Reinforcement - Leavining Assignment - 2

Question - 1)

a) we terminate the algorithm when 
$$\| V_{k+1} - V_k \|_{\infty} \le \varepsilon$$

Lets say we didn't stop it at this condition, instead we let the value function converge.

The iteration scheme is

$$V^{(k+1)}(s) = \sum_{\alpha} \pi(\alpha | s) \sum_{s'} \rho_{ss'}^{\alpha} (R_{ss'}^{\alpha} + \gamma V^{(k)}(s)) - 1$$

$$V^{(k+2)}(s) = \sum_{\alpha} \pi(\alpha | s) \sum_{s'} \rho_{ss'}^{\alpha} (R_{ss'}^{\alpha} + \gamma V^{(k+1)}(s)) - 2$$

$$\sqrt{(k+2)}(s) - \sqrt{(k+1)}(s) = \sum_{\alpha} \pi(\alpha | s) \sum_{s'} P_{ss'}^{\alpha} \gamma \left( \sqrt{(k+1)}(s) - \sqrt{(k)}(s) \right) - 3$$

we know that  $\|V^{(k+i)} - V^{(k)}\|_{\infty} \leq \varepsilon$ 

$$\Rightarrow |V^{(k+1)}(s)| \leq \epsilon \quad \forall s \in S$$

Using 3 and 9

similarly we can say 
$$-V^{2} \leq V^{(k+2)} - V^{(k+2)}(s) \leq V^{2}(s)$$

Now

$$- Y \in \{ (k+2)(s) - V^{(k+1)}(s) \}$$
  $\{ (k+3)(s) - V^{(k+2)}(s) \}$   $\{ (k+3)(s) - V^{(k+2)}(s) \}$ 

Adding these equations

Hence Proved

b) we strow that L (Bellman optimality operator) is a contraction map. Since VT is the optimal value,  $L(V^{\pi}) = V^{\pi} \iff V^{\pi} \text{ is fixed for}$ from the properties of contraction map we know that 11 L(V(V)) - L(VT) 1 5 8 11 V(KM) - VT / - (1) our algorithm L(V(K)) = V(K+1) Substituting in (1) & using  $L(v^{\pi}) = V^{\pi}$ 1 V(X+1) - VT 1 E Y 1 V(N - VT)  $\| \sqrt{k} - \sqrt{\pi} \|_{\infty} \leq \| \gamma \| \sqrt{k-1} - \sqrt{\pi} \|_{\infty}$ 11 52 - VATILON & 8 11 V(1) - VT/100

L(V) = max [Ra+ YPa] c) pa is probability matrix which has all positive interes. we know that land or if x ? o -Claim: Pax >0 if x >0 all the entries of Para positive, and also all the entries of x we positive, we me take inner product in rowwise manner all the terms would again be non negative. ⇒ P<sup>a</sup>(v-v) > 0 => Pau > Pau adding Ra on both sides Pr+Ro > pa+Ra This holds for all a  $\lim_{\alpha} \left( P_{v}^{\alpha} + R^{\alpha} \right) > \max_{\alpha} \left( P_{v}^{\alpha} + R^{\alpha} \right)$ 

Hence Proved

⇒ L(V) > L(U)

## Problem-2

## Part-a

For P

$$||P(v) - P(u)|| \le \gamma_1 ||v - u||$$

and for Q

$$||Q(v) - Q(u)|| \le \gamma_2 ||v - u||$$

In the first equation substitute v by Q(v) and u by Q(u). We get,

$$||P(Q(v)) - P(Q(u))|| \le \gamma_1 ||Q(v) - Q(u)||$$

From the second equation

$$||P(Q(v)) - P(Q(u))|| \le \gamma_1 \gamma_2 ||v - u||$$

 $\therefore P \circ Q$  is a contraction mapping

Now, there's nothing unique about P or Q, we could just swap them and we would still get the same result. Or we would follow the same procedure and get

$$||Q(P(v)) - Q(P(u))|| \le \gamma_1 \gamma_2 ||v - u||$$

## Part-b

From the solution to above subpart, we can see that the contraction coefficient for both the composite functions is  $\gamma_1\gamma_2$  where  $\gamma_1$ ,  $\gamma_2$  are the contraction coefficients for P and Q respectively.

