{ij} A_{ij} S_{ij} = -\sum_{ij} A_{ji} S_{ji} = -\sum_{ji} A_{ij} S_{ij} \Rightarrow$$

$$\Rightarrow 2 \sum_{ij} A_{ij} S_{ij} = 0 \Rightarrow \sum_{ij} A_{ij} S_{ij} = 0 \quad \text{Q.E.D.}$$

Problem 11

$$1) \quad b_i = \pi_{ij} a_j \Rightarrow b'_i = \pi'_{ij} a'_j = d_{ik} d_{je} \pi_{ke} d_{jm} a_m =$$

$$= d_{ik} d_{mj}^T d_{je} \pi_{ke} a_m = d_{ik} \delta_{me} \pi_{ke} a_m =$$

$$= d_{ik} \pi_{kj} a_j = d_{ik} b_k \quad \text{Q.E.D.}$$

$$2) \quad c_j = \sum_i \pi_{ij} a_i \Rightarrow c'_j = \sum_i d_{ik} d_{je} \pi_{ke} d_{im} a_m =$$

$$= d_{im}^T d_{ik} d_{je} \pi_{ke} a_m = \delta_{mk} d_{je} \pi_{ke} a_m =$$

$$= d_{je} \pi_{se} a_s = d_{je} c_e \quad \text{Q.E.D.}$$