1

Gate Assignment - 2

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Download all the python codes from

https://github.com/cmaspi/EE3900/tree/main/ GateAssignment-2/code

latex-tikz codes from

https://github.com/cmaspi/EE3900/blob/main/ GateAssignment-2/main.tex

1 Problem

(GATE EC 2009 Q42) The 4-point discrete fourier transform (DFT) of a discrete time sequence [1,0,2,3] is given by

- 1) [0, -2 + 2i, 2, -2 2i]
- 2) [2, 2 + i, 6, 2 2i]
- 3) [6, 1-3j, 2, 1+3j]
- 4) [6, -1 + 3j, 0, -1, -3j]

2 Solution

The discrete input signal is

$$x(n) = [1, 0, 2, 3]$$
 (2.0.1)

Let \mathbf{F}_N be the N-point DFT matrix.

Using the property of complex exponentials, we can express \mathbf{F}_N in terms of $\mathbf{F}_{N/2}$

$$\mathbf{F}_{N} = \begin{pmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{pmatrix} \begin{pmatrix} \mathbf{F}_{N/2} & \mathbf{0} \\ \mathbf{0} & \mathbf{F}_{N/2} \end{pmatrix} \mathbf{P}_{N} \qquad (2.0.2)$$

Where

$$\mathbf{F}_{N} = \begin{pmatrix} 1 & 1 & \cdots & 1\\ 1 & w & \cdots & w^{N-1}\\ \vdots & \vdots & \ddots & \vdots\\ 1 & w^{N-1} & \cdots & w^{(N-1)(N-1)} \end{pmatrix}$$
(2.0.3)

where $w = e^{\frac{-2\pi j}{N}}$

$$\mathbf{D}_{N} = \begin{pmatrix} w_{2N}^{0} & 0 & \cdots \\ 0 & w_{2N}^{1} & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix}$$
 (2.0.4)
$$\begin{pmatrix} X(2) \\ X(3) \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \end{pmatrix} - \begin{pmatrix} 3 \\ 3j \end{pmatrix}$$

$$\mathbf{D}_N = \operatorname{diag}(w_{2N}^0, w_{2N}^1, \dots, w_{2N}^{N-1}) \tag{2.0.5}$$

 P_N is the permutation matrix defined as

$$\mathbf{P}_{N} = \left[a_{ij} \right]_{N \times N}, \ i, j \in \{0, 1, \dots, N - 1\}$$
 (2.0.6)

$$a_{ij} = \begin{cases} 1 & j = 2i, \ i < \frac{N}{2} \\ 1 & j = 2\left(i - \frac{N}{2}\right) + 1, \ i \ge \frac{N}{2} \\ 0 & otherwise \end{cases}$$
 (2.0.7)

For N = 4

$$\mathbf{F}_4 = \begin{pmatrix} \mathbf{I}_2 & \mathbf{D}_2 \\ \mathbf{I}_2 & -\mathbf{D}_2 \end{pmatrix} \begin{pmatrix} \mathbf{F}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{F}_2 \end{pmatrix} \mathbf{P}_4 \tag{2.0.8}$$

 I_2 is 2×2 matrix

$$\mathbf{D}_2 = \begin{pmatrix} w_4^0 & 0\\ 0 & w_4^1 \end{pmatrix} \tag{2.0.9}$$

$$\mathbf{P}_4 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \tag{2.0.10}$$

Now,

$$\begin{pmatrix} X(0) \\ X(1) \end{pmatrix} = \begin{pmatrix} X_e(0) \\ X_e(1) \end{pmatrix} + \mathbf{D}_2 \begin{pmatrix} X_o(0) \\ X_o(1) \end{pmatrix}$$
(2.0.11)

$$\begin{pmatrix} X(2) \\ X(3) \end{pmatrix} = \begin{pmatrix} X_e(0) \\ X_e(1) \end{pmatrix} - \mathbf{D}_2 \begin{pmatrix} X_o(0) \\ X_o(1) \end{pmatrix}$$
(2.0.12)

This results in

$$\begin{pmatrix} X(0) \\ X(1) \end{pmatrix} = \mathbf{F}_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & -j \end{pmatrix} \mathbf{F}_2 \begin{pmatrix} 0 \\ 3 \end{pmatrix}$$
 (2.0.13)

$$\begin{pmatrix} X(0) \\ X(1) \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \end{pmatrix} + \begin{pmatrix} 3 \\ 3j \end{pmatrix} \tag{2.0.14}$$

$$\begin{pmatrix} X(0) \\ X(1) \end{pmatrix} = \begin{pmatrix} 6 \\ -1 + 3j \end{pmatrix} \tag{2.0.15}$$

and

$$\begin{pmatrix} X(2) \\ X(3) \end{pmatrix} = \mathbf{F}_2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & -j \end{pmatrix} \mathbf{F}_2 \begin{pmatrix} 0 \\ 3 \end{pmatrix}$$
 (2.0.16)

$$\begin{pmatrix} X(2) \\ X(3) \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \end{pmatrix} - \begin{pmatrix} 3 \\ 3j \end{pmatrix} \tag{2.0.17}$$

$$\begin{pmatrix} X(2) \\ X(3) \end{pmatrix} = \begin{pmatrix} 0 \\ -1 - 3j \end{pmatrix} \tag{2.0.18}$$

The correct answer is option 4

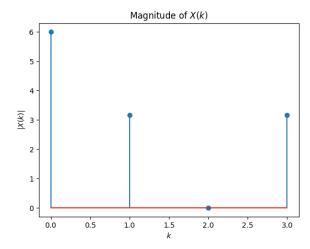


Fig. 4: Magnitude of X(k)

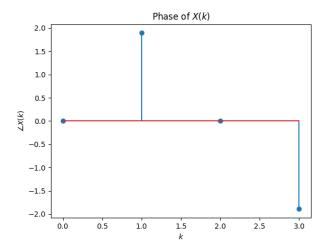


Fig. 4: Phase of X(k)