## Part-c

The value iteration scheme under the operator would converge to a unque solution if it follows

$$||B(v) - B(u)|| \le ||v - u||$$

Writing B as a composite function, we can arrive at a general solution with a specific behaviour

$$||F(L(v)) - F(L(u))|| \le ||v - u||$$

Assume  $||F(v) - F(u)|| \le \eta ||v - u||$  Now

$$||F(L(v)) - F(L(u))|| \le \eta ||L(v) - L(u)|| \le \eta \gamma ||v - u||$$

We get that  $\eta < \frac{1}{\gamma}$ 

Problem - 3)

a) A generic form of the trajectory is

S...A

S can occur > 1 times

b) First visit MC makes sense only when we are given some experience However, we can find the value vector by calculating expectation of  $G_t$ 

for a trajectory with m of size m, the state S would have been visited m-1 times

 $G_t^{(m)} = m-1$  since state S is visited m-1 times

Note that the trajectory starts  $E[G_t] = \sum_{m=2}^{\infty} \rho(1-p)(m-1)$  with S

$$= \rho + 2\rho(1-\rho) + 3\rho(1-\rho)^{2} + \dots$$

 $V(s) = p + 2p(1-p) + 3p(1-p)^{2} + \dots$   $(1-p)V(s) = p(1-p) + 2p(1-p)^{2} + \dots$ 

p V(s) = p+ p(1-p) + p(1-p) 2+...

$$\rho V(s) = \frac{\rho}{\rho}$$

$$V(s) = 1$$

for the value at A. All the trajectories and with A and that's the first visit to A in that trajectory Since. The reward for being in State A is 0

$$\therefore \quad \forall = \left( \begin{array}{c} \frac{1}{P} \\ 0 \end{array} \right)$$

c) Again consider a trajectory  $G_{t}^{(m)} = \frac{1+2+...+(m-1)}{m-1} = \frac{(m-1)(m-1)}{2(m-1)}$ 

V(A) = 0 using the same argument is the previous subpart.  $E[G_t] = V(S) = \sum_{m=2}^{\infty} p(1-p)^{m-2} \frac{m}{2}$ 

$$V(S) = p + p(1-p)\frac{3}{2} + p(1-p)^{2}2+...$$

$$V(s)(1-p) = p(1-p) + p(p)^{\frac{2}{3}} + \dots$$

$$V(s) (1-p) = p(1-p) + p(1-p)^{2} + ...$$

$$V(S) p = P + \frac{1}{2} (P(1-p) + P(1-p) + \dots$$

$$= P + \frac{1}{2} \frac{p}{R} (1-p)$$

 $= p + \frac{1}{2} - \frac{1}{2}$ 

$$V(s) = \frac{p+1}{2p} = \frac{1}{2} + \frac{1}{2p}$$

$$V = (I - YP)^{-1}R$$

$$= \left( \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} PP & PP \\ 0 & 0 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} \rho & -\rho \\ 0 & 1 \end{bmatrix}^{-\frac{1}{2}} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \frac{1}{P} \begin{bmatrix} 1 & P \\ 0 & P \end{bmatrix} \begin{bmatrix} 1 \\ 6 \end{bmatrix}$$
$$= \begin{bmatrix} \frac{1}{P} \\ x \end{bmatrix}$$

e) Jes, every visit MC estimate is

The true value function Evaluated at state S

is 1'P

while every visit MC gives us  $\frac{1}{2} + \frac{1}{2p}$ we know that p < 1

 $\frac{1}{2\rho} > \frac{1}{2}$   $\frac{1}{\rho} - \frac{1}{2\rho} > \frac{1}{2}$ 

 $\Rightarrow \frac{1}{\rho} > \frac{1}{2} + \frac{1}{2\rho}$ ... there is bias

d) Every visit MC will converge faster

because the number of samples would be for more in case of

would be four more in case of every visit MC compared to first visit MC.

$$E_{\pi} (8_{t} | S_{t} = S) = E_{\pi} [\gamma_{t+1} + \gamma_{V} (S_{t+1}) - V^{\pi}(S_{t}) | S_{t} = S]$$

Expectation is linear

$$\Rightarrow \qquad \bigvee^{\pi}(s) - \bigvee^{\tau}(s)$$

$$= E_{\pi} [Y_{t+1} + \gamma V^{\pi}(s_{t+1}) | s_{t} = s, a_{t} = a] - E[V^{\pi}(s_{t}) | s_{t} = s, a_{t} = a]$$

vT(s)

$$= Q^{\pi}(s, a) - V^{\pi}(s)$$

c) 
$$G_t^{\lambda} = (1-\lambda) \sum_{n=1}^{\infty} \lambda^{n-1} G_t^{(n)}$$

The first coefficient is

 $Q^{\pi}(s, a)$ 

The coefficients we 
$$(1-\lambda)\lambda$$
,  $(1-\lambda)\lambda^2$ , ...

by definition 
$$(1/2) \leq (1/2)$$

$$\eta(\lambda) \log \lambda \leq -\log 2$$

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$$\frac{\log 2}{\log \lambda}$$

we can write  $\gamma(x) \leq \log v_{x}^{2}$ 

given  $\eta(\lambda) = 3$ 

$$3 \leq \log_{1/\lambda}^{2}$$

$$\lambda^{-3} \geq 2$$

$$\lambda \geq 2^{-1/3}$$

$$\lambda > 2^{-1/3}$$

Problem 5

$$\alpha_{1} = \frac{1}{t^{p}}$$

$$\sum_{r=1}^{\infty} \alpha_{t} = \sum_{r=1}^{\infty} \frac{1}{t^{p}}$$

$$\sum_{r=1}^{\infty} \alpha_{t} = \sum_{r=1}^{\infty} \frac{1}{t^{p}}$$

$$\sum_{r=1}^{\infty} \frac{1}{t^{p}} \leq \sum_{t=1}^{\infty} \frac{1}{t^{p$$

$$\log t | \overset{\infty}{\leq} \sum_{t=1}^{\infty} \frac{1}{t} \leq 1 + \log t | \overset{\infty}{\leq}$$

the summation diverges

1) 
$$\alpha_t = \frac{1}{t}$$

$$\sum \alpha_t^2 < \infty$$
 }  $P = 1$  diverges  $\sum \alpha_t^2 < \infty$  }  $P = 2$  converges

2) 
$$\alpha_{t} = \frac{1}{t^{2}}$$
  
 $\Xi \alpha = \Xi + \frac{1}{t^{2}} < \infty$  }  $\beta = 2$  converges

$$\sum \alpha_t^2 = \sum_{t=1}^{t} \langle \alpha \rangle$$
  $\beta p = 4$  converges

3) 
$$\alpha_{4} = \frac{1}{t^{2/3}}$$

$$\sum \alpha_{i} = \sum \frac{1}{t^{2/3}} = \infty$$
  $\int P = \frac{2}{3}$  diverges  $\sum \alpha_{i}^{2} = \sum \frac{1}{t^{4/3}} < \infty$   $\int P = \frac{4}{3}$  converges

 $\alpha_{t} = \frac{1}{t^{1/2}}$ 

$$\sum \alpha_1 = \sum \frac{1}{t^{1/2}} = \infty$$
  $\int \rho = \frac{1}{2}$  divergen

$$\sum \alpha_t^2 = \sum_{t=0}^{\infty} \sum_{t=0}^{\infty} \int_{\mathbb{R}^2} P^{-1} diverges$$

i. it won't converge